

Chapter 5: Introduction to Digital Communication



AAiT

Addis Ababa Institute of Technology
አዲስ አበባ ተክኖሎጂ ሊቃናተኝ-ት/ዩ-ን-ቲ
Addis Ababa University
አዲስ አበባ ዩኒቨርሲቲ

Undergraduate Program
School of Electrical and Computer Engineering

Contents

- Introduction to Digital Communication
- Analog to digital conversion
- Baseband and Band pass Transmission of Digital Data
 - Line coding
 - Digital to analog conversion



Digital communications is:

- Simply the practice of exchanging information by using finite sets of signals.
- Is all about coding (at least at the physical layer).
- Is concerned with answering the question
 - *Which signal was transmitted?*

Analog ?

Digital ?

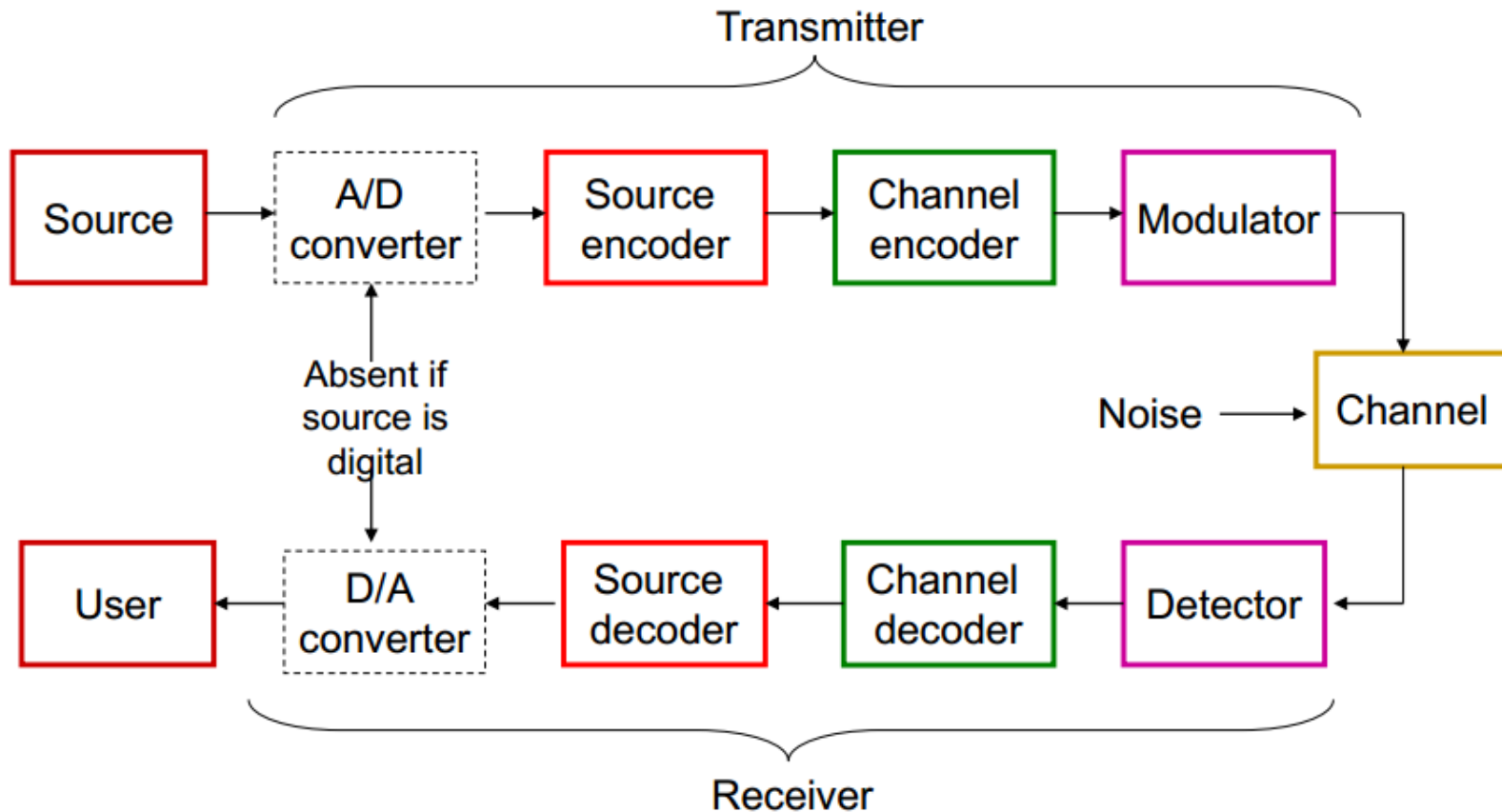


Why Digital Communication ??

- **Cheap Hardware**
 - flexible, complex hardware is becoming cheaper all the time.
- **Demand for new services**
 - e.g. email, ecommerce, teleworking, network applications etc.
- **Control of Quality**
 - i.e. powerful error control techniques can be employed to guarantee high quality communication.
- **Compatibility and flexibility**
 - digital signals are easier and cheaper to store and process than analogue signals.
- **Transmission**
 - digital signals are more spectrally efficient than analogue signals which means more information can be carried in a given bandwidth.
- **Security**
 - powerful encryption techniques exist to ensure the confidentiality and integrity of the information, critical for ecommerce applications

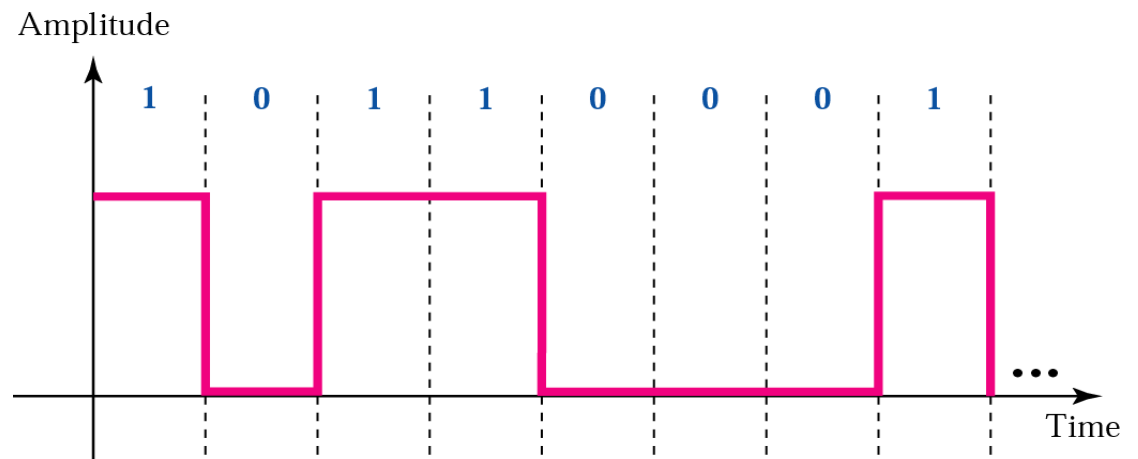


Digital Communication System

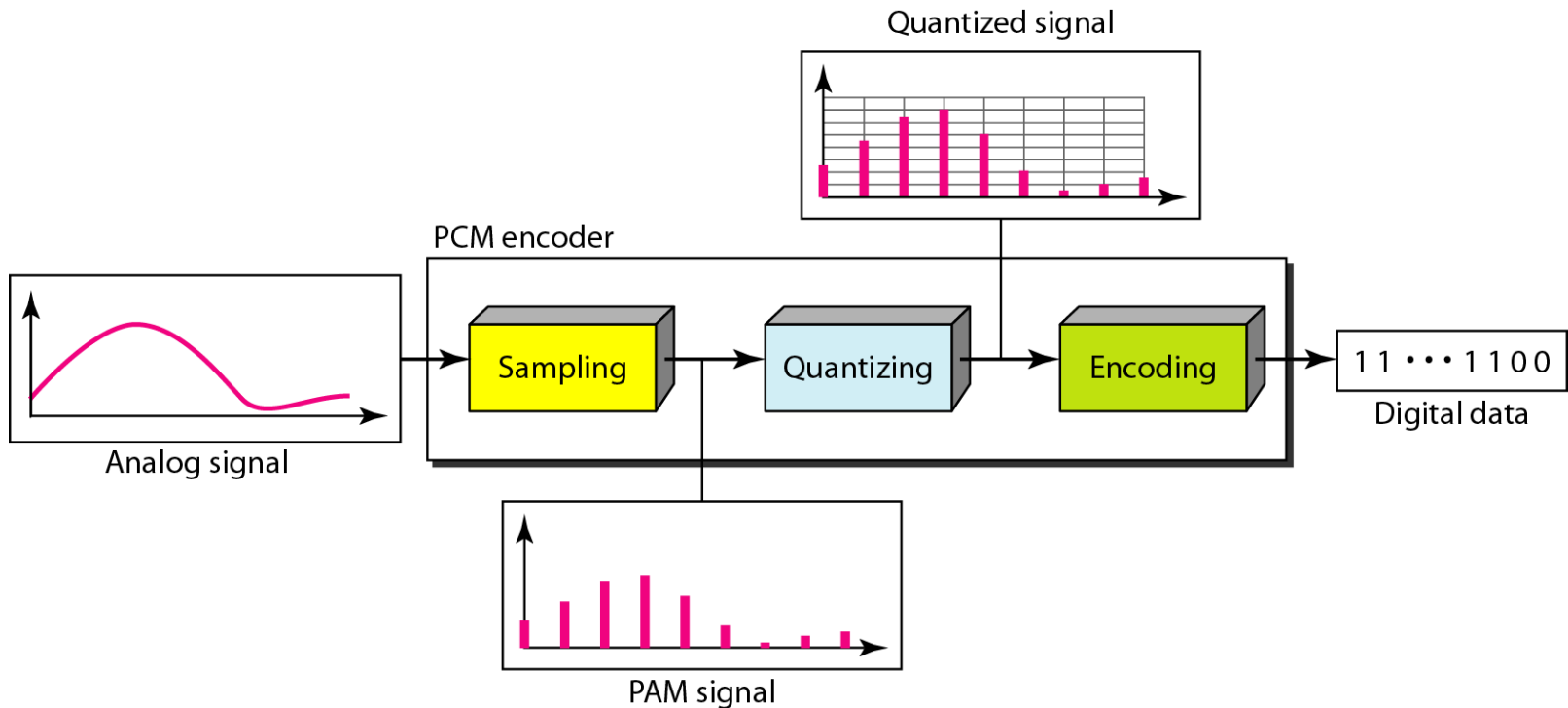


Digital terms

- Pulse
- Pulse duration
- Pulse amplitude
- Signal strength



Analog to digital conversion



Analog to digital conversion

- **Sampling:** an analog signal is converted into a corresponding sequence of samples that are usually spaced uniformly in time.
 - Proper selection of the sampling rate, so that the sequence of samples can uniquely define the original analog signal!!!
 - anti-aliasing filter might be used.
- **Quantization:** Approximating (rounding –off) the sampled values to a finite number of discrete amplitude levels.
- **Encoding:** The discrete signals coded in binary form.

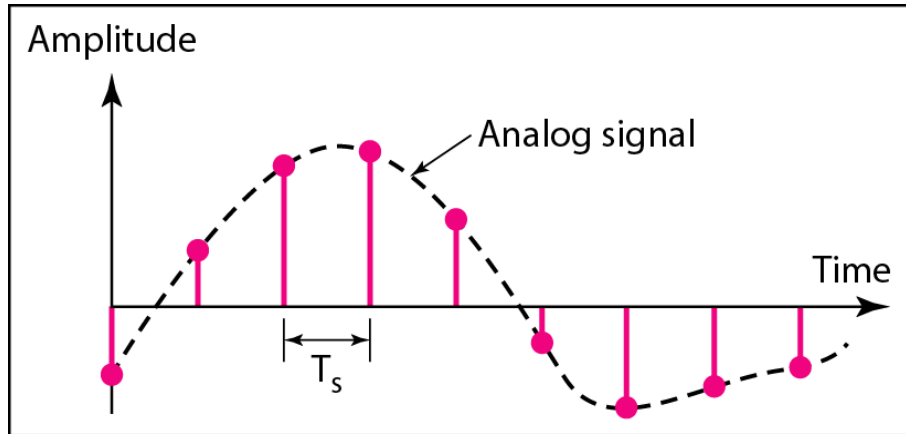


Sampling

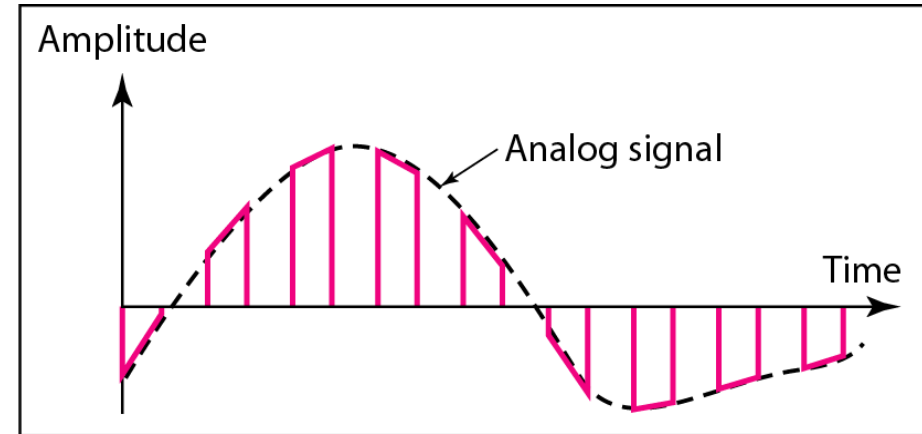
- Analog signal is sampled every T_s sec.
 - T_s is referred to as the sampling interval.
 - $f_s = 1/T_s$ is called the sampling rate or sampling frequency.
- According to the *Nyquist theorem*, the sampling rate must be at least 2 times the highest frequency contained in the signal.
- There are 3 sampling methods:
 - *Ideal* - an impulse at each sampling instant
 - *Natural* - a pulse of short width with varying amplitude
 - *Flattop* - sample and hold, like natural but with single amplitude value
- The process is referred to as pulse amplitude modulation PAM and the outcome is a signal with analog (non integer) values



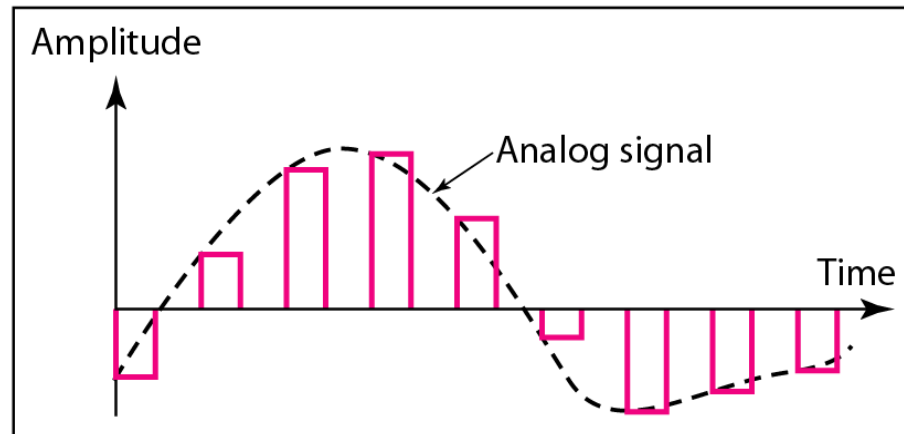
Three different sampling methods for PCM



a. Ideal sampling



b. Natural sampling

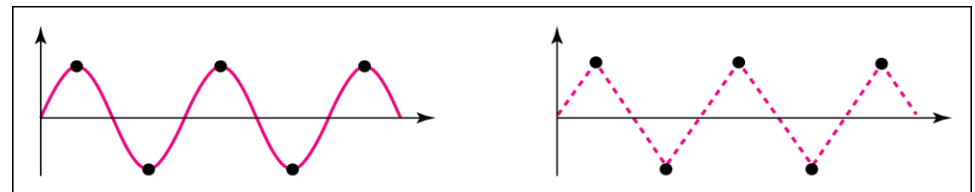


c. Flat-top sampling

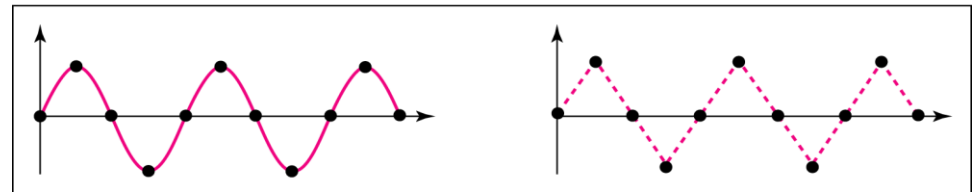


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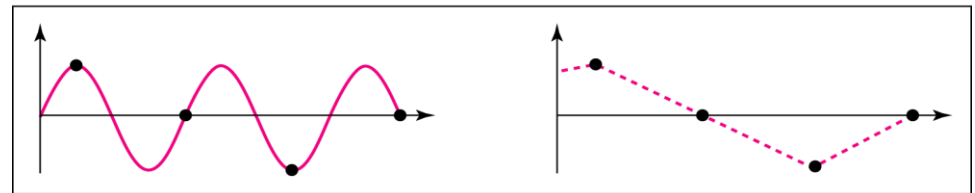
- For an intuitive example of the Nyquist theorem, let us sample a simple sine wave at three sampling rates: $f_s = 4f$ (2 times the Nyquist rate), $f_s = 2f$ (Nyquist rate), and $f_s = f$ (one-half the Nyquist rate). Figure shows the sampling and the subsequent recovery of the signal



a. Nyquist rate sampling: $f_s = 2f$



b. Oversampling: $f_s = 4f$



c. Undersampling: $f_s = f$



Example 1:

- Standard sampling rate for telephone network is adopted to be 8000 Hz.

Example 2:

- A complex low-pass signal has a bandwidth of 200 kHz.
What is the minimum sampling rate for this signal?



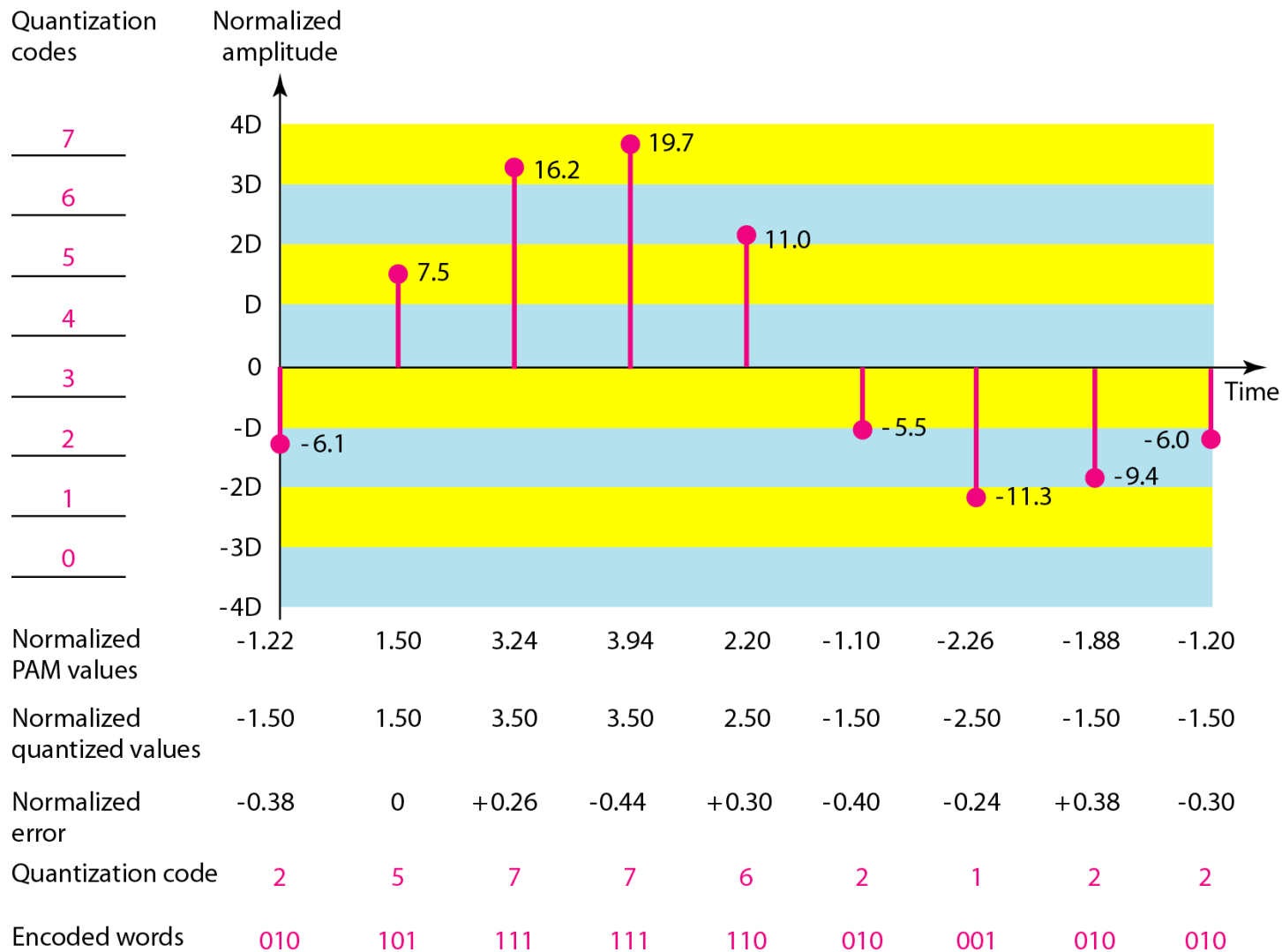
Quantization

- Sampling results in a series of pulses of varying amplitude values ranging between two limits: a min and a max.
- The amplitude values are infinite between the two limits.
- We need to map the *infinite* amplitude values onto a finite set of known values.
- This is achieved by dividing the distance between min and max into L quantization levels (zones), each of height Δ .

$$\Delta = (\max - \min) / L \dots \dots \text{uniform quantization}$$



Figure Quantization and encoding of a sampled signal



Quantization Levels

- The midpoint of each zone is assigned a value from 0 to $L-1$ (resulting in L values)
- Each sample falling in a zone is then approximated to the value of the midpoint.



Quantization Zones

- Assume we have a voltage signal with amplitudes $V_{\min} = -20V$ and $V_{\max} = +20V$.
- We want to use $L=8$ quantization levels.
- Zone width $\Delta = (20 - -20)/8 = 5$
- The 8 zones are: -20 to -15, -15 to -10, -10 to -5, -5 to 0, 0 to +5, +5 to +10, +10 to +15, +15 to +20
- The midpoints are: -17.5, -12.5, -7.5, -2.5, 2.5, 7.5, 12.5, 17.5



Encoding : Assigning Codes to Zones

- Each zone is then assigned a binary code.
- The number of bits required to encode the zones, or the number of bits per sample as it is commonly referred to, is obtained as follows:

$$n_b = \lceil \log_2 L \rceil$$

- Given our example, $n_b = 3$
- The 8 zone (or level) codes are therefore: 000, 001, 010, 011, 100, 101, 110, and 111
- Assigning codes to zones:
 - 000 will refer to zone -20 to -15
 - 001 to zone -15 to -10, etc.



Quantization Error

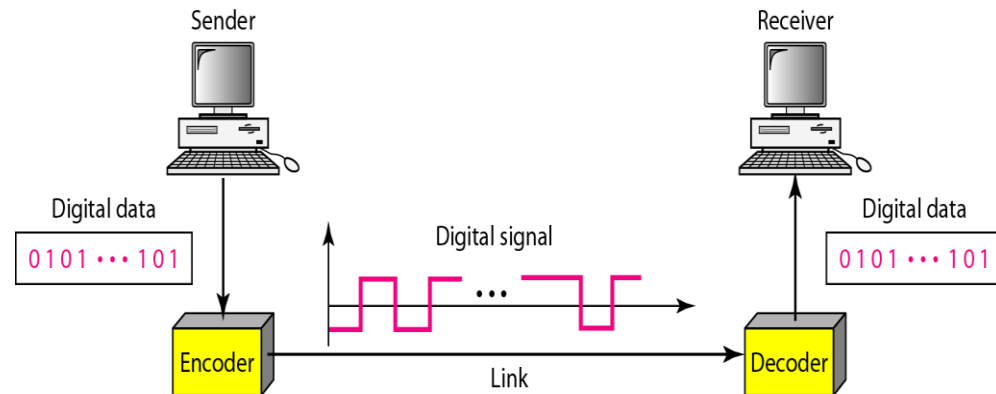
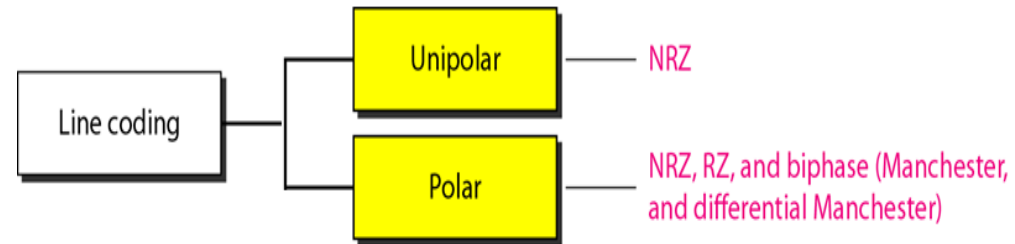
- When a signal is quantized, we introduce an error , **max of $\Delta/2$** - the coded signal is an approximation of the actual amplitude value.
 - Irreversible Noise of **$\Delta^2/12$**
- The difference between actual and coded value (midpoint) is referred to as the quantization error.
 - **The more zones, the smaller Δ which results in smaller errors.**
 - BUT, the more zones the more bits required to encode the samples -> ***higher bit rate***
- The bit rate of a PCM signal can be calculated from the number of bits per sample x the sampling rate

$$\text{Bit rate} = n_b \times f_s$$



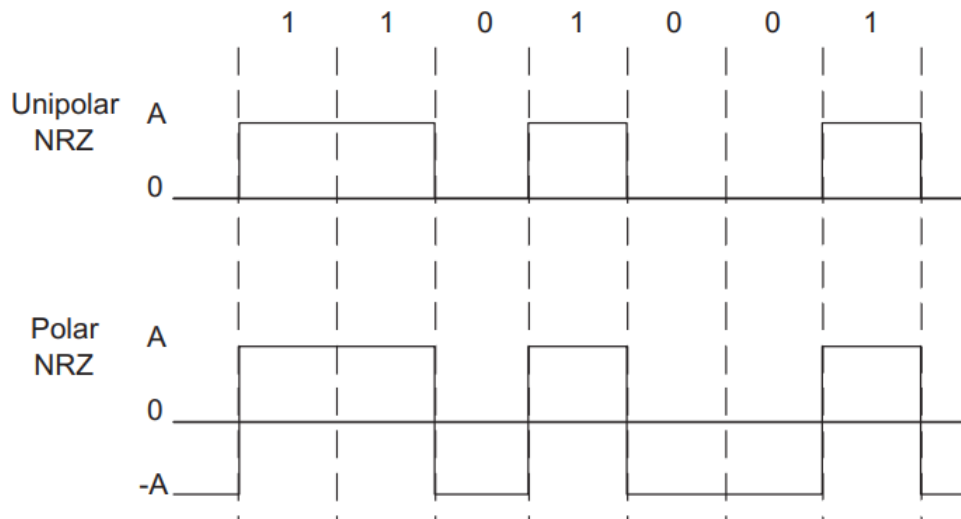
Line Coding: Baseband Transmission of Digital Data

- Electrical representation of that binary sequence
 - Converting a string of 1's and 0's (digital data) into a sequence of signals that denote the 1's and 0's.
- For example a high voltage level (+V) could represent a "1" and a low voltage level (0 or -V) could represent a "0".



Non-Return To Zero

- All signal levels are on one side of the time axis - either above or below
- The signal level does not return to zero during a symbol transmission.
- Scheme is prone to DC components. It has no synchronization or any error detection. It is simple but costly in power consumption.



- The voltages are on both sides of the time axis.
- Polar NRZ scheme can be implemented with two voltages. E.g. +V for 1 and -V for 0.
- There are two versions:
 - *NRZ - Level (NRZ-L)* - positive voltage for one symbol and negative for the other
 - *NRZ - Inversion (NRZ-I)* - the change or lack of change in polarity determines the value of a symbol. E.g. a “1” symbol inverts the polarity a “0” does not.



Cont....

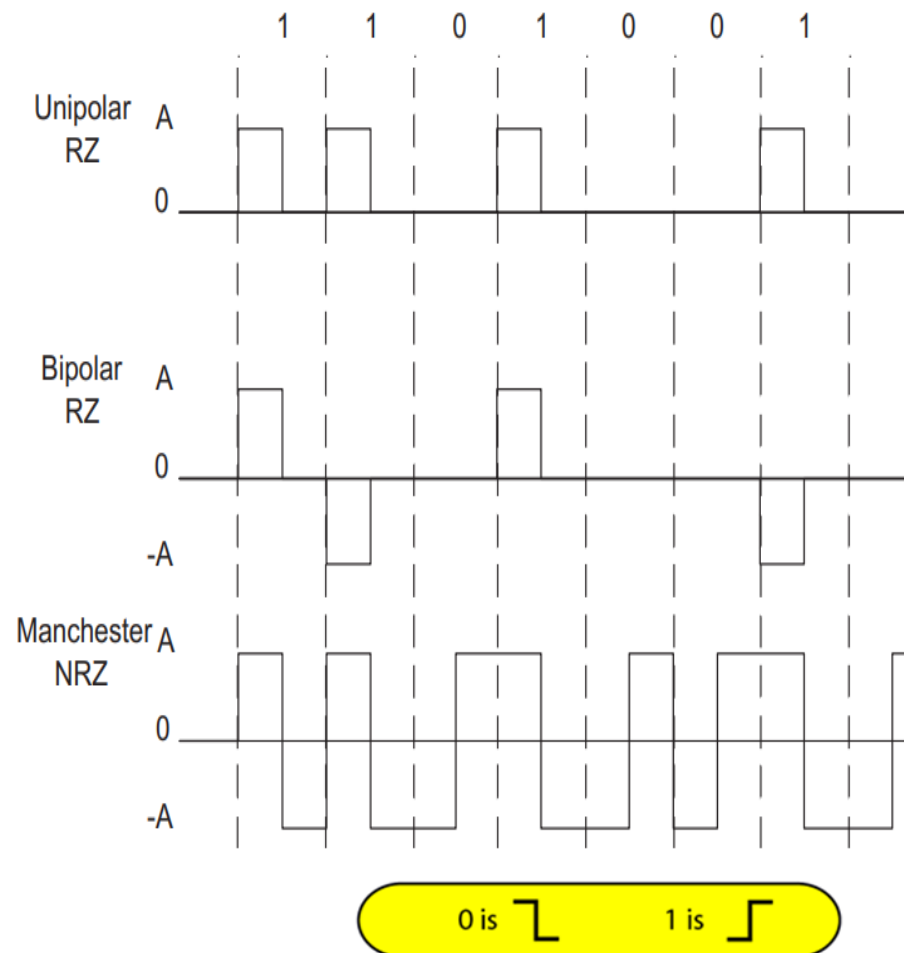
Note:

- In NRZ-L the level of the voltage determines the value of the bit. In NRZ-I the inversion or the lack of inversion determines the value of the bit.
- NRZ-L and NRZ-I both have a DC component problem, it is worse for NRZ-L. Both have no self synchronization & no error detection. Both are relatively simple to implement.



Cont....

- **Bipolar (Pseudoternary) Signaling:** Binary 1's are represented by alternating +ve or -ve values. The binary 0 is represented by a zero level.
 - This is also called alternate mark inversion (AMI) signaling
- **Manchester Signaling:** Each binary 1 is represented by a positive half-bit period pulse followed by a negative half-bit period pulse. Similarly, a binary 0 is represented by a negative half-bit period pulse followed by a positive half-bit period pulse.
 - This type of signaling is also called split-phase encoding



Mapping Data symbols onto Signal levels

- A data symbol (or element) can consist of a number of data bits:
 - 1, 0 or
 - 11, 10, 01,
- A data symbol can be coded into a single signal element or multiple signal elements
 - 1 \rightarrow +V, 0 \rightarrow -V
 - 1 \rightarrow +V and -V, 0 \rightarrow -V and +V
- The ratio 'r' is the number of data elements carried by a signal element.

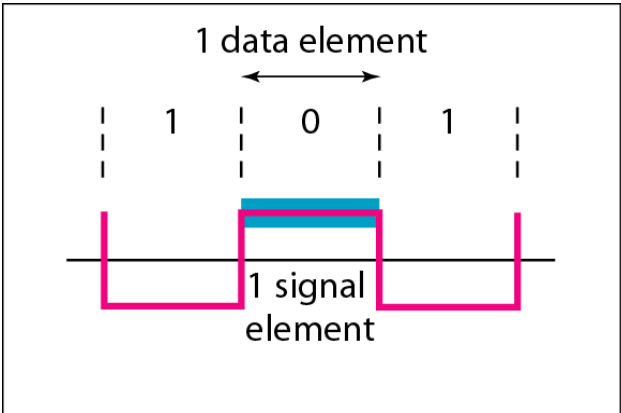


Relationship between data rate and signal rate

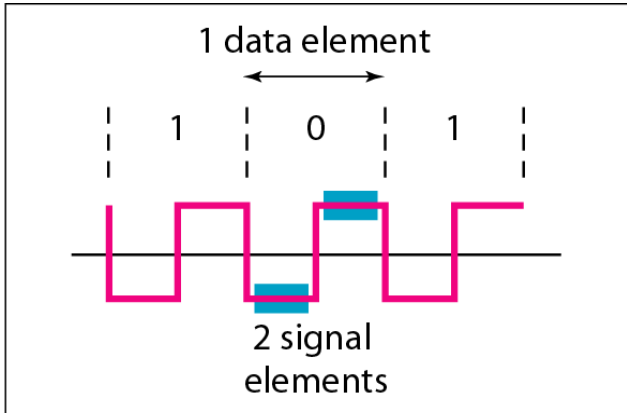
- The data rate defines the number of bits sent per sec - bps. It is often referred to the bit rate.
- The *signal rate* is the number of signal elements sent in a second and is measured in *bauds*. It is also referred to as the modulation rate.
- Goal is to increase the data rate at the same time as reducing the baud rate.



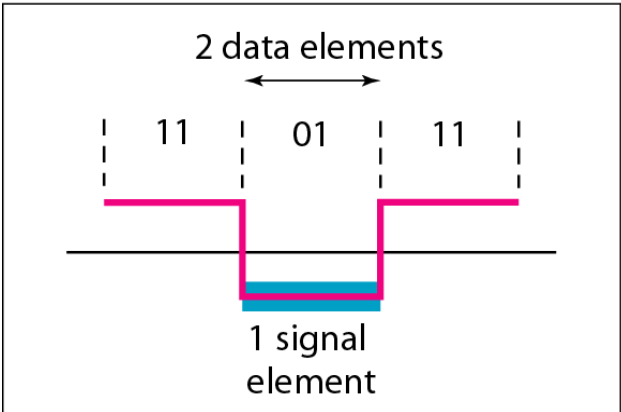
Signal element versus data element



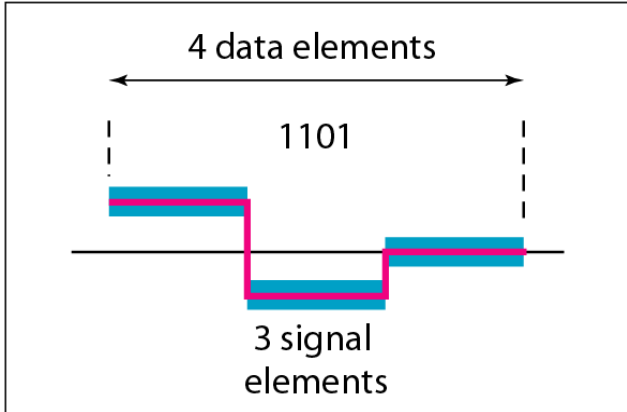
a. One data element per one signal element ($r = 1$)



b. One data element per two signal elements ($r = \frac{1}{2}$)



c. Two data elements per one signal element ($r = 2$)

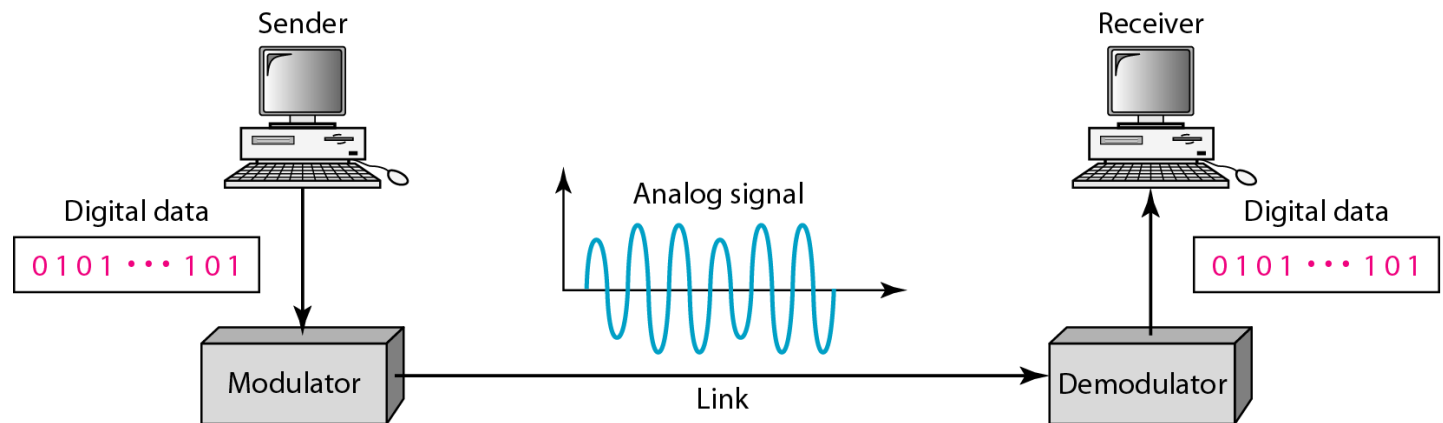


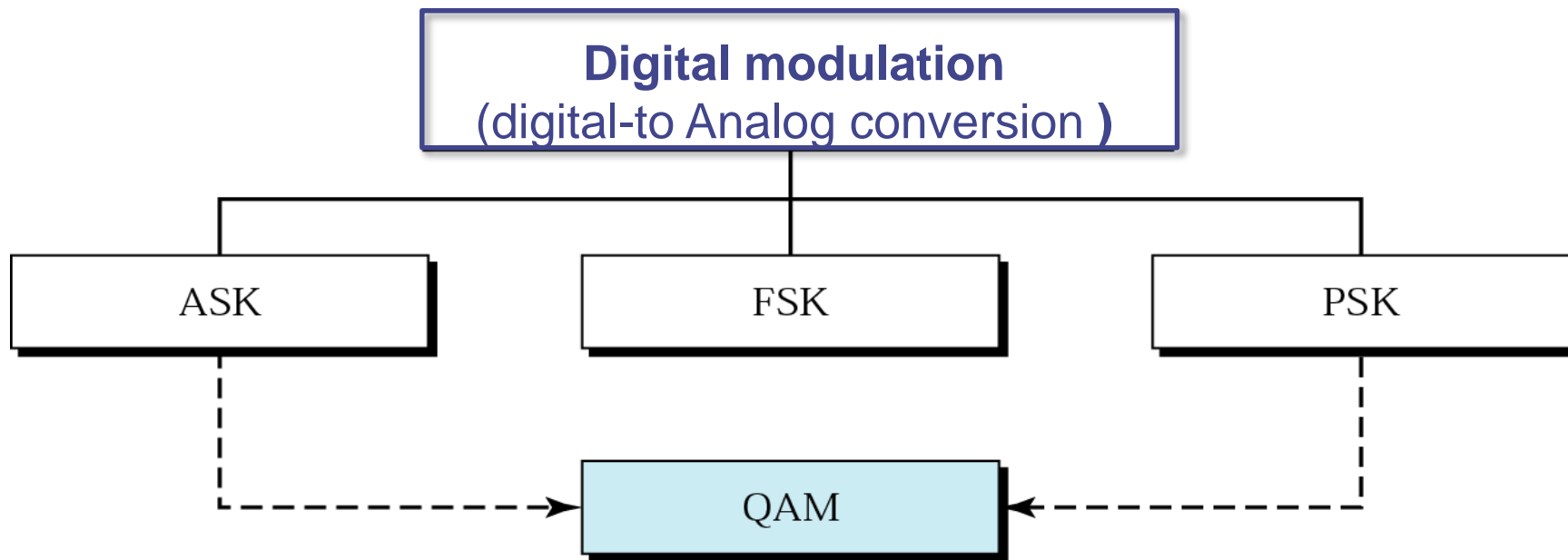
d. Four data elements per three signal elements ($r = \frac{4}{3}$)



Band pass Transmission of Digital Data

- Digital modulation (Digital-to-analog conversion) is the process of changing one of the characteristics of an analog signal based on the information in digital data.
 - Digital data needs to be carried on an analog signal.
- A carrier signal (frequency f_c) performs the function of transporting the digital data in an analog waveform.
- The analog carrier signal is manipulated to uniquely identify the digital data being carried.

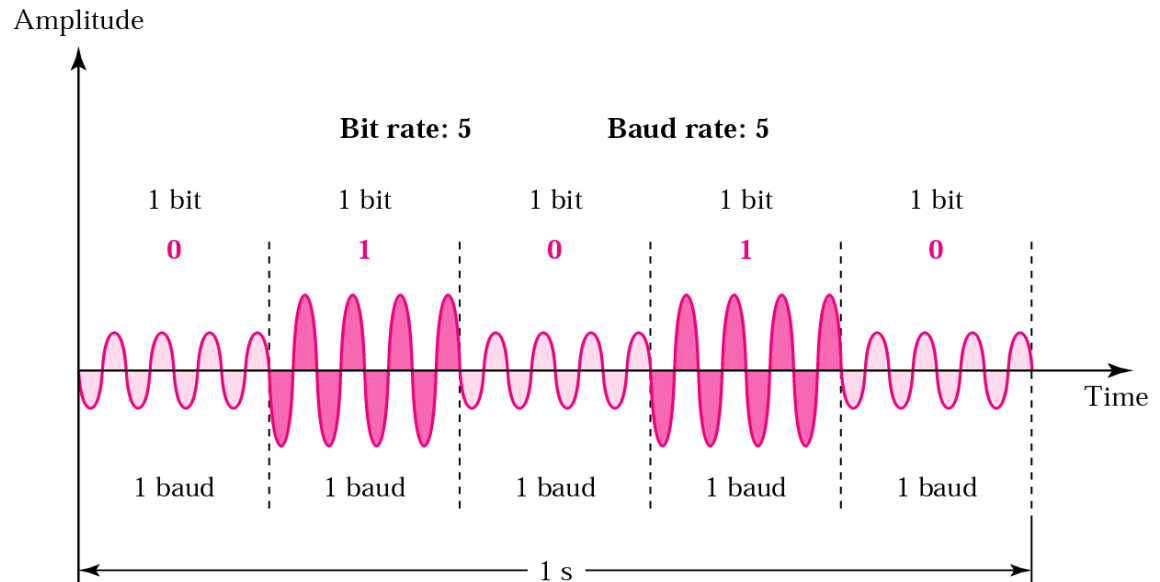




Amplitude Shift Keying (ASK)

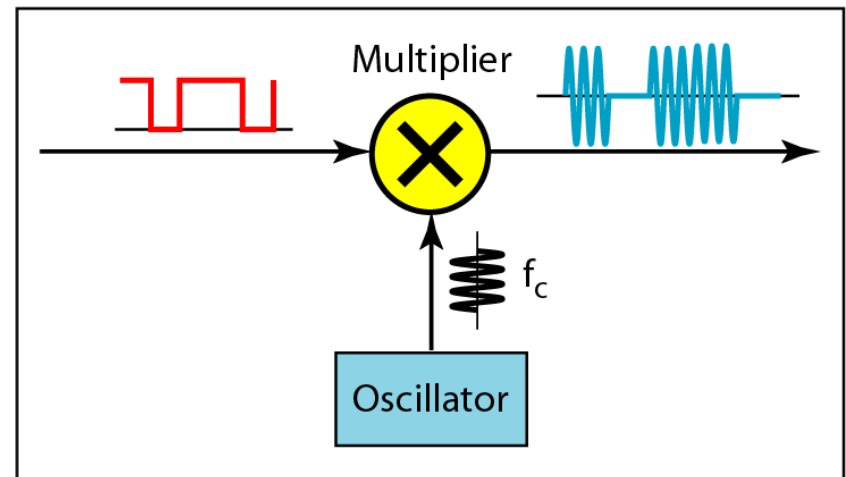
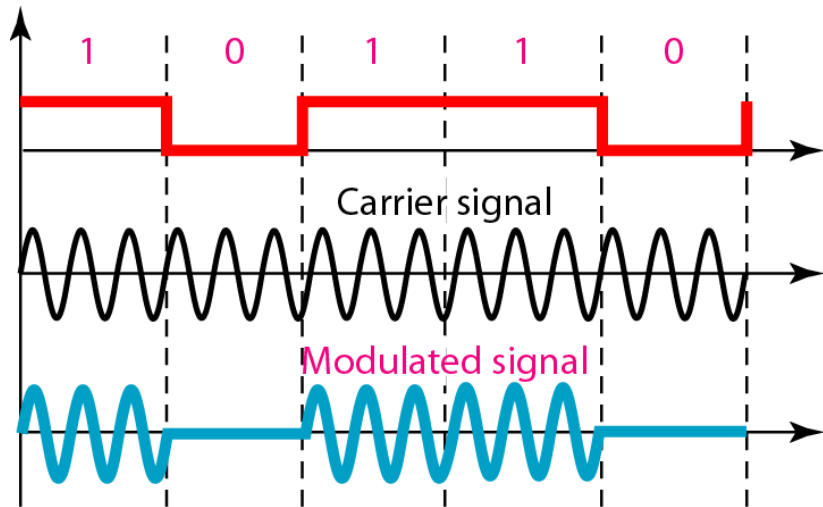
$$s(t) = \begin{cases} A \cos(2\pi f_c t) & \text{binary 1} \\ 0 & \text{binary 0} \end{cases}$$

On/Off keying



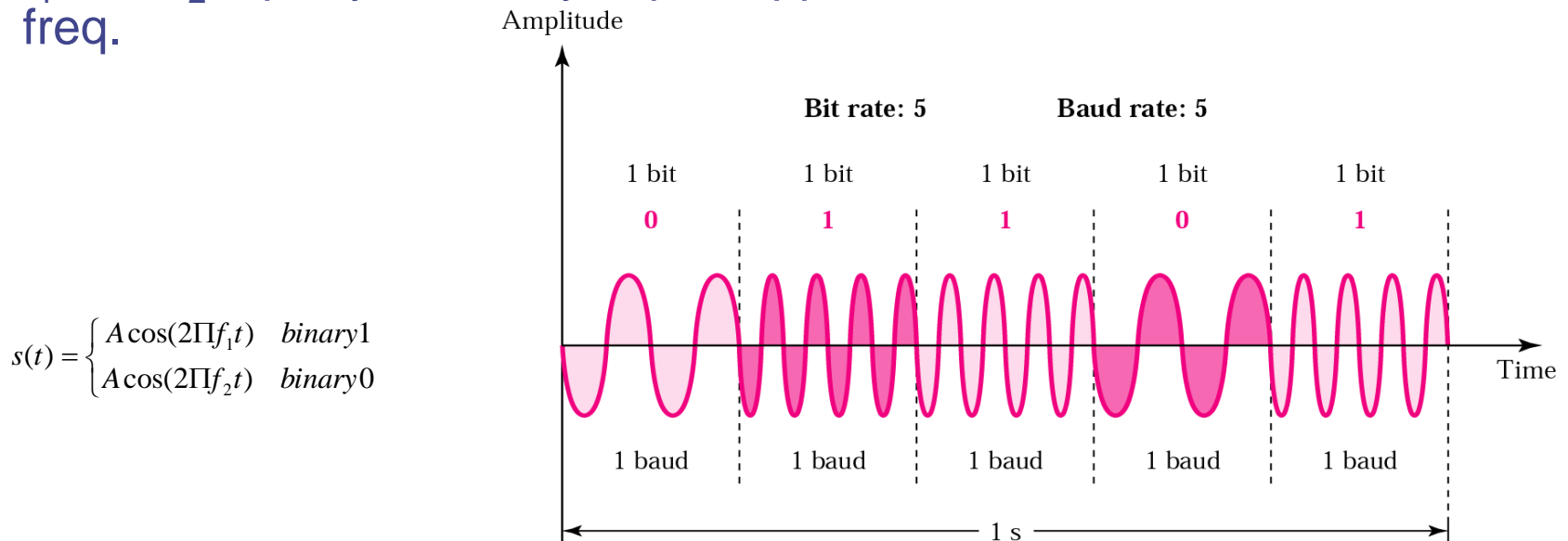
- The strength/amplitude of the carrier signal is varied to represent binary 1 and 0.
- Frequency and phase remains the same.
- Highly susceptible to noise interference.
- Used up to 1200 bps on voice grade lines, and on optical fiber.



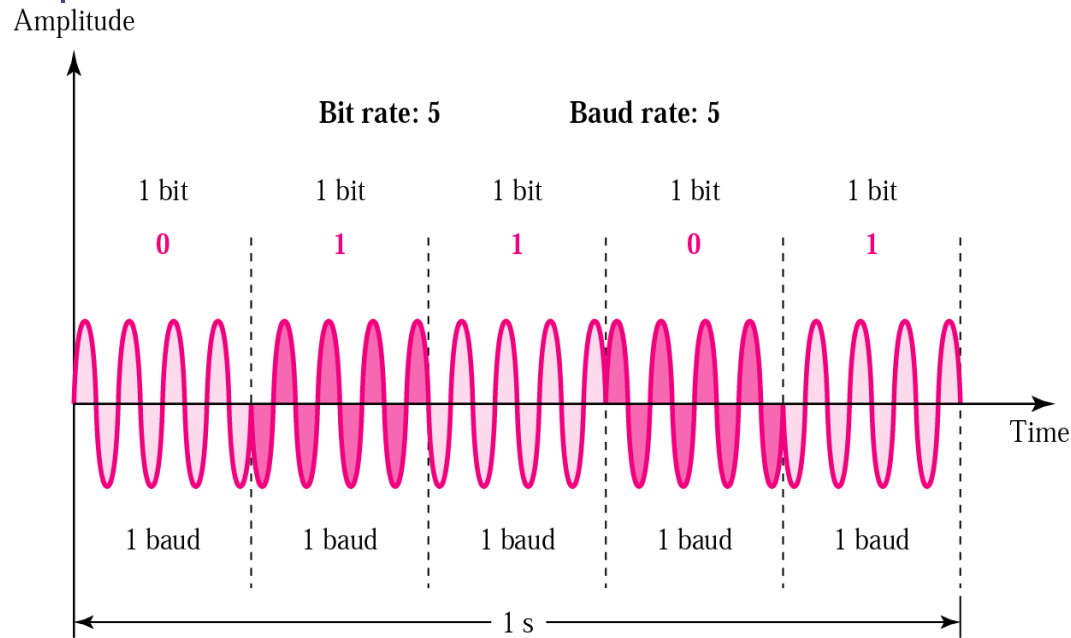


Frequency Shift Keying

- Frequency of the carrier is varied to represent digital data (binary 0/1)
- Peak amplitude and phase remain constant.
- Avoid noise interference by looking at frequencies (change of a signal) and ignoring amplitudes.
- Limitations of FSK is the physical capabilities of the carrier.
- f_1 and f_2 equally offset by equal opposite amounts to the carrier freq.



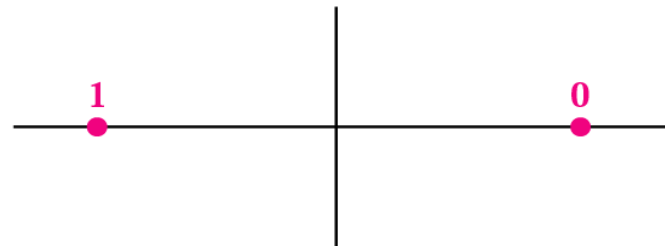
Phase Shift Keying



- Phase of the carrier is varied to represent digital data (binary 0 or 1)
- Amplitude and frequency remains constant.
- If phase 0 deg to represent 0, 180 deg to represent 1. (2-PSK)
- PSK is not susceptible to noise degradation that affects ASK or bandwidth limitations of FSK

Bit	Phase
0	0
1	180

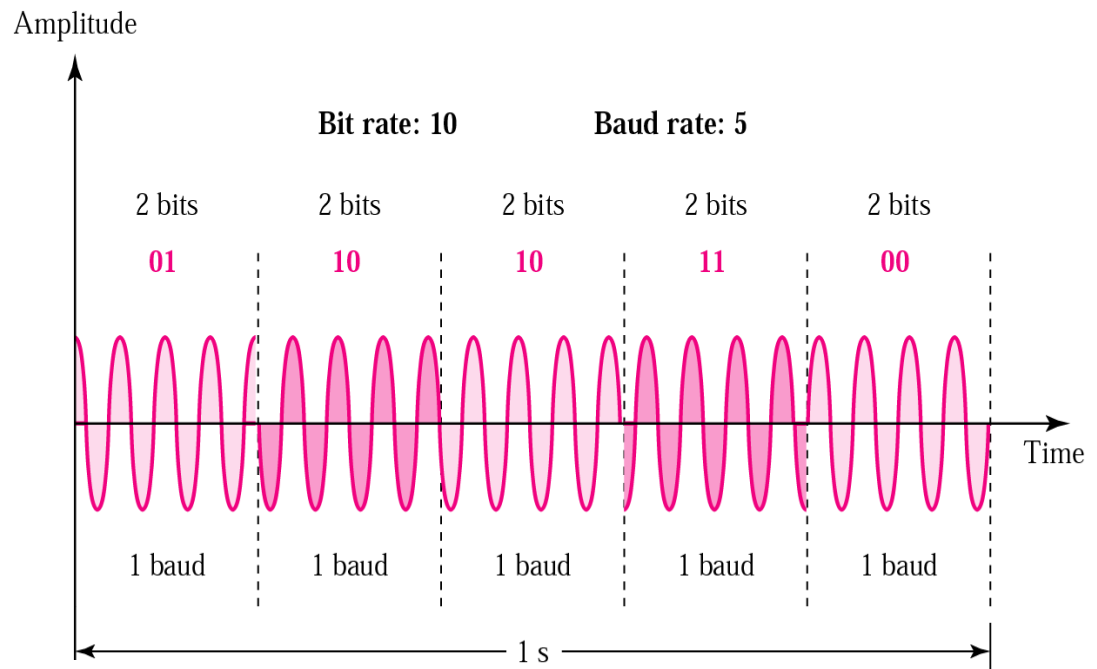
Bits



Constellation diagram

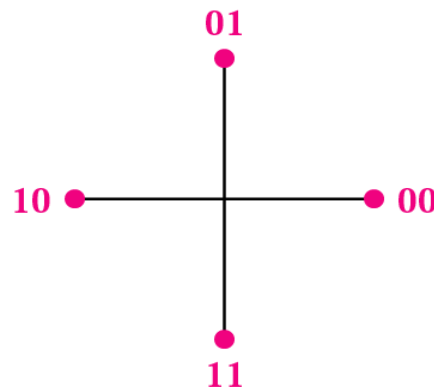


4-PSK (QPSK) method



Dibit	Phase
00	0
01	90
10	180
11	270

Dibit
(2 bits)



Constellation diagram

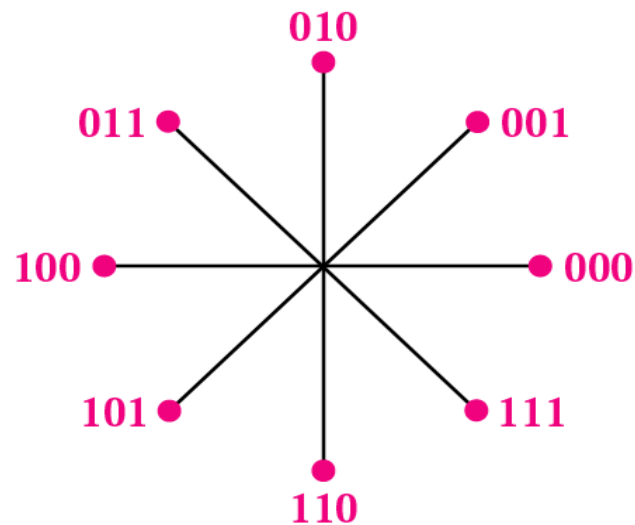


8-PSK

- We can extend, by varying the the signal by shifts of 45 deg (instead of 90 deg in 4-PSK)
- With $8 = 2^3$ different phases, each phase can represents 3 bits (tribit).

Tribit	Phase
000	0
001	45
010	90
011	135
100	180
101	225
110	270
111	315

Tribits
(3 bits)



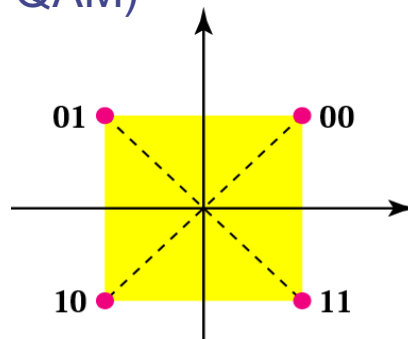
Constellation diagram



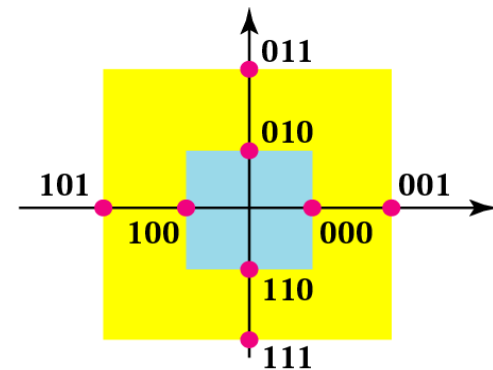
Quadrature Amplitude Modulation

- PSK is limited by the ability of the equipment to distinguish between small differences in phases.
 - Limits the potential data rate.
- Quadrature amplitude modulation is a combination of ASK and PSK so that a maximum contrast between each signal unit (bit, dibit, tritbit, and so on) is achieved.
 - We can have x variations in phase and y variations of amplitude
 - $x \cdot y$ possible variation (greater data rates)
- Numerous variations. (4-QAM, 8-QAM)

of phase shifts > # of amplitude shifts



4-QAM
1 amplitude, 4 phases



8-QAM
2 amplitudes, 4 phases

