NUCLEAR PRINCIPLES IN ENGINEERING

Tatjana Jevremovic





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Dedication

This book is dedicated to my mother

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Preface

This book is an introduction to nuclear principles with special emphasis on engineering applications. Topics such as neutron physics, nuclear structure and radiation interactions are illustrated through numerous examples that include detailed solutions and links to theory. The reader will find plenty of descriptive easy-to-grasp models and analogies with rather simplified mathematics. A mathematical formula says little unless we understand the physical context. Hence, priority is given to developing physical intuition rather than mathematical formalism.

Nuclear engineering is a broad discipline that requires knowledge (of reasonable depth) in physics, mathematics and computation. The discipline is grounded in the scientific understanding of the subatomic realm and energy-matter processes that are taking place at the *femtometer* range $(10^{-15}$ meter). Several areas of application are driving a renaissance in nuclear engineering including, but not limited to, new safe nuclear reactor development, a revolution in nuclear medicine, nuclear space propulsion, and homeland security.

This book offers background and a basis for technology development in inherently safe reactors, medical imaging and integrated cancer therapies, food technology, radiation shielding, and nuclear space applications. It is intended to be a resource for practicing engineers and a text for university students in science and engineering.

> Tatjana Jevremovic, Ph.D. School of Nuclear Engineering Purdue University West Lafayette February 2005

Foreword

Nuclear Principles in Engineering is an appropriate starting point for the new series *Smart Energy Systems: Nanowatts to Terawatts.* Not only because the nuclear universe stands at the boundary of human knowledge with respect to scale, but also, and most importantly, because nuclear ideas have a largely untapped potential for new sources of energy. When viewed in this light, nuclear principles offer renewed hope for energy innovation much needed by a global community confronting the inescapable environmental and geological limitations of fossil fuels.

The realm of nuclear processes occupies tiny microscopic dimensions, in the range of 10⁻¹⁵ meter or *femtometer*. It is a realm inaccessible by our senses, yet intelligible through the power of Modern Physics. The book brings the nuclear universe into clear view for the benefit of technical pedagogy and technological development. A plethora of existing technologies can be traced to the fruitful application of nuclear principles, including, but not limited to, weaponry, atomic and nuclear energy, medicine and instrumentation. The number is likely to grow as innovations are needed in smart materials, nanostructures, space, homeland security and biomedical engineering.

In recent years few books have appeared articulating nuclear principles for engineers. The enthusiasm of the 1950's and 60's (the Atomic Age) gave way to a much impeded if not diminished interest. But nuclear principles are far from fading hues of past scientific theories. Witnessing a renaissance in applications of nuclear technology, the book is aimed at engineering students who need material in a compact and easily digestible form. Professionals and students of science may benefit as well. With nuclear principles, energy shares the view that much is yet to be gained from converting tiny specks of matter into useful work. This book appears on the centennial of Einstein's famous formula $E = mc^2$. A century of Modern Physics and half a century of accrued technical experience with nuclear power strongly support a renewed optimism on the technological potential of nuclear ideas. Professor Jevremovic's book presents principles that have stood the test of time and open new vistas for future energy.

Lefteri H. Tsoukalas, Ph.D. School of Nuclear Engineering Purdue University West Lafayette February 2005

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Chapter 1

NUCLEAR CONCEPTS *From nano-watts to tera-watts*

"The dreams of ancient and modern man are written in the same language as the myths whose authors lived in the dawn of history. Symbolic language is a language in which inner experience, feelings and thoughts are expressed as if they were sensory experiences, events in the outer world. It is a language which has a different logic from the conventional one we speak in the daytime, a logic in which time and space are not the ruling categories but intensity and association." *Erich From* (The Forgotten Language, 1937)

1. INTRODUCTION

Early 20th century marked tremendous and fascinating discoveries in physics and chemistry. For the first time in human history hard evidence was produced supporting the existence of atoms. In his book *Imagined Worlds*, the eminent astrophysicist Freeman Dyson calls the changes in physics that occurred in the 1920's, a *concept-driven revolution*; theory had primacy over experiment. Quantum mechanics and the theory of relativity explained atomic and nuclear structures. Yet, the technology for accessing the atomic and subatomic level remained rather primitive. It was not until decades later that serious technological applications appeared.

The middle of the 20th century marked the advent of nuclear technology. First weaponry, which left a trace of fear and apprehension in the meaning of the world "nuclear." After all, the press release for the new technology became Hiroshima and Nagasaki. Nuclear power for naval and terrestrial

applications, nuclear medicine, radiochemistry, imaging and space exploration came later.

Significant institutional development took place concomitantly to regulate and protect the public and the environment from the deleterious effects of radiation. National authorities such as the Nuclear Regulatory Commission in the U.S., and international bodies such as the UN International Atomic Energy Agency as well as trade and professional organizations were formed. Nuclear technology cannot be developed and deployed without serious technical and institutional safeguards.

2. TERRESTRIAL NUCLEAR ENERGY

A major requirement for sustaining human progress is to adequately provide, generate and distribute energy. In the last fifty years we have seen nuclear energy grow to become an important source of carbon free electricity. Concerns about global climate change and energy supply/demand imbalances bring renewed attention to nuclear energy. The unparalleled safety record of light water reactors (LWR) and the high capacity factors achieved by nuclear generators give plenty of motivation for new nuclear power expansion. Whereas in the 1990's, nuclear power plants were considered expensive dinosaurs, there is a growing world wide interest in new generation with US utilities clamoring for permission to build new plants. There is every indication that the successes of LWRs, global warming, and growing worldwide energy challenges, generate a unique confluence of reasons for a serious reexamination of the nuclear option.

Nuclear power comes mainly from the fission of uranium, plutonium or thorium. The fission of an atom of uranium produces several million times more energy than the energy produced by the combustion of an atom of carbon in fossil fuels, giving nuclear power an extraordinary advantage in power density. Energy released in fission is converted into electric energy (this type of electricity represents eighty percent of the electricity generated in France and over twenty two percent in the United States). More than four hundred nuclear power plants produce over 15% of the world's electricity. Having accumulated over 12,000 years of operational experience with civilian nuclear power, mankind is becoming more confident about the economic, safety and environmental benefits of nuclear power generation.

For the vast majority of nuclear reactors the fuel is slightly enriched uranium, material which is relatively abundant and ubiquitous. Nuclear power plants typically use enriched uranium in which the concentration of ²³⁵U is increased from 0.7% (as found in nature) to about 4% to 5%. At present, global reserves of uranium are deemed sufficient for at least one

hundred years. In the very long term, however, breeder reactors are expected to be used to breed new fuel. Breeder reactors can generate nearly 100 times as much fuel as they consume.

One of the main issues with nuclear power is the problem of nuclear waste. Significant technical progress has been made in this area and a number of countries, including the U.S., move towards addressing the political aspects of the problem. It is important to note that nuclear power takes full responsibility for its waste. Radioactive waste coming from nuclear power reactors is small in quantity and could be turn into useful nuclear fuel with known chemical processes.

The nuclear industry is developing and upgrading reactor technologies for nearly fifty years. Future reactor designs focus on safety, economics and proliferation resistant fuel cycles. Great attention is paid to fuel improvements targeting, for example, the capability of light water reactors to burn plutonium, hence, reducing the amount of radioactive waste.

3. SPACE EXPLORATION AND NUCLEAR POWER

Radioisotope generators in space have been providing electrical power for a variety of spacecrafts. For example, Cassini, the first craft ever to orbit Saturn, is powered by a radioisotope thermoelectric generator (RTG). After six years of travel to the Saturn Rings, Cassini reached its destination in 2004 and is scheduled to remain in orbit until 2008. RTGs is proven technology for missions to distant space destinations. They consist of a radioisotope (for example ²³⁸Pu, a non-weapon-grade material, because of its long half life ~ 87 years) and a thermoelectric conversion system. Heat produced from the radioisotope is converted directly to electricity using thermocouples. For example, Cassini is powered by three RTGs (with nearly 33 kg of plutonium) that produce 750 W of power. The power generated diminishes somewhat with time due to the exponential decline of radioactivity. At the end of the 11th year of operation the Cassini system will produce close to 630 W of power. The development of such systems by the U.S. Department of Energy generated astonishing success for missions to Moon, Neptune, and even beyond the Solar system. Famous spacecrafts such as Pioneer 10 and 11, Apollo, Galileo, and Voyager were powered by RTGs. Thus far, 44 RTGs have powered 24 U.S. space vehicles. Russia has also developed RTGs using ²¹⁰Po. There are currently two Russian generators in orbit powering satellites. RTGs using short-lived radionuclides can power small devices deployed in remote areas on earth or other planets. Such systems could stay intact and power instrumentation for collecting data that includes climate variables, chemical composition of air or soil, salinity, ozone, and temperature. After a gap of several decades, there is new interest in U.S. and Russia for nuclear power in space missions. In 2002, NASA announced the Nuclear Systems Initiative for space code-named *Project Prometheus*. It focuses at space mission design enabling nuclear-powered manned missions to Mars and distant planet exploration.

The Jupiter Icy Moon Orbiter (JIMO) is a spacecraft currently in development, powered by a nuclear reactor to explore Jupiter's dark and cold satellites. A major limiting factor for long term space travel or manned mission to distant planets is radiation protection for the crew and the electronics. Nuclear principles will be used for the design of light but effective radiation shield.

4. MEDICINE AND NUCLEAR PRINCIPLES

Soon after the German physicist Wilhelm Conrad Roentgen discovered them, X rays revolutionized medicine. A century later advanced three-dimensional imaging, computerized treatment planning and high energy X ray machines have revolutionized the diagnostics and treatment of heart disease, cancer, and surgery. A remarkable application of nuclear principles has been the use of gamma ray narrow beams to irradiate small tumors with high precision, an instrument called the *gamma knife*.

In 1932 Chadwick discovered an electrically neutral constituent of the nucleus which he called the "neutron." Few years later it was recognized that neutron interactions producing short range highly ionizing particles could be used to treat cancer. In the early 1940's, Neutron Capture Therapy (NCT) was proposed. This is a bimodal radiotherapy utilizing directed uptake of neutron absorbing isotopes in tumor tissue and subsequent neutron irradiation. Neutron interaction products deposit most of the energy from highly exothermic capture reactions in relatively small space. This is in the order of cellular dimensions thus delivering to tumor cells a far greater dose than what is incurred in surrounding healthy tissue. NCT has a great advantage particularly if the tumor is not imagable or difficult to spatially define. It has been applied clinically as a post-operative sterilization of potentially remnant brain tumors. The most prominent element used in NCT is ¹⁰B, which undergoes a neutron interaction producing alpha particle and ⁷Li. The potential for other elements has been also studied. Gadolinium, lithium, and uranium can strongly absorb thermal neutrons and hence they are considered for NCT. The products of neutron capture in ¹⁵⁷Gd, for example, are quite different than neutron capture with other isotopes creating a mixture of prompt and cascade-induced photons and electrons. A novel application of the nuclear principles upon which NCT is based is application to breast and lung cancer. Recent literature points to novel ways of combining the NCT principles with the identified genomic signature of specific cancers. For example, it has been shown that thirty percent of breast cancers over-express certain proteins, a fact that can be exploited for custom made treatments. Monoclonal antibodies (MABs) are currently used as part of chemotherapy for metastatic and late stage breast cancer. A recent study explores the possibility and effectiveness of using the MABs as a targeting vehicle for boron to breast cancer cells. This approach is called targeted (radiation) therapy. In such therapies the radiation or drug agent is brought directly to the cancer cells. This radioimmunotherapy combines radionuclides with MABs to deliver radiation to designated areas where it produces high irradiation effects.

A startling new picture of how cells respond to radiation is beginning to emerge from microbeam studies in which individual cells are targeted with a precise dose of radiation. Cells damaged by radiation communicate with neighboring cells using messenger molecules (cytokines) that can be transmitted between the cells. As a result, cells not hit by radiation, called bystander cells, generate molecular and cellular responses similar to cells that are irradiated. Study of bystander-cell effects will have profound implications in planning for radiation therapy and also for the assessment of health risks of low radiation doses. On the other hand, the precise and non-invasive nature of microbeams is useful in radiobiology, cell and biomolecular diagnostics, and intracellular micromanipulations. For example, biological tissues are mostly transparent to photon radiation giving the unique possibility to act on cell structure without changing the features or disturbing the vital functions. Recent advances in tissue and molecular engineering call for new technologies to analyze and possibly modify cell and tissue behavior while minimizing undesirable signaling (contamination) in the broader cellular environment.

Neutrons offer powerful tools for the investigation of macromolecular structures, such as the structure of proteins, membranes, polymers and other complex biological materials. The use of cold neutrons rather than thermal neutrons improves the detection limits of miniscule amounts of light elements such as hydrogen. They are widely used as a *microscopic probe* in fields ranging from elementary physics to biological science. Cold neutrons are finding a fabulous application in depth profiling of light element spatial deposition; for example, mapping the spatial distribution of boron atoms in a tumor region (thus providing information that may profoundly advance BNCT). Cold neutrons are of great interest since they are noninvasive and a sample can be reused for other profiling tests by different techniques.

5. BOOK CONTENT

This book offers an overview of basic nuclear principles in engineering including, but not limited to physical processes in radiation interaction with matter, neutron transport and reactor physics, nuclear and atomic structure, and radioactive decay. The understanding of principles is essential in developing engineering applications. For example, prediction of nuclear parameters in reactors or accurate radiation treatment in medicine are both based on principles of radiation interactions with matter. They share the same tools for predicting energy deposition along different pathways.

The book material is organized as follows:

- Atomic structure principles are described in Chapter 2. This knowledge is important in analyzing the probabilities of interaction leading to ionization of a medium (of extreme importance in biological tissues) and in understanding the energy levels and electronic configuration of atoms.
- The majority of nuclear interactions involve electron clouds or nuclei of a medium. For example, in a reactor we find interactions of neutron with nuclear fuel and structure materials. Understanding these interactions is of great importance in predicting reactor power, achieving reactor control and selecting fuel characteristics. In order to predict such parameters with high accuracy, knowledge of the nature of particle interactions and the structure of nucleus are of great importance and are described in Chapter 3. In addition, a brief overview of Quantum Mechanics starting from the concept of Planck's quanta and the de Broglie wavelength through Heisenberg principle and Schrödinger equation is provided in this chapter as well.
- Radioactivity, a phenomenon discovered at the end of 19th century, has found applications in many scientific and engineering approaches (radioactive dating, radioisotope generators, nuclear medicine) and is described in detail in Chapter 4.
- The interaction of various particles with matter is described in Chapter 5. The concept of stopping power, range of interactions, and the attenuation of radiation beam are essential aspects in particle transport and applications of radiation effects.
- Chapter 6 focuses at description and analysis of the cross sections for neutron interactions; the nature of neutron interactions; and, basic principles of the fission process.
- Reactor steady-state and kinetic physics are described in Chapter 7. The basic principles of neutron diffusion theory, reactor power, fission chain reaction, critical mass, spatial distribution of neutron flux and reaction

rates are described with details needed to pursue analysis of reactor behavior giving a solid background for understanding time-dependent physics parameters of thermal reactors.

- Aspects of reactor control, the effects of neutron poisoning as well as temperature coefficients of reactivity are summarized in Chapter 8.

Chapter 2

ATOMIC THEORY *Basic Principles, Evidence and Examples*

"Among all physical constants there are two which will be universally admitted to be of predominant importance; the one is the velocity of light, which now appears in many of the fundamental equations of theoretical physics, and the other is the ultimate, or elementary, electrical charge", **Robert Millikan** (1868 - 1953)

1. INTRODUCTION

Around the 5th century BC, Greek philosopher Democritus invented the concept of the *atom* (from Greek meaning "indivisible"). The atom, *eternal*, *constant, invisible, and indivisible*, represented the smallest unit and the building block of all matter. Democritus suggested that the varieties of matter and changes in the universe arise from different relations between these most basic constituents. He illustrated the concept of atom by arguing that every piece of matter could be cut to an end until the last constituent, is reached. Today the word atom is used to identify the basic component of molecules that create all matter, but it is now known that the atom itself is made up of particles even more fundamental, some of which are elementary. The first theoretical and experimental models of the structure of matter came as late as the 19th century, which is the time marked as the beginning of modern science. At that time a more empirical approach, mainly in chemistry, opened a new era of scientific investigations.

The work of Democritus remained known through the ages in writings of other philosophers, mainly Aristotle. Modern Greece has honored Democritus as a philosopher and the originator of the concept of the atoms through their currency. The 10-drachma coin, before Greek currency was replaced with the euro, depicted the face of Democritus on one side, and the schematic of a lithium atom on the other (see Fig. 2-1).



Figure 2-1. Greek 10–drachma coin featuring Democritus and the lithium atom (Courtesy of the Bank of Greece)

This chapter introduces the structure of atoms and describes atomic models that show evidence for the existence of atoms and electrons.

2. ATOMIC MODELS

2.1 The Cannonball Atomic Model

All matter on Earth is made from combination of 90 naturally occurring different atoms. Early in the 19th century, scientists began to study the decomposition of materials and noted that some substances could not be broken down past a certain point (for instance, once separated into oxygen and hydrogen, water cannot be broken down any further). These primary substances are called *chemical elements*. By the end of the 19th century it was implicit that matter can exist in the form of: a pure element, chemical compound of two or more elements, or as a mixture of such compounds. Almost 80 elements were known at that time and a series of experiments provided confirmation that these elements were composed of atoms. This led to a discovery of the law of definite proportions: two elements, when combined to create a pure chemical compound, always combine in fixed ratios by weight. For example, if element A combines with element B, the unification creates a compound AB. Since the weight of A is constant and the weight of B is constant, the weight ratio of these two will always be the same. This also implies that two elements will only combine in the defined proportion; adding an extra quantity of one of the elements will not produce more of the compound.

Example 2.1: The law of definite proportion

Carbon (C) forms two compounds when reacting with oxygen (O): carbon monoxide (CO) and carbon dioxide (CO_2)

1g of C + 4/3 g of O \rightarrow 2 1/3 g of CO

1 g of C + 8/3 g of O \rightarrow 3 2/3 g of CO₂

The two compounds are formed by the combination of a definite number of carbon atoms with a definite number of oxygen atoms. The ratio of these two elements is constant for each of compounds (molecules): C:O = 3:4 for CO, and C:O = 3:8 for CO₂.

The first atomic theory with empirical proofs for the law of definite proportion was developed in 1803 by the English chemist John Dalton (1766-1844). Dalton conducted a number of experiments on gases and liquids and concluded that, in chemical reactions, the amount of the elements combining to form a compound is always in the same proportion. He showed that matter is composed of atoms and that atoms have their own distinct weight. Although some explanations in Dalton's original atomic theory are incorrect, his concept that chemical reactions can be explained by the union and separation of atoms (which have characteristic properties) represents the foundations of modern atomic physics. In his two volume book, New System of Chemical Philosophy, Dalton suggested a way to explain the new experimental chemistry. His atomic model described how all elements were composed of indivisible particles which he called atoms (he depicted atoms like cannonballs, see Fig. 2-2), and that all atoms of a given element were exactly alike. This explained the law of definite proportions. Dalton further explained that different elements have different atoms and that compounds were formed by joining the atoms of two or more elements.



Figure 2-2. Cannonball atomic model (John Dalton, 1803)

In 1811, Amadeo Avogadro, conte di Quaregna e Ceretto (1776-1856), postulated that equal volumes of gases at the same temperature and pressure

contain the same number of molecules. Sadly, his hypothesis was not proven until two years after his death at the first international conference on chemistry held in Germany in 1860 where his colleague, Stanislao Cannizzaro, showed the system of atomic and molecular weights based on Avogadro's postulates.

Example 2.2: Avogadro's law

As shown in Example 2.1, the ratio of carbon and oxygen in forming CO_2 is 3:8. Here is the explanation of this ratio: since a single atom of carbon has the same mass as 12 hydrogen atoms, and two oxygen atoms have the same mass as 32 hydrogen atoms, the ratio of the masses is 12:32 = 3:8. This shows that the description of the reaction is independent of the units used since it is the ratio of the masses that determines the outcome of a chemical reaction. Thus, whenever you see wood burning in a fire, you should know that for every atom of carbon from the wood, two oxygen atoms from the air are combined to form CO_2 ; the ratio of masses is always 12:32.

It follows that there must be as many carbon atoms in 12 grams of carbon as there are oxygen atoms in 16 grams of oxygen. This measure of the number of atoms is called a *mole*. The mole is used as a convenient measure of an amount of matter; similarly as "a dozen" is a convenient measure of 12 objects of any kind. Thus, the number of atoms (or molecules) in a mole of any substance is the same. This number is called Avogadro's number (N_A) and its value was accurately measured in the 20th century as 6.02×10^{23} atoms or molecules per mole.

For example, the number of moles of hydrogen atoms in a sample that contains 3.02×10^{21} hydrogen atoms is:

Moles of H atoms =
$$\frac{3.02 \times 10^{21} atoms H}{6.02 \times 10^{23} atoms / mole} = 5.01 \times 10^{-3} moles H$$

2.2 The Plum Pudding Atomic Model

Shortly before the end of the 19^{th} century, a series of new experiments and discoveries opened the way for new developments in atomic and subatomic (nuclear) physics. In November 1895, Wilhelm Roentgen (1845-1923) discovered a new type of radiation called *X rays*, and their ability to penetrate highly dense materials. Soon after the discovery of X rays, Henri Becquerel (1852-1908) showed that certain materials emit similar rays independent of any external force. Such emission of radiation became known as *radioactivity*.

ATOMIC THEORY

During this same time period, scientists were extensively studying a phenomenon called *cathode rays*. Cathode rays are produced between two plates (a cathode and an anode) in a glass tube filled with very low-density gas when an electrical current is passed from the cathode to the high voltage anode. Because the glowing discharge forms around the cathode and then extends toward the anode, it was thought that the rays were coming out of the cathode. The real nature of cathode rays was not understood until 1897 when Sir Joseph John Thomson (1856-1940) performed experiments that led to the discovery of the first subatomic particle, the electron. The most important aspect of his discovery is that cathode rays are a stream of particles. Here is the explanation of his postulate: from the experiment he observed that cathode rays were always deflected by an electric field from the negatively charged plate inside the cathode ray tube, which led him to conclude that the rays carried a negative electric charge. He was able to determine the speed of these particles and obtained a value that was a fraction of the speed of light (one tenth the speed of light, or roughly 30,000 km/sec or 18,000 mi/sec). He postulated that anything that carries a charge must be of material origin and composed of particles. In his experiment, Thomson was able to measure the charge-to-mass ratio, e/m, of the cathode rays; a property that was found to be constant regardless of the materials used. This ratio was known for atoms from electrochemical analysis and by comparing the value obtained for the electrons he could conclude that the electron was a very small particle, approximately 1,000 times smaller than the smallest atom (hydrogen). The electron was the first subatomic particle identified and the fastest small piece of matter known at that time.

In 1904, Thomson developed an atomic model to explain how the negative charge (electrons) and positive charge (speculated to exist since it was known that atoms were electrically neutral) were distributed in the atom. He concluded that the atom was a sphere of positively charged material with electrons spread equally throughout like raisins in a plum pudding. Hence, his model is referred to as the *plum pudding model*, or *raisin bun atom* as depicted in Fig. 2-3. This model could explain

- The neutrality of atoms
- The origin of electrons
- The origin of the chemical properties of elements However, his model could not answer questions regarding
- Spectral lines (according to this model, radiation emitted should be monochromatic; however, experiments with hydrogen shows a series of lines falling into different parts of the electromagnetic spectrum)
- Radioactivity (nature of emitted rays and their origin in the atom)
- Scattering of charged particles by atoms. Thomson won the Nobel Prize in 1906 for his discovery of the electron.

He worked in the famous Cavendish Laboratory in Cambridge and was one of the most influential scientists of his time. Seven of his students and collaborators won Nobel Prizes; amongst them his son who, interestingly, won the Nobel Prize for proving the electron is a wave.



Figure 2-3. Plum pudding atomic model (J. J. Thomson, 1904)

2.3 Millikan's Experiment

In 1909 Robert Millikan (1868-1953) developed an experiment at the University of Chicago to measure the charge of the electron. The experiment is known as the "Millikan oil-drop experiment."

Millikan determined the mass of the electron based on his experimentally measured value of the electron charge, 1.60×10^{-19} C, and Thomson's charge-to-mass ratio, 1.76×10^{8} C/g. He found the electron mass to be 9.10 x 10^{-28} g (about 2000 times smaller than that of hydrogen, the lightest atom); the presently accepted value is 9.10939 x 10^{-28} g.

How was the charge of an electron measured from oil drops? Millikan's experimental apparatus consisted of a chamber with two metal plates placed at the top and the bottom. The plates were connected to a voltage source and oil droplets were allowed to fall between (see Fig. 2-4). In the absence of voltage (electrical field, E, equal to zero) droplets were allowed to fall until they reached their terminal velocity (when the downward force of gravity, mg, is balanced with the upward force of air resistance). By measuring the terminal velocity he was able to determine the mass of the oil droplets. By introducing an electrical field, the forces (gravitational and electrical) could be balanced and the drops would be suspended in mid–air. The resulting force is zero, because the gravitational force is equal to the electrical force

 $mg = qE \tag{2-1}$

where the total charge of the oil droplet, $q = N \cdot e$, is an integer times the charge of one electron (because the electron cannot be divided to produce a

fractional charge). By changing the electric charge of oil droplets (irradiating them with X rays known at that time to ionize the molecules), Millikan noticed that the charge was always a multiple of the same number, -1.6×10^{-19} coulombs. Robert Millikan was awarded the Nobel Prize in 1923 for this work.



Figure 2-4. Schematics of Millikan's oil drop experiment (1909)

2.4 The Planetary Atomic Model

2.4.1 Disproof of Thomson's Plum Pudding Atomic Model

Thomson's atomic model described the atom as a relatively large, positively charged, amorphous mass of a spherical shape with negatively charged electrons homogenously distributed throughout the volume of the sphere, the sizes of which were known to be on the order of an Ångström $(1 \text{ Å} = 10^{-8} \text{ cm} = 10^{-10} \text{ m})$. In 1911 Geiger and Marsden carried out a number of experiments under the direction of Ernest Rutherford (1871-1937) who received the Nobel Prize in chemistry in 1908 for investigating and classifying radioactivity. He actually did his most important work after he received the Nobel Prize and the 1911–experiment unlocked the hidden nature of the atom structure.

Rutherford placed a naturally radioactive source (such as radium) inside a lead block as shown in Fig. 2-5. The source produced α particles which were collimated into a beam and directed toward a thin gold foil. Rutherford hypothesized that if Thomson's model was correct then the stream of α particles would pass straight through the foil with only a few being slightly deflected as illustrated in Fig. 2-6. The "*pass through*" the atom volume was expected because the Thomson model postulated a rather uniform distribution of positive and negative charges throughout the atom. The deflections would occur when the positively charged α particles came very close to individual electrons or regions of positive charges. As expected, most of the α particles went through the gold foil with almost no deflection. However, some of them rebounded almost directly backwards – a phenomenon that was not expected (see Fig. 2-7). The main challenge was to explain what caused such a large deflection angle and what caused other particles to go through the atom without noticeable scattering.



Figure 2-5. Schematics of the Rutherford's experiment (1911)



Figure 2-6. Expected scattering of α particles in Rutherford's experiment

Rutherford explained that most of the α particles pass through gold foil with little or no divergence not because the atom is a uniform mixture of positive and negative charges, but because the atom is largely empty space and there is nothing to interact with the α particles. He explained the large scattering angle by suggesting that some of the particles occasionally collide with, or come very close to, the "massive" positively charged nucleus that is located at the center of an atom. It was known at the time that the gold nucleus has a positive charge of 79 units and a mass of about 197 units while the α particle has a positive charge of 2 units and a mass of 4 units. The repulsive force between the α particle and the gold nucleus is proportional to the product of their charges and inversely proportional to the square of the distance between them. In a direct collision, the massive gold nucleus would thus be hardly moved by the α particle. The diameter of the nucleus was shown to be about 1/105 the size of the atom itself or around 10⁻¹³ m. Clearly these ideas defined an atom very different from Thomson's model.



Figure 2-7. Actual scattering of α particles in Rutherford's experiment

Ernest Solvay (1838-1922), a Belgian industrial chemist who made a fortune from the development of a new process to make washing soda (1863), was known for his generous financial support to science, especially physics research. Among the projects he financially supported was a series of international conferences, known as the Solvay conferences. The *First Solvay Conference on Physics* was held in Brussels in 1911 and it was attended by the most famous scientists of the time. Rutherford was one of them; he announced the discovery of the atomic nucleus and explained the structure of the atom. According to his explanation, the electrons revolve around the nucleus at relatively great distances. Since each electron carries one elementary charge of negative electricity, the number of electrons must equal the number of elementary charges of positive electricity carried by the nucleus for the atom to be electrically neutral. The visual model is similar to the solar planetary system and is illustrated in Fig. 2-8.



Figure 2-8. Planetary atomic model (Rutherford, 1911)

2.4.2 Idea of a Nucleus in the Center of an Atom

Rutherford's scattering experiment showed that a positive charge distributed throughout the volume of Thomson's atom could not deflect the α particles by more than a small fraction of a degree. A central assumption of Thomson's atomic model was that both the positive charge and the mass of the atom were distributed nearly uniformly over its volume. The electric field from this charge distribution is the field that must scatter the α particles, since the light–weight electrons would have a negligible impact. The expected deflection of an α particle from the gold nucleus according to Thomson's atomic model is shown in Fig. 2-9. The thickness of the gold foil used by Rutherford was about 400 atoms (or ~ 5 x 10⁻⁷ m). The gold atom has a positive charge of 79*e* (balanced by 79 electrons in its normal state). Neglecting the electrons, the maximum electric force the α particle would encounter is that at the surface of the positively charged sphere.

Johannes Kepler was first to mathematically formulate Tycho Brahe's precise measurements of the motion of planets, showing that the orbit of the planets around the sun is elliptical. Newton later proved that these elliptical orbits are a consequence of the attractive gravitational force (GmM/r^2) . He also established that the motion of heavenly bodies in the field of a central attractive force with a $\sim 1/r^2$ dependence (such as the gravitational field of the sun) is always a conical section, depending on the initial conditions: a hyperbola (body has sufficient kinetic energy to avoid capture by the gravitational field), an *ellipse* (the body is captured), and a *parabola* (a limiting case between these two). The scattering of particles in the electric field follows the same law that describes the motion of bodies in a gravitational field, except that the force can be both attractive and repulsive (the latter being the case for α particles and a positively charged nucleus). These two forces, electric and gravitational, are generated according to modern quantum physics by the exchange of a massless particle (or field quantum). In the case of the electric force the field quantum is a photon and in the case of the gravitational force the field quantum is called a graviton.



Figure 2-9. Trajectory of the α particle in the electric field of an atom in Rutherford's experiment according to the plum pudding and planetary atomic model

If the mass of an α particle is *m* with charge q = 2e, and the charge of the gold foil nucleus is Q = Ze = 79e, then the electric force acting on the α particle (a Coulomb repulsion force due to the positively charged nucleus) is written as

$$F = \frac{kQq}{r^2} = \frac{k(79e)(2e)}{r^2}$$
(2-2)

where k is the Coulomb force constant, $1 / (4\pi\epsilon_0) = 8.99 \times 10^9 \text{ Nm}^2/\text{C}^2$. Assuming the atom to be represented by a sphere of radius 10^{-10} m, Eq. (2-2) gives the repulsive force that acts on the incoming α particle as 3.64×10^{-6} N. The assumption that only the Coulomb force acts on the α particle was shown to be correct since the α particles never penetrated the gold nucleus and Rutherford's theoretical explanation agreed with the experimental measurements for all cases.

Due to the nature of the Coulomb force acting on the α particle (inverse square law), the α particle follows a hyperbolic trajectory (see Fig. 2-9) that is characterized by the *impact parameter*, *b*. The impact parameter represents the distance from the nucleus perpendicular to the line of approach of the incident α particle. The angle of deflection, θ , of any α particle is related to the impact parameter through the following relation

$$b = \frac{k(Ze)(ze)}{T\tan(\theta/2)} = \frac{k(79e)(2e)}{T\tan(\theta/2)}$$
(2-3)

where T denotes the kinetic energy of the incident α particle. It follows that the impact parameter is smaller for larger scattering angles and larger energy of the incident particle. Table 2-1 illustrates dependence of the

Table 2-1. Impact parameter and scattering angle of α particles in Rutherford's experimentImpact parameter, $b (10^{-15} \text{ m})$ Scattering angle, θ (degrees)81.14035.28017.01205.2160

impact parameter on scattering angle as measured in Rutherford's experiment.

From the distribution of the α particle's scattering angles, Rutherford concluded that the structure of an atom most likely mimics the solar planetary system. The size of the nucleus at the center of the atom was estimated based on the kinetic energy, *T*, of the incident α particle and its potential energy at the point of closest approach, *d*. The closest approach occurs in the case of a head–on collision in which the α particle comes to rest before it bounces back at an angle of 180 degrees (see Fig. 2-10). At that point the kinetic energy is zero, and the potential energy equals the initial kinetic energy

Figure 2-10. Deflection of α particle by the gold nucleus (of radius *R*)

Knowing the kinetic energy of the incident α particles, the closest approach of an α particle to any nucleus in the gold foil (on the order of 10^{-14} m) and the approximate size of the gold nucleus (on the order of 10^{-15} m) may be determined. The unit of 10^{-15} m is designated as a Fermi, fm. The small volume of the nucleus implies its high density and the need for a strong attractive force in the nucleus to overcome the Coulomb repulsive force. It was also understood that this attraction must be of a very short range.

Example 2.3: Size of the gold nucleus in Rutherford's experiment

In Rutherford's experiment the kinetic energy of the incident α particles was 7.7 MeV. Estimate the upper limit size of the gold nucleus and comment on the effect of increased energy of the incident α particles in the experiment.

According to Fig. 2-10 the point of closest approach will determine the size of the nucleus. For the head–on collision it follows from Eq. (2-4)

$$d < \frac{k(79e)(2e)}{7.7MeV} = \frac{(79)(2)ke^2}{7.7MeV} = \frac{(79)(2)(1.44MeV \cdot fm)}{7.7MeV} = 30\,fm$$

This implies that the gold nucleus has radius smaller than 30 fm (the actual measurement is about 8 fm).

If the incident energy of the α particles in Rutherford's experiment is increased, some of the α particles would penetrate the nucleus; first in the head-on collisions and then for smaller angles as the energy is further increased. The limiting kinetic energy for the incident α particle above which the Rutherford experiment would not agree with theoretical explanation

$$T \approx \frac{(79)(2)ke^2}{R} \cong 28.5 MeV$$

where R represents the radius of the gold nucleus.

2.4.3 Rutherford's Scattering Formula

Rutherford's experiment eliminated Thomson's plum pudding atomic model on the base of large–angle scattering. Relatively heavy α particles could not be turned around by much lighter electrons or by the combined mass of positive and negative charges if this mass were distributed uniformly over the whole volume. The electrostatic repulsion would only be strong enough to deflect incoming α particles through such large angles if the positive charge is concentrated (as he proposed in a central nucleus). This scattering of charged particles by the nuclear electrostatic field is called *Rutherford scattering*. The probability of large–angle scattering is very small due to the extremely small size of the nucleus relative to the whole atom (radius of 10^{-15} m versus 10^{-10} m); indeed, according to Rutherford's experiment, only 1 out of 8000 events resulted in large–angle scattering.

Based on his planetary model of the atom, Rutherford was able to define the angular distribution of the scattered α particles. A particle with an impact parameter less than *b* will be scattered at an angle larger than θ (see Fig. 2-
10). Therefore, all particles hitting the gold foil through the area πb^2 (where *b* is the radius), will scatter at an angle θ or larger (see Fig. 2-11). Assuming that the incident beam is made of *N* alpha particles and has a cross sectional area *A*, the number of particles scattered by θ or larger is $\pi b^2/A$. Thus, the number of particles scattered through an angle of θ or larger by one gold atom in the foil is

$$\frac{N_{scatt}}{atom} = N\left(\frac{\pi b^2}{A}\right)$$
(2-5)

The number of atoms encountered by the beam of particles in the gold is

$$N_{foil} = nAt \tag{2-6}$$

where t is the target (foil) thickness and n is the number of atoms per unit volume.



Figure 2-11. Correlation between the deflection angle of α particle and its impact parameter

Therefore, it follows from Eqs. (2-5) and (2-6) that the total number of α particles scattered through an angle θ or larger by the gold foil in Rutherford's experiment is

$$N_{scattered} = Nnt\pi b^2 \tag{2-7}$$

or

$$N_{scattered} = Nnt\pi \left[\frac{Zke^2}{T\tan(\theta/2)}\right]^2$$
(2-8)

where T is the kinetic energy of the α particle. The number of particles that emerge between θ and $\theta + d\theta$ is obtained by differentiating Eq. (2-8)

$$N_{scatt, \; \theta \to d\theta} = Nnt\pi \left[\frac{Zke^2}{T}\right]^2 \frac{\cos(\theta/2)}{\sin^3(\theta/2)} d\theta$$
(2-9)

At some distance s from the gold foil (where the detector is located) particles with a deflection angle between θ and $\theta + d\theta$ pass through the annulus as shown in Fig. 2-12 and are uniformly distributed over the surface area

$$A_{ring} = (2\pi s \sin \theta) (s \ d\theta) \tag{2-10}$$



Figure 2-12. Detection of α particles after scattering through θ

The number of particles per unit area that pass through the annulus at distance s and at angle θ is

$$n(\theta) = \frac{Nnt}{4s^2} \left[\frac{Zke^2}{T} \right]^2 \frac{1}{\sin^4(\theta/2)}$$
(2-11)

This is called the *Rutherford scattering formula* or inverse square scattering formula. According to this formula, the number of particles scattered at a certain angle is: proportional to the thickness of the foil and to the square of the nuclear charge of the foil, and inversely proportional to the incident particle kinetic energy squared and to the fourth power of sin ($\theta/2$).



This was confirmed in all of the experiments with gold foil. Rutherford derived the above formula (2-11) assuming that the only force acting between the nucleus and α particle is the Coulomb repulsive force, and since all of the experimental data agreed, this assumption was valid (see Example 2.3). However, some years later he repeated the experiment using aluminium foil. The experimental results for small angle scattering agreed with his formula, but large angle scattering departed from it. Rutherford deduced that in the large–angle scattering that corresponded to a closer approach to the nucleus, the α particle was actually striking the nucleus. This meant that the size of the nucleus could be obtained by finding the maximum angle for which the Rutherford formula is valid, and finding the incident particle's closest approach to the center of the nucleus.

2.4.4 Stability of the Planetary Atomic Model

The Rutherford planetary atomic model could not explain:

- How are the electrons (negatively charged bodies) held outside the nucleus (a positively charged body) despite the attractive electrostatic force? According to the planetary model electrons are revolving around the nucleus like planets around the sun, though planets are electrically neutral and thus stay in their orbits. According to classical electromagnetic theory any charge placed in circular motion will radiate light (electromagnetic energy), which means that electrons orbiting around the nucleus would spiral inwards and collapse into the nucleus due to the loss of kinetic energy. This would produce extremely unstable atoms.
- The radiated energy of photons from spiralling electrons would change in frequency during the deceleration process and produce a continuous spectrum; however, at that time, the spectra of some of the elements were known to show specific discrete lines.
- What holds the positive charges in the nucleus together in spite of the repulsive electrostatic forces?

2.5 The Smallness of the Atom

Rutherford's gold foil experiment was the first indication and proof that the space occupied by an atom is huge compared to that occupied by its nucleus. In fact, the electrons orbiting the nucleus can be compared to a few flies in a cathedral. As a qualitative reference, a human is about two million times "taller" than the average *Echerichia coli* bacterium; Mount Everest is about 5000 times taller than the average man; and a man is about ten billion times "taller" than the oxygen atom. If the atom were scaled up to a size of a golf ball, on that same scale a man would stretch from Earth to the Moon. Atoms are so small that direct visualization of their structure is impossible. Today's best optical or electron microscopes can not reveal the interior of an atom.

The picture shown in Fig. 2-13 was taken with a scanning transmission electron microscope and shows a direct observation of cubes of magnesium oxide, but details of the atoms cannot be seen.



Figure 2-13. Magnesium oxide crystallites as seen with scanning transmission electronic microscope produced at the Institute of Standards and Technology in the USA (Courtesy National Institute of Standards and Technology)

At the National Institute of Standards and Technology (NIST), however, the Nanoscale Physics Facility is used to manipulate and arrange atoms, one by one, into desired patterns.

The image shown in Fig.2-14 represents an eight-nanometer square structure with cobalt atoms arranged on a copper surface. Such arrangements of atoms are used to investigate the physics of ultra-tiny objects. The structure shown below was observed with a scanning tunneling microscope at a temperature of 2.3 Kelvin (about -455 degrees Fahrenheit): the larger peaks (upper left and lower right) are pairs of cobalt atoms, while the two smaller peaks are single cobalt atoms. The swirls on the copper surface illustrate how the cobalt and copper electrons interact with each other.



Figure 2-14. Nanoscale structure of cobalt and copper atoms produced at the Institute of Standards and Technology in the USA (Courtesy of J. Stroscio, R. Celotta, A. Fein, E. Hudson, and S. Blankenship, 2002)

2.6 The Quantum Atomic Model

2.6.1 Quantum Leap

In 1913 Niels Bohr (1885-1962), developed the atomic model that resolved Rutherford's atomic stability questions. His model was based on the work of Planck (energy quantization), Einstein (photon nature of light), and Rutherford (nucleus at the center of the atom).

In 1900 Max Planck (1858-1947) resolved the long-standing problem of black body radiation by showing that atoms emit light in bundles of radiation (called *photons* by Einstein in 1905 in his theory of the photoelectric effect). This led to formulation of Planck's *radiation law*: a light is emitted as well as absorbed in *discrete quanta* of energy. The magnitude of these discrete energy quanta is proportional to the light's frequency (f, which represents the color of light), as shown in Eq. (2–12)

$$E = hf = \frac{hc}{\lambda} \tag{2-12}$$

where h is Planck's constant ($h = 6.63 \times 10^{-34} \text{ J s}$), c is the speed of light and λ is the wavelength of the emitted or absorbed light.

Bohr applied the quantum theory of light to the structure of the electrons by restricting them to exist only along the certain orbits (called the *allowed* *orbits*) and not allowing them to appear at arbitrary locations inside the atom. The angular momentum of the electrons is quantized and thus prohibits random trajectories around the nucleus. Consequently the electrons cannot emit or absorb electromagnetic radiation in arbitrary amounts since an arbitrary amount would lead to an energy that would force the electron to move to an orbit that does not exist. Electrons are thus allowed to move from one orbit to another. However, the electrons never actually cross the space between the orbits. They simply appear or disappear within the allowed states; a phenomenon referred to as a *quantum leap* or *quantum jump*.

For his theory of atoms that introduced the new discipline of quantum mechanics in physics, Bohr received a Noble Prize in 1922. He was also a founder of the Copenhagen school of quantum mechanics. One of his students once noticed a horseshoe nailed above his cabin door and asked him: "Surely, Professor Bohr, you don't believe in all that silliness about the horseshoe bringing good luck?" With a gentle smile Bohr replied: "No, no, of course not, but I understand that it works whether you believe it or not".

2.6.2 Absorption and Emission of Photons

In Bohr's atomic model, an electron jumps to a higher orbit when the atom absorbs a photon, and back to a lower orbit when the atom emits a photon. In other words, a quantum leap to a higher orbit requires energy, while a quantum leap to a lower orbit emits that energy (see Fig. 2-15).

Bohr's atomic model resolved the problem of atomic instability (Section 2.4.4) by changing the classical mechanics into quantum mechanics. This explains the existence of discontinuities in the absorption and emission of energy which is determined by the allowable electronic states in atoms. These allowed orbits are also called stationary orbits or stationary states. Since the orbits are discrete and quantized, so are their energies. The electrons in an atom can thus only have discrete energies. According to Bohr's theory, in an electrically neutral atom, an electron is in its stationary state and does not radiate energy as long as it is not disturbed. This explained the stability of atoms but does not explain why electrons don't radiate energy while orbiting along their stationary trajectories. The theory also explained the reason for the discontinuities in the atomic spectra. When an electron jumps to higher orbit a photon must be absorbed and its energy is equal to the energy difference of the two orbits. Conversely, a photon is emitted when an electron drops to a lower orbit and the photon energy is again equal to the energy difference of the two orbits (see Fig. 2-15)

$$hf = E_n - E_m, \ n > m \tag{2-13}$$

Both the emission and absorption of energy by an atom thus correspond to electron transition, which is the movement of an electron from one level to another. The electrons of an electrically neutral atom are normally all in the lowest possible energy levels. The addition of energy excites the electrons and the resulting atom is in an excited state (absorption of energy by an atom). Generally the electrons remain in this excited state for a short duration and soon return to a more stable, lower energy level by releasing the extra energy (emission of energy by an atom).



Figure 2-15. Schematic representation of a quantum leap of electrons in the quantum atomic model (Niels Bohr, 1913)

2.6.3 The Bohr Model of the Hydrogen Atom

According to the Bohr atomic model, the hydrogen atom consists of an electron of mass m and charge -e, which orbits around a nucleus of charge +e (see Fig. 2-16). For simplicity, it is assumed that the electron orbits the nucleus in a circular motion and that the nucleus is fixed in its position (since the hydrogen nucleus consists of one proton that is much heavier than the electron, this assumption does not affect the final result).

The only force that is thus acting on the electron is the attractive Coulomb force from the positively charged nucleus

$$F = \frac{ke^2}{r^2} \tag{2-14}$$

where k is the Coulomb force constant, $k = 1/4\pi\varepsilon_0 = 8.99 \times 10^9 \text{ Nm}^2/\text{C}^2$, and $\varepsilon_0 = 8.8542 \times 10^{-12} \text{ C}^2/\text{Nm}^2$ is the permittivity of free space.

The Coulomb force of attraction is equal to the electron's centripetal force and according to Newton's second law it can be written as

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$$m\frac{v^2}{r} = \frac{ke^2}{r^2}$$
(2-15)

where v^2/r is the centripetal acceleration. Equation (2-15) can be rewritten as follows

$$mv^2 = \frac{ke^2}{r} \tag{2-16}$$

and according to classical mechanics, this indicates possible values for electron velocity and its distance from the nucleus that range continuously from 0 to ∞ . The electron's kinetic energy is $T = mv^2/2$ and its potential energy in the field of the proton is $U = -ke^2/r$. By convention the potential energy is zero (U = 0) when the electron is far away from the nucleus ($r \rightarrow \infty$). For an electron in a circular orbit around a positively charged nucleus kinetic and total energy are

$$T = -\frac{1}{2}U\tag{2-17}$$

$$E = T + U = \frac{1}{2}U = -\frac{1}{2}\frac{ke^2}{r}$$
(2-18)



Figure 2-16. Circular motion of an electron in the Bohr model of the hydrogen atom

The negative value for the total energy indicates that the electron is bound to the nucleus and cannot escape to infinity. Since the distance from the nucleus ranges from 0 to infinity, it follows from Eq. (2-18) that the electron's total energy can have values between $-\infty$ and 0.

The above analysis is based on classical mechanics and does not show that the energy of the electron is quantized. Bohr's hypothesis was that the electron's angular momentum (L = mvr) was quantized in multiples of Planck's constant (this is because Planck's constant has a unit of angular momentum) and for circular orbits

$$L = m vr = n \frac{h}{2\pi} = n\hbar \quad (n = 1, 2, 3, ...)$$
(2-19)

where $\hbar = h/2\pi = 1.055 \times 10^{-34}$ Js (read as "*h* bar"). Combining Eqs. (2-18) and (2-19)

$$m\left[\frac{n\hbar}{mr}\right]^2 = \frac{ke^2}{r} \implies r_n = \frac{n^2\hbar^2}{ke^2m} = n^2a_0 \quad (n = 1, 2, 3, ...)$$
(2-20)

Eq. (2-20) gives quantized values for the radius of the electron's orbit. In addition, it defines the so-called *Bohr radius*, a_0

$$a_0 = \frac{\hbar^2}{ke^2m} = 0.0529 \,\mathrm{nm} \tag{2-21}$$

From the possible electron orbit radii the possible energy levels are calculated as follows

$$E = T + U = \frac{1}{2}U = -\frac{1}{2}\frac{ke^2}{r}$$
 and $r_n = \frac{n^2\hbar^2}{ke^2m} = n^2a_0$ gives

$$E_n = -\frac{ke^2}{2a_0} \frac{1}{n^2} \quad (n = 1, 2, 3, ...)$$
(2-22)

The energy of the photons that are absorbed or emitted from the hydrogen atom during electronic transitions between orbits n and m (n > m, see Fig. 2-15) can be now determined

$$E_{\gamma} = E_n - E_m = \frac{ke^2}{2a_0} \left[\frac{1}{m^2} - \frac{1}{n^2} \right]$$
(2-23)

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In the chapters that follow this equation is explored further and connected to the work of Rydberg.

2.7 Atomic Spectra

A spectrum is defined as the distribution of light (electromagnetic radiation) as a function of its frequency or wavelength. Newton performed the first light color spectrum experiment in 1666 by shining white light through a glass prism. The experiment produced a rainbow of colors and showed that what we observe as white light is a mixture of many different colors. In 1814 a German physicist, Joseph von Fraunhofer, noticed a multitude of dark lines, indicating that certain colors are missing in the solar light spectrum. These dark lines were caused by the absorption of some of the solar light's components by the gases in the sun's outer atmosphere. A series of experiments followed and by the middle of the 19th century it was understood that gases absorb light (specific frequencies of light) that are characteristic of the gas constituents.



Absorption spectrum



Emission spectrum



If white light is shone through a gas that consists of only one kind of atom, the gas will absorb light of frequency (energy) that is characteristic to that atom. If the light is then subsequently transmitted through a glass prism, the resulting spectrum will lack the colors corresponding to the absorbed frequencies. This spectrum is called the *absorption spectrum* and the dark lines correspond to the absorbed frequencies (see the hydrogen absorption spectrum in Fig. 2-17). By 1859 Robert Bunsen discovered that sufficiently heated gases also emit light and an *emission spectrum* is observed when the emitted light is transmitted through a glass prism (see the hydrogen emission

spectrum in Fig. 2-17). The emission spectrum's bright lines correspond to the dark lines in the absorption spectrum. At the same time, his colleague, Gustav Kirchhoff, while analysing the spectra of sunlight and heated sodium, realized that the dark lines in the solar spectrum represented the light frequencies that were absorbed by the sodium atoms in the solar gases.

The emission and absorption spectra thus represents a "signature" of an atom. The Kirchhoff-Bunsen discovery was not fully understood until Bohr explained the transition of electrons between strictly defined orbits (energy levels), but it represents the beginning of the science of spectroscopy. By 1870 spectroscopy became a tool that was used to analyse the chemical compositions of the sun and stars.

2.7.1 The Balmer-Rydberg Formula

In 1885 a Swiss school teacher, Jakob Balmer (1825-1898), analysed the hydrogen atomic spectral data and showed that the observed wavelengths correlate to the formula

$$\frac{1}{\lambda} = R \left[\frac{1}{4} - \frac{1}{n^2} \right] \tag{2-24}$$

where *R* is a constant with a dimension of inverse length, according to Balmer equal to 0.0110 nm^{-1} for the hydrogen spectrum, and *n* is an integer with values of 3, 4, 5 and 6 that correspond to the four observed hydrogen spectral lines. Balmer correctly assumed that this dependence could not be a random coincidence and that other lines must exist (*n* can be greater than 6). The Balmer formula can be rewritten in the form

$$\frac{1}{\lambda} = R \left[\frac{1}{2^2} - \frac{1}{n^2} \right] \quad (n = 3, 4, 5, ...)$$
(2-25)

Johannes Rydberg later extended Balmer's work to include all lines in the hydrogen atom emission spectrum

$$\frac{1}{\lambda} = R \left[\frac{1}{m^2} - \frac{1}{n^2} \right] \quad (n > m)$$
(2-26)

where n and m are both integers. Equation (2-26) is called the *Rydberg* formula and R the *Rydberg constant*. At the time when this formula was developed, it only represented empirical data and no explanation was given as to why the spectral lines obey such regularities. In 1913, Neils Bohr

developed an atomic model that explained this nature of absorption and emission spectra of atoms. Rewritten in terms of photon energy, the Rydberg formula becomes

$$E_{\gamma} = hc/\lambda$$
 and $\frac{1}{\lambda} = R\left[\frac{1}{m^2} - \frac{1}{n^2}\right]$ $(n > m)$ give

$$E_{\gamma} = Rhc \left[\frac{1}{m^2} - \frac{1}{n^2} \right] \quad (n > m) \tag{2-27}$$

Recall from Section 2.6.3 (Eq. 2-23) the energy of emitted or absorbed photons according to the Bohr atomic model

$$E_{\gamma} = E_n - E_m = \frac{ke^2}{2a_0} \left[\frac{1}{m^2} - \frac{1}{n^2} \right]$$

From last two relations it can be seen that Bohr's model predicts Rydberg formula and gives the value for the Rydberg constant

$$R = \frac{ke^2}{2a_0} \frac{1}{hc} = \frac{1.44eVnm}{2(0.0529nm)(1240eVnm)} = 0.0110nm^{-1}$$
(2-28)

which is in perfect agreement with the measured values. The term, hcR is called the *Rydberg energy*, E_R

$$E_R = hcR = \frac{ke^2}{2a_0} = \frac{m(ke^2)^2}{2\hbar^2} = 13.6eV$$
(2-29)

Thus, the allowed energies of the electron in a hydrogen atom can be expressed in terms of the Rydberg energy

$$E_n = -\frac{E_R}{n^2} \tag{2-30}$$

and the energies of the photons emitted or absorbed by the hydrogen atom are given by

$$E_{\gamma} = E_n - E_m = E_R \left[\frac{1}{m^2} - \frac{1}{n^2} \right] \quad n > m$$
 (2-31)

2.7.2 Properties of the Hydrogen Atom According to Bohr's Atomic Model

Bohr's model of the atom correctly predicts:

- Possible electron energies in a hydrogen atom are quantized and with values of $E_n = -E_R/n^2$ where n = 1, 2, 3, ...
- The lowest possible energy level corresponds to the ground state for which n = 1 and $E_1 = -E_R = -13.6eV$.
- A minimum energy of +13.6eV is needed to completely remove the electron from a hydrogen atom. This energy is called the binding energy of the hydrogen atom and it is in perfect agreement with the empirical value.
- The radius that corresponds to the ground state of a hydrogen atom is equal to the Bohr radius, $r_1 = a_0 = 0.0529nm$ which agrees well with measured values of the size of the hydrogen atom.
- The radius of the n^{th} circular electron orbit is $r_n = n^2 a_0$.
- The orbits with radii greater than the ground state radius are called the *excited states* of an atom. There are infinitely many levels and all are between the ground state and the zero energy level. For the hydrogen atom, the energies of excited states are $E_2 = -E_R / 4 = -3.4eV$, $E_3 = -E_R / 9 = -1.5eV$... These energy levels are generally plotted as illustrated in Fig. 2-18 in a format commonly referred to as *energy-level diagrams*. The transition from the ground state (n = 1) to the n = 2 energy level is called the *first excitation level*, and the energy required to raise the hydrogen atom to that level is $E_1 E_2 = 10.2eV$.

The spectral lines of the hydrogen atom (see Fig. 2-19) are given names based on the names of the scientists who discovered them:

- 1. Lyman series: transition to the ground state m = 1
- 2. *Balmer series*: transition to the level m = 2
- 3. *Paschen series*: transition to the level m = 3
- 4. *Bracket series*: transition to the level m = 4.



Figure 2-18. Energy-level diagram of the hydrogen atom



Figure 2-19. Spectral lines in hydrogen atom

Example 2.4 Electron transitions in a hydrogen atom

Calculate the wavelength and energy of the light emitted when the electron in a

hydrogen atom falls from the first excited state to the ground level.

According to the Balmer formula

$$\frac{1}{\lambda} = R \left[\frac{1}{m^2} - \frac{1}{n^2} \right] \quad (n > m)$$

Therefore, the wavelength of the emitted light is

$$\frac{1}{\lambda} = R \left[\frac{1}{1^2} - \frac{1}{2^2} \right] = \frac{3}{4}R \implies \lambda = \frac{4}{3R} = \frac{4}{(3)(0.0110nm^{-1})} = 121nm$$

and the required energy of this transition is

$$E_{\gamma} = E_R \left[\frac{1}{1^2} - \frac{1}{2^2} \right] = \frac{3}{4} E_R = \frac{3}{4} (13.6eV) = 10.2eV$$

Example 2.5 Orbiting velocity of the electron in a hydrogen atom

Calculate the highest velocity, the smallest orbit radius and the time it takes for an electron to complete one revolution in a hydrogen atom.

The electron has its highest velocity and smallest orbit radius while in the ground state. The ground state radius in the hydrogen atom corresponds to the Bohr radius, $r_1 = a_0 = 0.0529nm$. The highest velocity is thus

$$m\upsilon_{1}r_{1} = n\hbar \quad r_{1} = a_{0} \quad n = 1 \implies$$

$$\upsilon_{1} = \frac{\hbar}{ma_{0}} = \frac{1.05 \times 10^{-34} \, kgm^{2} \, / \, s}{(9.31 \times 10^{-31} \, kg)(0.0529 \times 10^{-9} \, m)} = 2.1 \times 10^{6} \, m \, / \, s$$

The time it takes for a ground state electron to complete one revolution around the nucleus is

$$t = \frac{2\pi a_0}{\nu_1} = 1.52 \times 10^{-16} s$$

2.7.3 Ionization and Excitation

Ionization or excitation of atoms occurs when a photon or a charged particle (electron, α , proton) collides with an orbital electron; thereby transferring energy to and changing the energy level of the electron. Ionization refers to the case in which the transferred energy causes the

ejection of an electron, while in the case of excitation the electron simply moves to a higher energy orbital. This is an important concept in health physics as it represents the mechanism through which energy is transferred from radiation to tissue.

The ionization energy (also called the ionization potential, IP) of an atom is the amount of energy required to remove the least tightly bound electron from the atom. To remove a second electron requires remarkably more energy and the removal of each subsequent electron becomes increasingly more difficult. For most elements, the first ionization potential is on the order of several eV (see Table 2-2). The first ionization potential of the hydrogen atom is calculated in Section 2.7.2. When a photon with energy greater than the ionization energy collides with a bound electron of an atom, the photon vanishes and the electron is ejected from the atom with a kinetic energy, E_{pe} , equal to the difference between the photon's initial energy and the ionization potential

$$E_{\rm pe} = hf - IP \tag{2-32}$$

This mechanism is called the *photoelectric effect* and is described in more detail in Chapter 5.

Atom	<i>IP</i> (eV)		
Hydrogen	13.6		
Helium	24.6		
Lithium	5.4		
Beryllium	9.3		
Boron	8.3		
Carbon	11.3		
Nitrogen	14.5		
Oxygen	13.6		
Fluorine	17.4		
Neon	21.6		
Sodium	5.14		

Table 2-2. First ionization potential (IP) for the first few atoms

Example 2.6 Excitation of the hydrogen atom

Sketch the excitation of the hydrogen atom for the corresponding absorption and emission of light of energy 10.2 eV.

The absorption of a photon with energy 10.2 eV will move the electron from its ground state to orbit n = 2. Conversely, the jump back to ground state will emit a photon of energy 10.2 eV (Fig. 2-20).



Energy is emitted and the electron falls from its excited state (n = 2) back to the ground level (n = 1)

Figure 2-20. Excitation and de-excitation of the hydrogen atom

Example 2.7 Ionization potential (IP)

For a photon of wavelength 10^{-7} m striking the outer orbital electron of a sodium atom, calculate the kinetic energy of the photoelectron (ejected electron). What is the maximum photon wavelength (minimum energy) required to ionize the sodium atom? The *IP* for sodium is given in Table 2-2.

The energy of the photon of wavelength 10^{-7} m is calculated by

$$E_{\gamma} = \frac{hc}{\lambda} = \frac{1240eVnm}{100nm} = 12.40eV$$

The kinetic energy of the photoelectron is $E_{pe}=hf - IP = 12.4 \text{ eV} - 5.14 \text{ eV} = 7.26 \text{ eV}$. The maximum photon wavelength (minimum energy) required for the ionization of a sodium atom is then

$$\lambda_{\min} = \frac{hc}{IP} = \frac{1240eVnm}{5.14eV} = 241nm$$

The electron is ejected because the wavelength of the photon is less than the required maximum wavelength (i.e. the photon energy exceeds the ionization potential).

2.7.4 Hydrogen-Like Ions

The Bohr's atomic model was valid for the hydrogen atom. Any attempt to generalize it for atoms having multiple electrons was unsuccessful until quantum mechanics development took place in 1925. Bohr's model can, however, be applied to all atoms that are like hydrogen, that is atoms that have lost all but one of their electrons. In such atoms (ions) the remaining electron revolves around the nucleus of charge +Ze in the same way as the electron in a hydrogen atom. All of the formulas developed for the hydrogen atom in previous sections are thus applicable to these ions, with the exception that the e^2 term is replaced by Ze^2 . Therefore,

• The radius of an electron moving around a nucleus of charge Ze is inversely proportional to Z

$$r_n = \frac{n^2 \hbar^2}{kZ e^2 m} = \frac{n^2}{Z} a_0 \quad (n = 1, 2, 3, ...)$$
(2-33)

• The potential energy of the electron in a hydrogen-like ion is

$$U = -\frac{kZe^2}{r}$$
(2-34)

• The total energy of the electron in a hydrogen-like ion is:

$$E = T + U = \frac{1}{2}U = -\frac{1}{2}\frac{kZe^2}{r}$$
(2-35)

• The allowed energies for the electron in a hydrogen-like ion are Z^2 times the corresponding energies in hydrogen atom:

$$E_n = -\frac{kZe^2}{2a_0}\frac{1}{n^2} = -Z^2\frac{E_R}{n^2} \quad (n = 1, 2, 3, ...)$$
(2-36)

• The energies of the photons emitted and absorbed by the electron in hydrogen-like ions are:

$$E_{\gamma} = E_n - E_m = Z^2 E_R \left[\frac{1}{m^2} - \frac{1}{n^2} \right] \quad n > m$$
(2-37)

Example 2.8 Helium ion and reduced mass correction

Calculate the ratio of the allowed energies in the helium ion to that in the hydrogen atom taking into account the effect of nuclear motion.

The assumption that the electron orbits around a fixed nucleus is not entirely correct. In reality, they both revolve around the common center of mass. Since the nucleus is much heavier than the electron, the center of mass is close to the nucleus, which is therefore almost stationary. In the equations for allowed energies as well as for the Rydberg energy, the electron mass, m, must be corrected for the motion of nucleus (mass = M). This is done by replacing the electron mass with the so-called *reduced mass*, μ , which is defined as

$$\mu = \frac{m}{1 + m/M} \tag{2-38}$$

The reduced mass is always less than the actual mass of the electron. In a hydrogen atom, the nucleus consists of a single proton and $m / M \sim 1/1800$. The helium ion (He⁺) nucleus is four times heavier than that of the hydrogen atom and thus m / M is four times smaller.

$$E_n^{He^*} = -2^2 \frac{E_R}{n^2} = -4 \frac{\mu^{He^*} (ke^2)^2}{2\hbar^2 n^2} \quad E_n^H = -\frac{\mu^H (ke^2)^2}{2\hbar^2 n^2}$$

$$\frac{E_n^{He^+}}{E_n^H} = \frac{4\mu^{He^+}}{\mu^H} = \frac{4 \times \frac{1}{1 + 1/(4 \times 1800)}}{\frac{1}{1 + 1/1800}} = 4.0017$$

When nuclear motion is accounted for, the ratio of allowed energy levels in the helium ion to that of hydrogen increases from exactly 4 to 4.0017. This small difference is observed in the measurements of atomic and ionic spectra.

2.7.5 Empirical Evidence of Bohr's Theory

Although Bohr's theory was shown to be almost completely valid for the hydrogen atom, great success was also achieved when it was used to describe hydrogen—like ions (as discussed in Section 2.7.4). Bohr's theory also proved to be valid for calculating the allowed energy levels of the innermost electron in multi–electron atoms. The latter application approximates the charge of the outer electrons to be uniformly distributed in a sphere surrounding the innermost electron. It follows that, due to the

spherical symmetry of the electric field, the innermost electron experiences no net force from the outer electrons. The only force acting on the innermost electron is the electrostatic force from the positively charged nucleus (Ze). The allowed energies for the innermost electron in multi–electron atoms are given by Eq. (2-36)

$$E_n = -\frac{kZe^2}{2a_0}\frac{1}{n^2} = -Z^2\frac{E_R}{n^2} \quad (n = 1, 2, 3, ...)$$

For example, the energy required to remove the innermost electron from its ground state orbit (n = 1) in an iron atom (Z = 26) is

$$E_1 = -Z^2 E_R = -(26)^2 (13.6eV) \approx 9,194eV$$

For heavier atoms the energy needed to remove the innermost electrons is on the order of thousands of eV and thus photons emitted or absorbed in such transition are in the range of X rays (see Chapter 3). Henry Moseley (1887 - 1915), a British physicist (killed at the age of 27 in World War I), was measuring the wavelengths of X rays emitted by various atoms when he discovered that the dependence on atomic number exactly followed Bohr's theory. His explanation of characteristic X rays was that if an innermost electron (n = 1) is ejected, the vacancy created is filled by an outer electron.

The transition of the outer electron to the inner shell will produce the emission of a characteristic photon with energy that is equal to the difference in allowed energies of the levels involved in the electron jump. For example, in the transition of an electron from level n = 2 to level n = 1, traditionally called K_{α} , the energy of the emitted photon is given by Eq. (2-37)

$$E_{\gamma} = E_2 - E_1 = Z^2 E_R (1 - \frac{1}{4}) = \frac{3}{4} Z^2 E_R$$

Moseley measured the frequencies of emitted photons for about 20 different elements and found that frequency changes with the square of the atomic number Z. He then plotted the square root of the frequencies as a function of known values of Z and verified that it is a linear function. This helped in the identification of the atomic numbers of several elements that were not known at the time (one of which was technetium, Z = 43, which does not occur naturally and was produced artificially in 1937).

The plot shown in Fig. 2-21 indicates that the line does not start from the origin as the relation would suggest. After detailed examination of the plot, Moseley concluded that the line crosses the Z-axis at a point close to Z = 1,

implying that $\sqrt{f} \propto (Z-1)$ or $E_{\gamma} \propto (Z-1)^2$. The prediction that characteristic X rays are emitted with frequencies proportional to Z^2 was based on the assumption that inner electrons experience a force due to the positive charge of nucleus (+*Ze*), but are not affected by the charges of the other (outer) electrons in the atom.

In reality, however, the inner electrons do experience a force from the outer electrons in the form of a screening of the nuclear attraction force; that is, the attractive force of the nucleus is somewhat diminished due to the presence of the outer electrons. This so-called *screening factor*, *a*, is usually close to unity and the energy of emitted (or absorbed) K_{α} X rays is



$$E_{\gamma} = \frac{3}{4} (Z - a)^2 E_R \quad a \cong 1$$
 (2-39)

Figure 2-21. Plot of $K_{\alpha}X$ ray characteristic lines known at the time of Moseley's experiments

Example 2.9 Characteristic K_{α} line

Estimate the wavelength of the characteristic K_{α} X ray from niobium, which has atomic number Z = 41. Assume that the screening factor is approximately equal to 1.

$$E_{\gamma} = \frac{3}{4}(Z-a)^2 E_R = \frac{3}{4}(41-1)^2(13.6eV) = 16,320eV$$

$$\lambda = \frac{hc}{E_{\gamma}} = \frac{1240eVnm}{16320eV} = 0.076nm$$

Example 2.10 Cascade of vacancies

Calculate the wavelength and determine the spectral region for a krypton atom (Z = 36) when an electron from n = 2 fills a vacancy in the n = 1 level. What happened to the n = 2 level when the electron fell to the n = 1 level?

Allowed energies for these two levels, taking into account the screening effect, are

$$E_1 = -13.6eV \times (36-1)^2 = -16,660eV$$
 $E_2 = -\frac{13.6eV}{4} \times (36-1)^2 = -4,165eV$

The energy of the emitted photon in this transition is 12,495 eV and the corresponding wavelength is 0.099 nm, which belongs to the X-ray region of the spectrum. After the n = 2 electron falls to the n = 1 level, an n = 3 or an n = 4 electron fills this orbital and emits another photon.

2.8 Atoms of Higher Z

2.8.1 Quantum Numbers

The light spectra of atoms with more than one electron are much more complex than that of the hydrogen atom (many more lines). The calculations of the spectra for these atoms with the Bohr atomic model are complicated by the screening effect of the other electrons (see Section 2.7.5). Examination of the hydrogen spectral lines with high resolution spectroscopes shows these lines to have very fine structures, and the observed spectral lines are each actually made up of several lines that are very close together. This observation implied the existence of sublevels of energy within the principal energy level, which makes Bohr's theory inadequate even for the hydrogen atomic spectrum.

Bohr recognized that the electrons are most likely organized into orbital groups in which some are close and tightly bound to the nucleus, and others less tightly bound at larger orbits. He proposed a classification scheme that groups the electrons of multi-electron atoms into "shells" and each shell corresponds to a so-called quantum number n. These shells are given names that correspond to the values of the principal quantum numbers

- n = 1 (K shell) can hold no more than 2 electrons
- n = 2 (*L* shell) can hold no more than 8 electrons
- n = 3 (*M* shell) can hold no more than 18 electrons, etc.

Moseley's work (described in Section 2.7.5) contributed to the understanding that the electrons in an atom existed in groups visualized as electron shells, and according to quantum mechanics, the electrons are distributed around the nucleus in *probability regions* also called the *atomic orbitals*.

In order to completely describe an atom in three dimensions, Schrödinger introduced three quantum numbers in addition to the principal quantum number, n. There are thus a total of four quantum numbers that specify the behaviour of electrons in an atom, namely

- principal quantum number, n = 1, 2, 3, ...
- azimuthal quantum number, l = 0 to n 1
- magnetic quantum number, m = -l to 0 to +l
- spin quantum number, s = -1/2 or +1/2.

The *principal quantum number* describes the shells in which the electrons orbit. The maximum number of electrons in a shell n is $2n^2$.

The sub-energy levels (s, p, d, etc...) are the reason for the very fine structure of the spectral lines and result from the electron's rotation around the nucleus along elliptical (not circular) orbits. The *azimuthal quantum number* describes the actual shape of the orbits. For example, l = 0 refers to a spherically shaped orbit, l = 1 refers to two obloid spheroids tangent to one another, and l = 2 indicates a shape that is quadra-lobed (similar to a four leaf clover). For a given principle quantum number, *n*, the maximum number of electrons in an l = 0 orbital is 2, for an l = 1 orbital it is 6, and an l = 2 orbital can accommodate a maximum of 10 electrons.

The magnetic quantum number is also referred to as the orbital quantum number and it physically represents the orbital's direction in space. For example when l = 0, m can only be zero. This single value for the magnetic quantum number suggests a single spatial direction for the orbital. A sphere is uni-directional and it extends equally in all directions, hence the reason for a single m value. If l = 1 then m can be assigned the values -1, 0, or +1. The three values for m suggest that the double lobed orbital has three distinctly different directions in three-dimensional space into which it can extend.

The *spin quantum number* describes the spin of the electrons. The electrons spin around an imaginary axis (as earth spins about the imaginary axis connecting the north and south poles) in a clockwise or counter - clockwise direction; for this reason there are two values, -1/2 or +1/2.

The allowed combination of quantum numbers is given in Fig. 2-22.

Example 2.11 Quantum numbers of the hydrogen atom

Write the quantum numbers of the ground and first excited level of the electron in a hydrogen atom. Comment on the values of angular momentum of the ground state atom using Bohr's atomic model. Use an energy-level diagram to indicate the quantum levels.

From Fig. 2-22 it follows that for the ground level, n = 1. The only possible value for the azimuthal quantum number is then zero (l = 0), indicating that the ground state of a hydrogen atom has zero angular momentum. This in turns gives only one value for the magnetic quantum number, m = 0. According to Bohr's atomic model, the ground state of a hydrogen atom has an angular momentum equal to $L = 1 \times \hbar$. However, the Schrödinger equation (see Chapter 4) predicts that L = 0.

For the first excited level, n = 2, which gives two values for the azimuthal quantum number; namely l = 0 and l = 1. When l = 0, the only possible value for *m* is zero. However, when l = 1, *m* assumes three values, m = 1, 0, or -1 and this results in three possible orientations for the angular momentum. In summary:

2

3 4 5

Ground state: n = 1, l = 0, m = 0

l =

First excited level: n = 2, l = 0 or l = 1, m = 0 or m = 1, 0 or -1. The energy-level diagram is shown in Fig. 2-23.

0 1

n = 11sn = 22s2pNot Allowedn = 33s3p3dn = 44s4p4dn = 55s5p5dn = 66s6p6dn = 77s7p7d

Figure 2-22. Allowed combinations of quantum numbers

2.8.2 The Pauli Exclusion Principle

Quantum numbers describe the possible states that electrons can occupy in an atom. Additional rules are required to define how the electrons occupy these available states and thus explain the structure of multi–electron atoms and the periodic system of elements. An atom in its ground state has the minimum possible energy and electrons are distributed among the available and allowed states according to the principle formulated by the Austrian physicist Wolfgang Pauli (1900 ~ 1958). This principle, called the *Pauli Exclusion Principle*, states that no two electrons in any atom can share the same set of four quantum numbers. As an analogy, consider the fact that a single seat in the bus can be occupied by only one passenger and not by all the passengers. The electron states for the first three elements are used to describe the Pauli Exclusion Principle.

i = 0 $i = 1$ $i = 2$ $i = 3$	l = 0	l = 1	l = 2	l = 3
-------------------------------	-------	-------	-------	-------

					- 1 - 0
4	4 <i>s</i>	4 <i>p</i>	4 <i>d</i>	4 <i>f</i>	E = E/16 = 0.0 eV
n = 4 n = 3	3 <i>s</i>	3 <i>p</i>	3 <i>d</i>		$E_4 = -E_R/10 = -0.9 \text{ eV}$ $E_3 = -E_R/9 = -1.5 \text{ eV}$
<i>n</i> = 2	2 <i>s</i>	2 <i>p</i>			$E_2 = -E_{\rm R}/4 = -3.4 {\rm eV}$

-F=0

$$n = 1$$
 $E_1 = -E_R/1 = -13.6 \text{ eV}$

Figure 2-23. Energy-level diagram for the hydrogen atom including the quantum numbers

<u>Hydrogen</u>, the first and simplest atom, has a nuclear charge of +1 (Z = 1), and thus only one electron. The principal quantum number must be 1. Therefore,

n = 1, l = 0, m = 0, s = +1/2 or -1/2

Since there is only one electron, the spin orientation can be either of the two values.

<u>Helium</u>, the second element, has 2 orbital electrons and positive nuclear charge of +2 (Z = 2). The first electron in a helium atom may have the same set of quantum numbers as the electron in a hydrogen atom, but the second electron must differ. Since there are two possible values for spin orientation, these two electrons will have different spin quantum numbers (see Fig. 2-24). Thus,

For the first electron: n = 1, l = 0, m = 0, s = + 1/2And for the second: n = 1, l = 0, m = 0, s = - 1/2 The second electron in a helium atom exhausts all possibilities for n = 1. The anti-parallel orientation of the spins in the 1s state results in a zero magnetic moment, which is observed for the helium atom in its ground state, thus providing proof of the exclusion principle. If the spins of these two electrons were parallel (forbidden states), this would produce a non-zero magnetic moment, which has never been observed.



Figure 2-24. The ground state of a helium atom according to the Pauli Exclusion Principle

In an excited helium atom as shown in Fig. 2-25, one electron can be in the 1s state and the other in 2s. In this case, according to Pauli Exclusion Principle, the spins of the two electrons can be parallel, which would give a non-zero magnetic moment, or anti-parallel, in which case the magnetic moment is zero. Both cases have been observed in reality and thus contribute evidence of the exclusion principle.



Figure 2-25. The lowest excited states of a helium atom

<u>Lithium</u>, which has three orbital electrons and atomic number Z = 3. The first two electrons occupy the 1s level with anti-parallel spins. The 1s level is thus filled and cannot accommodate any more electrons (all seats are taken!). Thus, the third electron, according to the exclusion principle, must occupy the next higher energy level and thus have a principal quantum number equal to 2. The lowest level in this state is the 2s level (see Fig.2-26). This orbital may be circular or elliptical, *i.e.* the azimuthal quantum number may be either 0 or 1:

if $l = 0 \implies m = 0$; if $l = 1 \implies m = -1$, 0 or +1.

Each of these states may contain 2 electrons, with each electron having a spin of +1/2 or -1/2.



Figure 2-26. The ground state of a lithium atom

The Pauli Exclusion Principle also applies to any electron-like particle, *i.e.* a particle with a half-integer spin. For example, neutrons, like the electrons, have a half-integer spin and the arrangement of neutrons inside the nucleus is similar to that of the electrons in their orbits around the nucleus (see Chapter 3).

2.8.3 The Aufbau Principle

The quantum numbers and the Pauli Exclusion Principle define the maximum number of electrons that can be found in each of the electron orbits of an atom and also explain how the electrons are arranged. The *aufbau principle* (German meaning "to build up") explains the order in which the electrons occupy the orbitals. According to this principle the lowest energy orbitals in an atom are filled before those in the higher energy levels. This explains the regularities in the chemical properties of the elements and the periodic table of elements as described in the following section.

2.9 The Periodic Table and Properties of the Elements

By the mid 19^{th} century, several chemists had discovered that when the elements are arranged by atomic mass they demonstrate periodic behaviour. In 1869, while writing a book on chemistry, Russian scientist Dmitri Mendeleev (1834 – 1907) realized this periodicity of the elements and he arranged them into a table that is today called the periodic table of elements. The table, as first published, was a simple observation of regularities in nature; the principles that defined this periodicity were not understood. Mendeleev's table contained gaps due to the fact that some of elements were

yet unknown. In addition, when he arranged the elements in the table he noticed that the weights of several elements were wrong.

In the modern periodic table, the elements are grouped in order of increasing atomic number and arranged in rows (see Fig. 2-27). Elements with similar physical and chemical properties appear in the same columns. A new row starts whenever the last (outer) electron shell in each energy level (principal quantum number) is completely filled. Properties of an element are discussed in terms of their chemical or physical characteristics. Chemical properties are often observed through a chemical reaction, while physical properties are observed by examining a sample of a pure element.



Figure 2-27. The periodic table of elements

The chemical properties of an element are determined by the distribution of electrons around the nucleus, particularly the outer, or valence, electrons. Since a chemical reaction does not affect the atomic nucleus, the atomic number remains unchanged. For example, Li, Na, K, Rb and Cs behave chemically similarly because each of these elements has only one electron in its outer orbit. The elements of the last column (He, Ne, Ar, Kr, Xe and Rn) have filled inner shells and all except helium have eight electrons in their outermost shells. Because their electron shells are completely filled, these elements cannot interact chemically and are therefore referred to as the inert, or noble, gases. Each horizontal row in the periodic table of elements is called a period. The first period contains only two elements, hydrogen and helium. The second and third periods each contain eight elements, while the fourth and fifth periods contain 18 elements each. The sixth period contains 32 elements that are usually arranged such that elements from Z = 58 to 71 are detached from main table and placed below it. The seventh and last period is also divided into two rows; one of which, from Z = 90 to 103, is placed below the second set of elements from the sixth period. The vertical columns are called groups and are numbered from left to right. The first column, Group 1, contains elements that have a closed shell plus a single s electron in the next higher shell. The elements in Group 2 have a closed shell plus two s electrons in the next shell. Groups 3 to 18 are characterized by the elements that have filled, or almost filled, p levels. Group 18 is also called Group 0, and contains the noble gases. The columns in the interior of the periodic table contain the transition elements in which the electrons are present in the *d* energy level. These elements begin in the fourth period because the first d level (3d) is in the fourth shell. The sixth and the seventh shells contain 4f and 5f levels and are called lanthanides, or rare earth elements, and actinides, respectively.

The elements are also grouped according to their physical properties; for instance, they are grouped into metals, non-metals, and metalloids. Elements with very similar chemical properties are referred to as families; examples include the halogens, the inert gases, and the alkali metals. The following sections only focus on those atomic properties that are closely related to the principles of nuclear engineering.

2.9.1 Electronic Configuration

The most common way to illustrate the electronic structure of the atoms in their ground states is to use energy–level diagrams (like these shown in Fig. 2-24 and 2-26) or notations as shown in Table 2-3.

First Shell	Second Shell	Third Shell
Hydrogen, H-1: 1s ¹	Lithium, Li-3: $1s^22s^1$	Sodium, Na-11: $1s^22s^22p^63s^1$
Helium, He-2: $1s^2$	Beryllium, Be-4: $1s^22s^2$	Magnesium, Mg-12: $1s^2 2s^2 2p^6 3s^2$
	Boron, B-5: $1s^22s^22p^1$	Aluminium, Al-13: $1s^22s^22p^63s^23p^1$
	Carbon, C-6: $1s^2 2s^2 2p^2$	Silicon, Si-14: $1s^22s^22p^63s^23p^2$
	Nitrogen, N-7: $1s^2 2s^2 2p^3$	Phosphor, P-15: $1s^22s^22p^63s^23p^3$
	Oxygen, O-8: $1s^2 2s^2 2p^4$	Sulphur, S-16: $1s^22s^22p^63s^23p^4$
	Fluorine, F-9: $1s^2 2s^2 2p^5$	Chlorine, Cl-17: $1s^22s^22p^63s^23p^5$
	Neon, Ne-10: $1s^22s^22p^6$	Argon, Ar-18: 1s ² 2s ² 2p ⁶ 3s ² 3p ⁶

Table 2-3. Electron configuration of the first 18 elements

Example 2.12 Electronic configuration

For Na and Li, write the electronic configurations in short notation based on the previous completed electron shell.

From Table 2-3 it follows:

Lithium, Li-3: $1s^22s^1 = [\text{He}] 2s^1$ Sodium, Na-11: $1s^22s^22p^63s^1 = [\text{Ne}] 3s^1$

2.9.2 Atomic Radius

The size of an atom, expressed as the atomic radius, represents the distance between the nucleus and the valence, or outermost, electrons. The boundary between the nucleus and the electrons is not easy to determine and the atomic radius is therefore approximated. For example, the distance between the two chlorine atoms of Cl_2 is known to be nearly 2Å. In order to obtain the atomic radius, the distance between the two nuclei is assumed to be the sum of the radii of two chlorine atoms. Therefore the atomic radius of chlorine is ~1Å (or 100 pm, see Fig. 2-28).



Figure 2-28. Trends of atomic radii (listed in picometers) in the periodic table

The atomic radius changes across the periodic table of elements and is dependent on the atomic number and the electron distribution. Since electrons repel each other due to like charges, the overall size of the atom increases with an increase in the number of electrons in each of the groups (see Fig. 2-28). For example, the radius of a hydrogen atom is smaller than the radius of the lithium atom. The outer electron of lithium is in the n = 2 level, so its radius must be larger than the radius of hydrogen which has its outermost electron in the n = 1 level.

However, in spite of the increase in the number of electrons, the atomic radius decreases when going from left to right across the periodic table. This is a result of the increase in the number of protons for these elements, which all have their valence electrons in the same quantum energy level. Since the electrons are attracted to the protons, the increased charge of the nucleus (more protons) binds the electrons more tightly and draws them closer to the nucleus, causing the overall atomic radius to decrease. For example, the first two elements in the second period of the periodic table are lithium and beryllium. The radius of a beryllium atom is 112 pm, which is smaller than that of lithium (152 pm). In beryllium, Z = 4, the fourth electron joins the third in the 2s level, assuming their spins are anti-parallel. The charge is thus larger and this causes the electrons to be bound more tightly to the nucleus; as a result the beryllium radius is less than the lithium radius. The effect of the increased charge should, however, be seen in the context of the quantum energy levels. For example, cesium has a large number of protons but it is one of the largest atoms. The valence electrons are furthest from the nucleus and the inner electrons shield them from the positive charge of the nucleus, thus the valence electrons experience a reduced effective nuclear charge and not the total charge of the nucleus. The effect of the increase in the nuclear charge thus only plays a role in the periods from left to right, e.g. from sodium to argon in the third period, since the additional valence electrons (in the same quantum energy level) are exposed to a greater effective nuclear charge along the period.

2.9.3 Ionization Energy

Another important property that shows a trend in the periodic table is the ionization energy (the energy required to remove an electron from an atom). An atom has as many ionization energies as there are electrons. By definition, the *first ionization energy* is the energy required to remove the most outer electron from a neutral atom (see Table 2-2)

 $M \rightarrow M^+ + 1e^-$

The second ionization energy is the energy required to remove the next outer electron from the singly charged ion

 $M^+ \rightarrow M^{2+} + 1e^-$

Each successive removal of an electron requires more energy because, as more electrons are removed, the remaining electrons experience a greater effective attraction.



Figure 2-29. Ionization potential of the first ten elements

The first ionization potential increases across a period (see Fig. 2-29), which is a direct result of the decrease in atomic radius (see Fig. 2-28). As the atomic radius becomes smaller the electrons feel a greater attraction from the nucleus. As the force of attraction increases, more energy is required to remove the electrons. The larger nuclear charge in helium (Z = 2) that is responsible for the smaller radius (31 pm) results in a higher ionization potential (24.6 eV) compared to that of hydrogen (radius 37 pm and ionization potential 13.6 eV). Lithium, however, has one more electron than helium and this electron is at a higher quantum energy level. The lithium radius is thus greater and the ionization potential is less. The outermost electron in lithium is located in the 2s level, which is outside the 1s level occupied by the first two electrons. The 2s electron is screened by the other two and experiences a charge on the order of one. Thus, the ionization energy of this electron can be estimated to be nearly that of the 2s hydrogen state (which is 3.4 eV). The observed lithium ionization potential, however, is 5.4 eV (see Table 2-2). The value is larger because the outer electron is not perfectly shielded by inner electrons and the effective charge is greater than the assumed value of one. Because lithium has such small ionization energy it is a chemically active element. Next to lithium is beryllium. Due to the larger charge, the radius is smaller (see Fig. 2-28) and the ionization potential is thus larger. Next is boron; the first four electrons occupy the 1s and 2s levels and the fifth electron is in 2p level. The increased charge causes the electrons in the new energy level to be more tightly bound, but the new energy level is further away from the nucleus and the valence electron is thus bound with a slightly weaker force. Consequently, the radius is reduced; the ionization potential is also reduced. Although there is an anomaly in the overall trend of ionization potential values across the period, the differences are small (the ionization potentials of beryllium and boron are 9.3 eV and 8.3 eV, respectively). In the next elements leading up to neon, the electrons occupy the 2p level (maximum of six electrons). The increasing charge decreases the atomic radius (see Fig. 2-28) and ionization potential increases as indicated in Fig. 2-29. The next period starts with sodium. Since the valence electrons of neon fill the 2p level, the sodium valence electron can only occupy the higher 3s level. This accounts for the larger atomic radius and smaller ionization potential.

The small drop in ionization potential of oxygen compared to nitrogen is due to the arrangement of electrons. In nitrogen, two electrons occupy the 1slevel and two others occupy the 2s level. The remaining three electrons occupy the 2p level. These three electrons occupy three available and distinct orbitals (2p level accommodates three orientations of the electron's orbital, see Section 2.8.1). This keeps them well separated and reduces the repulsion between them. This in turn makes nitrogen relatively stable with relatively large ionization energy. In oxygen, the fourth electron occupies the 2p level and must share one of the orbitals (with opposite spin). These two electrons thus overlap in the orbital they share which increases the repulsion between them and decreases the ionization potential relative to nitrogen.

Examples of the periodic behaviour of the elements is evident from the similarities between helium and neon (both very stable, with large ionization potential and small radii), or lithium and sodium (both with very low ionization potential and very large radii).

Example 2.13 First ionization potential

Explain which element from the list has the larger first ionization energy and why: Mg, Na, or Al.

Magnesium (Mg), when compared to sodium (Na), has a larger first ionization potential because the first ionization energy tends to increase across a row of the periodic table from left to right (period 3, see Fig. 2-27). Mg also has a larger ionization potential than aluminum (Al) even though Al is to the right of Mg in the periodic table. The electron configurations for Mg and Al are (see Table 2-3)

Mg (12 electrons): $1s^2 2s^2 2p^6 3s^2$

Al (13 electrons): $1s^2 2s^2 2p^6 3s^2 3p^1$

The outermost electron of Al (in the 3p level) is further away from the nucleus than the outermost Mg electrons which are in the 3s level. Less energy is thus required to remove the outermost Al electron.

2.10 Atomic Parameters

Atomic mass is given in either the absolute unit of grams or in a relative unit called the *atomic mass unit* (u or amu):

- 1 mole of any substance contains 6.02 x 10^{23} molecules (Avogadro's number), N_a
- The weight in grams of 1 mole of a substance is numerically equal to its molecular weight
- The unified atomic mass unit is exactly one twelfth of the mass of a C atom (C-12), *i.e.* the atomic mass of carbon-12 is equal to 12 *amu*

1 amu =
$$\frac{m_{\rm C-12}}{12}$$
 = 1.661×10⁻²⁴ kg = 931.5MeV/ c^2 (2-40)

Example 2.14 Number of atoms

How many ¹²C atoms are there in 12 g of carbon? What is the mass of one atom of carbon in kg?

Number of atoms in 12 g of carbon is

$$\frac{12g}{(1.661 \times 10^{-24} \text{ g/amu})(12 \text{ amu/atom})} = 6.02 \times 10^{23} \text{ atoms}$$

Since the molar mass of carbon-12 is 12 g, the mass of one atom of carbon 12 can be found by dividing the molar mass by Avogadro's number

$$\frac{12g/mol}{6.02 \times 10^{23} \text{ atoms/mol}} = 1.993 \times 10^{-23} \text{ g/atom} = 1.993 \times 10^{-26} \text{ kg/atom}$$

The chemical properties of atoms are determined by the distribution of electrons (see Section 2.9), and the number of electrons is called the *atomic number* and is usually denoted by Z. The number of protons in an atomic nucleus is also equal to Z, which is a requirement for electrical neutrality. When a neutral atom loses some of its electrons the atom becomes positively charged and is called a *positive ion*. For example, Ca²⁺ is a calcium atom that has lost two of its electrons. An atom can, however, gain electrons and thus become a *negative ion*. For example, Cl⁻ is a chlorine atom that gained one electron. The *atomic mass number*, A, is an integer that is almost equal to the atomic mass in *amu*. It is equal to the number of nucleons in the nucleus; that is, it is equal to the sum of the number of protons (Z) and the number of neutrons (N). Atoms (the elements of the periodic table) are denoted as follows:

 $^{A}_{Z}X$

Atoms with the same atomic number Z (for example ${}^{35}Ar$, ${}^{38}Ar$, ${}^{40}Ar$) are

called the *isotopes* of that element (argon). A naturally occurring sample of any element consists of one or more isotopes of that element and each isotope has a different weight. The relative amount of each isotope represents the isotope distribution for that element, and the *atomic weight* is obtained as the average of the isotope weights, weighted according to the isotope distribution.

Example 2.15 Atomic weight

Chromium (atomic weight 51.996) has four naturally–occurring isotopes. Three of these are: 50 Cr with isotopic weight 49.9461 and abundance 4.31%, 52 Cr with isotopic weight 51.9405 and abundance 83.76%, and 54 Cr with isotopic weight 53.9389 and abundance 2.38%. Determine the isotopic weight of the fourth isotope.

$$M^{Cr} = \frac{4.31}{100}M^{50} + \frac{83.76}{100}M^{52} + \frac{2.38}{100}M^{54} + \frac{100 - (4.31 + 83.76 + 2.38)}{100}M^{x} = 51.996$$

 $M^{53} = 52.9237$ with an abundance of 9.55 %.

Example 2.16 Mass of an atom

Calculate the mass in grams of a 52 Cr atom. The atomic mass is 51.94051 amu. A mole contains N_a number of same particles (atoms or molecules), thus

$$M(^{52}\text{Cr}) = \frac{52(g/\text{mol})}{6.02 \times 10^{23} \text{ (atoms/mol)}} = 8.638 \times 10^{-23} \text{ g/atom}$$

However, knowing the atomic mass as given in the problem, the more precise mass of the atom is obtained as follows

 $M({}^{52}\mathrm{Cr}) = \frac{51.9405(g/\mathrm{mol})}{6.02 \times 10^{23} \,(\mathrm{atoms/mol})} = 8.628 \times 10^{-23} \,\mathrm{g/atom}$

Example 2.17 Atom number density

Calculate the molecular weight of water and then determine the atom density of hydrogen in water.

The molecular weight of water is

 $2A_{\rm H} + A_{\rm O} = 2 \times 1 + 16 = 18$ giving the molecular density of water

$$N(H_2O) = \frac{\rho N_a}{A} = \frac{1(g/cm^3) \times 6.02 \times 10^{23} \text{(molecules/mol)}}{18(g/mol)} =$$

= 3.35×10²² molecules/cm³

The molecular weight of hydrogen is

$$N(H_2) = 2 \times N(H_2O) = 2 \times 3.35 \times 10^{22} \text{ atoms/cm}^3$$

= 6.69×10²² atoms/cm³

PROBLEMS

2.1 Write the electron configuration for: potassium, lanthanum, copper, bromine.

2.2 Name the elements whose electron configuration is: (a) $1s^2 2s^2 2p^6 3s^2 3p^6 4s^2 3d^3$ (b) $1s^2 2s^2 2p^6 3s^2 3p^6 4s^2 3d^{10} 4p^6 5s^2 4d^9$ (c) $1s^2 2s^2 2p^6 3s^2 3p^6$

2.3 How many electrons are in an atom specified by $1s^2 2s^2 2p^6 3s^2 3p^4$?

2.4 (a) The attractive electrostatic force of the positively charged atomic nucleus forces the negatively charged electron of the hydrogen atom to a circular motion. Write the equation that describes this statement.

(b) Knowing that only orbital radii are allowed for which angular momentum is an integer multiple of $h/(2\pi)$ and using the equation from (a) develop the relation for the allowed radii.

2.5. (a) Express the relation for the frequency of revolution of the electron in hydrogen atom for n = 1.

(b) For this case show that $v/c = (ke^2)(2\pi)/hc = 1/137$ that is called the fine structure constant, α .

2.6 Starting from the Bohr's equation for the energy of the n – th state of an electron in hydrogen atom, write the equation describing the frequency of light given off when an electron makes a transition from an initial to a final state. From there derive the value for Rydberg constant.
2.7 Calculate the largest velocity, lowest energy level and smallest orbit radius for the electron in hydrogen like atoms. When the orbit becomes infinite what is the value of energy?

2.8 Calculate how many times in second an electron in hydrogen atom orbiting at the level n = 30 goes around the nucleus?

2.9 What is the excited state of sodium atom? What is the excited state of hydrogen atom?

2.10 Knowing that the first excited state of sodium atom is at 2.1 eV above 3s level, determine the wavelength and frequency of the photon emitted in the 3p -> 3s transition.

2.11 The ground state of hydrogen atom has one electron in the 1*s* level with its spin pointing either way. Calculate the energy of the electron in this orbit using Bohr's theory. What is the value of the ionizing energy?

2.12 The ground state of helium atom has two electrons and both in 1s level. How are their spins oriented? The first ionization potential is found experimentally to be 24.6 eV. Calculate the effective charge, Z_{eff} .

2.13 Calculate the value of Rydberg constant for the hydrogen atom taking into account the effect of reduced mass.

2.14 For heavy hydrogenic ions how the reduced mass changes and consequently what is the value of Rydberg constant?

2.15 Calculate the wavelengths of Balmer lines in hydrogen atom.

2.16 Explain departure from Rutherford formula. Give an example.

2.17 Calculate the first ionization potential of hydrogen helium atom.

2.18 Draw possible trajectories of an α particle in Rutherford experiment for different impact parameters and scattering angles.

2.19 For a gold (assuming to have a nuclear radius about 7fm and atomic radius of about 0.13nm) foil used in Rutherford experiment what is its maximum thickness that would not produce the multiple scattering of α particles?

2.20 For an ion of ²³Mg write the number of protons, neutrons, and electrons.

2.21 Study the Millikan's experiment. Knowing that the oil droplets were produced such to have a radius of 1 μ , and that the voltage between plates positioned at the distance of 0.042 m was recorded whenever the droplets become stationary, using data provided show that the charge difference is always the integral multiples of 1.602 x 10⁻¹⁹ C. Assume that the density of oil is 900 kg/m³. The voltage as measured in Millikan's experiment is: 391.49 V, 407.80 V, 376.43 V, 337.49 V, 362.49 V, 376.43 V.

2.22 What is the difference between the atomic weight and atomic mass? Give an example.

2.23 Show that mass of a hydrogen atom is 1.6735×10^{-24} grams, and that of the oxygen atom is 2.6561×10^{-23} grams.

2.24 If naturally occurring carbon consists of 98.892 % ¹²C and 1.108 % ¹³C what is the average mass (in amu) of carbon?

2.25 Calculate the molecular mass of methane (CH_4) . What is the percentage by mass of the elements in this compound?

2.26 Using Eq. (2-3) write the computer code to plot the 7.7 MeV α particle's trajectories as a function of impact parameters and angles of deflection. Indicate the points of closest approach.

2.27 Use the Bohr's atomic model and write the computer code to calculate the orbiting velocity of the electron in hydrogen atom (see Example 2.5), helium ion, lithium ion, and boron ion. Comment on the results.

2.28 To the computer code developed for the Problem 2.27 add the calculation of the time it takes for an electron to complete one revolution in hydrogen atom and ions of helium, lithium and boron. How does the time change with the orbits moving further away form the nucleus? Comment on the results.

2.30 Write the computer code to reproduce the spectral lines shown in Fig. 2-19.

2.31 Plot the Rydberg energy for hydrogen atom, and first 11 ions from the table of elements. Comment on the results.

2.32 Calculate the ratio of allowed energies in the helium and lithium ion to that in the hydrogen atom taking into account the effect of nuclear motion (see Example 2.8).

Chapter 3

NUCLEAR THEORY Basic Principles, Evidence and Examples

"The dazzling complexity of the material world can, for almost all purposes, be reduced to a simple trinity: the proton, the electron, and the neutron. The neutron, a component of the nucleus of every atom except that of hydrogen, was the last of the trinity to be discovered, in 1932. Had they all been a little younger, the scientist who uncovered the neutron might have met on the battlefields of World War II." *Brian L. Silver*, ("The Ascent of Science", 1998)

1. INTRODUCTION

Atomic physics is the science of atoms, their structure and their behavior. To discuss the properties of atoms we need to know about the number of electrons and their configuration (see Chapter 2). In this context the information related to the atomic nucleus is not of great interest except to know that a neutral atom caries Z protons and A - Z neutrons (where Z represents the atomic number and A the atomic mass number).

Nuclear physics is the science of nuclei. Atomic and nuclear physics use similar laws to describe the motion of electrons and the constituents of a nucleus (protons and neutrons). However, innovative approaches had to be developed to describe the forces that hold protons and neutrons in a nucleus. A theoretical understanding of the forces acting inside the nucleus is not yet complete.

In this chapter the basic principles and laws of nuclear theory are presented.

2. THE NUCLEUS

The nucleus of an atom is composed of two types of particles, protons and neutrons, collectively called *nucleons*. The nucleus depicted in Fig. 3-1 is currently understood to be a quantum system composed of nucleons of nearly equal mass and the same intrinsic angular momentum (spin) of ¹/₂. The neutron, an electrically neutral particle, was discovered by the British physicist Chadwick in 1932. Its presence in the nucleus accounts for the difference between the atomic number and the atomic mass number and also supplies forces that hold the nucleus together. The proton, a positively charged particle, was discovered by Ernest Rutherford in 1919. In addition to its atomic number and atomic mass number, a nucleus is characterized by its size, shape, binding energy, angular momentum, and stability.



Figure 3-1. Schematic representation of a 10 B nucleus (N - neutrons, P - protons) indicating the size of the atom, nucleus and nucleons

2.1 Size, Shape and Density of Nucleus

As described in Chapter 2 (Section 2.4) Rutherford's experiment showed that it was possible to determine the size of a nucleus by bombarding a gold foil with a beam of α particles. According to the evidence from his

experiments, it was understood that an atom has a large radius in comparison with the size of its nucleus. At that time, α particles were used because they were easily attainable as a product of radioactive decay of unstable nuclei (see Chapter 4). Currently, experiments designed to probe the shapes and sizes of nuclei utilize accelerated beams of electrons, protons and α particles. One of the best ways to determine the size of a nucleus is to scatter high–energy electrons from it. From the angular distribution of the scattered electrons, which is dependant on the proton distribution in the nucleus, the shape and an average radius of a nucleus are determined.

Data from these types of experiments indicates that most nuclei have a spherical shape; though some (for example those with Z between 56 and 71) have ellipsoidal shapes with eccentricities of less than 0.2 (departure from spherical shape). Figure 3-1 shows the nucleus of a Boron-10 atom which consists of 5 protons (which give the nucleus a charge of +5) and 5 neutrons (giving it a total mass number of 10). Since departure from spherical shape is usually minimal, most theoretical models assume that the nucleus is spherical.

The nuclear radius of known elements ranges from 2 fm (helium) to 7 fm (uranium). The radius of any nucleus can be approximated using the *Fermi model*:

$$R = R_0 A^{1/3} \tag{3-41}$$

where A represents the atomic mass number, and $R_0 = 1.07$ fm. Since the volume of a sphere of radius R is proportional to R^3 , it follows from Eq. (3-41) that the nuclear volume is proportional to A, *i.e.* to the total number of nucleons:

$$V = \frac{4}{3}\pi R^3 = \frac{4}{3}\pi R_0^3 A = V_0 A \tag{3-42}$$

Thus, if the volume of a nucleus is proportional to A, it is clear that the volume per nucleon, V_0 is approximately the same for all nuclei. In other words, the density of nucleons (nuclear density) is the same for all nuclei as is the degree of packing of nucleons for all nuclei.

Example 3.1 Nuclear density Compare the nuclear densities of ¹²C and ²³⁵U. The radii of these nuclei are

$$R^{^{12}C} = R_0 A^{1/3} = (1.07 \text{ fm})(12)^{1/3} = 2.45 \text{ fm}$$
$$R^{^{235}U} = R_o A^{1/3} = (1.07 \text{ fm})(235)^{1/3} = 6.60 \text{ fm}$$

Knowing that a mass of ${}^{12}C$ atom is 12 amu and of ${}^{235}U$ atom is 235 amu, (see Chapter 2, Section 2.10) it can be shown that the nuclear density is a constant value

$$V^{^{12}C} = V_0 A = 12V_0 = (12)(\frac{4}{3}\pi R_0)^3$$
$$V^{^{25}U} = V_0 A = 235V_0 = (235)(\frac{4}{3}\pi R_0)^3$$

where $V_0 = 5.13 \times 10^{-45} m^3$. Thus

$$\rho^{^{12}C} = \frac{M^{^{^{12}C}}}{V^{^{^{12}C}}} = \frac{12amu}{12V_0} = \frac{1.661 \times 10^{-27} \, kg}{5.13 \times 10^{-45} \, m^3} = 3.2 \times 10^{17} \, kg \, / \, m^3$$
$$\rho^{^{^{235}U}} = \frac{M^{^{^{215}U}}}{V^{^{^{215}U}}} = \frac{235amu}{235V_0} = 3.2 \times 10^{17} \, kg \, / \, m^3$$

The obtained density inside the nucleus is some 14 orders of magnitude greater than the density of ordinary matter like solids or liquids. For example the density of water at standard temperature and pressure is 1000 kg/m³.

Investigation of nuclear size and structure took place in 1950's producing several Nobel Prizes. For example, for his pioneering studies of electron scattering in atomic nuclei and for his discoveries concerning the structure of the nucleons Robert Hofstadter (1915 - 1990) was awarded the Nobel Prize for physics. He shared the prize with Rudolf Mossbauer. Robert Hofstadter is the father of the cognitive scientist and philosopher Douglas R. Hofstadter best known for his 1980 – Pulitzer Prize winning book, *Gödel, Escher, Bach: an Eternal Golden Braid*.

2.2 Equivalence of Mass and Energy

Albert Einstein in his special theory of relativity postulated that the velocity of light in vacuum is the upper limit of speed in the universe. According to his theory, the mass of a moving body is not constant (as classical mechanics would predict) but is a function of velocity. The relation between mass and velocity of a moving body indicates that as the velocity increases, the mass of a body increases

$$m = \frac{m_0}{\sqrt{1 - \frac{v^2}{c^2}}}$$
(3-43)

where

m - mass of a moving body (called also the variable mass) m_0 - rest mass of a body (velocity is zero) v - velocity of a moving body *c* - speed of light. The ratio, v^2 / c^2 is usually denoted as β^2 . Thus

$$m = \frac{m_0}{\sqrt{1 - \beta^2}}$$
(3-44)

Similarly, the relativistic energy of a body moving with velocity v is

$$E = \frac{m_0 c^2}{\sqrt{1 - \beta^2}}$$
(3-45)

In the relativistic case, velocity increase due to additional energy is smaller than in the non-relativistic case, because the additional energy serves to increase the mass of the moving body rather than its velocity. Equation (3-45) suggests that:

- The more energy an object has, the heavier it is.
- The closer the velocity of a moving body is to the speed of light, the larger the force needed to accelerate the body.
- An infinite force is needed to accelerate a material object to the speed of light, which is not physically possible. The only particle that travels at the speed of light is a photon (that has a zero mass). It is also assumed that the graviton moves at the speed of light but there is still no evidence of its existence.
- Mass and energy are equivalent. In other words, all matter contains potential energy by virtue of mass.
- A body at rest ($v = 0 \rightarrow \beta = 0$) (non-relativistic approximation) possesses energy given by the famous Einstein equation

$$E = m_0 c^2 \quad (v = 0) \tag{3-46}$$

In terms of momentum and mass

$$E^{2} = (pc)^{2} + (m_{0}c^{2})^{2}$$
(3-47)

Graphically, the three terms in Eq. (3-47) can be represented as the sides of a right triangle (see Fig. 3-2). The energy–momentum equation is therefore often referred to as the "Pythagorean relation".



Figure 3-2. Graphic representation of the relativistic energy-momentum relation: (a) when $pc < m_0c^2$ the total energy is mostly rest energy, (b) when $pc > m_0c^2$ the total energy is mostly kinetic energy of the moving particle

Example 3.2 Rest energy of nuclear fuel

How much energy can be obtained from 1 gram of nuclear fuel?

$$E = m_0 c^2 = (1g)(3 \times 10^{10} \, cm/s)^2 = 9 \times 10^{20} \, erg = 9 \times 10^{13} \, J$$
$$= (9 \times 10^{20} \, erg)(2.78 \times 10^{14} \, KWh/erg) = 2.5 \times 10^7 \, KWh$$

The result suggests

- A small amount of mass corresponds to a large amount of energy (because the speed of light is large).
- In nuclear reactions an atomic nucleus of initial mass *M* is transformed into a nucleus of mass *M*' and the difference in mass is released as energy

$$E = (M - M')c^{2}$$
(3-48)

Example 3.3 Electron volt (eV)

Show that the energy given to an electron (of charge $e = -1.6 \times 10^{-19}$ coulomb) by accelerating it through 1 volt of electric potential difference called 1 eV is equal to $1.60 \times 10^{-19} J$.

The work needed to move one electron through a voltage drop of 1 volt is $e \Delta V = (-1.6 \times 10^{-19} \text{ coulomb}) (-1 \text{ volt}) = 1.602 \times 10^{-19} J = 1 eV$

Example 3.4 Rest mass of an electron

Calculate the rest energy of an electron in eV and its mass in eV/c^2 if its mass is 9.109 x 10^{-31} kg.

The rest energy is

$$E = m_0 c^2 = (9.109 \times 10^{-31} \, kg) (3 \times 10^{10} \, cm/s)^2 = 81.98 \times 10^{-15} \, joules$$
$$= (81.98 \times 10^{-15} \, J) (\frac{1eV}{1.602 \times 10^{-19} \, J}) = 5.11 \times 10^5 \, eV = 0.511 \, MeV$$

Thus, $m_0 = 0.511 \text{ MeV} / c^2$.

Example 3.5 Relativistic momentum of an electron

Prove the energy–momentum relation given in Eq. (3-47)

$$E^{2} = (pc)^{2} + (m_{0}c^{2})^{2}$$

By definition, momentum can be described as a function of the mass and velocity of a moving body

$$p = m\upsilon = \frac{m_0 \upsilon}{\sqrt{1 - \frac{\upsilon^2}{c^2}}}$$
(3-49)

Squaring equation (3-45)

$$E^{2} = m^{2}c^{4} = \frac{m_{0}^{2}c^{4}}{1 - \frac{\nu^{2}}{c^{2}}} \rightarrow m^{2}c^{4}\left(1 - \frac{\nu^{2}}{c^{2}}\right) = m_{0}^{2}c^{4} \rightarrow m^{2}c^{4} = E^{2} = m_{0}^{2}c^{4} + m^{2}c^{2}\nu^{2}$$

where p = mv, thus

$$E^{2} = (pc)^{2} + (m_{0}c^{2})^{2}$$

For a massless particle (like a photon) it follows that the total energy depends on its momentum and the speed of light: E = pc. This aspect will be discussed in greater

detail in later sections.

Example 3.6 Transition of masses

Assume a peace of solid matter initially weighs 6 grams. Following a reaction, the mass of the products is one half of the initial mass. Calculate the energy (in J) released in this mass "transition".

From equation (3-48)

$$E = \left(M - \frac{M}{2}\right)c^{2} = (6 \times 10^{-3} \, kg - 3 \times 10^{-3} \, kg)(3 \times 10^{8} \, m/s)^{2} = 27 \times 10^{13} \, J$$

2.3 Binding Energy of a Nucleus

Since an atom contains Z positively charged particles (protons) and N (= A - Z) neutral particles (neutrons), the total charge of a nucleus is +Ze where *e* represents the charge of one electron. Thus, the mass of a neutral atom, M_{atom} , can be expressed in terms of the mass of its nucleus, M_{nuc} , and its electrons, m_e

$$M_{atom} = M_{nuc} + Zm_e$$
 $M_{nuc} = Zm_p + (A - Z)m_n$ (3-50)

where m_p is the proton mass, m_e the mass of an electron and m_n the mass of a neutron.

For example the mass of the rubidium nucleus, ${}^{87}Rb$, which contains 37 protons and 50 neutrons, can be calculated as

$$M_{muc}(^{87}Rb) = 37 \times 1.007277 + 50 \times 1.008665 = 87.7025 amu$$
(3-51)

The atomic mass, indicated on most tables of the elements, is the sum of the nuclear mass and the total mass of the electrons present in a neutral atom. In the case of ${}^{87}Rb$, 37 electrons are present to balance the charge of the 37 protons. The atomic mass of ${}^{87}Rb$ is then

$$M_{atom}(^{87}\text{Rb}) = M_{nuc}(^{87}\text{Rb}) + Zm_{e}$$

$$= 87.7025 + 37 \times 0.00055 = 87.7228amu$$
(3-52)

From the periodic table, the measured mass of a ${}^{87}Rb$ atom is found to be $M_{atom}^{measured}({}^{87}Rb) = 86.909187 \ amu$. These two masses are not equal and the difference is given by

$$\Delta m = M_{atom} ({}^{87}Rb) - M_{atom}^{measured} ({}^{87}Rb) = 0.813613amu$$
(3-53)

Expanding the terms in Eq. (3-53) shows that the difference in mass corresponds to a difference in the mass of the nucleus

$$\Delta m = M_{atom} - M_{atom}^{measured}$$

= $Zm_p + Zm_e + (A - Z)m_n - M_{nuc}^{measured} - Zm_e$ (3-54)

which reduces to

$$\Delta m = M_{atom} - M_{atom}^{measured}$$

= $Zm_p + (A - Z)m_n - M_{nuc}^{measured} = M_{nuc} - M_{nuc}^{measured}$ (3-55)

Thus, when using atomic mass values given by the periodic table, the mass difference between the measured and calculated is given by

$$\Delta m = M_{nuc} - M_{nuc}^{measured} = Zm_p + Zm_e + (A - Z)m_n - M_{atom}^{measured}$$
(3-56)

Notice also that

$$Zm_p + Zm_e = Zm_H \tag{3-57}$$

where m_H is a mass of the hydrogen atom.

From this and other examples it can be concluded that the actual mass of an atomic nucleus is *always* smaller than the sum of the rest masses of all its nucleons (protons and neutrons). This is because some of the mass of the nucleons is converted into the energy that is needed to form that nucleus and hold it together. This converted mass, Δm , is called the "*mass defect*" and the corresponding energy is called the "*binding energy*" and is related to the stability of the nucleus; the greater the binding energy, the more stable the nucleus. This energy also represents the minimum energy required to separate a nucleus into protons and neutrons. The mass defect and binding energy can be directly related, as shown in Eqs. (3-58) and (3-59)

$$BE = \Delta m \times 931.5 MeV / amu \quad \text{or} \tag{3-58}$$

$$BE = \left(Zm_p + Zm_e + (A - Z)m_n - M_{atom}^{measured}\right)c^2$$
(3-59)

Since the total binding energy of the nucleus depends on the number of nucleons, a more useful measure of the cohesiveness is the *binding energy* per nucleon, E_b

$$E_b = \frac{BE}{A} = \frac{\Delta m(amu) \times 931.5(MeV / amu)}{A(\text{nucleons})} [MeV/\text{nucleon}]$$
(3-60)



Figure 3-3. Variation of binding energy per nucleon with the atomic mass number

The binding energy per nucleon varies with the atomic mass number, A, as shown in Figure 3-3. For example, the binding energy per nucleon in a rubidium nucleus is 8.7 *MeV*, while in helium it is 7.3 *MeV*. The curve indicates three characteristic regions:

- Region of stability A flat region between A equal to approximately 35 and 70 where the binding energy per nucleon is nearly constant. This region exhibits a peak near A = 60. These nuclei are near iron and are called the iron peak nuclei representing the most stable elements.
- Region of fission reactions From the curve it can be seen that the heaviest nuclei are less stable than the nuclei near A = 60, which suggests that energy can be released if heavy nuclei split apart into smaller nuclei having masses nearer the iron peak. This process is called *fission* (the basic nuclear reaction used in atomic bombs as uncontrolled reactions and in nuclear power and research reactors as controlled chain reactions).

Each fission event generates nuclei commonly referred to as fission fragments with mass numbers ranging from 80 to 160. Fission is described in detail in Chapter 6.

• Region of fusion reactions – The curve of binding energy suggests a second way in which energy could be released in nuclear reactions. The lightest elements (like hydrogen and helium) have nuclei that are less stable than heavier elements up to the iron peak. If two light nuclei can form a heavier nucleus a significant energy could be released. This process is called *fusion*, and represents the basic nuclear reaction in hydrogen (thermonuclear) weapons.

2.4 Stability of the Nucleus

Nuclei that have the same number of protons and different number of neutrons are called *isotopes*. For example, two isotopes of oxygen, ${}^{16}_{8}O_8$ and ${}^{17}_{8}O_9$, both have eight protons, but one has eight neutrons while the other has nine. Nuclei with the same mass number such as ${}^{14}_{6}C_8$ and ${}^{14}_{7}N_7$ are called *isobars*, while *isotones* are nuclei with the same number of neutrons, for example, ${}^{13}_{6}C_7$ and ${}^{14}_{7}N_7$.



Figure 3-4. Nuclear stability curve (see also Chapter 4)

The naturally occurring elements have atomic numbers (Z) between 1 and 92 with neutron numbers (N) between 0 and 146. If the number of protons is plotted against the number of neutrons for all nuclides existing in

nature as shown in Fig. 3-4, the following tendencies are observed:

- For light nuclei (A \leq 40), Z and N are nearly equal. This tendency of $Z \sim N$ is called the *symmetry effect* and is characteristic of stable nuclei. As a result of the fundamental similarity between protons and neutrons, an unstable nucleus will transform a proton into a neutron or vice versa in order to reach the stable $Z \sim N$ arrangement.
- For heavier nuclei more neutrons are needed to form a stable configuration and the ratio of N to Z approaches 1.5 for the heaviest nuclei. The tendency for N to be bigger than Z is due to the electrostatic repulsion force acting between the protons. If a nucleus has too many or too few neutrons it is unstable and may spontaneously rearrange its constituent particles to make a stable formation. Isotopes of atoms with unstable nuclei are called *radioisotopes* and are said to be *radioactive* (see Chapter 4).
- A preference for Z and N to be even is observed in the majority of nuclei. When the numbers of neutrons and protons are both even numbers, the isotopes tend to be far more stable than when they are both odd (see Table 3-1). This tendency is the result of a *pairing effect* that is described in Section 2.7.

Ζ	N	Number of stable nuclei	
Even	Even	148	
Even	Odd	51	
Odd	Even	49	
Odd	Odd	4	

Table 3-1. Configuration of stable nuclei

2.5 **Protons and Neutrons**

In 1919 Ernest Rutherford discovered a new particle, that he called a *proton* (the first particle known to be a constituent of every nucleus). He was investigating the effect of α particles interacting with nitrogen gas and noticed signs of hydrogen in the detectors. Rutherford postulated that this hydrogen could have come only from the nitrogen, and therefore that nitrogen contains hydrogen nuclei. At that time it was known that hydrogen had an atomic number equal to 1; thus he suggested that the hydrogen nucleus itself was an elementary particle and he named it proton using the Greek word for "first", *protos*. From this experiment it was understood that the proton carries a positive electrical charge equal in magnitude to the negative charge of an electron because the number of protons in a nucleus was found to be the same as the number of electrons surrounding it for an atom in its neutral state.

In 1932 Rutherford's colleague James Chadwick discovered another

constituent of the nucleus which he named the *neutron*. Neutron carries no electrical charge and thus can pass through material without being deflected by electrical forces.

Protons and neutrons are approximately equal in mass (each roughly 2,000 times heavier than an electron) and are both composed of up and down quarks whose fractional charges (2/3 and -1/3) combine to produce the 0 or +1 charge of the neutron and proton respectively.

2.5.1 Protons and Proton Decay

The positive charge of the nucleus of any atom is due to the presence of protons. Every atomic nucleus contains at least one proton and the total number of protons (atomic number) is different for every element. The basic characteristics and constituents of the proton are summarized in Fig.3-5.

The possibility that the proton may have a finite lifetime has been under experimental investigation for the last decade. The latest experimental evidence suggests that the lower boundary for proton lifetime is over 10^{35} years (many times the present age of the universe, which is estimated to be on the order of 15×10^9 years). How is it possible to detect a time that is longer than the existence of the universe?



Figure 3-5. Nuclear properties of proton

Obviously it is not possible to watch one proton for 10^{35} years to see if it decays; however, 10^{35} protons can be observed for one year with a 50–50 probability that one proton out of 10^{35} will decay. There are two laboratories equipped for this experiment; one in Minnesota and the other in Japan (the Super-Kamiokande). The dominant mode of proton decay is into a positron and a neutral pion: $p \rightarrow e^+ + \pi^0$. A positron is an anti-electron; a particle with the same mass and same charge as an electron, but with the opposite charge sign (*i.e.* a positively charged electron). The pion (or " π meson") is the collective name for three subatomic particles, π^0 , π^+ and π^- . The Super-Kamiokande detector has the capability to observe this mode of

proton decay. Using a huge pool of water as a source of protons, a proton from either hydrogen or oxygen may decay into a positron and a neutral pion. Upon contact with an electron, the positron is destroyed in a process known as electron–positron annihilation (see Chapter 5). Upon contact, the positron and electron destroy each other, producing two 511 keV photons. The π^0 has a mass of 135 MeV/ c^2 and decays into two photons with a very short half life of 84×10^{-18} seconds. The experiments look for these electromagnetic showers as an indication of proton decay. To date, proton decay has not been observed at either facility.

2.5.2 Neutrons and Neutron Decay



Figure 3-6. Experimental setup that led to the discovery of a neutron (1932)

From the time of Rutherford it has been known that the atomic mass number A of nuclei is more than twice the atomic number Z for most atoms and that almost all of the mass of the atom is concentrated in its center, *i.e.* at the nucleus. However, it was presumed that the only fundamental particles were protons and electrons. Rutherford had speculated that the nucleus was composed of protons and proton-electron pairs tightly bound together and the fact that an atom was neutral in charge required that somehow a number of electrons were bound in the nucleus to partially cancel the charge of the protons. Quantum mechanics, however, indicated that there was not enough energy available to contain electrons in the nucleus (see Section 5.4). An experimental breakthrough came in 1930 when Bothe and Becker bombarded a beryllium target with α particles emitted from a radioactive source. The experiment produced neutral radiation that was observed to be highly penetrating but non-ionizing. In the following years Curie and Joliot showed that when paraffin (a material rich in protons) is bombarded with this neutral radiation it ejects protons with energy of about 5.3 MeV (see Fig 3-6). Bothe and Joliot – Curie each explained that the radiation was high energy gamma rays. This, however, proved to be inconsistent with what was known about gamma ray interactions with matter (see Chapter 5).

In 1932 Chadwick performed a number of experiments using different

target materials to discover that the emitted radiation was actually a stream of new particles that he named neutrons. The discovery proved that there is a neutral particle in the nucleus, but also that there are no free electrons in the nucleus as Rutherford had speculated. Amazingly, once free from the nucleus, neutrons are unstable and decay with a half life of about 15 minutes into a proton, an electron, and an antineutrino.

The α -Be reaction in the experiment shown in Fig. 3-6 was explained by Chadwick

$${}^{4}_{2}He + {}^{9}_{4}Be \rightarrow {}^{1}_{0}n + {}^{12}_{6}C$$
(3-61)

where $\frac{4}{2}He$ represents the α particle. He argued that if a photon interacts with a proton in the paraffin target and transfers 100 MeV/*c* of recoil momentum, the photon itself must have had a momentum of nearly 50 MeV/*c*, which corresponds to an energy of 50 MeV (see Section 2.2). As the energy of the α particles striking the beryllium target was only about 5 MeV, it was impossible that 50 MeV gammas were being emitted. Instead, Chadwick suggested a new particle with approximately the same mass as a proton, which solved the contradiction related to the energy of the assumed photons. In the collision of two particles of equal masses, the incident particle (neutron) can transfer all of its kinetic energy to the target particle (proton). Thus for the observed momentum of 100 MeV/*c*, the kinetic energy of the neutron was $T = p^2 / 2m = (100 \text{ MeV/}c)^2 / (2 \times 938 \text{ MeV}/c^2) = 5.3 \text{ MeV}.$



Figure 3-7. Properties and composition of the neutron

By examining the interactions of neutrons with various materials, Chadwick determined the actual mass of the neutron to be between 1.005 amu and 1.008 amu, or 938 +/- 1.8 MeV. The presently accepted value is 939.57 MeV (see Fig. 3-7).

The following is the original note Chadwick sent to *Nature* in February of 1932 describing the arguments for the existence of a neutron. Chadwick

was awarded a Noble Prize for his discovery in 1935.

Possible Existence of a Neutron

James Chadwick, Nature, p. 312 (Feb. 27, 1932)

It has been shown by Bothe and others that beryllium when bombarded by α particles of polonium emits a radiation of great penetrating power, which has an absorption coefficient in lead of about 0.3 (cm)⁻¹. Recently Mme. Curie-Joliot and M. Joliot found, when measuring the ionization produced by this beryllium radiation in a vessel with a thin window, that the ionization increased when matter containing hydrogen was placed in front of the window. The effect appeared to be due to the ejection of protons with velocities up to a maximum of nearly 3 x 10⁹ cm per sec. They suggested that the transference of energy to the proton was by a process similar to the Compton effect, and estimated that the beryllium radiation had a quantum energy of 50 x 10⁶ electron volts.

I have made some experiments using the valve counter to examine the properties of this radiation excited in beryllium. The valve counter consists of a small ionization chamber connected to an amplifier, and the sudden production of ions by the entry of a particle, such as a proton or α particle, is recorded by the deflexion of an oscillograph. These experiments have shown that the radiation ejects particles from hydrogen, helium, lithium, beryllium, carbon, air, and argon. The particles ejected from hydrogen behave, as regards range and ionizing power, like protons with speeds up to about 3.2 x 10⁹ cm. per sec. The particles from the other elements have a large ionizing power, and appear to be in each case recoil atoms of the elements.

If we ascribe the ejection of the proton to a Compton recoil from a quantum of 52×10^6 electron volts, then the nitrogen recoil atom arising by a similar process should have an energy not greater than about 400,000 volts, should produce not more than about 10,000 ions, and have a range in air at N.T.P. of about 1.3 mm. Actually, some of the recoil atoms in nitrogen produce at least 30,000 ions. In collaboration with Dr. Feather, I have observed the recoil atoms in an expansion chamber, and their range, estimated visually, was sometimes as much as 3 mm at N.T.P.

These results, and others I have obtained in the course of the work, are very difficult to explain on the assumption that the radiation from beryllium is a quantum radiation, if energy and momentum are to be conserved in the collisions. The difficulties disappear, however, if it be assumed that the radiation consists of particles of mass 1 and charge 0, or neutrons. The capture of the α -particle by the Be⁹ nucleus may be supposed to result in the formation of a C¹² nucleus and the emission of the neutron. From the energy relations of this

process the velocity of the neutron emitted in the forward direction may well be about 3 x 10^9 cm per sec. The collisions of the neutron with the atoms through which it passes give rise to the recoil atoms, and the observed energies of the recoil atoms are in fair agreement with this view. Moreover, I have observed that the protons ejected from hydrogen by the radiation emitted in the opposite direction to that of the exciting α -particle appear to have a much smaller range than those ejected by the forward radiation. This again receives a simple explanation of the neutron hypothesis.

If it be supposed that the radiation consists of quanta, then the capture of the α -particle by the Be⁹ nucleus will form a C¹³ nucleus. The mass defect of C¹³ is known with sufficient accuracy to show that the energy of the quantum emitted in this process cannot be greater than about 14 x 10⁶ volts. It is difficult to make such a quantum responsible for the effects observed.

It is to be expected that many of the effects of a neutron in passing through matter should resemble those of a quantum of high energy, and it is not easy to reach the final decision between the two hypotheses. Up to the present, all the evidence is in favor of the neutron, while the quantum hypothesis can only be upheld if the conservation of energy and momentum be relinquished at some point.

J. Chadwick. Cavendish Laboratory, Cambridge, Feb. 17.

2.6 Nuclear Forces

Electrons are held in their orbits around the positively charged nucleus by the electrostatic (Coulomb) force of attraction. Within the nucleus, however, there reside only neutral particles (neutrons) and positively charged particles (protons). Therefore the only electrostatic force that acts within the nucleus is a repulsive force between protons. Furthermore, the gravitational force that acts on all matter regardless of charge is too weak to hold the nucleus in tact, as illustrated in Example 3.7.

Example 3.7 Gravitational force within the nucleus

Use Bohr's atomic model for hydrogen to show that it is impossible to find an atom on the quantum level bound by gravity. Also, show that the gravitational force can not hold nucleons in the nucleus.

According to Coulomb's law, which has the same form as Newton's universal law of gravity, the electrostatic and gravitational forces acting between an electron of mass m and charge q and a proton of mass M and charge Q are

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$$F_{el} = \frac{kqQ}{r^2} = \frac{ke^2}{r^2}$$
 and (3-62)

$$F_{grav} = \frac{GmM}{r^2}$$
(3-63)

where $G = 6.67 \times 10^{-11} Nm^2 / kg^2$ and $k = 8.99 \times 10^9 Nm^2 / C^2$.

According to Bohr's atomic model the energy of an electron in its ground state in hydrogen atom is

$$E_n = -\frac{ke^2}{2a_0} \frac{1}{n^2} \quad (n = 1, 2, 3, ...); \quad a_0 = \frac{\hbar^2}{ke^2m} = 0.0529 \, nm \tag{3-64}$$

Equation (3-64) can be rewritten as

$$E_n = -\frac{(ke^2)^2 m}{2\hbar^2} \frac{1}{n^2}$$
(3-65)

If the force that bound electrons to the atom was gravitational, Eqs. (3-62), (3-63), and (3-65) yield

$$F_{el} = F_{grav} \implies \frac{ke^2}{r^2} = \frac{GmM}{r^2} \implies ke^2 = GmM$$

$$\implies E_n = -\frac{(GmM)^2 m}{2\hbar^2} \frac{1}{n^2}$$
(3-66)

$$E_{1} = -\frac{(6.67 \times 10^{-11} Nm^{2} / kg^{2})^{2} (9.1 \times 10^{-31} kg)^{3} (1.67 \times 10^{-27} kg)^{2}}{2(1.0545 \times 10^{-34} Js)^{2}} \frac{1}{1^{2}} \Longrightarrow$$
$$E_{1} = -2.6 \times 10^{-78} eV$$

Recall that according to Bohr's atomic model, the lowest possible energy level corresponds to the ground state for which n = 1 and $E_1 = -13.6 \text{ eV}$.

The ratio of the gravitational and electrostatic forces shown in Eq. (3-67) (which is independent of distance between the particles) shows that the gravitational force is too weak to overcome the repulsion between the protons and thus hold the nucleons together in the nucleus. In the following equation, the masses are those of two protons:

$$\frac{F_{grav}}{F_{el}} = \frac{GMM}{ke^2} = \frac{(6.67 \times 10^{-11} Nm^2 / kg^2) (1.67 \times 10^{-27} kg)^2}{(8.99 \times 10^9 Nm^2 / C^2) (1.6 \times 10^{-19} C)^2} = 8 \times 10^{-37}$$
(3-67)



Figure 3-8. Strong nuclear force and force carrier (meson)

The force that holds the nucleus together is called the nuclear force (or the strong force since it must overcome the electrostatic force of repulsion between the protons) and is the strongest of the four known natural forces (gravitational, electrostatic, nuclear and weak). The force is transferred between nucleons through force carrier particles called mesons, π (see Fig. 3-8). The exchange of mesons can be understood in analogy to having a ball constantly being thrown back and forth between two people. The strong nuclear force has a very short range, and thus the particles must be extremely close (about 1 to 2 x 10^{-15} m; approximately the diameter of a proton or neutron) in order for meson exchange to take place. When a nucleon gets closer than this distance to another nucleon, the exchange of mesons can occur, and the particles will bond to each other. When nucleons cannot come within this range, the strong force is considered to be too weak to keep them together, and the competing force (the electrostatic force of repulsion) causes the particles to move apart. Additionally, at distances less than 1 fm, the electrostatic force will overcome the strong nuclear force and the nucleons will repel one another (see Fig. 3-8). In other words, when two nucleons are separated by a distance of approximately 1 fm they are bound to each other by the strong nuclear force. Inside of that distance, the electrostatic force becomes dominant and outside of that distance the nuclear force is too weak to bind the nucleons.

As explained in Section 2.3, the mass of any nucleus is always smaller than the sum of the rest masses of its individual nucleons. This difference in mass is a result of the conversion of some mass into the binding energy needed to hold the nucleus together, which is a measure of the strength of the strong nuclear force. This same energy must be applied in order to separate a nucleus into its constituents.

The nuclear density is constant for all nuclei (see Section 2.1) because it is limited by the short range repulsion. The maximum size of a nucleus (see Chapter 2) is limited by the fact that the attractive force dies away exponentially with distance between nucleons.

2.7 The Pauli Exclusion Principle and the Symmetry Effect

Nuclei tend to be more stable for nearly equal numbers of neutrons and protons especially for elements with small atomic mass numbers (see Section 2.4), a phenomenon known as the symmetry effect. Protons and neutrons, like electrons, obey the Pauli Exclusion Principle (see Chapter 2), which states that no two identical particles, *i.e.* no two protons or two neutrons, can occupy the same quantum level. According to this principle, however, a single neutron and a single proton <u>may</u> occupy the same quantum level.

A nucleus, like an atom, can be found in the ground state (the lowest energy level) and in excited states. The ground state corresponds to the arrangement of all nucleons in their lowest energy levels and according to the Pauli Exclusion Principle:

- Such arrangements forbid the nucleons to be involved in interactions that would lower their energy, because there are no lower energy states they can move to. Thus the scattering from an incident particle which raises the energy of a nucleon is an allowed interaction, but scattering that lowers an energy level is blocked by the Pauli Exclusion Principle.
- A dense collection of strongly interacting nucleons would assume the high probability of constant collisions resulting in redirection and perhaps loss of energy for the nucleons. The Pauli principle however blocks the loss of energy because only one nuclear particle can occupy a given energy state (with spin 1/2). In this dense collection of matter, all of the low energy states will fill up first.

It is important to mention here that the Pauli principle is applied only to define the behavior of so-called *fermions*. The fermions are particles which form anti-symmetric quantum states and have half-integer spin: protons, neutrons and electrons. Particles like photons and gravitons (called *bosons*) do not obey the Pauli Exclusion Principle (they form symmetric quantum states and have integer spin).

The ground state structures of the nuclei of three isobars $\binom{12}{6}C_6$, $\frac{12}{7}N_5$ and $\frac{12}{5}B_7$) are illustrated in Fig. 3-9. From the arrangement of nucleons, following the Pauli Exclusion Principle, it can be seen that the seventh neutron in ${}_{5}^{12}B_{7}$ must occupy a higher quantum energy level compared to the arrangement in ${}_{6}^{12}C_{6}$ and thus the total energy of the ${}_{5}^{12}B_{7}$ nucleus is higher. Similarly, the seventh proton in ${}_{7}^{12}N_{5}$ must occupy a higher quantum energy level than any of the nucleons in ${}_{6}^{12}C_{6}$ and thus has a greater total energy. This example leads to the conclusion that among any set of isobars (nuclei having the same number of nucleons) the nucleus with equal numbers of protons and neutrons will have the lowest total energy. It can be seen from Fig. 3-4 that if a nucleus possesses more energy than the neighboring isobar it will have a tendency to move toward the lowest and most stable energy configuration. This process, as indicated in Fig. 3-4, is called β decay and is explained in Chapter 4.



Figure 3-9. Arrangements of protons and neutrons in their ground states for three isobars with the atomic mass number of 12

3. NUCLEAR MODELS

3.1 The Liquid Drop Model and the Semi-empirical Mass Formula

As explained in Section 2.3, the binding energy, BE, of a nucleus is a measure of the strong nuclear force and represents the energy required to separate the nucleus into its constituent protons and neutrons; therefore, the greater the binding energy, the more stable the nucleus. The nuclear binding energy is large enough to cause a difference in the mass of a nucleus and the sum of the separate masses of protons and neutrons, which is given in terms of the binding energy as discussed in Section 2.3, Eq. (3-59)

$$BE = \left(Zm_p + Zm_e + (A - Z)m_n - M_{atom}^{measured}\right)c^2$$

Theoretically, the total binding energy may be directly measured by

completely separating all components of the nucleus; this process, however, is seldom possible. It is much easier to determine the binding energy of a single nucleon, for example a neutron (E_{bN})

$$E_{bN} = BE - BE_{N-1} \tag{3-68}$$

where *BE* is the binding energy of the nucleus and BE_{N-1} is the binding energy of the remaining nucleus once a single neutron has been removed.

Example 3.7 Binding energy of a single nucleon

The binding energies of ${}^{16}_{8}O_{8}$ and ${}^{17}_{8}O_{9}$ are 127.6 *MeV* and 131.8 *MeV*, respectively. Determine the energy required to separate the neutron from ${}^{17}_{8}O_{9}$.

$$E_{bN} = BE - BE_{N-1} = 131.8 - 127.6 = 4.2 MeV$$

The liquid drop model was proposed by Bohr and Wheeler to explain the structure and shape of the nucleus. In this model, a nucleus is described in analogy with a drop of incompressible liquid. This is a crude model that does not explain all of the properties of nuclei, but can easily account for the spherical shape of most nuclei and explain the process of fission (see Chapter 6). The liquid drop model considers the nucleus as a homogeneous mixture of nucleons that interact strongly with each other and maintain a spherical geometry due to surface tension. Mathematical analysis of the model produces a semi–empirical equation that can be used to predict the binding energy of a nucleus as a function of Z, N and A. An empirically refined form is presented here. The formula is also called the Weizsaecker semi–empirical formula:

• The binding energy of a nucleus is proportional to the number of nucleons, A: there are two reasons for this tendency. First, the strong nuclear force as discussed in Section 2.6 acts only within a very small distance between nucleons (up to $\sim 2 fm$; see Fig 3-10), which means that each nucleon is bound to only a fraction of the other nucleons. The second reason is that the nuclear density as described in Section 2.1 is approximately constant for all nuclei, which means that the degree of packing of nucleons is also nearly equal for all nuclei, and consequently each nucleon is bound to roughly the same number of neighboring nucleons. Thus the average binding energy for each individual nucleon is the total number of nucleons, A. Furthermore, the total number of nucleons, and therefore the total binding energy, is proportional to the volume of the nucleus. This is expressed mathematically using a volume term

$$BE \propto BE_{vol} = a_{vol}A \tag{3-69}$$

where a_{vol} is a constant such that $a_{vol} > 0$.

• Surface nucleons tend to reduce the total binding energy of a nucleus: Nucleons near the surface of a nucleus are less tightly bound because they have fewer neighboring nucleons (see Fig. 3-10). The number of surface nucleons is proportional to the surface area of a nucleus, which is related to the total number of nucleons by the Fermi model

$$4\pi R^2 = 4\pi R_0^2 A^{2/3} \tag{3-70}$$

Thus the total binding energy of a nucleus is reduced by a factor proportional to $A^{2/3}$

$$BE \propto BE_{vol} + B_{surf} = a_{vol}A - a_{surf}A^{2/3}$$
(3-71)

where a_{surf} is a constant such that $a_{surf} > 0$.



Figure 3-10. Distribution of nucleons in the interior of a nucleus (each nucleon is bound only to the nucleons within the short range of ~ 2fm)

• Electrostatic (Coulomb) repulsion forces between protons tends to reduce the total binding energy of a nucleus: this reduction is equal to the potential energy of the total nuclear charge, which is given by the following equation, assuming that the total charge of Ze is uniformly distributed within the sphere

$$U_{Coulomb} = \frac{3}{5} \frac{k \left(Ze\right)^2}{R_0 A^{1/3}} = a_{Coulomb} \frac{Z^2}{A^{1/3}}$$
(3-72)

The total binding energy of a nucleus is thus further reduced by a factor proportional to $Z^2 / A^{1/3}$

$$BE \propto BE_{vol} + B_{surf} + B_{Coulomb} = a_{vol}A - a_{surf}A^{2/3} - a_{coulomb}\frac{Z^2}{A^{1/3}}$$
(3-73)

The exact value of $a_{Coulomb}$ is dependent on the real shape of the nucleus and the approximation of Eq. (3-73) is thus valid for spherical nuclei.

• Due to the symmetry effect the total binding energy of a nucleus tends to decrease as the quantity Z - N increases: as discussed in Section 2.7 a nucleus with Z = N has the highest binding energy (and greatest stability). As the nuclei depart from this equality (as Z - N increases), the total binding energy decreases. This phenomenon is accounted for mathematically as follows

$$BE \propto BE_{vol} + B_{surf} + B_{Coulomb} + B_{symm} =$$

$$a_{vol}A - a_{surf}A^{2/3} - a_{Coulomb}\frac{Z^2}{A^{1/3}} - a_{symm}\frac{(Z-N)^2}{A}$$
(3-74)

• The pairing effect (described in next section) affects the total binding energy of a nucleus: as described in Chapter 2, a nucleus having an even number of both protons and neutrons tends to have the greatest stability, and therefore greater binding energy. This preference requires a correction to the total binding energy of the form

$$BE \propto BE_{vol} + B_{surf} + B_{Coulomb} + B_{symm} + B_{pair} = a_{vol}A - a_{surf}A^{2/3} - a_{Coulomb}\frac{Z^2}{A^{1/3}} - a_{symm}\frac{(Z-N)^2}{A} + \delta a_{pair}\frac{1}{A^{1/2}}$$
(3-75)

where a_{pair} is a constant and δ is dependent upon nuclear configuration as shown in Table 3-2.

From the Weizsaecker semi-empirical formula it can be concluded that the total binding energy of a nucleus depends primarily on *A*, which is why *BE* is usually discussed in terms of binding energy per nucleon (Section 2.3).

δ	Z	N	
1	Even	Even	
0	Even or Odd	Odd or Even	
-1	Odd	Odd	

Table 3-2. Correction term for the semi-empirical binding energy formula

The five constants of the formula are determined empirically so as to fit as many experimentally measured binding energies as possible. For those nuclides that are difficult to measure experimentally, the following set of values is generally used to approximate the binding energy (all values are given in MeV)

$$a_{vol} = 15.75$$
 $a_{surf} = 17.8$ $a_{Coulomb} = 0.711$ $a_{symm} = 23.7$ $a_{pair} = 11.2$

Example 3.8 Prediction of nuclear binding energy from the Weizsaecker semi-empirical formula

Calculate the total binding energy for ${}^{87}_{37}$ Rb₅₀ and compare with the measured value of 757853.053 +/- 2.487 keV.

$$BE \propto (15.75)(87) - (17.8)(87)^{2/3} - 0.711 \frac{(37)^2}{(87)^{1/3}} - 23.7 \frac{(37-50)^2}{(87)} + 0$$

 $\Rightarrow BE = 755.05 MeV$

The liquid drop model also permits the development of a semi-empirical formula for the prediction of nuclear masses.

$$M = 0.99389A - 0.00081Z + 0.014A^{2/3} + 0.083 \cdot \frac{(A/2 - Z)^2}{A} + 0.000627 \cdot \frac{Z^2}{A^{1/3}} + \Delta X = 0.000627 \cdot \frac{Z^$$

where the values of Δ are given in Table 3-3.

Δ	Ζ	Α	
$-0.036 / A^{3/4}$	Even	Even	
$+0.036 / A^{3/4}$	Odd	Even	
0		Odd	

Table 3-3. Correction term for the semi-empirical nuclear mass formula

Example 3.9 Prediction of a nucleus mass from the Weizsaecker semi-empirical formula

Calculate the nuclear mass for ${}^{87}_{37}$ Rb₅₀ and compare with the measured value of 86.9091835 +- 0.0000027 amu.

$$M = 0.99389(87) - 0.00081(37) + 0.014(87)^{2/3} + 0.083 \cdot \frac{(87/2 - 37)^2}{87} + 0.000627 \cdot \frac{37^2}{87^{1/3}} - 0.036 \frac{1}{(87)^{3/4}} = 86.94609 amu$$

3.2 The Shell Model

An alternative to Bohr and Wheeler's liquid drop model of the nucleus is the *shell model*, according to which the various nucleons exist in certain energy levels within the nucleus (see Fig. 3-9). Each nucleon is identified by its own set of quantum numbers similar to electrons in their orbits. In this manner, nuclear energy levels containing successively 2, 8, 20, 50, 82, and 126 nucleons exhibit a very high level of stability due to completely filled energy levels. For this reason, as with atoms that have a full valence electron shell, nuclei containing these *magic numbers* of nucleons are inert in the nuclear sense. For example, these nuclei do not readily react when bombarded with neutrons. Table 3-4 illustrates the atomic and nuclear closed-shell numbers.

Table 3-4. Atomic and nuclear closed-shell numbers

Tuble b 1. Thomas and indical closed shell numbers			
Atomic closed-shell numbers	2, 10, 18, 36, 54, 86		
Nuclear closed-shell numbers	2, 8, 20, 28, 50, 82, 126		
(magic numbers)			

Nuclei which have both a magic number of neutrons and protons are particularly stable and are labeled "doubly magic"

 ${}^{4}_{2}He_{2}$ ${}^{16}_{8}O_{8}$ ${}^{40}_{20}Ca_{20}$ ${}^{48}_{20}Ca_{28}$ ${}^{208}_{82}Pb_{126}$

The existence of the magic numbers and the shell structure of a nucleus are confirmed through many observations

- 1. Nuclei with a magic number of neutrons or protons tend to have more stable isotopes. For example, (a) tin $({}_{50}Sn)$ has ten stable naturally occurring isotopes: ${}^{112}Sn$ (0.97%), ${}^{114}Sn$ (0.65%), ${}^{115}Sn$ (0.34%), ${}^{116}Sn$ (14.54%), ${}^{117}Sn$ (7.68%), ${}^{118}Sn$ (24.22%), ${}^{119}Sn$ (8.58%), ${}^{120}Sn$ (32.59%), ${}^{122}Sn$ (4.63%), ${}^{124}Sn$ (5.79%); (b) isotones with N = 82 have seven stable isotopes.
- 2. The stable elements at the end of the naturally occurring radioactive series (see Chapter 4) all have a magic number of neutrons or protons.

The thorium, uranium and actinium series decay to lead, which has a magic number of 82 protons, while the neptunium series ends with bismuth, which has a magic number of 126 neutrons.

- 3. The neutron absorption cross section (see Chapter 6) for nuclei with a magic number of neutrons is much lower than that for the neighboring isotopes. The closed neutron shells increase the stability of the nuclei making them less likely for neutron interactions.
- 4. The binding energy of the last neutron in nuclei with a magic number plus one drops rapidly when compared to that of a nucleus with a magic number of neutrons.

Example 3.10 Separation energy of the last neutron

Compare the separation energy of the last neutron in ${}^{40}Ca_{20}$ with its binding energy per nucleon. What is the separation energy of the last neutron when one neutron is added to the nucleus of ${}^{40}Ca_{20}$.

The masses are

 $m({}^{40}Ca_{20}) = 39.9625912 amu; m({}^{39}Ca_{19}) = 38.9707177 amu; m_n = 1.008665 amu; m_p = 1.007277 amu; m({}^{41}Ca_{21}) = 40.9622783 amu$

The separation energy of the last neutron in ${}^{40}Ca_{20}$ is

 $E_{bn} = (38.9707177 + 1.008665 - 39.9625912) \times 931.5 MeV = 15.6 MeV$

The binding energy per nucleon is (see Section 2.3 and 3.1)

$$BE = (Zm_p + Zm_e + (A - Z)m_n - M_{atom}^{measured})c^2$$

= (20×1.007277 + 20×0.00055 + 20×1.008665 - 39.9625921)c²
= 342.1MeV \Rightarrow

BE/40 = 8.6 MeV

The separation energy of the last neutron is almost twice the average nucleon binding energy in the doubly magic isotope of calcium–20.

When one neutron is added, according to the Pauli principle and shell structure of the nucleus, the nucleons must begin to fill a new shell.

The separation (or the binding) energy of that neutron is thus much less

 $E_{bn} = (39.9625912 + 1.008665 - 40.9622783) \times 931.5 MeV = 8.3 MeV$

5. The excitation energy from the ground energy level to the first excited energy level is greater for the closed-shell nuclei. An interesting observation to point out is that the discrete energy levels of the electrons in an atom are measured in eV or keV, while the energy levels of a nucleus are on the order of MeV. Nuclei, like atoms, tend to release energy and return to the ground state following excitation. The excitation energies for the even-A nuclei of lead are shown in Fig. 3-11. The histogram indicates that the required energy is dramatically larger for the nucleus with a magic number of neutrons.



Figure 3-11. First excited energy level in even-A nuclei of lead

4. PLANCK'S THEORY OF QUANTA

In 1900 Max Planck developed the theory that energy is absorbed and emitted in small energy packets that he called *quanta*. The size of quanta of low frequency (red) light is smaller than the size of quanta of high frequency (violet) light. In 1905, Albert Einstein published his famous paper on the photoelectric effect postulating the quantum nature of light (for which he received the Nobel Prize in 1921). According to Einstein's theory (see Chapter 5), light is composed of particles (which he called *photons*) such that a beam of light is analogous to a stream of bullets. Thus, ultraviolet (UV) light having a frequency of 10^{16} Hz consists of a stream of photons each having 100 times the energy of photons of infrared (IR) light having a frequency of 10^{14} Hz. That is why UV light can cause skin cancer while IR has no significant effect on the skin.

The energy of an atom, as discussed in Chapter 2, can be increased only in discrete values, just as American money cannot be counted in units less than cents. The energy of the quanta (E) is proportional to the frequency (f) of oscillation of the light wave. Therefore the total energy can be equal only to an integer number of quanta (similar to the fact that one can have 3 dollars and 20 cents, but can not have 3 dollars and 20.5 cents). The size of the energy quantum is given by

$$E = hf \tag{3-76}$$

where h is Planck's constant equal to 6.626×10^{-34} Js.



Figure 3-12. Definition of a wave

It is important to note that increasing the intensity of a light source increases the rate at which photons are emitted. If the frequency of emitted light has not changed, the energy of the emitted photons has also not changed. The relationships between frequency, wavelength, velocity and energy of a light wave are sketched in Fig. 3-12.

4.1 Black Body Radiation

At the beginning of the 20th century it was known that heat causes the molecules and atoms of matter to oscillate and that any body with a temperature greater than absolute zero radiates some energy. It was also observed that the intensity and frequency distribution of the emitted radiation depended on the detailed structure of the heated body. The model analyzed for more than 40 years in order to explain the dependence of

emitted radiation energy on wavelength was the "black body" model, (see Fig. 3-13). A black body is a hypothetical object that absorbs 100 % of all radiation that it is exposed to.



Figure 3-13. Black body



Figure 3-14. Black body radiation spectrum (not to scale)

At normal temperatures such a body reflects no radiation and thus appears to be perfectly black. When heated, the radiation emitted by a black body is called black body or cavity radiation and is characteristic of this body only and is not dependent upon the type of incident radiation. In practice no material has been found to exhibit the exact properties of this model. A black body may be thought of as a furnace with a small hole in the door through which heat energy can enter from the outside. Once inside the furnace, the heat is entirely absorbed by the inner walls, which may emit radiation to be absorbed by another part of the furnace wall or to escape through the hole in the door. The radiation that escapes from a black body may contain any wavelength.

The black body radiation spectrum (Fig. 3-14), which represents the intensities of each of the wavelengths of radiation emitted from a black body as a function of the energy of radiation, indicates that

- A black body radiates energy at every wavelength, while energy decreases exponentially as wavelength increases.
- A black body emits most of its radiant energy at a peak wavelength. For example, at 5000 K the peak wavelength is about $5 \times 10^{-7}m$ (500 nm) which is in the visible light (yellow-green) region.
- At each temperature a black body emits a standard amount of energy represented by the area under the curve. A hotter body thus emits radiation with shorter wavelengths. For example, black bodies at higher temperatures are blue, and those at lower temperatures are red.
- As the temperature increases, the peak wavelength emitted by a black body decreases and begins to move from the infra-red to the visible end of the spectrum. Since none of the curves cross the x-axis it follows that radiation is emitted at every wavelength.
- As the temperature increases, the total energy emitted increases nonlinearly (the total area under the curve increases in uneven steps).

4.2 Wein's Displacement Law

When the temperature of a black body increases, the overall emitted energy increases and the peak of the radiation curve moves to shorter wavelengths (see Fig. 3-14) as defined by the Wein's displacement law

$$\lambda_{\max} T = 2.8898 \ 10^{-3} \, mK \tag{3-77}$$

where λ_{\max} is the wavelength at which the energy of the emitted radiation is maximum, and *T* is the temperature in *Kelvin*.

Wein's displacement law is used to evaluate the temperatures of any radiant object whose temperature is far above that of its surroundings (such as stars, for example). Wilhelm Wein was awarded the Nobel Prize in Physics in 1911 for his work in optics and radiation.

Example 3.11 Wein's displacement law

Use Wien's displacement law to calculate the temperature (in K) of a star whose maximum wavelength is 3.6×10^{-9} m (an X ray star).

From Eq. (3-77)

 $\lambda_{\rm max} T = 2.8898 \ 10^{-3} \, mK$ $T = 8.03 \, \times 10^5 \, K$

4.3 The Stefan-Boltzmann Law

According to the Stefan-Boltzmann law the energy, E, radiated by a black body per unit time and unit area (energy flux or emissive power) is proportional to the fourth power of the *absolute* temperature, T

$$E = \sigma T^4 \tag{3-78}$$

where σ is the Stefan–Boltzmann constant equal to 5.67 x 10^{-8} W m^{-2} K^{-4} .

The Stefan–Boltzmann law gives the total energy that is emitted at all wavelengths from a black body (which corresponds to the area under the black body radiation spectrum, Fig. 3-14) and explains the increase in the height of the curves with temperature. The increase in energy is very abrupt, since it is proportional to the fourth power of the temperature.

Example 3.12 Stefan–Boltzmann law

Calculate the ratio of radiated energy from the sun to that of the earth assuming their temperatures are 6000 K and 300 K, respectively. Determine the maximum wavelengths of the emitted radiation.

According to Stefan–Boltzmann law, Eq. (3-78) $E_{sun} = 5.67 \times 10^{-8} Watts m^{-2} K^{-4} (6000 K)^4 = 7.3 \times 10^7 Watts m^{-2}$ $E_{earth} = 5.67 \times 10^{-8} Watts m^{-2} K^{-4} (300 K)^4 = 459 Watts m^{-2}$ $E_{sun} / E_{earth} = (6000 K)^4 / (300 K)^4 = 1.6 \times 10^5$

According to Wein's displacement law: Sun: $\lambda_{max} = 2.8898 \ 10^{-3} \ mK \ / \ 6000 \ K = 0.48 \ \mu m$ Earth: $\lambda_{max} = 2.8898 \ 10^{-3} \ mK \ / \ 300 \ K = 9.6 \ \mu m$

4.4 The Rayleigh–Jeans Law

At the beginning of the 20th century a major problem in physics was to predict the intensity of radiation emitted by a black body at a specific wavelength. Wien's displacement law (see Section 4.3) could predict the overall shape of the black body spectrum, but at long wavelengths the predictions disagreed with experimental data. Rayleigh and Jeans developed

a theory that the radiation within a black body is made up of a series of standing waves. They argued that electromagnetic radiation was emitted by atoms oscillating in the walls of the black body. The oscillating atoms emit radiation that creates a standing wave moving back and forth between the walls. Their formula is shown in Fig. 3-15.

The Rayleigh–Jeans formula agreed with the experimental data for long wavelengths, but in the region of short wavelengths the disagreement with measured values was extreme. According to the Rayleigh–Jeans formula, the radiation intensity becomes infinite as wavelength approaches zero. When compared to the radiation energy distribution as a function of temperature and wavelength of the emitted light (see Fig. 3-14) it can be observed that the peak wavelength was not predicted by the Rayleigh–Jeans law. This failure to account for the decrease in energy emitted at short wavelengths (the UV wavelengths) is known as the *ultraviolet catastrophe*.

At a meeting of the German Physical Society in October of 1900, Max Planck presented his theory that radiation is emitted in discrete portions, quanta, and showed that his formula fit all experimental data.



Figure 3-15. Rayleigh-Jeans law of black body radiation

4.5 Planck's Law

Planck explained that the oscillating electrons of the surface atoms of a black body emit radiation according to Maxwell's laws of electromagnetism. At that time, classical mechanics predicted that such radiation could have any value of energy.

Planck postulated that the energy is emitted or absorbed only in discrete amounts because the frequencies of the oscillating electrons could have only specific discrete values. Since the energy of electromagnetic radiation is proportional to frequency (E = hf), it, too, can be available only in discrete amounts

$$E = 0, hf, 2hf, 3hf, \dots$$
 (3-79)

Equation (3-79) defines Planck's law which represents the basic law of quantum theory. According to this law the energy of electromagnetic waves is restricted to quanta radiated or absorbed as a whole with magnitude proportional to frequency.

5. THE WAVE PARTICLE DUALITY

The ultimate belief and tendency in modern physics is toward a large overview that will incorporate all laws of nature into one unified theory. This theory would bring together the laws of the subatomic world and laws of galaxies and everything in between; a concept that Einstein called the *ideal limit of knowledge*.

Kepler, Galileo, Copernicus, and Newton where the first to develop the theory of the universe, according to which the universe was infinite in all directions and light travelled at infinite or near infinite speed. With the 20th century came Einstein's theories of quantum mechanics and the understanding of physics from the macro–world to the subatomic realm changed.

A *quantum* is a discreet quantity and *mechanics* is the study of motion; thus quantum mechanics describes a nature to consist of small, discreet parts (quanta) and is applied to describe events on the subatomic scale. Newtonian (classical) physics is applicable to the macro-world, but is not applicable to the subatomic realm.

Newton's laws are based on every day observations and predict *events* such as ball trajectory or the velocity of celestial bodies. Quantum mechanics is based on subatomic experiments and predicts *probabilities*. Subatomic phenomena cannot be observed or detected directly, as an atom
or subatomic particle can not be seen by the same means as macro objects. Using Newton's laws of motion, the future or the past of a moving object can be easily predicted given initial conditions. For example, if the present positions and velocities of the earth, the moon, and the sun are known, it is possible to predict where the earth has been or will be in relation to the moon and the sun. For example, the space program would not be possible without Newtonian calculations of the movements of spacecraft relative to the movements of the earth and moon.

The ability to predict the future and the past based on knowledge of the present and Newton's laws of mechanics suggests that from the moment the universe was created and set into motion, everything that was to happen within the universe was already determined. However, according to quantum mechanics, it is not possible to know enough about the present to make a complete prediction of the future. A prediction or observation of the subatomic world requires a decision as to which of aspects must be known, because the laws of quantum mechanics forbid precise knowledge of more than one of them at the same time.

This section introduces the basic aspects of the quantum mechanics concept, describes the evidence for the wave-particle duality nature of subatomic constituents, explains the uncertainty principle, and gives a brief introduction to the Schrödinger wave equation.

The scope of the presented theories is directly related to applications in nuclear engineering disciplines.

5.1 De Broglie's Hypothesis

The development of quantum mechanics began in 1900 with Planck's study of black body radiation (see Section 4.1.). Planck found that the energy of oscillation of electrons that produce the radiation is absorbed and emitted in discrete amounts, quanta, given by E = nhf, where *n* is an integer value and *h* is Planck's constant which value was determined from the black body radiation spectra. However, Planck was not able to explain why the energy would be quantized, because at that time radiated energy was considered to be *wave-like*. This theory was derived from the Thomas Young's double-slit experiment (see Section 5.2) that in 1803 demonstrated the interference pattern of light.

In 1905, Einstein explained the photoelectric effect that proved Planck's discovery of quanta, and showed not only that energy absorption and emission are quantized, but that the energy of light itself is quantized. With this explanation he introduced a new concept of light; theorizing that light quanta are *particle–like* (photons) and that light, therefore, behaves as a series of particles. This was a confrontation to classical physics and the two

sets of (repeatable *by demand*) experiments (the photoelectric effect and the double-slit experiment) were proving different natures of light.

The idea that light could behave as a wave *and* as a particle created a new question: does an electron have particle–wave properties or, in a larger frame, is the dual particle–wave nature of light a property of all material objects as well.

The answer to this question was given by Prince Louis de Broglie in his Doctoral thesis of 1923 in which he argued that all material objects can behave, like light, both as a particle and as a wave at the same time. Equation (3-76)

E = hf

was difficult to apply to particles with finite mass. It describes a total, kinetic or total relativistic energy (as all are identical) of light.

However, the relationship of momentum, p, to wavelength

$$p = h / \lambda \tag{3-80}$$

is valid for any particle or material object.

De Broglie suggested (without any experimental evidence) that for any particle with non-zero mass (such as electrons, protons, or bowling balls) moving with momentum p, there is an associated wave of wavelength λ related to momentum as

$$\lambda = h / p \tag{3-81}$$

The wavelength of a moving particle calculated from this equation is called the *de Broglie wavelength*.

Example 3.13 De Broglie wavelength

effect of its wave nature is important.

Calculate the de Broglie wavelength for: (1) an electron moving at $3.0 \times 10^6 \text{ m/sec} (= 0.01c)$, and (2) a 1000-kg car travelling at 100 km/hr.

(1) $\lambda = h / p = 6.6 \times 10^{-34} Js / [(9.11 \times 10^{-31} kg) (3.0 \times 10^6 m/sec)] = 2.4 \times 10^{-10} m$ Since the wavelength of the electron is comparable to atomic dimensions, the

(2) $\lambda = h / p = 6.6 \times 10^{-34} Js / [(1000 kg) (100 \times 10^3 m/3600 sec)] = 2.4 \times 10^{-38} m$

The wave character of the car is much smaller than the car itself; hence the wave-like motion of the car (or of any macro object, for that matter) is not evident.

Using the analogy of sound waves (known to vibrate at discrete frequencies when confined to a finite region such as an organ pipe), de Broglie argued that the quantization of electron energy in an atom can be explained as the quantization of electron–wave frequency (for an electron confined inside the atom), which would explain the quantization of the angular momentum of an electron in a hydrogen atom.

De Broglie pictured the electron wave oscillating along the circular orbit of Bohr's atom (see Fig. 3-16) such that its circumference is equal to the finite integral number of wavelengths

$$2\pi r = n\lambda, \qquad n = 1, 2, 3, \dots$$
 (3-82)

Replacing the wavelength of the electron wave with the de Broglie relation of Eq. (3-81), it follows

$$rp = \frac{nh}{2\pi} \tag{3-83}$$

For a circular orbit, *rp* represents the angular momentum, *L*. Combining last equation it gives

$$L = \frac{nh}{2\pi} = n\hbar, \qquad n = 1, 2, 3,...$$
 (3-84)

the Bohr quantization condition was obtained (see Chapter 2).



Figure 3-16. Electron wave in Bohr's atom according to the de Broglie representation

5.2 Double–Slit Experiment

In 1803, the British physicist, physician, and Egyptologist, Thomas Young (known for deciphering the Rosetta stone), carried out a very simple but unique experiment known as the *double-slit experiment*. The goal of this experiment was to understand the nature of light. He analyzed the pattern created by light while passing through two slits (either through one or both).

In order to understand the nature of such an experiment we start with a brief review of the properties of waves. The best analogy for understanding the wave property of light is to consider the water waves created at the entrance of a harbour. For example, if the mouth of the harbour is wide enough the waves move straight through it. This is because the distance between the crests, the wavelength, is smaller than the size of harbour entrance as illustrated in Fig. 3-17 (a). However, if the mouth of the harbour is small (smaller than or equal to the wavelength) the waves spread out into semicircles, a phenomenon called the *diffraction* of waves. Diffraction of waves is illustrated in Fig. 3-17 (b).

It was assumed that since light is a wave it should behave the same way when passing through slits of sizes smaller or larger than its wavelength.

If light passes through the cut-out screen as shown in Fig.3-18 (a), it will behave as the ocean waves passing through the large harbour entrance, since the opening in the slit is large compared to the wavelength.

When the slit opening is small (see Fig. 3-18 (b)) the light diffracts and there is no sharp boundary between the bright and dark area at the screen where the image is projected.

Knowing this, Thomas Young developed an experiment as shown in Fig. 3-19. He analyzed the patterns that are created by the light on the wall screen depending on the size of the slits and whether one or both are opened.

Young observed that when one slit was closed the image obtained at the wall indicated light diffraction (like that shown in Fig. 3-18 (b)). However, when both slits were opened, the expected image of a simple sum of the light waves did not appear. Instead, the pattern showed bands of light and dark areas (see Fig. 3-19), a phenomenon called light *interference*.

Since the spacing of the maxima and minima in the interference pattern depend on light wavelength, changing the wavelength (color) of light will change the location and number of bright and dark bands on the screen. If the distance between the slits is increased more bands of light will be created on the screen.

This experiment showed that light has a wave–like property because only waves can show interference. However, 100 years later, Einstein proved that light also exhibits the properties of a particle.



(a) $d >> \lambda$



(b) $d\sim\lambda$

Figure 3-17. Patterns that water waves create while passing through a harbor entrance of different sizes: (a) the entrance is larger than the wavelength of water waves; (b) the entrance is smaller than the wavelength of water waves

Assuming light to be a stream of particles, the double-slit experiment can be analyzed in a very interesting way. When both slits are opened, photons *"fired from the light gun one at the time"* will hit the screen (wall) at particular areas and there will be places where the photons will never land (otherwise there would be no dark areas and the image would be the same as when there is only one slit).



(a) Size of the slit larger than light wavelength



(b) Size of the slit comparable to light wavelength

Figure 3-18. Patterns created by light passing through slits of various sizes



Figure 3-19. Thomas Young's double slit experiment (1803)

Now the question is *how* the photons know where to land and where not to land or how the photons know that there are two slits and that both are opened? If one of the slits is closed there will be no interference and the dark bands will disappear (the whole wall becomes illuminated including areas that are dark when both slits are opened). When only one slit is opened, the future of the event can be easily predicted because the laws governing the phenomenon are known, as well as the initial conditions (the origin of light, its speed and its direction). Using Newton's laws of motion it is possible to determine where the photons will land on the wall surface. The initial conditions for each case (one slit or two) are identical. However, in the case when both slits are opened, Newton's laws of motion will give exactly the same results as in the previous case, which will be wrong. In other words, two photons having exactly the same initial conditions, in two different experiments, will not go to the same location. In the second experiment it can be understood that a wave pattern is created on the screen by a large group of photons. In that pattern it is not possible to know where a single photon will land. All that can be known is the probability of finding a single photon in a given location. What determines WHERE a single photon will land?

According to quantum mechanics there is only a probability which guides a photon to a particular area. The experiment can be viewed once again considering the light as a particle, as a wave, or as a wave--particle:

Light as a particle – if light is considered as a stream of particles we may ask why the photons avoid making spots on certain areas of the screen when both slits are open. Every particle has two opportunities, two slits to pass through. These two opportunities interfere with each other since the image obtained at the wall shows the bands of light and dark areas. The interference can be explained by saying that the particles are controlled in such a way that each particle passes through a slit alone. The particles do not bump into each other and two particles never pass through one slit at the same time. The next question is how to explain this interference using quantum mechanics.



Figure 3-20. Wave-particle duality

<u>Light as a wave</u> – if light is considered to behave as a wave it can reach both slits at the same time, which a particle can not do. The wave can then break up into two waves and each would pass through each slit individually.

This phenomenon is seen when a real wave (at a harbour, for example) comes to two openings (like the space between piers). Two waves can travel separate paths, go through separate slits, and reach the wall where they can interfere with each other. Waves are made of moving hills and valleys (see Fig. 3-12); if at some point on the wall the valley of one wave meets the hill of another wave, these two waves cancel out at that point. This easily explains the light and dark bands at the wall when both slits are opened. If one slit is closed, then there would be no reason for the wave to split into two parts and the wave will reach the screen unimpeded.

This consideration seems to solve the problem by stating that the possibilities always interfere with each other if an object behaves as a wave. It could be concluded that there were no particles in the stream of light, and that the stream was simply a wave. However, when the waves arrive at the screen they do not land everywhere like waves reaching the beach shore, indicating that light does not always behave like a wave.

Light as a particle and a wave – Waves reach the screen in a series of points. Since the real waves can not do that, it can be concluded that a particle always leaves a track while travelling as a wave through the space. This statement can explain that waves are particles and that particles are the waves.

Such behaviour of particles when confronted with two or more possibilities is called wave-particle duality (see Fig. 3-20). Although it is still not known why subatomic matter behaves in this way, the laws of quantum mechanics can explain the phenomena (lasers, microchips, photocells, nuclear reactors, long-range deep-space communication devices, transistors, materials at very low temperatures).

5.3 Experimental Evidence for the Wave–Particle Duality

De Broglie's hypothesis as discussed in Section 5.1 explained that matter waves were not evident in the macroscopic world because the wavelength was much smaller than the size of the objects. His equation, however, indicated that because the size of subatomic particles is smaller than the wavelengths of their associated waves the wave properties are noticeable. For example, for a non-relativistic particle of mass *m* and kinetic energy $E = p^2 / 2m$, the de Broglie wavelength can be expressed as

$$\lambda = \frac{h}{\sqrt{2mE}} \tag{3-85}$$

This relation clearly indicates that particles of lower mass have longer wavelengths. It follows that the particle–wave behaviour of the lightest known particle, the electron, should be easy to detect. By expressing the kinetic energy of an electron in eV and placing its mass of 9.109 x 10^{-31} kg into Eq. (3-85), the de Broglie wavelength for an electron is

$$\lambda = \sqrt{\frac{1.5}{E}}(nm) \tag{3-86}$$

For example, an electron with energy 1.5 eV has a wavelength of 1 nm, while an electron with energy 15 keV has a wavelength of 0.01 nm. Since the distances between the atoms in crystalline structures of solid matter are in the order of electron wavelengths for electron energies in the range of eV to keV, electrons are expected to be diffracted by crystal lattices. In 1926, just two years after de Broglie presented his hypothesis, C. J. Davisson and L. H. Germer, at the Bell Telephone Laboratories, were able to verify the wave property of electrons in crystal diffraction experiments. Davison used electrons with energy of 54 eV and wavelength of 0.167 nm which were diffracted from a nickel–coated surface. In 1927 G. P. Thomson used electrons with energy of approximately 40 keV and wavelength 0.006 nm to demonstrate diffraction by micro crystals.

In the Davisson-Germer experiment the electrons were of low energy and thus they did not penetrate very far into crystal. To analyze the experimental data and show evidence of the wave nature of electrons, it is sufficient to assume that the diffraction took place in the plane of atoms on the surface of the nickel. From independent X ray diffraction data available at that time it was known that the spacing between the rows of atoms in a nickel crystal was 0.091 *nm*. Therefore, according to Bragg's law (knowing that the maximum angle of diffraction was measured to be $\theta = 65^{\circ}$), the wavelength of the diffracted electron was 0.165 *nm* (see Fig. 3-21). This value, when compared with the de Broglie wavelength of 0.167 nm, provides strong evidence for wave–like behavior of electrons.



Figure 3-21. The Bragg's law

Example 3.14 Electron diffraction from crystal planes

Electrons accelerated through a voltage of 100 V are diffracted from a crystal with a plane distance of $d = 2 \times 10^{-10}$ m. Calculate the electron scattering peaks for the first three orders of diffraction.

The electron wavelength can be obtained as follows

$$qV = \frac{p^2}{2m} \rightarrow p = \sqrt{2mqV} \rightarrow$$
$$\lambda = \frac{h}{p} = \frac{h}{\sqrt{2mqV}} = \frac{6.626 \times 10^{-34} Js}{\sqrt{2(9.1 \times 10^{-31} kg)(1.6 \times 10^{-19} C)(100V)}} = 1.228 \times 10^{-10} m$$

Using Bragg's law (see Fig. 3-21) the scattering peaks for the first three orders of diffraction are:

$$2d\sin\theta = n\lambda \quad \to \quad \theta = \sin^{-1}\frac{n\lambda}{2d} = \sin^{-1}(0.30699n) \quad \to \\ \theta(n=1) = 17.88^{\circ} \quad \theta(n=2) = 37.88^{\circ} \quad \theta(n=3) = 67.07^{\circ}$$

Since these first experiments of particle diffraction many more were

carried out to confirm the wave-particle duality of protons, neutrons, atoms and molecules. Additionally, the double-slit interference experiment was performed with electrons (1989), neutrons (1991) and even atoms (1991) and molecules (1999). The double-slit interference experiments with electrons demonstrated that a very weak source of electrons (only one electron passing through the slits at any given time) generated the pattern of waves on the screen. Such experiments showed that particles of matter are not classical solid particles with well predicted and defined trajectories, but that they behave as waves whenever there is a choice of more than one possibility (such as in the double-slit experiment). In other words, in the double-slit experiment every particle is given two trajectories. In a wave form the particle travels along both trajectories arriving at a random point on the screen causing the interference pattern. In all experiments with all types of particles, the pattern consists of bands with a spacing of $\lambda L / a$, where a is the separation between the slits, L is the distance between the slits and the screen, and λ is the de Broglie wavelength (see Fig. 3-19).



Figure 3-22. Single slit diffraction pattern

Example 3.15 Single slit diffraction

For red light (660 nm) impinging on slits of width a = 0.05 mm and a = 0.2 mm placed L = 1 m away from the screen, determine the angular separation θ between

the center line and the first minimum of the resulting diffraction pattern and its distance from the first maximum, y (see Fig. 3-22).

$$a\sin\theta = n\lambda, \quad n = 1 \quad \rightarrow \quad \theta = \sin^{-1}\frac{\lambda}{a} \quad \rightarrow$$

 $\theta(0.05mm) = 0.76^\circ; \ \theta(0.2mm) = 0.19^\circ$
 $y = L\tan\theta \quad \rightarrow \quad y(0.05mm) = 13.2mm; \ y(0.2mm) = 3.3mm$

5.4 The Uncertainty Principle

The double-slit experiment considering photons as both particles and waves is discussed in Section 5.2. In order to introduce the uncertainty principle associated with the subatomic realm, we will analyze this experiment using electrons as shown in Fig. 3-23 (a). In the experiment it is assumed that all electrons coming from the "gun" have nearly the same energy. The electrons behave in the same way as photons (as discussed in Section 5.3) and produce interference pattern on the screen. The question is can we "watch" each of the electrons to see their trajectories and thus understand which slit they go through and at which point on screen they land.

In order to do this, two modifications are made to the experimental setup: (1) a light source is placed directly behind the slit screen and (2) a detector or an array of detectors is placed on the wall. As each electron passes through a slit, the light emitted from the source is reflected such that the observer may determine which slit the electron passed through.

The detectors then indicate where the electron struck the wall. Thus every electron that arrives at the screen is placed into one of two categories: those that passed through slit one and those that passed through slit two. From the number of events recorded in each category, we obtain the probabilities, P'_1 and P'_2 , respectively, of each event. The distribution of these probabilities as a function of distance from the centreline is shown in Fig. 3-23 (b). When the light source is in place we "watch" each electron passing through the screen; we obtain the expected result: each electron passes through only one slit regardless of the number of open slits. In this case, when both slits are open, the probabilities of each event simply add to determine the total probability, $P'_{12} = P'_1 + P'_2$, and no interference is observed. However, if the light source is removed, interference is once again observed (P_{12}) as in the original experiment. The conclusion is that the observation of the electron trajectories via the light source somehow changes the distribution of electrons at the screen. When a photon from the light source is reflected, or scattered, by the electron, the motion of the electron is changed such that it may fall into a different part of the probability distribution (a minima instead of a maxima, or vice versa). This is why interference is observed.





Figure 3-23. (a) Double-slit experiment with electrons and (b) the results of the experiment when electron trajectories are "watched" by shining a light on the electrons

The next question then becomes what will happen to the probability distribution if the intensity of the light source is reduced? Remember, however, that when the intensity is reduced, the energy (quanta) of the photons is not changed; only the rate at which they are emitted from the source. Thus when the source of light is dim, we may not see each electron trajectory and must now record the events into three categories: those electrons that passed through slit one, those that passed through slit two, and those that were not seen, but were registered at the detector. The probabilities of these events are P'_1 , P'_2 , and P_{12} , respectively. Those electrons that are not seen cause interference, which is understandable because when we do not see the electron, it means there were no photons to disturb its trajectory (to change the direction and speed of motion), and when we do see it, there is a photon disturbing it (changing the direction and the speed of motion). We now come naturally to the last question: is there any way we can see the electrons without disturbing them?

The momentum carried by a photon is $p = h / \lambda$, implying that in order to disturb electrons only slightly, not the intensity, but the frequency of the light source should be changed. Using a light of lower frequency (for example red light), *i.e.* longer waves, the interference pattern at the screen will be restored. If the interference pattern is restored, however, we are no longer able to see where the electron hits the screen. The conclusion from this experiment is that it is impossible to design an apparatus such that it can be used to distinguish which slit the electron passed through without disturbing the electrons enough to destroy the interference pattern. This introduces the basic characteristic of subatomic wave-particle duality, known as the *uncertainty* in measuring more than one of the particle's parameters.

In the above experiment there was a reason why we have chosen a light source (photons) to monitor the trajectories of the electrons. In the macro world the objects we are able to see is due to the reflection of light from those objects. For example, a lamp in the night emits photons that travel through space and interact with the surrounding objects. The reflected photons travel back toward our eyes where we detect the image. Therefore, the interaction of the photons with the objects around us is the core of the process; if an object can be observed, it must have undergone interactions with light (photons). In the macro world, where Newtonian physics applies, the interactions of photons with measured objects are ignored since such interactions will not affect the motion of macro objects (a table in a room will not move when the light is turned on). Thus in the macro world the act of measurement does not affect the object being measured. From the double-slit experiment, however, we have seen that the motion of subatomic particles is affected by observation and measurement. The very important conclusion is that every measurement taken on a quantum scale has an effect on the system.

Werner Heisenberg, after earning his Doctoral degree in Munich, Germany, worked with Bohr and Born in the emerging field of quantum mechanics. He developed the *Heisenberg uncertainty principle* as an explanation for the uncertainty in measuring parameters of the subatomic particles. The principle states

(uncertainty in position) **x** (uncertainty in velocity) > h/m

or

$$\Delta x \times \Delta v \ge \frac{\hbar}{2m} \tag{3-87}$$

where m is the mass of the particle and h is Planck's constant. The uncertainty in position, Δx , represents the error made in measuring the position of the particle, and the uncertainty in velocity, Δv , refers to the error made in measuring the velocity of the particle. Thus, if we choose to measure the position of the particle we will introduce an uncertainty in the velocity and vice versa. That is why the product of these two measured values is not equal to zero. In other words, as the uncertainty in one variable becomes smaller and smaller, the uncertainty in the other becomes larger and larger in order to maintain a constant product. At the conceptual limit, if we could know the exact location of a particle in the subatomic realm, we would not know anything about its velocity; or, if we knew the exact speed of the particle, we would not be able to know where the particle is. The uncertainty principle applies not only to position and velocity, but to all parameters of a subatomic particle. For example, if we want to measure the energy of a quantum system we will need a certain amount of time. Δt , to take the measurement. During this time the energy of the system may change, ΔE , without our knowledge. The uncertainty principle describing the relation between the energy of a quantum system and the time needed to measure it is given by

$$\Delta E \times \Delta t \ge \frac{\hbar}{2} \tag{3-88}$$

The principle states that if a particle has a definite energy ($\Delta E = 0$), then Δt must be infinite. In other words, a particle with definite energy is localized in the same region for all time. Such states are called the stationary states corresponding to Bohr's stationary orbits as discussed in Chapter 2. If a particle does not remain in the same state forever, Δt is finite and therefore ΔE is not zero and the energy of the particle must be uncertain. An example of this condition is an unstable atom or nucleus. As mentioned previously, an unstable atom or nucleus will eventually rearrange in order to reach a stable condition, thus Δt is finite and the energy of an unstable atom or nucleus has a minimum uncertainty given as

$$\Delta E \approx \frac{\hbar}{2\Delta t} \tag{3-89}$$

Finally, the uncertainty principle can be expressed in terms of particle momentum, p, and particle position, knowing that p = mv

$$\Delta x \times \Delta p \ge \frac{\hbar}{2} \tag{3-90}$$

Example 3.16 Uncertainty in the position and energy of an electron confined in a nucleus and an atom

If the size of an atom is 10^{-10} m, and the size of a nucleus is 10,000 times smaller, calculate the momentum and energy of an electron confined in an atom and in a nucleus. Compare these to the binding energy of an electron in a hydrogen atom.

For an electron confined in the nucleus

$$r_{nucleus} = 1 \times 10^{-14} \, m \therefore \Delta x = 1 \times 10^{-14} \, m$$
$$\Delta x \Delta p \ge \frac{\hbar}{2} \implies \Delta p = \frac{\hbar}{2\Delta x} = \frac{6.626 \times 10^{-34} \, Js/2\pi}{2 \times 10^{-14} \, m} = 5.27 \times 10^{-21} \, kgm/s$$
$$E = \frac{(\Delta p)^2}{2m} = \frac{(5.27 \times 10^{-21} \, kgm/s)^2}{2(9.1 \times 10^{-31} \, kg)} = 1.53 \times 10^{-11} \, J \times \frac{1eV}{1.6 \times 10^{-19} \, J} = 9.55 \times 10^7 \, eV$$

The energy of an electron localized in a volume comparable to that of a nucleus is very large when compared to the binding energy of the electron in a hydrogen atom (see Chapter 2).

This implies clearly that an electron can not be localized to such a small volume in the atom.

For an electron confined in an atom

$$r_{atom} = 1 \times 10^{-10} \, m \therefore \Delta x = 1 \times 10^{-10} \, m$$
$$\Delta x \Delta p \ge \frac{\hbar}{2} \implies \Delta p = \frac{\hbar}{2\Delta x} = \frac{6.626 \times 10^{-34} \, Js/2\pi}{2 \times 10^{-10} \, m} = 5.27 \times 10^{-25} \, kgm/s$$
$$E = \frac{(\Delta p)^2}{2m} = \frac{(5.27 \times 10^{-25} \, kgm/s)^2}{2(9.1 \times 10^{-31} \, kg)} = 1.53 \times 10^{-19} \, J \times \frac{1eV}{1.6 \times 10^{-19} \, J} = 0.95 eV$$

The energy of an electron localized in a volume comparable to that of an atom is comparable to the binding energy of the electron in a hydrogen atom.

6. SCHRÖDINGER EQUATION

6.1 Interpretation of Quantum Mechanics

A quantum system is divided into two parts: (a) the observed system, and (b) the observing system. For example, the observed system in the double-slit experiment is a photon. The observing system represents the environment that surrounds the observed system including the experimenter (observer). The observed system travels according to a physical law called the Schrödinger wave function. This wave function refers to probabilities, e.g. the probability of finding a subatomic particle in one location rather than another (see Fig. 3-20). In the macroscopic world it is intuitive that every event exists in three dimensions and in time. For example, a wave function associated with two particles will be written in six spatial dimensions (three for each particle). If the wave function represents the probability associated with 20 particles, it will exist in 60 spatial dimensions. Thus when an experiment with subatomic particles is carried out their multi-dimensional reality is reduced to three dimensions in order to be compatible with our macroscopic world. The wave-particle duality that employs the concept that an entity simultaneously possesses localized (particle) and distributed (wave) properties has been introduced in order to account for observations in experiments with subatomic particles. The dominant view of this approach is that quantum probabilities become determinate by the act of measurement. Thus it is said that the wave function is collapsed when an observer looks at the system. In the double-slit experiment, according to classical physics, a photon emitted from the light source travels from the source to the slit, passes through the slit, and travels to the screen where it is detected. Thus its location at the screen can be determined. However, according to quantum mechanics, there is no real particle that travels between the source and the screen. There is only a wave function and the probability that the photon will pass though one slit or the other. The photon is detected only when the observer looks at the screen. In other words, the quantum reality is not described until an act of measurement takes place, at which point the wave function collapses to a single possibility.

In the autumn of 1927, the 5th Solvay Conference was held in Brussels, Belgium. The conclusion of this meeting became known as the Copenhagen interpretation of quantum mechanics. During this Conference Bohr and Einstein conducted their famous debate:

"I shall never believe that God plays dice with the world!" questioning the probabilistic nature of quantum theory. And Bohr's answer: "Einstein, stop telling God what to do!" The Copenhagen interpretation of quantum mechanics, for the first time, acknowledged that a complete understanding of reality lies beyond the capability of a rational thought.

In 1957 Hugh Everett, John Wheeler and Neill Graham proposed another explanation of the quantum wave functions called the many worlds interpretation of quantum mechanics. According to this theory the wave function is real, and all possibilities that it predicts are real. This theory can also be demonstrated by analyzing the double-slit experiment. Suppose that when a photon goes through slit one, you run up the stairs. When a photon goes through slit two you run down the stairs. According to the Copenhagen interpretation of quantum mechanics, these two possibilities are mutually exclusive because it is not possible for you to run up and down the stairs at the same time. However, according to the many worlds interpretation of quantum mechanics, at the moment the wave function "collapses" the universe splits into these two worlds. In one of them you run upstairs, and in another one you run downstairs. There are two editions of you doing different things at the same time; but each of these two editions is unaware of the existence of the other. These two editions of you will never meet, as these worlds remain forever separated branches of reality.

6.2 Standing Waves

De Broglie's hypothesis (Section 5.1) that each material object has a wave property opened new developments in quantum mechanics. It immediately pointed to a much more natural way of understanding atomic phenomena than Bohr's model of the atom. Bohr's model of hard, spherical electrons that orbit the nucleus at specific distances and specific energy levels, emitting photons by jumping between the orbits, explained the spectrum of simple atoms. However, it did not explain *why* each shell contains a certain number of electrons or *how* electrons move between shells. Austrian physicist Erwin Schrödinger postulated that electrons are not spherical objects, but rather *patterns of standing waves*.

The standing wave can be explained in analogy with a rope tied to one pole at one end and then flicked sharply upward and downward from the other end, forming a hump, or a wave, that appears to travel between the two ends. By sending a series of waves down the rope, a pattern of standing waves as shown in Fig.3-24 is generated. The simplest pattern is that of a single standing wave, shown in Fig. 3-24 with n = 1. This pattern is formed by the superposition of two waves travelling in opposite directions. In reality, it is not the rope that is moving, but the *pattern*; these stationary patterns are called standing waves. Regardless of the length of the rope, the rope will always show a pattern of a whole number of standing waves (*i.e.* one wave, two waves, three waves, etc.) that must divide the rope evenly into whole sections. The number of wavelengths or half–wavelengths that will fit on the rope is determined by its length. The first three possible standing waves are shown in Fig.3-24. The lowest frequency is called the fundamental frequency or the first harmonic, and the higher frequencies are called overtones. Integer multiples of the fundamental frequency (the 1st harmonic) are labelled as the 2nd harmonic, 3rd harmonic, etc.



Figure 3-24. Standing waves and electron's orbits around the nucleus

In 1925 Schrödinger proposed that standing waves of subatomic particles are "quantized", similar to the waves in the rope. For example, an electron orbiting a nucleus must travel a certain distance around the nucleus, which can be thought of as the length of the rope; therefore, only a whole number of standing waves, never a fraction of one, can form the length of orbiting electrons. Schrödinger developed the complex equation (now called the Schrödinger equation) to describe the quantum wave function of subatomic particles. The equation can be solved exactly only for the simplest structure, the one–proton and one–electron structure of atomic hydrogen. The reason that the Schrödinger equation cannot be solved exactly for an atom which contains more than one electron is a mathematical problem that also appears in other areas such as astronomy: there is no exact solution to the equations describing the motion of more than two mutually interacting bodies. No exact solution of the Schrödinger equation is possible for any of the atoms heavier than hydrogen, but methods of successive approximations can be used to obtain solutions. The solution of the Schrödinger equation gives the energies an electron should have in an atom. Since light is emitted or absorbed by an atom when an electron moves from one permitted location to another, knowledge of the energies of the various levels available to an electron also gives the emission and absorption spectra of the atom.

The electrons are confined to the space surrounding the nucleus in similar to the way in which the waves of a guitar string are controlled within the string. The tautness of the string forces it to vibrate with specific frequencies, as an electron can only vibrate with specific frequencies (see Chapter 2). In the case of an electron, these frequencies are called *eigenfrequencies* and the states associated with these frequencies are called *eigenstates* or *eigenfunctions*. The set of all eigenfunctions for an electron form a mathematical set called the *spherical harmonics*. There is an infinite number of spherical harmonics, with no in-between states. Thus an atomic electron can only absorb and emit energy in specific quanta. It does this by making a quantum leap from one eigenstate to another. This term has been introduced in Chapter 2.

Shortly before Schrödinger's discovery, another Austrian physicist, Wolfgang Pauli, discovered that no two electrons in an atom can be exactly the same (as described in Chapters 2 and 3). In terms of Schrödinger's standing wave theory, Pauli's Exclusion Principle means that once a particular wave pattern forms in an atom, it excludes all others of its kind. Schrödinger's equation shows that there are only two possible wave patterns in the lowest orbit of Bohr's atomic model and therefore there can be only two electrons existing in that orbit. There are eight different standing wave patterns possible in the next energy level; therefore there can be only eight electrons, and so on. Although Schrödinger was sure that electrons were standing waves, he was not sure *what was waving*. He was however convinced that something was waving and that he called "*psi*" (Ψ), a *quantum wave function*.

6.3 General Characteristics of the Quantum Wave Function

Each particle is represented by a wave function, $\Psi(x,t)$, which is obtained by solving the Schrödinger equation

$$i\hbar \frac{\partial \Psi(x,t)}{\partial t} = -\frac{\hbar^2}{2m} \frac{\partial^2 \Psi(x,t)}{\partial x^2} + U(x,t)\Psi(x,t)$$
(3-91)

where *i* is the square root of negative 1, \hbar is Plank's constant divided by

 2π , and U(x,t) is the potential energy field. This equation plays the role of Newton's law of conservation of energy in classical mechanics. The equation predicts the probability of future behaviour of dynamic quantum subatomic systems; given a large number of events, it predicts the distribution of probabilities. Specifically, the square of the wave function represents the probability amplitude for finding a particle at a given point in space at a given time. In order to represent a physically observable system the wave function must satisfy the following constraints: must be a solution to the Schrödinger equation, must be normalized implying that the total probability over all x is unity, must be a continuous function of x and must have a continuous slope. Basic steps in developing the fundamental quantum mechanics equation are as follows:

1. Conservation of energy:

$$E = T + U \tag{3-92}$$

where E is the total energy, $T(mv^2/2 = p^2/2m)$ is the kinetic energy and U is the potential energy of a particle with mass m.

2. De Broglie hypothesis: for a free particle with momentum p, the wavelength, λ , is equal to h/p. If we write: $k = 2\pi \lambda$, where k is called a wave number, then it follows

$$p = \frac{h}{\lambda} = \frac{hk}{2\pi} \tag{3-93}$$

Combining Eqs. (3-92) and (3-93), the kinetic energy of a free particle to which a de Broglie wave is associated can then be written as

$$T = \frac{mv^2}{2} = \frac{p^2}{2m} = \frac{h^2k^2}{4\pi^2 2m}$$
(3-94)

which bears a clear resemblance to the kinetic energy term (first term) of the Schrödinger equation.

- 3. *Continuous solution*: a solution concerning the location or state of motion of a particle should not show discontinuity (the particle can not appear and disappear at different locations in a system).
- 4. *Single-valued solution*: a solution should give only one probability for the particle to be in a specific location at a specific time.

5. *Linear solution*: solution must be linear in order to assure that de Broglie waves will have the superposition property expected for waves.

The following sections will explore the time-independent Schrödinger equation where the time-dependant solution is assumed to be separable in the following form

$$\Psi(x,t) = \psi(x)f(t) \tag{3-95}$$

The partial derivatives in the Schrödinger equation may now be transformed into two absolute derivatives under the assumption that the potential field is not a function of time

$$i\hbar \frac{1}{f(t)} \frac{df(t)}{dt} = E$$

$$-\frac{\hbar^2}{2m} \frac{\partial^2 \psi(x)}{\partial x^2} + U(x)\psi(x) = E\psi(x)$$
(3-96)

In this technique, a separation constant, E is introduced representing the particle energy state. The time-dependant portion is easy to solve and has the following general solution

$$f(t) = Ce^{\frac{iEt}{\hbar}}$$
(3-97)

The remaining time-independent portion will now be analyzed for some specific potential energy distributions.

6.4 Wave Function for a Particle in an Infinite Well

Perhaps the simplest case to analyze is that of a single particle in an infinite well, namely

$$U(x) = \begin{cases} 0, & \text{for } 0 \le x \le a, \\ \infty, & \text{otherwise} \end{cases}$$
(3-98)

An illustration of this distribution is shown in Fig. 3-25.

For this case, the wave function takes a zero value *outside* of the well because the infinitely high walls confine the particle within. Therefore, inside the well, the time-independent Schrödinger equation reduces to

$$-\frac{\hbar^2}{2m}\frac{d^2\psi(x)}{dx^2} = E\psi(x),$$
(3-99)

or, equivalently

$$\frac{d^2\psi(x)}{dx^2} = -k^2\psi(x), \text{ where } k \equiv \frac{\sqrt{2mE}}{\hbar}.$$
(3-100)



Figure 3-25. Infinite square well potential distribution

In this form, it is clear that the general solution is the same as that for the classical simple harmonic oscillator

$$\psi(x) = A\sin(kx) + B\cos(kx) \text{ for } 0 \le x \le a, \qquad (3-101)$$

where A and B are constants to be determined using boundary conditions for wave function continuity at the boundaries

$$\psi(0) = \psi(a) = 0. \tag{3-102}$$

Imposing the first boundary condition implies that B must be zero and the solution reduces to

$$\psi(x) = A\sin(kx). \tag{3-103}$$

Imposing the second boundary condition implies that the argument of the sine function must be zero. Sine is a periodic function which takes a zero value when evaluated at integers multiples of π , therefore

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$$ka = \frac{\sqrt{2mE}}{\hbar} = n\pi$$
, where $n = 1, 2, 3,$ (3-104)

This gives a result for energy which can take only discrete values unlike the classical case where energy is continuous

$$E_n = \frac{n^2 \pi^2 \hbar^2}{2ma^2}$$
(3-105)

The full solution for this case is the product of the time--dependant and time-independent components

$$\Psi(x,t) = \Psi(x)f(t) = A\sin\left(\frac{n\pi x}{a}\right)e^{\frac{iEt}{\hbar}},$$
(3-106)

where the two constants have been combined into a single constant, A.

Now, to determine the constant A, we must normalize the integral of the square of the wave function to one as explained in Section 6.3.

$$\int ||\Psi(x,t)|^2 \, dx dt = \int \Psi(x,t) \Psi^*(x,t) \, dx dt = 1, \tag{3-107}$$

where Ψ^* is the complex conjugate of the wave function. Expanding the conjugate product reveals that the time-dependant terms cancel each other leaving only a simple integral with respect to x. Evaluating this integral gives $A^2 = 2/a$, and the full solution is, therefore

$$\Psi(x,t) = \sqrt{\frac{2}{a}} \sin\left(\frac{n\pi x}{a}\right) e^{-i\left(\frac{n^2\pi^2\hbar}{2ma^2}\right)t} \quad \text{for } 0 \le x \le a.$$
(3-108)

This wave function may now be used to determine the probability that the particle will be located at any position x and time t within the infinite well.

6.5 A Wave Function for a Free Non – Relativistic Particle

In this case, the particle is assumed to be totally free, namely U(x) = 0 for all x. Upon insertion of this potential distribution, the time-independent Schrödinger equation takes the same form as inside the infinite square well

and has a solution in the following form

$$\psi(x) = A\sin(kx) + B\cos(kx). \tag{3-109}$$

At this point in solving the infinite well problem, we applied the appropriate boundary condition which determined the allowed values for k and therefore, E. However, in this case there are no such boundary conditions to restrict the value of the k because the particle is totally free. However, upon closer inspection of the definition of k, the allowed energies may be found to be

$$E = \frac{\hbar^2 k^2}{2m},\tag{3-110}$$

which is precisely the same as the energy predicted by the De Broglie hypothesis for a free particle. One important thing to note is that due to the lack of a restriction on k, the energy values are not quantized, meaning that a free particle can possess any energy value.

Another interesting note about this solution, is that it is not normalizable, namely the integral of $|\Psi(x,t)|^2$ is infinite. Thus, the wave function can never be normalized and the wave function obtained here may not be used to predict probabilities.

6.6 Hydrogenic Wave Functions

As mentioned before, the Schrödinger equation is analytically solvable only for the simplest case of the hydrogen atom consisting of a single proton and a single electron. In this case, the only relevant force is the attractive force between these two particles. However, when more particles are introduced into the system, like for instance a helium atom, the problem becomes increasingly more difficult. There are now additional force terms representing the repulsion of like particles as well as additional attractive terms for the newly introduced particles. You can imagine that if one were to try and solve this problem for a high–Z atom such as uranium how complex the system would be.

There are however some special cases other than hydrogen where a solution may be obtained. These are known as hydrogenic atoms, literally meaning atoms which are *like* hydrogen. The simplest example is that of a singly ionized helium atom. In this case, the nucleus contains two protons as compared to the one in hydrogen and there in only one orbital electron. The actual solution of such cases is outside the realm of this text, however a list of recommended literature is provided if a more in–depth study if desired.

NUMERICAL EXAMPLE

Wave Function States in Infinite Square Well

As described in Section 6.4, the wave function of a particle in an infinite square well is represented by Eq. (3-108). At time = 0, plot the first three probability distribution functions for an electron trapped in an infinite well of width equal to twice the Bohr radius ($r_0 = 0.0529$ nm). Also, compute the energy of these three states.



Figure 3-26. Probability distributions for first three states on an electron trapped in an infinite well of width twice the Bohr radius.

Solution in MATLAB:

clear all a = 2*(0.529*10^-10); % m m = 9.109*10^-31; % kg hbar = 6.626*10^-34 / (2*pi); % J*sec

```
 \begin{aligned} x &= \text{linspace}(0,a); \\ \text{for } n &= 1:3 \\ & E(n) &= (n^2 * pi^2 * hbar^2 / (2 * m * a^2)) / (1.602 * 10^{-19}); \enskiplikelihow events \\ \text{for } i &= 1:100 \\ & phi(n,i) &= (\text{sqrt}(pi/a) * \sin(n * pi * x(i)/a))^2; \\ & \text{end} \\ & \text{subplot}(3,1,4\text{-}n) \\ & plot(x/a, phi(n,:), k') \\ & xlabel('Distance Normalized to a)') \\ & ylabel('Probability Density') \\ & \text{end} \\ & \text{disp}(E) \end{aligned}
```

PROBLEMS

3.1. If the radius of a nucleus is given by Eq. (3-41), calculate the density of nuclear matter in g/cm^3 and in nucleons/ fm^3 . Assume the mass of a nucleon is $1.67 \times 10^{-24} g$.

3.2. Use the Eq. (3-41) to calculate the radius of ${}^{3}H$, ${}^{60}Co$ and ${}^{239}Pu$.

3.3. Show by expanding $[1 - (\nu/c)^2]^{1/2}$ in powers of $(\nu/c)^2$ that the kinetic energy can be written as:

 $T = \frac{1}{2}m_0v^2 + \frac{3}{8}m_0\frac{v^4}{c^2} + \dots$

Does non-relativistic formula $m_0 v^2/2$ overestimate or underestimate the kinetic energy of particle with the rest mass m_0 and speed v?

3.4. An electron and proton are each accelerated from rest by a total potential of 500 million volts (500 *MeV*). Calculate the increase in mass and fractional increase in mass of each of these particles as well as their final speeds.

3.5. Calculate the total binding energy and the binding energy per nucleon for ${}^{32}P_{17}$ (atomic mass = 31.975697 *amu*).

3.6. Calculate how much energy would be absorbed or released if two atoms of ¹²C were fused together to create one atom of ²⁴Mg₁₂ (A = 23.985042 amu).

3.7. Calculate the amount of energy needed to dissociate one atom of ¹²C into three atoms of ⁴He (atomic mass = 4.002603 amu).

3.8. Calculate the magnitude of the Coulomb and gravitational potential energy between adjacent protons using the radius of a nucleus as the separation distance. Compare these two energies with the binding energy per nucleon of ${}^{32}P_{17}$. Use the Eq. (3-41) to calculate the radius of a nucleus.

3.9. How much energy is required to remove a proton from ${}^{40}Ca_{20}$ (atomic mass = 39.962589 *amu*)?

3.10. Find the energy released in the reaction: ${}^{238}_{92} U \rightarrow {}^{234}_{90} Th + {}^{4}_{2} He$. M(${}^{238}_{92}U$) = 238.050786 *amu*, M(${}^{234}_{90}Th$) = 234.043583 *amu*, M(${}^{4}_{2}He$) = 4.002603 *amu*.

3.11. The radius of a heavy nucleus is ~ 10^{-12} cm. When the velocity of neutron becomes large enough that $\lambda/2\pi$ is of the same order of magnitude as the nuclear radius, the neutron can be diffracted about the nucleus what is known as *shadow* scattering. Show that at neutron energy of ~0.21 *MeV* this effect becomes important [$h = 6.62 \times 10^{-27}$ erg-sec; neutron mass = 1.675×10^{-24} g].

3.12. Show that on average 200 MeV is released when one atom of ²³⁵U fissions by capture of a thermal neutron? In fission usually two fission fragments are released. Use Fig.3-3 to estimate the average binding energy of fission fragments. What is the binding energy of a captured neutron?

3.13. Calculate the wavelength of a proton needed to excite an electron in Li^{2+} from the state n = 2 to the state n = 5.

3.14. Calculate the minimum de Broglie frequency of the neutron that is capable of exiting an electron in He⁺ from the ground state to the state n = 3. What is the wavelength of the X ray emitted when electron falls back to its ground state?

3.15. Starting from the Bohr's atomic model show that the energy (kinetic plus potential) corresponding to the circular orbit of the mass *m* in a three-dimensional harmonic oscillator potential is $n\hbar\sqrt{k/m}$.

3.16. Calculate the de Broglie wavelength of the electron and proton with the kinetic energy of 50 MeV.

3.17. Show that the minimum mass using the semi-empirical formula (3-75) is obtained for

$$Z(\min \ mass) = \frac{A}{2 + 0.015A^{2/3}}$$

3.18. Using the solution of the Eq. (3-75) for minimum mass show that for light stable nuclei $Z \sim A/2$ and give few examples. Also, show that for stable heavy nuclei $Z \sim A^{1/3}/0.015$.

3.19. The two red stars are observed to be part of a binary star system. What can be concluded about their temperatures?

3.20. What is the ratio of temperatures of two starts which spectral peaks are observed at 3,500 A and at 7,000 A.

3.21. It takes about 1 *Mev* of energy to produce a positron and an electron. Use the uncertainty principle to estimate for how long can this energy exist before the positron and electron annihilate each other?

3.22. For a particle that lives for 6×10^{-22} s what will be a mass-energy uncertainty?

3.23. A 1, 5 and 15 kg mass attached to a spring with the constant k = 400 N/m is undergoing simple harmonic motion on a frictionless surface with an amplitude of A = 10 cm. Assuming that the energy levels are quantized according to the Planck's relation E = nhf, calculate the corresponding quantum number *n* for all of three masses? Comment on the results calculating the energy difference between the states *n* and *n*+1. [The total energy associated with the system of mass *m* is $kA^2/2$].

3.24. Suppose light of wavelength $\lambda = 8 \times 10^{-7} m$ is used to determine the position of an electron. What is the minimum uncertainty in electron's speed?

3.25. Following the numerical example shown above calculate and plot the first three probability distribution functions for an electron trapped in an infinite well of width equal to the Bohr radius (a = 0.0529nm). Compare the results when the width is increased to two and three Bohr radii.

3.26. For the free particle in the box with infinite walls, the probability for finding it inside the box is equal to one. Write the condition for normalization for the time-independent wave function and solve it for the one-dimensional wave function. [Since the probability must be one for finding the particle somewhere, the wave function must be normalized]. You should obtain the equation as (3-108) but without the time dependent term.

3.27. Treating the system as a photon–like entity the time–dependent wave equation is written in the form

$$\frac{\partial^2 E}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 E}{\partial t^2}$$

Assuming the solution to be:

 $E(x,t) = E_0 \cos(kx - \omega t)$ show that the energy of a photon is E = pc.

3.28. The Schrödinger time-dependent one dimensional equation for an electron can be written in the following form

$$-\frac{\hbar^2}{2m}\frac{\partial^2\Psi(x,t)}{\partial x^2} + U(x,t)\Psi(x,t) = i\hbar\frac{\partial\Psi(x,t)}{\partial t}$$

Assuming the potential energy to be constant $(U = U_0)$ and that the solution of the above wave equation can be expressed as

$$\Psi(x,t) = Ae^{i(kx-\omega t)} = A[\cos(kx-\omega t) + i\sin(kx-\omega t)]$$

show that the total energy of the electron is a summation of potential and kinetic energy

$$\hbar\omega = U_0 + \frac{\hbar^2 k^2}{2m}$$

3.29. Based on the wave particle duality in one dimension (the de Broglie's relation between wavelength and momentum and the Planck's relation between frequency and energy) show that the Schrödinger equation for free particle (like electron for example)

$$-\frac{\hbar^2}{2m}\frac{\partial^2\Psi(x,t)}{\partial x^2} = i\hbar\frac{\partial\Psi(x,t)}{\partial t} \qquad \text{has the following solution}$$

$$\Psi(x,t) = Ae^{i(kx-\omega t)} = Ae^{i(\frac{2\pi}{\lambda}-\omega t)}.$$

3.30. A particle of energy *E* that is smaller than the height of barrier (potential energy U_0) according to classical mechanics is forbidden to penetrate inside the region (see figure below). The wave function associated with the free particle must be continuous and thus there is a finite probability that the particle will

tunnel through the barrier. For a particle approaching the barrier, a wave function for free particle can be used. However when a particle reaches the barrier, it must satisfy the Schrödinger equation in the form

$$-\frac{\hbar^2}{2m}\frac{\partial^2 \Psi(x)}{\partial x^2} = (E - U_0)\Psi(x) \qquad \text{which has a solution}$$

$$\Psi(x) = Ae^{-\alpha x} \quad \alpha = \sqrt{\frac{2m(U_0 - E)}{\hbar^2}}.$$

Calculate the tunneling probability for the α particle described in Example 4.6 (Chapter 4).



3.31. Shells and orbits of the electron in Bohr's atomic model are quantized and so are the lengths of the waves of de Broglie's electrons in each shell. As the electron moves further away from the nucleus, the wavelength becomes longer (because electron's velocity is reduced when the radius of shell is increased). Capture this dependence by plotting the bar–like diagram showing on the one the velocity and on the other the wavelength.

3.32. The resolving power of an electron microscope is assumed to be equal to the wavelength of the used light. Calculate the required kinetic energy of electrons in order to be able to "see" an atom. The required resolving power is 10^{-11} m.

3.33. Find the probability function for the wave described as

$$\Psi(x,t) = \frac{A}{\sqrt{2}} \sqrt{\frac{1}{a+i\gamma t}} e^{i(k_0 x - \omega_0 t)} e^{-(x-\beta t)^2/4(a+i\gamma t)}$$

3.34. Determine the change in wavelength of the 2p-1s photon when a hydrogen atom is placed in a magnetic field of various intensities: 3T, 5T, 10T and 30T. Comment on the results.

3.35. Use Eq. (3-45) to write a computer code to calculate and plot the dependence of a mass of a moving body and its energy.

3.36. Use the Planck's law to write a computer code that will calculate the black body radiation as a function of light frequency.

3.37. Plot the dependence of de Broglie wavelength and the velocity of motion for an electron, proton and a 1000 kg body moving at non-relativistic speeds.

3.38. Calculate the nuclear density of the smallest and the largest nucleus in the periodic system of elements. Comment on the results.

3.39. Calculate the separation energy of last neutron in first ten nuclei in the periodic system of elements. Comment on the result.

3.40. Select an even-*A* nuclei and plot the excitation energy of the first excited state. Compare with the Fig. 3-11 and discuss the differences.

3.41. Plot the Eq. (3-76). What can you conclude from the slope of the plot?

3.42. Compare the size of the nuclei (calculated using the Fermi model) and the size of the corresponding atoms across the periodic system of elements. What is your observation? How would you explain the change in nucleus size analyzing the number of nucleons, nuclear forces, Coulomb forces, and nuclear density?

3.43. Show that when two deuterons react they form tritium with the net gain in binding energy of the system of $4.02 \ MeV$.

3.44. Calculate the binding energy per nucleon of 238 U. What is an approximate gain in the binding energy of the system if 238 U splits into two equal nuclei? What would be the corresponding amount of energy released in this reaction? Compare with the values discussed in Chapters 6 and 7.

NOTE: Some of the problems listed are adopted from the web–site developed by Dr. C. N. Booth, <u>http://www.shef.ac.uk/physics/teaching/phy303/</u>.

Chapter 4

RADIOACTIVE DECAY

Radioactivity, Kinetics of Decay, Examples

"It can be thought that radium could become very dangerous in criminal hands, and here the question can be raised whether mankind benefits from knowing the secrets of Nature, whether it is ready to profit from it or whether this knowledge will not be harmful for it.

The example of the discoveries of Nobel is characteristic, as powerful explosives have enabled man to do wonderful work. They are also a terrible means of destruction in the hands of great criminals who are leading the people towards war. I am one of those who believe with Nobel that mankind will drive more good than harm from new discoveries." *Pierre Curie* (1859 – 1906), 1903 Nobel Prize address.

1. INTRODUCTION

Nuclides exist in two main forms, stable and unstable. A nuclide is considered to be stable if there is no proof of its spontaneous transformation into another nuclide. The probability of transformation is characterized by the half–life, which is defined as the time needed for half of the starting amount of an unstable nuclide to transform. Elements above lead are all unstable and have very long half–lives (order of 10^8 to 10^{10} years) compared to the age of the atom (assumed to be formed some 10 billion years ago).

If, for example, a stable nucleus of ⁵⁹Co with 27 protons and 32 neutrons, receives one neutron (which must possess an energy of 7.5 MeV), the newly formed nucleus ⁶⁰Co is artificial (does not exist in nature), unstable and in an

excited state. The instability is caused by the addition of a new particle (with its associated energy) that requires rearrangements of nucleons inside the nucleus. The process nuclei undergo in order to return to the ground state is called radioactive decay. In the case of ⁶⁰Co the radioactive decay scheme is sketched in Fig. 4-1.



Figure 4-1. Radioactive decay scheme for ⁶⁰Co

None of the artificially created isotopes are stable; all are radioactive and decay with half-lives in the range of microseconds to years. However, based on the quantum mechanics (see Chapter 3) it is expected that it is possible to create isotopes in a new "island" of stability (see Fig. 4-2).

The most stable nuclides are those whose protons and neutrons close the shells (energy levels). These are nuclides with a magic number of protons, neutrons or both.

The next proton magic number is 114 (beyond those already known to exist). The best estimate for the number of neutrons needed to overcome the proton–proton repulsion in such a nucleus is at least 184 neutrons, and perhaps as many as 196. It is not easy to bring together two nuclei that would give both the correct number of protons and the necessary neutrons with a half–life long enough to be detected. Element 114 was experimentally observed in 1998 at Russia's Joint Institute for Nuclear Research in Dubna. Their very complex experiments showed the possibility to create short–lived heavy nuclei around the new "island" of stability. By accelerating atoms of ⁴⁸Ca into a target of ²⁴⁴Pu, atoms of element 114 (with a nuclear weight of 289) were detected through their decay into element 112

 $^{244}_{94}$ Pu + $^{48}_{20}$ Ca $\rightarrow ^{289}_{114}$ Uuq + 3 ¹n 175 neutrons

 $^{244}_{94}$ Pu + $^{48}_{20}$ Ca $\rightarrow ^{288}_{114}$ Uuq + 4 ¹n 174 neutrons

The lifetimes of elements 114 and 112 are 30 sec and 280 msec, respectively.

This chapter focuses on the laws of physics governing the mechanisms, kinetics and types of radioactive decays.



Figure 4-2. The new "island" of stable super-heavy nuclides

2. MECHANISM OF RADIOACTIVE DECAY

Radioactivity is defined as the spontaneous nuclear transformation of an unstable element resulting in the formation of a new one. The process of radioactive decay is statistical and therefore random in its nature. For example, whether a radioactive uranium atom will or will not decay at any given instant is purely a matter of probability. There is no physical difference between uranium atom that is decaying and one that is not decaying.

In 1895 Wilhelm Conrad Roentgen discovered a new phenomenon that he called the X rays. Soon after, Henri Becquerel decided to study the correlation between newly discovered X rays and the fluorescence phenomena of uranium salts. Once exposed to ultraviolet photons (sun light), the uranium salts radiate visible light (the fluorescence phenomenon).

However, due to bad weather in Paris, Becquerel was not able to expose the samples to sun light for a few weeks, during which time he left them in a closet. Later he found that the plates were exposed and concluded that a new type of radiation was emitted from the non-fluorescence uranium and correctly speculated that some materials at rest emitted radiation in a spontaneous fashion without the addition of any external energy. Becquerel called this new radiation "U rays", later renamed radioactivity. Pierre and Marie Curie worked on radioactivity and demonstrated that thorium also exhibited radioactive properties. In July of 1898, they succeeded in isolating a new material, a million times more radioactive than uranium, that Marie Curie called "polonium." From pitchblende ore, they were able to extract by hand a few milligrams of another new material, 2.5 million times more radioactive than uranium, which they called radium. For this discovery, Pierre and Marie Curie received the physics Nobel Prize in 1903. Some years later, Marie, alone since the death of Pierre in 1906, isolated metallic radium with an electrolytic procedure for which she received the Noble prize for Chemistry in 1911. In 1934, Irene and Frederic Joliot-Curie discovered artificial radioactivity, making a great step toward the use and control of radioactivity. For this discovery, they received the Nobel Prize in chemistry in 1935. Neither Marie Curie nor her daughter Irene, both Nobel Prize winners, were members of the French Academy of Science (an oddity probably having more to do with gender than scientific accomplishment).

The spontaneous nuclear transformations are accomplished by the emission of an alpha (α) particle, a beta (β^-) particle or a positron (β^+) as well as by orbital electron capture, neutron emission (n) or proton emission (p). Each of these reactions may or may not be accompanied by gamma radiation (γ). Radioactivity is a nuclear process that originates in the nucleus and is therefore not determined by the chemical or physical states of the atom. As discussed in Chapters 2 and 3, an isotope of a given element is an atom that contains the same number of protons and has the same electronic structure, but differs in the number of neutrons. Most elements have several isotopes; chlorine, for example has two: 75.4% ³⁵Cl and 24.6% ³⁷Cl. A few radioisotopes arise naturally; however, most of them are created artificially. There are more than 2930 known isotopes, but only 65 are naturally occurring and exist either as a product of cosmic radiation in the atmosphere (³H, ⁷Be and ¹⁴C) or are products of radioactive decay of primordial isotopes (⁴⁰K and ²³⁸U).

The exact mode of radioactive decay depends on two factors:

- 1. The particular type of nuclear instability (whether the neutron-to-proton ratio is too high or too low), and
- 2. The mass-energy relationship among the parent nucleus, daughter nucleus and the emitted particle.
Radioactive decay of a nucleus changes the arrangement of its nucleons. This change usually influences the entire atom by affecting the electron cloud. The change can even propagate further and affect the molecule. The decay, however, obeys a series of physical laws of conservation. The conservation laws are a direct consequence of the symmetries in nature that require certain variables to stay unchanged. The following conservation laws must be satisfied for radioactive decay to exist:

- 1. Conservation of mass energy: radioactive decay of a nucleus changes mass into energy. In other words, in the process of radioactive decay the total mass is reduced but the energy is increased. The difference in masses before and after the decay is emitted as energy of the emitted particles in the decay. It can be shown that conservation of mass and energy holds for the radioactive decay as a consequence of symmetry in time. Every experiment will give the same decay results for the same nucleus no matter when it was performed.
- 2. *Conservation of momentum*: the sum of the momentum before and after the decay must be the same. This law is a direct consequence of the symmetry in space. Namely, all points in Euclidian space are equivalent and thus the physical laws are the same for all points in space.
- 3. *Conservation of angular momentum*: the sum of angular momentum and spins must remain the same before and after the decay. Angular momentum describes the degree of rotation of a system. Since in space all directions are equally probable, the physical laws are independent of orientation of motion of a system in space.
- 4. *Conservation of charge*: the sum of charges before and after the decay remains the same. The charge can only be redistributed between the particles and can not be lost in the process of radioactive transformations. For example, this law says that an electron can not appear or disappear on its own. In order for an electron to disappear there should exist its counterpart; a positron. Interaction of these two particles will result in the annihilation of both (see Chapter 5). The fact that an electron can not change its appearance without its opposing particle (positron) assures the stability of the electron and thus the stability of matter.
- 5. *Conservation of nucleons*: the total number of nucleons for any decay mode must be conserved. This law forbids neutrons (and protons) confined within a nucleus to decay into other particles and assures the stability of matter.

3. KINETICS OF RADIOACTIVE DECAY

3.1 Decay Constant

Radioactive decay although a random process that occurs at a characteristic rate can be predicted. The length of time, the number of steps required completing the transformation, and the kinds of radiation released at each step of the decay are well known.

The *decay constant*, λ , represents the probability that a radionuclide will decay in a unit time. Thus, the probability that a radionuclide will decay in time *dt* is λdt . The characteristics of the decay constant confirmed experimentally are:

- The decay constant is the same for all nuclei of a given atom. It cannot be changed by ambient pressure or temperature.
- The decay constant does not depend on the age of nuclides, *i.e.*, it does not change with time.

3.2 Radioactive Decay

If the probability for a nucleus to decay in time dt is

$$\lambda dt$$
 (4-111)

then from the total number of nuclei N, in time dt, the number of nuclei that will decay, dN, can be calculated as

$$-dN = N\lambda dt \tag{4-112}$$

Since the decay constant is not dependent on time (as explained in Section 3.1), the solution of the above equation is simply

$$N = N_0 e^{-\lambda t} \tag{4-113}$$

where N_0 is the starting number (amount) of nuclei, and N represents the amount of nuclei that did not decay after time t. As Fig. 4-3 shows, the amount of the initial radionuclide decreases exponentially with time.

3.3 Activity

3.3.1 Definition

Activity, A, is the number of nuclei decaying per unit time. If the probability for a nucleus to decay is λ , and there are N nuclei present, the average number of decaying nuclei is $N\lambda$, and is defined as activity

$$A = N\lambda \tag{4-114}$$



Figure 4-3. Radioactive decay

Thus, from Eq. (4-113)

$$A \equiv N\lambda = N_0 \lambda e^{\lambda t} = A_0 e^{-\lambda t} \tag{4-115}$$

Radiation detectors do not usually measure the total activity, that is, the total number of decays per second, but some fraction of this called the *count rate* (see Problems 4.6. - 4.8.). In any given situation, if all else is kept equal, the count rate is proportional to the activity

 $R = kA \quad where \quad k \le 1 \tag{4-116}$

Therefore the decay equation can be expressed in terms of count rate

$$R_1 = R_0 e^{-\lambda t} \tag{4-117}$$

3.3.2 Units

The Becquerel, Bq, is a unit used to measure radioactivity. One Becquerel is, by definition, one nuclear decay or nuclear transformation per second. Often radioactivity is expressed in larger multiples of this unit such as: thousands (kBq), millions (MBq) or even billions (GBq) of Becquerel.

The curie, Ci, is the original unit used to measure radioactivity and is, by definition, 37,000,000,000 transformations in one second. This is roughly the activity (the rate of disintegration) of 1 gram of the radium isotope, 226 Ra (see Problem 4.1). Radioactivity is often expressed in smaller multiples of this unit such as: thousandths (mCi), millionths (μ Ci) or even billionths (nCi) of a curie.

As a result of having one Becquerel being equal to one transformation per second, there are 3.7×10^{10} Bq in one curie.

Example 4.1 Disintegration of ⁶⁰Co

Determine the number of disintegrations released per one curie of ⁶⁰Co (see Fig. 4-1).

From the decay scheme shown in Fig. 4-1, it can be seen that each disintegration of a 60 Co nucleus releases one beta particle and two gamma rays. Therefore, the total number of radiations is: $3 \times 3.7 \times 10^{10} = 11.1 \times 10^{10}$ per second per curie 60 Co.

3.4 Half-Life

The *half–life*, $T_{1/2}$, of a nuclide is the time needed for half of the atoms present to decay. Half–lives can range from less than a millionth of a second to millions of years. After one half–life, the level of radioactivity of a substance is halved; after two half–lives it is reduced to one quarter; after three half–lives to one–eighth, and so on (see Fig. 4-3). The products of radioactive decay are the particles emitted and the remaining nucleus called the daughter of the decaying atom. Radioactive decay proceeds exponentially, as does the growth of the daughter product.

The decay constant and the half-life of a given nuclide are related. The quantitative relationship can be found by setting

$$A = \frac{A_0}{2} \implies \frac{A_0}{2} = A_0 e^{-\lambda t} = A_0 e^{-\lambda T_{1/2}} \implies \frac{1}{2} = e^{-\lambda T_{1/2}} \implies$$

$$T_{1/2} = \frac{\ln(2)}{\lambda} = \frac{0.693}{\lambda}$$
(4-118)

Example 4.2 Activity of radium

Calculate the percent of ²²⁶Ra that will decay during a period of 1000 years if the half-life is 1600 years.

$$A = A_0 e^{-\lambda t} = A_0 e^{-0.693t/T_{1/2}} \implies \frac{A}{A_0} = e^{-0.693 \times 1000/1600} = 0.648 = 64.8\%$$

The percent that decayed away during 1000 years is 100 % - 64.8 % = 35.2 %.

Example 4.3 Estimate of decay constant and half-life for radium

Calculate the decay constant and half-life for 226 Ra if one microgram emits 3.65 x 10⁴ alpha particles per second.

The number of radium atoms per microgram of radium, N, is

$$N = \frac{N_a (\text{atoms/mole}) \times M(g)}{A(g/\text{mole})} =$$

$$\frac{(6.02 \times 10^{23} \text{ atoms/mole}) \times (10^{-6} \text{ g})}{226(g/\text{mole})} = 2.66 \times 10^{15} \text{ atoms}$$

The decay constant is thus obtained from the known number of radium nuclei that decayed and the number of radium nuclei that did not decay per unit time

$$-dN = N\lambda dt \implies \lambda = \frac{-dN/N}{dt} = -\frac{(3.65 \times 10^4 \text{ atoms})/(2.66 \times 10^{15} \text{ atoms})}{1 \text{ sec}} \implies \lambda = 1.37 \times 10^{-11} \text{ sec}^{-1} = 4.26 \times 10^{-4} \text{ yrs}^{-1}$$

This gives the half-life

$$T_{1/2} = \frac{\ln 2}{\lambda} = \frac{\ln 2}{4.26 \times 10^{-4}} = 1627 \,\mathrm{yrs}$$

which is very close when compared with the measured value of 1600 yrs (see Example 4.2).

Example 4.4 Specific activity of a radioactive nuclide

A sample of ^{113}In has a mass of 2 μg and a physical half-life of 1.6582 hours. Calculate:

- a) The number of ¹¹³In atoms present.
- b) The number of ¹¹³In atoms remaining after 4 hours.
- c) The activity of the sample (in Bq and Ci) after 4 hours.
- d) The specific activity of the ¹¹³In sample.
- a) Number of atoms present in the 2 μ g sample is

$$N_0 = \frac{N_a (\text{atoms/mole}) \times M(g)}{A(g/\text{mole})}$$

$$=\frac{(6.02\times10^{23} \text{ atoms/mole})\times(2\times10^{-6} \text{ g})}{113(\text{g/mole})}=1.065\times10^{16} \text{ atoms}$$

b) Number of atoms that remain after 4 hours is

$$N = N_0 e^{-\lambda t} = (1.065 \times 10^{16} \text{ atoms}) e^{-\frac{\ln 2}{1.6582} \times 4} = 2.00 \times 10^{15} \text{ atoms}$$

c) Activity of the sample after 4 hours is

$$A \equiv N\lambda = (2.00 \times 10^{15} \text{ atoms}) \left(\frac{\ln 2}{1.6582h}\right) = 8.36 \times 10^{14} \text{ atoms/h}$$
$$A = (8.36 \times 10^{14} \frac{\text{ atoms}}{\text{ h}}) \left(\frac{\text{ h}}{3600 \text{ sec}}\right) = 2.32 \times 10^{11} \text{ Bq}$$
$$A = (2.32 \times 10^{11} \text{ Bq}) \left(\frac{1}{3.7 \times 10^{10} \text{ Ci}}\right) = 6.3 \text{Ci}$$

d) The ratio of nuclide activity to the total mass of the element present is known as the specific activity of the sample, *SA* (see also Problem 4.9)

$$SA = \frac{A}{M} = \frac{6.3 \text{Ci}}{2 \times 10^{-6} \text{ g}} = 3.15 \times 10^{6} \text{Ci/g}$$

3.5 Radioactive Decay Equilibrium

Most radioactive decay schemes contain more than one member, and it is therefore interesting to analyze the relation between the radioactivities and the number of nuclei that disintegrate per unit time in such a series. For example, the radioactive chain in which the parent, A, decays into a daughter nucleus, B, which is also radioactive is written as:

 $A \rightarrow B \rightarrow C \rightarrow \dots$

The equilibrium of radioactive decay is attained when the ratio between the activities of the successive members in the series remains constant. Considering only the first two members in the above chain, as shown in Fig. 4-4, the rate of change is:

• Rate of change of parent nuclide

$$\frac{dN_p}{dt} = -\lambda_p N_p \tag{4-119}$$

• Rate of change of daughter nuclide (= rate of production – rate of decay)

$$\frac{dN_d}{dt} = \lambda_p N_p - \lambda_d N_d \tag{4-120}$$



Figure 4-4. Two successive members in radioactive chain

Eqs. (4-119) and (4-120) are a system of first-order linear differential equations whose solution is

$$N_d(t) = N_p(0) \frac{\lambda_p}{\lambda_d - \lambda_p} \left(e^{-\lambda_p t} - e^{-\lambda_d t} \right) + N_d(0) e^{-\lambda_d t}$$
(4-121)

According to the relation between the activity and number of atoms that decay, Eq. (4-114), it follows that

$$A_d(t) = A_p(0) \frac{\lambda_d}{\lambda_d - \lambda_p} \left(e^{-\lambda_p t} - e^{-\lambda_d t} \right) + A_d(0) e^{-\lambda_d t}$$
(4-122)

The second term in the above activity equation represents the residual daughter product activity from that present at t = 0. This equation is known as the *Bateman equation*.

The general behaviour of the parent and daughter activities described by this equation is shown in Fig. 4-5. The correct assumption is usually that the initial activity of the daughter nuclide is zero, $N_d(0) = 0$. As expected, the activity and the number of daughter nuclides will start building up with the decay of the parent nuclide. After some time the activity will peak and eventually start to decay.

The time when the daughter nuclide reaches its maximum activity can be estimated as follows



Figure 4-5. General trend of activity change with time according to the Bateman equation

$$\frac{dN_d(t)}{dt} = \frac{d}{dt} \left[N_p(0) \frac{\lambda_p}{\lambda_d - \lambda_p} \left(e^{-\lambda_p t} - e^{-\lambda_d t} \right) \right] = 0$$
(4-123)

....

which gives $\lambda_p e^{-\lambda_p t_{\text{max}}} = \lambda_d e^{-\lambda_d t_{\text{max}}}$. Solving for time (see Fig. 4-5)

$$t_{\max} = \frac{\ln(\lambda_d / \lambda_p)}{\lambda_d - \lambda_p}$$
(4-124)

Thus, the time when the activity of the daughter nuclide reaches its maximum value depends only on the decay constants of the parent and daughter nuclides.

The Bateman equation is usually analyzed for the following cases

1. The daughter nuclide is stable, $\lambda_d = 0$: assuming that N_d (0) = 0, Eq. (4-120) becomes

$$\frac{dN_d}{dt} = \lambda_p N_p = \lambda_p N_p(0) e^{-\lambda_p t} \implies N_d(t) = N_p(0)(1 - e^{-\lambda_p t})$$
(4-125)

The decay of a parent and accumulation of a stable daughter nuclide is shown in Fig. 4-6 for the decay of ⁶⁰Co to stable ⁶⁰Ni (decay scheme of ⁶⁰Co is given in Fig. 4-1).



Figure 4-6. Serial decay of parent to stable daughter (⁶⁰Co to ⁶⁰Ni)

2. The half-life of the parent nuclide is shorter than that of the daughter, $T_{1/2p} < T_{1/2d}$: in this case the daughter nuclide builds up faster than it decays. Essentially all parent nuclei transform into daughter nuclei and the activity of the sample comes from the daughter nuclide only. This condition is called *no equilibrium*. One example is the decay of 210 Bi into 210 Po as shown in Fig. 4-7.

3. The half-life of the parent nuclide is longer than that of the daughter, $T_{1/2p} > T_{1/2d}$: the change (decrease) of the activity of the parent nuclide becomes negligible. This case is called a *transient equilibrium* and is schematically depicted in Fig. 4-8. Examples include ¹³²Te (78 hours) decaying to ¹³²I (2.3 hours) and ¹¹³Sn decaying to ^{113m}In (1.7 hours). However, the best example is the ⁹⁹Mo (65.94 hours) parent - ^{99m}Tc (6.01 hours) daughter relationship. The Bateman equation reduces to the following form

$$\lambda_p < \lambda_d \quad \therefore \quad e^{-\lambda_d t} << e^{-\lambda_p t} \quad \longrightarrow \quad N_d(t) = N_p(0) \frac{\lambda_p}{\lambda_d - \lambda_p} \left(e^{-\lambda_p t} \right) \tag{4-126}$$

The ratio of the rate change of parent to daughter nuclides thus becomes

$$N_{p}(t) = N_{p}(0)e^{-\lambda_{p}t} \longrightarrow \frac{N_{p}(t)}{N_{d}(t)} = \frac{\lambda_{d} - \lambda_{p}}{\lambda_{p}}$$
(4-127)



Figure 4-7. No equilibrium decay of ²¹⁰Bi ($T_{1/2}$ = 5.013 days) to ²¹⁰Po ($T_{1/2}$ = 138.376 days)

4. The half-life of parent nuclide is much longer than that of the daughter, $T_{1/2p} >> T_{1/2d}$: For example, ²²⁶Ra with a half-life of 1600 years decays into ²²⁶Rn, which has a half-life of only 4.8 days. The observation period is therefore very small compared to the 1600-year half-life of ²²⁶Ra. From Eq. (4-127)

$$\frac{N_p(t)}{N_d(t)} = \frac{\lambda_d - \lambda_p}{\lambda_p} \qquad \lambda_p << \lambda_d$$

it follows

$$\frac{N_p(t)}{N_d(t)} = \frac{\lambda_d}{\lambda_p} \quad \to \quad N_p(t)\lambda_p = N_d(t)\lambda_d \quad \to \quad A_p(t) = A_d(t) \tag{4-128}$$

The activity of the parent and daughter are the same and total activity of the sample remains effectively unchanged during the time of observation. This is called a *secular equilibrium* and the example for ²²⁶Ra → ²²⁶Rn is shown in Fig. 4-9 (see also Problem 4.11). The half–life of long–lived nuclides can be estimated knowing that they are in a secular equilibrium. Knowing the atomic composition of a mixture of two radionuclides that are in a secular equilibrium, such as ²²⁶Ra and ²³⁸U in uranium ore, the decay constant or half-life of one nuclide can be determined given the half-life for the other using Eq. (4-128).



Figure 4-8. Transient equilibrium decay when $T_{1/2p} > T_{1/2d}$



Figure 4-9. Secular equilibrium decay: buildup of daughter activity when $T_{1/2p} >> T_{1/2d}$

Example 4.5 99 Mo (65.94 hours) parent – 99m Tc (6.01 hours) daughter relationship

Sketch a diagram of the activity change in time for the transient equilibrium of these two nuclides and find the time at which the daughter reaches a maximum activity. From the decay of ⁹⁹Mo it is known that 87% decays into ^{99m}Tc. Assume that the activity of the parent nuclide at t = 0 is 1 Ci.



Figure 4-10. Activity change for ⁹⁹Mo and ^{99m}Tc

Starting from the Bateman equation and assuming that the activity of the daughter nuclide at t = 0 was zero,

$$A_{d}(t) = A_{p}(0) \frac{\lambda_{d}}{\lambda_{d} - \lambda_{p}} \left(e^{-\lambda_{p}t} - e^{-\lambda_{d}t} \right)$$

and rearranging it into the form of the ratio of the activities

$$\frac{A_{d}(t)}{A_{p}(t)} = \frac{A_{p}(0)\frac{\lambda_{d}}{\lambda_{d}-\lambda_{p}}\left(e^{-\lambda_{p}t} - e^{-\lambda_{d}t}\right)}{A_{p}(0)e^{-\lambda_{p}t}} \quad \rightarrow \quad \frac{A_{d}(t)}{A_{p}(t)} = \frac{\lambda_{d}}{\lambda_{d}-\lambda_{p}}\left(1 - e^{-(\lambda_{d}-\lambda_{p})t}\right)$$

it follows

$$\lambda_p = \frac{\ln 2}{65.94 \text{h}} = 0.01051 \text{h}^{-1}$$
 $\lambda_d = \frac{\ln 2}{6.01 \text{h}} = 0.11531 \text{h}^{-1}$

$$\begin{split} A_d(t) &= 0.87 \times A_p(t) \frac{0.11531}{0.11531 - 0.01051} \left(1 - e^{-0.1048t} \right) \\ &= 0.957A_p(t) \left(1 - e^{-0.1048t} \right) \\ &= 0.957A_p(0) e^{-0.01051t} \left(1 - e^{-0.1048t} \right) \end{split}$$

The time when the daughter reaches its maximum activity is obtained by differentiating the above equation (Fig. 4-10)

$$\frac{dA_d(t)}{dt} = 0 \quad \Rightarrow \quad t_{\text{max}} = 22.8\text{h} \quad A_d(22.8\text{h}) = 0.684\text{Ci}$$

3.6 Production of Radioisotopes

The activity of isotopes irradiated in nuclear reactors or accelerators changes according to secular equilibrium of radioactive decay. If a nuclear reaction produces an isotope with concentration N_2 from N_1 atoms at a rate $R = \lambda_1 N_1(0)$, then assuming the activity of the isotope that is produced by this reaction at t = 0 is zero

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$$N_{2}(t) = N_{1}(0) \frac{\lambda_{1}}{\lambda_{2} - \lambda_{1}} \left(e^{-\lambda_{1}t} - e^{-\lambda_{2}t} \right)$$
(4-129)

The production of radioisotopes is constant (similar to secular equilibrium in which the half-life of a parent is much longer than the halflife of daughter)

$$\lambda_{1} \ll \lambda_{2} \implies N_{2}(t) \cong N_{1}(0) \frac{\lambda_{1}}{\lambda_{2}} \left(e^{-\lambda_{1}t} - e^{-\lambda_{2}t} \right) \implies$$

$$A_{2}(t) \cong R \left(e^{-\lambda_{1}t} - e^{-\lambda_{2}t} \right) \qquad (4-130)$$

However, since the decay constant of the isotope that is irradiated is much smaller than the decay constant of the produced isotopes, the exponent term, $e^{-\lambda_{1}t} \sim 1$ and the above equation reduces to

$$A_2(t) \cong R(1 - e^{-\lambda_2 t})$$
 (4-131)

This equation is called the *activation equation* (see Fig. 4-11). Initially, when λt is small, the activity of the produced radioisotope increases almost linearly due to the behaviour of $(1 - e^{-\lambda_2 t})$. After some time the activity reaches its saturated value. At an irradiation time equal to one half-life of the radioisotope, half of the maximum activity is formed. It is easy to realize that the activity of the produced isotope will saturate and therefore irradiation times that exceed twice the half-life are usually not worthwhile.



Figure 4-11. Activation curve - production of radioisotopes

4. ALPHA DECAY

4.1 Mechanism of Alpha Decay

An alpha (α) particle is a highly energetic helium nucleus consisting of two protons and two neutrons. Whenever a nucleus has too many protons, causing excessive repulsion, it is unstable and has a tendency to decay by emitting an α particle, which reduces the repulsive force. Most α emitters are towards the end of the periodic table.



Figure 4-12. Uranium series

The products of the decay are called a radioactive series, and there are four natural α radioactive series: (1) uranium series, (2) thorium series, (3) actinium series and (4) neptunium series. The uranium series starts with the ²³⁸U isotope, which has a half–life of 4.5 x 10⁹ years, and is shown in

Fig. 4-12. Because of the very long half–life of the parent nuclide, this chain is still present today. The thorium and actinium series are also present today, whereas the parent nucleus of the neptunium series, $^{237}_{93}$ Np, has a half–life of 2.2 x 10⁶ years and has already disappeared. However, it is possible to produce this element artificially and thus determine the half–lives of the series.

Alpha particles do not exist as such inside the heavy nuclei. Instead, they form, exist for some time, disintegrate, form and disintegrate again. Occasionally, some of them have enough energy to overcome the potential barrier of the nucleus; this results in a net decrease in mass of the nucleus and consequently an energy release.

The emission of an α particle leads to the formation of a more stable nuclear configuration. The daughter product, however, may also be unstable and continue to decay. Emitted α particles may have energies ranging from 4 to 7 MeV. There are almost no α particles with energies below 2 MeV since the probability for an α particle to cross the potential barrier decreases exponentially with energy. One example is the decay of ²³²Th into ²²⁸Ra with the energies of emitted α particles shown in Fig. 4-13.



Energy (keV)	Intensity
4012.3	78.2
3947.2	21.7
3811.1	0.069

Figure 4-13. α decay of ²³²Th \rightarrow ²²⁸Ra and energies of the emitted α particles

The half–lives of α emitters range from microseconds to 10^{17} years.

The half–life of an α emitter is directly dependent on the energy of the emitted α particle. For example, the half–life of ²¹³Po is 4.2 µsec and the energy of α particle emitted in the decay is 8.37 MeV. Thorium-232 emits α

particles of energy around 4 MeV with a half–life of 1.405 x 10^{10} years, while ²¹⁸Th emits α particles of energy of about 10 MeV and has a half-life of only 0.11 µsec. To further illustrate this point, the energy and half–lives of the ²³⁸U decay series (shown in Fig. 4-12) are plotted in Fig. 4-14 indicating similar correlation between energy of the α particle and half–lives of the nuclides. Why in some cases α decay takes billions of years when it is driven by the process involving the α particle energy of the order of MeV?

The mechanism of α decay as well as the observed relation is explained by considering the α particle as being bound in the potential of the nucleus (see Fig. 4-15). Alpha particles in a level with negative energy cannot penetrate the Coulomb barrier, but those in a positive energy level may have enough energy to overcome the barrier and exit the nucleus. The region between -*a* and +*a* in Fig. 4-15 represents the inner part of the nucleus where α particles are bound by a strong nuclear potential. The regions left and right are governed by the Coulomb repulsive potential between the charge of the α particle, +2*e*, and the charge of the remaining nucleus, +(*Z* – 2)*e*.



Figure 4-14. Geiger–Nuttall plot of the energy of emitted α particles versus the half–lives of nuclides in ²³⁸U decay series

The three energy levels shown in Fig. 4-15 are not to scale and are shown only to illustrate the mechanism of α decay. Namely, if an α particle has

energy corresponding to energy level one, the energy is depicted as negative in order to indicate that it cannot exit the nucleus, and thus no α decay is expected to take place. However, if an α particle has an energy corresponding to levels two or three, then it may penetrate the potential barrier via the tunnel effect and α decay will happen. The following example illustrates how the potential energy can be estimated.



Figure 4-15. Coulomb potential of an α particle in a nucleus (simplified one-dimensional representation)

Example 4.6 Coulomb potential barrier in α decay

Calculate the Coulomb potential at the nuclear surface felt by an α particle emitted by the parent nucleus ²¹²Po, and compare with the decay energy of 8.954 MeV.

Approximate the daughter nucleus as well as the α particle as uniformly charged spheres and plot energy versus center-to-center separation. Also, estimate the velocity of the particle inside the nucleus and the frequency of hitting the wall of the Coulomb potential. See problem 3.30 for definition of tunneling probability.

The Coulomb repulsion potential energy, V_0 (also known as the height of the potential barrier), when two spheres just touch is given by (see illustration in Fig. 4-16)

$$V_{0} = \frac{2(Z-2)e^{2}k}{R}$$

$$= \frac{2(82)(1.6 \times 10^{-19} \text{ C})^{2}(8.99 \times 10^{9} \text{ Nm}^{2}/\text{C}^{2})}{8 \times 10^{-15} \text{ m}}$$

$$= 4.72 \times 10^{-12} \text{ J} \frac{1 \text{ eV}}{1.6 \times 10^{-19} \text{ J}} = 29 \text{ MeV}$$
(4-132)

where the radius, R, is estimated by the Fermi model (see Chapter 3)

$$R = 1.07 A^{1/3} = 1.07 (4^{1/3} + 208^{1/3}) = 8 \text{fm}$$

$$f = \frac{v}{2R} = \frac{2.08 \times 10^7 \, m/s}{2(8 \times 10^{-15} \, m)} = 1.3 \times 10^{21} \, / \sec$$



Figure 4-16. Coulomb potential barrier in ²¹²Po α decay

The distance at which the Coulomb potential becomes equal to the energy of the observed decay of 212 Po is

$$8.954 \text{MeV} = \frac{2(Z-2)e^2k}{R} \implies R' = 26 \text{fm}$$

Thus the width of the 212 Po Coulomb barrier seen by the α particle is

R' - R = 26 fm - 8 fm = 18 fm

For the known α particle energy, its velocity, v, moving inside the nucleus, and the frequency, f, of hitting the wall of the potential barrier may be estimated as

$$T = 8.954 \text{MeV} = \frac{mv^2}{2} = \frac{3727 MeV}{2} \frac{v^2}{c^2} \implies v/c = 0.0693$$
$$v = 2.08 \times 10^7 \text{ m/s}$$

4.2 Kinetics of Alpha Decay

Generally, for α particle emission to happen, the following conservation equation must be satisfied

$$M_{parent}c^2 = M_{daughter}c^2 + M_{\alpha}c^2 + Q \qquad (4-133)$$

where Q represents the energy released in the α decay.

If there is no γ ray emission, the Q value is distributed between the α particle and the daughter, which recoils after the α particle is emitted.

As discussed in Section 2, certain conservation laws apply to radioactive decay.

From the law of conservation of energy it follows that

$$Q = \frac{1}{2}M_{\alpha}v_{\alpha}^{2} + \frac{1}{2}M_{daughter}v_{daughter}^{2}$$
(4-134)

while from the law of conservation of momentum it follows

$$M_{\alpha}v_{\alpha} = M_{daughter}v_{daughter} \tag{4-135}$$

When combined, Eqs. (4-134) and (4-135) lead to:

$$Q = \frac{1}{2}M_{\alpha}v_{\alpha}^{2} + \frac{1}{2}M_{daughter}\frac{M_{\alpha}^{2}}{M_{daughter}^{2}}v_{\alpha}^{2} =$$

$$= \frac{1}{2}M_{\alpha}v_{\alpha}^{2}(1 + \frac{M_{\alpha}}{M_{daughter}}) = T(1 + \frac{M_{\alpha}}{M_{daughter}})$$
(4-136)

where T represents the kinetic energy of the α particle.

From the above equation describing the kinetics of α decay, it is understood that the spontaneity condition for the decay is Q > 0.

Example 4.7 Kinetics of α decay

Find the energy released in the decay of ²³⁸U

 $^{238}_{92}U \rightarrow ^{234}_{90}Th + \alpha$

Calculate the energy of the emitted α particle and the recoil nucleus, if

 $m_{\alpha} = 4.002603$ amu $m_{Tb} = 234.043583$ amu $m_U = 238.050786$ amu

The energy released in the reaction is obtained from the mass difference between the nuclei and particle involved (see Chapter 3) is

 $Q = [m_{tt} - (m_{th} + m_{a})]c^2 = 4.28 \text{MeV}$

This energy is also equal to

 $Q = T(1 + \frac{m_{\alpha}}{m_{Th}})$

which gives the energy of the emitted α particle

$$T = Q/(1 + \frac{m_{\alpha}}{m_{Th}}) = 4.208 \text{MeV}$$

The energy released in the reaction is also equal to the energy of emitted α particle plus the energy of recoil nucleus.

It follows

$$Q = T + E_{Th} \rightarrow E_{Th} = 4.28 \text{MeV} - 4.208 \text{MeV} = 0.072 \text{MeV}$$

5. BETA DECAY

5.1 Mechanism of Beta Decay

Beta decay is a process that involves nucleon transformation and therefore is a unique decay mode. Beta unstable nuclei can decay in one of the following three modes:

- β^- particle (electron) emerges in a weak decay process where one of the neutrons inside nucleus decays to a proton, an electron and an antielectron-type neutrino: $n \rightarrow p + e^- + \overline{v}_e$
- β^+ particle (positron) emerges in a process where a proton decays into a neutron, a positron and an electron-type neutrino: $p \rightarrow n + e^+ + v_e$
- Nuclei having an excess number of protons may capture an electron from one of the inner orbits which immediately combines with a proton in the nucleus to form a neutron and an electron-type-neutrino: p + e⁻ → n + v_e

All of these reactions are a result of restructuring the nucleus within an unstable nuclide in order to approach the region of stability as discussed in Chapter 3. In all of these decay modes, the laws of conservation as described in Section 2 must be satisfied. In order to determine which nuclei are β emitters, it is useful to compare the masses of the isobars, ${}^{A}_{Z}M$

$$^{A}_{Z}M >_{Z+1}M$$
 possible β^{-} decay $Z \rightarrow Z+1$

$$^{A}_{Z}M <_{Z+1}^{A}M + E_{b}$$
 possible orbital electron capture $Z + 1 \rightarrow Z$

$$^{A}_{Z}M + 2m_{0}c^{2} > ^{A}_{Z+1}M$$
 possible β^{+} decay $Z + 1 \rightarrow Z$

Beta-minus decay will occur if an atom of higher Z has a smaller mass. Orbital electron capture requires the mass difference to be greater than the binding energy of the electron to be captured. Beta-plus decay is possible only in the case when the mass difference is greater than two electron rest masses. An example that illustrates the conditions for various beta decay modes is shown in Table 4-1 for six isobars with atomic mass number A = 90 (Zr). It can be seen that the even-even nucleus, ${}^{90}_{40}$ Zr has the smallest mass and the highest binding energy. This is the only stable element among the six listed isobars. Masses of all other nuclei, up and down from the ${}^{90}_{40}$ Zr, are increasing. This is illustrated in Fig. 4-17. Nuclei left of ${}^{90}_{40}$ Zr decay by β^- forming a decay chain whereas those to the right decay either through β^+ or electron capture and also form a decay chain. Since beta decay is caused by the difference in the masses of the two isobars, there are no two stable neighbouring isobars.

Table 4-1. Decay modes of six isobars with A = 90				
Nuclide	Mass (amu)	BE (MeV)	Decay mode	Half-life
$^{90}_{36}$ Kr	89.9195238	773.217	β-	32.32 s
⁹⁰ 37Rb	89.9148089	776.826	β.	158 s
⁹⁰ 38Sr	89.9077376	782.631	β.	28.79 years
⁹⁰ 39Y	89.9071514	782.395	β-	64.00 h
⁹⁰ 40Zr	89.9047037	783.892	stable	stable
⁹⁰ 41Nb	89.9112641	776.999	β+	14.60 h
⁹⁰ 42Mo	89.9139362	773.728	β+	5.56 h

Table 4-1 Decay modes of six isobars with A = 90



Figure 4-17. Isobars with A = 90

The energy spectrum of every beta emitter is continuous up to a maximum finite value. Every emitted electron or positron particle is accompanied by the emission of an antineutrino or neutrino, whose energies are equal to the difference between the kinetic energy of the beta particle and the maximum energy of the spectral distribution for the beta decay of that nuclide. The antineutrino and neutrino have no electrical charge and have a small mass that is usually neglected in analyzing the kinetics of the decay. The energy released in β^- decay is distributed between the emitted particles: electron, neutrino, and the recoil nucleus, which usually has negligibly small energy and is not taken into account. Therefore

$$E_{\max} = E_{\beta} + E_{\nu} \tag{4-137}$$



Kinetic Energy (~MeV)

(b) Figure 4-18. Energy spectrum of electron (β^-) decay (a) general β energy spectrum and (b) complex β energy spectrum

The electron spectrum is asymmetric, with a higher population of emitted electrons at lower energies and the average energy of around $(0.3)E_{max}$. A general β energy spectrum is shown in Fig. 4-18 (a). Beta-minus decay does not often lead to only one element, but a series of nuclides that all decay by β emission. In such cases, the electron energy spectrum is complex and consists of a number of partial energy spectrums (see Fig. 4-18 (b)).

The positron energy spectrum is similar to the electron energy spectrum except it is shifted to a higher energy region with the average energy of around $(0.4)E_{max}$. Every positron, once emitted, annihilates very rapidly in collision with its material counter-particle, the electron, creating two photons each with energy 0.511 MeV (see Chapter 5). A general trend of the positron energy spectrum is shown in Fig. 4-19.

When β decay leaves the residual nucleus in an excited state, the nucleus, in order to achieve stability, may either emit a γ ray or transfer the excitation energy to an electron. The latter is called internal conversion and is an

alternative mechanism for an excited nucleus to relax into the ground state. It is an interaction in which a tightly bound electron interacts with the nucleus, absorbs the excitation energy and is ejected from the atom (see Section 5.5). A list of the most commonly used β emitters (sources) is shown in Table 4-2.



Figure 4-19. Energy spectrum of positron (β^+) decay

Nuclide	Half–life	E_{max} (MeV)	Production
³ H	12.33 years	0.019	⁹ Be(d, 2α)
			6 Li(n, α)
^{14}C	5730 years	0.156	$^{13}C(d, p)$
			$^{14}N(n, p)$
^{32}P	14.262 d	1.711	$^{31}P(n, \gamma)$
			$^{32}S(n, p)$
⁴⁵ Ca	162.61 d	0.257	44 Ca(n, γ)
⁹⁰ Sr	28.79 years	0.546	fission
⁹⁰ Y	64.00 h	2.280	⁹⁰ Sr→ ⁹⁰ Y, fission
²¹⁰ Bi	5.013 d	1.163	209 Bi(n, γ)

Table 4-2. Most commonly used β emitters

5.2 Kinetics of Beta–Minus Decay

Beta-minus decay produces an electron, an antineutrino that always accompanies the decay, and the daughter atom that is left in an ionized state. The electron and antineutrino move away from the nucleus and the residual nucleus has one more proton than did the parent. Since an atom gains a proton during β^- decay, it changes from one element to another. For example, after undergoing β^- decay, an atom of carbon (with six protons) becomes an atom of nitrogen (with seven protons).

Beta minus decay preserves the total number of nucleons, A. The beta decay process is a nucleon transformation that can be written as follows: $n \rightarrow p + e^{-} + \overline{v}_{e}$ (see Section 5.1).

For beta emission to be energetically possible, the exact nuclear mass of the parent, M_{parent} , must be greater than the sum of the exact masses of the daughter nucleus, $M_{daughter}$, and the β particle, m_e

$$M_{parent} = M_{daughter} + m_e + Q \tag{4-138}$$

If atomic masses are used the above equation reduces to

$$M_{parent} = M_{daughter} + Q \tag{4-139}$$

The energy of β decay, Q, appears as kinetic energy of the β particle and is equivalent to the difference in mass between the parent nucleus and the sum of daughter nucleus and β particle. An extremely small part of the released energy is dissipated by the recoil nucleus, since the ratio of beta particle mass to that of the recoil nucleus is very small. The following example illustrates the energy conservation of β^- decay and explains how atomic masses may be used in a calculation instead of nuclear masses (masses of nuclei only).

Example 4.8 Kinetics of beta-minus decay

Calculate the energy released in the β decay of ³²P. The atomic mass of the parent nucleus is 31.9739072 amu. The daughter product is ³²S with an atomic mass of 31.9720707 amu.

The reaction is

 $^{32}_{15}P \rightarrow ^{32}_{16}S + e^{-} + \overline{\nu_e}$

Although it was explained in Chapter 3 (Section 2.3) that the atomic masses can be used as nuclear masses, here again is a summary of this explanation based on the example of phosphorus decay. From the reaction equation it follows that the mass balance equation (neglecting the mass of antineutrino) is

$$M_{nucleus}({}^{32}P) = M_{nucleus}({}^{32}S) + m_e$$

However, the tabulated masses are the atomic masses, thus

$$M_{atom} = M_{nucleus} + Zm_{e}$$

Adding the same number of electron masses to both sides for the reaction equation

$$M_{nucleus}({}^{32}P) + 15m_e = M_{nucleus}({}^{32}S) + m_e + 15m_e$$

It can now be seen that the masses obtained are equal to the atomic masses. Thus, for β decay the energy equation becomes

$$M_{parent} = M_{daughter} + Q \rightarrow$$
$$Q = [M_{atom}(^{32}P) - M_{atom}(^{32}S)]c^{2} = 1.7107 \text{MeV}$$

This energy corresponds to the maximum energy of the ³²P β spectrum and is exactly equal to the measured value as shown in Table 4-2. For example, if the energy of the emitted electron is 650 keV, the energy of the antineutrino will be 1.06 MeV. As discussed, an extremely small part of the β decay energy is observed in the recoil nucleus, because the ratio of β particle mass to the recoil nucleus mass is very small. In this example it is 0.00055/31.9720707 = 0.000017.

5.3 Kinetics of Beta–Plus Decay

When the neutron-to-proton ratio is too low and α emission is not energetically possible, the nucleus may reach stability by emitting a positron. During β^+ decay, a proton in the nucleus transforms into a neutron, emitting a positron and neutrino. The positron and neutrino move away from the nucleus, and the residual nucleus has one less proton than the parent nucleus. Since the atom loses a proton during β^+ decay, it changes from one element to another. For example, after undergoing β^+ decay, an atom of carbon (with 6 protons) becomes an atom of boron (with 5 protons). The beta-plus decay preserves the total number of nucleons, A. The decay process is a nucleon transformation and as discussed in Section 5.1 can be written as follows: p \rightarrow n + e⁺ + v_e. The reaction equation in the form of nuclear masses is identical to that for β^- decay given in Eq. (4-138)

 $M_{parent} = M_{daughter} + m_e + Q$

If the atomic masses are used the above equation becomes

$$M_{parent} = M_{daughter} + 2m_e + Q \tag{4-140}$$

The following example illustrates the energy conservation of β^+ decay and again illustrates that atomic masses can be used instead of nuclear masses.

Example 4.9 Kinetics of beta-plus decay

Calculate the energy released in the $\bar{\beta}^+$ of ${}^{13}_7$ N given the following masses: $M({}^{13}_7$ N) = 13.0057386 amu, $M({}^{13}_6$ C) = 13.0033548 amu, $m_e = 0.00055$ amu.

Starting from the reaction

 $^{13}_{7}N \rightarrow ^{13}_{6}C + e^+ + v_e$

From the above reaction equation it follows that the mass balance equation (neglecting the mass of neutrino) is

$$M_{nucleus}({}^{13}N) = M_{nucleus}({}^{13}C) + m_{e^{+}}$$

However, the tabulated masses are atomic masses, thus

 $M_{atom} = M_{nucleus} + Zm_e$

Adding the same number of electron masses to both sides for the reaction equation

$$M_{nucleus}({}^{13}N) + 7m_e = M_{nucleus}({}^{13}S) + m_{e^+} + 7m_e$$

It can now be seen that the masses obtained are equal to the atomic masses if

$$M_{atom}({}^{13}N) = M_{atom}({}^{13}S) + 2m_e$$

Thus

$$M_{parent} = M_{daughter} + 2m_e + Q \longrightarrow$$
$$Q = [M_{atom}(^{13}N) - M_{atom}(^{13}C) - 2m_e]c^2 = 1.196 \text{MeV}$$

The positive Q value indicates that the decay is possible, *i.e.* that ${}^{13}_{7}$ N is unstable and decays by positron emission.

5.4 Kinetics of Orbital Electron Capture

The energy balance equation for positron emission

$$M_{parent} = M_{daughter} + 2m_e + Q \tag{4-141}$$

indicates that if a neutron-deficient atom is to attain stability by positron emission, it must exceed the weight of its daughter by at least two electron rest masses. If this requirement cannot be met, then the neutron deficiency is overcome by a process called electron capture or *K*-capture. In this radioactive transformation, one of the lowest positioned (*K*-shell) electrons is captured by the nucleus and combines with a proton to produce a neutron and a neutrino (see Section 5.1): $p + e^- \rightarrow n + v_e$. A schematic of this decay mode is shown in Fig. 4-20.



Figure 4-20. Orbital electron capture (*K*-capture)

The energy conservation for K-capture is therefore

$$M_{parent} + m_e = M_{daughter} + E_b + Q \tag{4-142}$$

where E_b is the binding energy of the captured electron and the masses are nuclear masses. The following example illustrates the kinetics of the *K*-capture decay mode.

Example 4.10 Kinetics of orbital electron capture (*K***–capture)**

For the decay shown in Fig. 4-21, determine the energy of the orbital electron capture decay mode. The K-shell binding energy of ${}^{22}_{11}$ Na is 1.0721 keV, and the

atomic masses of ${}^{22}_{11}$ Na and ${}^{22}_{10}$ Ne are 21.9944368 amu and 21.9913855 amu, respectively.



Figure 4-21. ²²₁₁Na decay scheme

In order to calculate the decay energy from the equation that is expressed in nuclear masses

$$M_{parent} + m_e = M_{daughter} + E_b + Q$$

it is necessary to translate them into atomic masses to be able to use the values as given in the problem. The daughter nucleus has one nucleon less than the parent and thus if Z denotes the atomic number of the parent it follows

$$M_{parent} + m_e + (Z - 1)m_e = M_{daughter} + (Z - 1)m_e + E_b + Q$$

For the decay of ${}^{22}_{11}$ Na it follows

$$M_{nucleus} \begin{pmatrix} 22\\11 \end{pmatrix} \text{Na} + m_e + (11-1)m_e = M_{nucleus} \begin{pmatrix} 22\\10 \end{pmatrix} \text{Ne} + (11-1)m_e + E_b + Q$$
$$M_{atom} \begin{pmatrix} 22\\11 \end{pmatrix} \text{Na} = M_{atom} \begin{pmatrix} 22\\10 \end{pmatrix} \text{Ne} + E_b + Q$$

The Q-value is

$$Q = M_{atom} ({}^{22}_{11}\text{Na}) - M_{atom} ({}^{22}_{10}\text{Ne}) - E_b = 2.841\text{MeV}$$

From the decay shown in Fig. 4-21 it can be seen that a photon is emitted with energy of 1.2746 MeV. Thus, the excess energy is equal to 2.841 MeV – 1.2746 MeV = 1.567 MeV. The recoil energy associated with the emission of a gamma ray photon is insignificantly small; therefore the excess energy is carried away by the neutrino. In order to conserve energy, whenever radioactive decay involves the capture or emission of an electron, a neutrino must be emitted. In the middle of the periodic table, the isotopes that are lighter than the most stable isotopes tend to decay by electron capture, and the heavier ones decay by beta-minus emission. One example is silver,

which has two stable isotopes: one of lower mass which decays by electron capture and one of greater mass which decays by beta emission.

5.5 Kinetics of Internal Conversion

Internal conversion is an alternative mechanism for an excited nucleus to release excess energy and return to its ground state. It is an interaction in which a tightly bound electron interacts with the nucleus, absorbs the excitation energy which is emitted as a gamma ray, and is then ejected from the atom. Internally converted electrons are monoenergetic, and the kinetic energy of the converted electron, E_e , is equal to the difference between the energy of the gamma ray emitted from the nucleus, E_p , and the binding energy of the converted electron of the daughter element, E_b

$$E_e = E_\gamma - E_b \tag{4-143}$$

Notice that in this process, the emitted electron was previously one of the orbital electrons, whereas the electron in beta decay is produced by the decay of a neutron from the nucleus.

Since the internal conversion process can interact with any of the orbital electrons (from K, L, M, N... shells), which all have different binding energies, the energy spectrum consists of many lines (see Fig. 4-22).

5.6 Auger Electrons

In the process of internal conversion and orbital electron capture, an electron leaves its atomic orbit and the vacancy is soon filled. There are two competing processes, emission of an X ray due to the transition of an electron from an outer shell to the vacancy in a shell closer to the nucleus, and another process that is similar to internal conversion in which the energy difference between two orbits is not released as an X ray but rather is used to knock another electron from the orbit. For example, if a vacancy in the K-shell is filled in with an electron from the L-shell, then the energy difference is enough to remove another electron from the L- or M-shell which causes another vacancy to form. This process is called Auger electron emission and can consist of a number of vacancies and thus emitted electrons. However, the entire process is not longer than 10^{-9} seconds. The Auger process is more probable in light nuclei, while emission of X rays is more probable in heavy nuclei. Auger electrons have energy in the range of 100 eV to a few keV. The kinetic energy of the Auger electron corresponds to the difference between the energy of the initial electronic transition and the ionization energy of the shell from which the Auger electron was ejected. These energy levels depend on the properties of the atom.



Figure 4-22. Internal conversion electron spectrum (not to scale)

This effect was discovered independently by both Lise Meitner and Pierre Auger. The discovery made by Meitner was published in 1923 in the *Journal Zeitschrift fur Physik*, two years before Auger discovered the same effect. However, the English speaking scientific community adapted Auger's name for the process.

6. GAMMA DECAY

6.1 Mechanics of Gamma Decay

Gamma (γ) decay follows α and β decay. The most common γ sources are β radioactive isotopes because they are easy to produce and have higher γ ray intensity than α emitters. Very penetrating γ rays were discovered in 1900 by Paul Villard, a French physicist. They are similar to X rays, but are emitted from the nucleus and generally have much shorter wavelengths. Gamma rays are the most energetic form of electromagnetic radiation, with more than 10,000 times the energy of visible light photons.

In γ decay, a nucleus rearranges its constituent protons and neutrons in order to transition from a higher energy state to a lower energy state through the emission of electromagnetic radiation. The number of protons and neutrons in the nucleus does not change in this process, so the parent and daughter atoms are the same chemical element. The emitted γ ray is monoenergetic having energy equal to the energy level difference less the small fraction transferred to the recoil nucleus (see Fig. 4-1). Gamma decay is a fast process with half–lives that are usually in the range of 10^{-13} seconds to days. The most common sources of γ radiation are listed in Table 4-3.

Isotope	Half–life	$E_{max} > 5\%$ (MeV)	
²⁴ Na	14.9590 h	2.75	
⁷² Ga	14.10 h	2.20	
¹⁴⁰ La	1.6781 d	2.52	
^{110m} Ag	249.79 d	1.52	
^{152,154} Eu	13.537 years, 8.593 years	1.40	
⁶⁰ Co	1925.1 d	1.33	
¹⁸⁷ W	23.72 h	0.78	

Table 4-3. Most commonly used γ emitters

In the case when lower energy photon radiation is required, the isotopes that decay by electron capture are used to produce X rays. A list of some of the isotopes that can be produced in a reactor and are X ray emitters is shown in Table 4-4.

Table 4-4. Most commonly used X ray emitters

Isotope	Half–life	E(K-shell) (keV)	
⁵⁵ Fe	2.73 years	6.404	
⁶⁵ Zn	244.26 d	8.639	
⁷⁵ Se	119.79 d	11.222	
¹⁷⁰ Tm	128.6 d	50.741	
²⁰⁴ Tl	3.78 years	72.872	

6.2 Kinetics of Gamma Decay

In the γ decay of a nucleus, a γ ray is produced by a transition between nuclear levels:

$$E_{initial} = E_{final} + E^* = E_{final} + E_{nucleus} + E_{\gamma}$$
(4-144)

where the excitation energy, E^* , is shared between the γ , E_{γ} , and the kinetic energy of the recoiling nucleus, $E_{nucleus}$. In general, the transition energy and γ energy may be considered equal because the energy of the recoil nucleus is much smaller than the energy of the emitted γ ray. Thus, the mass-energy equation for γ decay reduces to:

$$E_{initial} = E_{final} + E^* = E_{final} + E_{\gamma}$$
(4-145)

7. NATURAL RADIOACTIVITY

Since its creation, the world has been naturally radioactive. The level of radioactivity differs from area to area depending on the naturally occurring radioisotope concentration and their half-lives. Background radiation describes the total exposure to existing, natural radionuclides, which are found in air, water and soil, but also in human bodies and are divided into three general categories:

- a) Primordial radioisotopes that have existed since before the creation of the Earth,
- b) Cosmogenic radioisotopes that are formed as a result of cosmic ray interactions, and
- c) Those produced due to human actions.

The primordial radionuclides are typically long lived, with half-lives often on the order of hundreds of millions of years:

- ²³⁵U (703800000 years): 0.72% of all natural uranium.
- ²³⁸U (4.468 x 10⁹ years): 99.2745% of all natural uranium
- 232 Th (1.405 x 10¹⁰ years)
- ²²⁶Ra (1600 years)
- ²²²Rn (3.8235 d)
- 40 K (1.277 x 10⁹ years).

One example of a primordial nuclide that is a constituent of every living creature is 40 K. The following example demonstrates the radiation level due to potassium decay in an average human.

Example 4.11 How radioactive is a human body?

Considering that there are about 140 g of potassium in a typical person's body, determine the total number of atoms of 40 K and its activity in the body. The abundance of 40 K is 0.0117%. The atomic weight is 39.0983.

The total number of ⁴⁰K atoms

$$N_{40_{K}} = \frac{(140g)(6.02 \times 10^{23} \text{ atoms/mole})(0.0117 \times 10^{-2})}{39.0983g/\text{mole}}$$

 $= 2.52 \times 10^{20}$ atoms

The activity is thus

$$A_{40_{K}} = \lambda_{40_{K}} N_{40_{K}} = \frac{\ln 2}{1.277 \times 10^{9} \times 365 \times 24 \times 3600 \text{ sec}} \times (2.52 \times 10^{20} \text{ atoms})$$

= 4.3kBq = 116nCi

Cosmic radiation can exist in many forms, from high-speed heavy particles to high-energy photons and muons. Cosmic radiation interacts with the upper atmosphere and produces radioactive nuclides. Although they can have long half-lives, the majority have shorter half-lives than the primordial nuclides. Three of the main cosmogenic radionuclides are:

- ${}^{14}C$ (5730 years): created by ${}^{14}N(n, p){}^{14}C$
- ³H (12.33 years): created through cosmic radiation interactions with N and O, or ⁶Li(n, α)³H
- ⁷Be (53.29 days): created through cosmic radiation interactions with N and O.

The most interesting is the cycle of radiocarbon in nature (see Fig. 4-23) and is explained in more details as follows. From the known content (activity) of radiocarbon $({}^{14}C)$ in organic matter it is possible to determine its age. This method is called the *carbon dating* and was developed after World War II by Willard F. Libby. It is used to determine the age of specimens (for example wood, charcoal, marine and freshwater shells) in archeology, geology, geophysics, and other branches of science. Carbon has many unique properties which are essential for life on earth. As sketched in Fig. 4-23, ¹⁴C is created in a series of events in the atmosphere that starts with cosmic radiation interactions in the upper atmosphere by removing neutrons from nuclei. These neutrons interact with ordinary nitrogen (¹⁴N) at lower altitudes, producing ¹⁴C. Unlike common carbon (¹²C), ¹⁴C is unstable and decays to nitrogen. Ordinary carbon is a constituent of the carbon dioxide (CO₂) in the air and is consumed by plants. Since plants are consumed by animals (including humans), carbon enters the food chain. Carbon-14 also combines with oxygen to form carbon dioxide ($^{14}CO_2$), that follows the same cycle as the non-radioactive CO_2 . The ratio of these two molecules of CO_2 can be determined by measuring a sample of the air. The ratio ${}^{14}C/{}^{12}C$ is fairly constant in air, leaves, or the human body because ${}^{14}C$ is intermixed with ¹²C. In living things the ¹⁴C atoms decay into ¹⁴N, and at the same time living things exchange carbon with the environment, so that the ratio remains approximately the same as in the atmosphere. However, as soon as a plant or animal dies, the ¹⁴C atoms continue to decay but are no longer replaced. Thus, the amount of ¹⁴C decreases with time; in other words, the ¹⁴C/¹²C ratio becomes smaller. The "clock" of radiocarbon dating thus starts ticking at the moment a living organism dies. Since the half-life of ¹⁴C is 5.730 years anything over approximately 50,000 years should theoretically have no detectable ¹⁴C. That is why radiocarbon dating cannot approximate an age of millions of years.

Humans have used radioactivity for one hundred years, and through its use, added to the natural inventories. However, the amount of radionuclides created by humans is small compared to the natural amounts discussed above. In addition, the majority of created radionuclides have short halflives. Major radionuclides produced by humans and included into the chain food are fission products produced from weapons testing: ¹³¹I (8.0207 d), ¹³⁷Cs (30.07 years), and ⁹⁰Sr (28.79 years).



Figure 4-23. Carbon cycle

Example 4.12 Radiocarbon dating

The ¹⁴C content in a living things decreases after death with a half-life of 5730 years. If the ¹⁴C content of an animal bone is found to be 22.5% of that of an equivalent presentday sample, determine its age. Calculate the activity of the bone assuming the initial activity to be 15 dis per minute per gram.

The age of the specimen is determined as follows

$$N(t) = N(0)e^{-\lambda t}$$
 $\lambda = \frac{\ln 2}{T_{1/2}} = 0.000121 \text{ yrs}^{-1}$

$$\frac{N(t)}{N(0)} = 0.225 \quad \rightarrow \quad t = 12,331 \text{ years}$$
The activity of the specimen knowing that the rate of disintegration is constant, A(0) = 15 dis/min/g, is

$$\frac{\lambda N(t)}{\lambda N(0)} = \frac{A(t)}{A(0)} = 0.225 \quad \rightarrow \quad A(t) = 15 \times 0.225 = 3.4 \text{ dis/min/gr}$$

NUMERICAL EXAMPLE

Solution of the Bateman Equation

Oxygen-20 decays by beta-minus according to the following decay scheme:

 $^{20}O \xrightarrow{\beta^-} ^{20}F \xrightarrow{\beta^-} ^{20}F(\text{stable})$

Calculate the decay as a function of time for 20 O as well as its daughter product 20 F by numerical solution of the Bateman equations. Also, using Eq. (4-124), compute the time of maximum 20 F concentration.

Solution in MATLAB:

```
clear all
global lambda_p lambda_d
Thalf_p = 13.51; %s half life of O-20
Thalf_d = 11.163; %s half life of F-20
lambda_p = log(2)/Thalf_p; \% s^{-1}
lambda_d = log(2)/Thalf_d; \% s^{-1}
% Numerical Solution
[t,N] = ode45(@Bateman, [0 100], [1 0]);
% Tmax calculation
tmax = log(lambda d/lambda_p) / (lambda_d - lambda_p)
plot(t,N(:,1),k')
hold on
plot(t,N(:,2),'k--')
plot([tmax tmax], [0 1], k:')
xlabel('Time (s)')
ylabel('Fraction Present')
function dN = Bateman(t,N)
global lambda p lambda_d
dN = zeros(2,1);
dN(1) = -lambda_p*N(1);
dN(2) = lambda_p*N(1) - lambda_d*N(2);
```



Figure 4-24. Numeric solution of the Bateman equations for ²⁰O decay

PROBLEMS

4.1. Write the decay of 226 Ra and show that the activity of 1 gram of pure radium is equal to one curie. Then calculate the activity of this sample 100 and 1000 years later. The half-life of 226 Ra is 1600 years.

4.2. A solution with radioactive sodium of activity of 12,000 disintegrations min^{-1} was injected into the blood stream of a patient. After 30 hours the activity of 1 cm³ of the blood was 0.5 disintegrations min^{-1} . If the half-life of the sodium isotope is 15 hours calculate the volume of blood in the body.

4.3. A sample contains an isotope of magnesium, ²⁷Mg, which undergoes β decay with a half-life of 9.46 min. A Geiger-counter measured the activity of the sample to be 1.69 x 10²¹ Bq. Write the decay of this isotope. Calculate the decay constant. How many moles of the isotope are present in the sample? How many radioactive isotopes are present after one hour? What is the activity of the sample after 10 h?

4.4. Use the nuclide table from http://atom.kaeri.re.kr/ton/nuc7.html and find the decay of 27 Mg. Sketch the decay scheme and find the energy of γ rays emitted with the probabilities of 29 % and 71 %.

4.5. A canister was found in a laboratory to contain 1,000,000 atoms of a certain isotope in 2004. The label on the canister showed that the number of nuclei in 1984 was 2,000,000. Calculate the decay constant and half-life of this isotope.

4.6. The disintegrations of radioactive nuclides are detected by an appropriate counting apparatus. The efficiency of such equipment is determined as the ratio of counts per unit time (usually a minute) to the number of disintegrations per same unit of time. If dpm represents the number of disintegrations per minute, and cpm number of counts per minute then the efficiency of measurement is given with:

Efficiency of measurement = [cpm / dpm] x 100 %

Calculate the efficiency of measurement if a sample had 1000 disintegrations per minute while the counter recorded 800 counts per minute.

4.7. Every measurement of sample radioactivity includes the background radioactivity caused by cosmic rays, natural radioactivity, radioactive fallout, and electronic noise in the circuitry of the equipment. Therefore the true value of the cpm of a sample must be reduced for the background value: sample cpm - background cpm. The efficiency of measurement is:

Efficiency of measurement = [(sample cpm - background cpm) / dpm] x 100 %

Calculate the efficiency for the counts from Problem 4.7 if the background radiation is 15 cpm.

4.8. A 0.01 μ Ci (1 μ Ci= 2.22 x 10⁶ dpm) source of ³⁵S (T_{1/2} = 87.51 days) was counted in a liquid scintillation counter after 200 days and was found to contain 2600 cpm. Calculate the efficiency of the counting apparatus.

4.9. Calculate the specific activity of 60 Co. The half-life is 1925.1 days.

4.10. Consider a decay chain $C_1 \rightarrow C_2 \rightarrow C_3 \rightarrow \dots \rightarrow C_n$. Write the coupled system of decay equations.

4.11. Use the nuclide table from <u>http://atom.kaeri.re.kr/ton/nuc7.html</u> to find the decay of ²³⁸U and its half–life. Compare the half-lives of ²³⁸U and its daughter nuclide and define the condition for secular equilibrium. Calculate the molar concentration of the daughter nuclide at secular equilibrium if the activity of ²³⁸U is 2.3 dpm/kg.

4.12. Use the nuclide table from http://atom.kaeri.re.kr/ton/nuc7.html to find decay of ²²⁰Ra and read the atomic masses of the parent and daughter nuclide. Calculate the Q value for the decay, kinetic energy of the α particle and the Coulomb barrier potential.

4.13. Use the nuclide table from <u>http://atom.kaeri.re.kr/ton/nuc7.html</u> to find decay of ⁵¹Ti. Calculate the decay energy, the maximum kinetic energy of the emitted β particle and the maximum kinetic energy of the anti-neutrino. The decay emits one γ ray of energy 0.32 MeV.

4.14. Show that the atomic mass of 252 Cf is 252.0816196 amu knowing that it decays by emission of α particle of energy 6.118 MeV. Show also that the decay energy is 6.217 MeV. Use the nuclide table from http://atom.kaeri.re.kr/ton/nuc7.html to find the necessary data.

4.15. A sample consists of mixture containing 239 Pu and 240 Pu. If the specific activity is 3.42 x 10⁸ dpm per mg, calculate the proportion of plutonium in the sample.

4.16. The half–life of 22 Na is 2.6019 years. It decays with 89 % by positive electron emission and with 11 % by electron capture. Calculate the partial decay constants.

4.17. Complete the decay schemes

$$^{13}O \xrightarrow{???} ^{13}N \xrightarrow{???} ^{13}C$$

$$^{20}O \xrightarrow{???} ^{20}F \xrightarrow{???} ^{20}Ne$$

4.18. Calculate the time when the rock is solidified if the ratio of 40 K to 40 Ar was found to be 0.1.

4.19. A rock sample of 200 g was found to contain 25 g of 40 K. Determine the age of the rock sample.

4.20. Estimate the age of the ore sample that contained 10.67 mg of 238 U and 2.81 g of 206 Pb.

4.21. Calculate the age of a sample containing 25 g of carbon with ¹⁴C activity measured to be 4 Bq. Assume that ${}^{14}C/{}^{12}C = 1.3 \times 10^{-12}$.

4.22. What is the age of a bone sample that is found to contain 1 mg of 14 C.

4.23. Write the equation of 14 C decay.

4.24. Define the unit of Bq and Ci. Explain the relation between these two units and correlate to the disintegration per minute.

4.25. Explain the decay of tritium.

4.26. There are a number of sources containing α emitting radionuclides. One such case is an americium-beryllium source. Use the nuclide table from <u>http://atom.kaeri.re.kr/ton/nuc7.html</u> to find decay of ²⁴¹Am. What is the most probable energy of the emitted α particle? What is the α particle energy spectrum for this decay?

4.27. What is the activity of 1 mCi of 14 C after ten weeks?

4.28. What is the activity of a sample of 250 μ Ci of ³²P after ten weeks?

4.29. Calculate the density of water and standard gas in unit of molecules per liter, and comment on the density of ionization interactions in these two media.

4.30. Explain what causes atoms to be radioactive.

4.31. Explain how does the radioactivity take place and how stable atoms can become radioactive? What are the isotopes, and what are the isotopes?

4.32. Calculate the activity of 2 gram-mole of 40 K in 2005 and million years later? What is the number of atoms present in 2 gram-mole in 2005 and million years later?

4.33. The biological removal of radioisotopes from the human body is taken into account through so called biological half–life. Very often, the radioactive half-life and the biological half–life are evaluated through the effective half–life

$$\lambda_{eff} = \lambda + \lambda_{bio}$$

Knowing that radioactive half–life for 131 I is 8 days and its biological removal half–life is 120 days, calculate the effective half–life of 131 I.

4.34. Knowing that after 500 years the activity of a sample containing 226 Ra was reduced to 80.4% of its original value, determine the half–life of 226 Ra. Compare the value you can find in the table of elements provided at <u>http://atom.kaeri.re.kr/ton/nuc7.html</u>.

4.35. Calculate the maximum kinetic energy of a positron emitted in the decay of vanadium-48.

Chapter 5

INTERACTIONS OF RADIATION WITH MATTER

Basic Principles, Evidence and Examples

"The social system of science begins with the apprenticeship of the graduate student with a group of his peers and elders in the laboratory of a senior scientist; it continues to collaboration at the bench or the blackboard, and on to formal publication – which is a formal invitation to criticism. The most fundamental function of the social system of science is to enlarge the interplay between imagination and judgment from a private into a public activity. The oceanic feeling of well-being, the true touchstone of the artist, is for the scientist, even the most fortunate and gifted, only the midpoint of the process of doing science". *Horace Freeland Judson* (b. 1931)

1. INTRODUCTION

Radiation interaction with matter is generally analyzed by considering charged particles and electromagnetic radiation separately. As discussed in Chapter 4 the two types of charged particles emitted are α and β particles (electrons or positrons). The mass of these particles differ by many orders of magnitude and the types of nuclear interactions they undergo are thus dramatically different. Other important heavy charged particles that need to be considered are protons, deuterons and helium. The characteristics of electromagnetic radiation (γ rays and X rays) interactions are quite different (photons are massless and travel at the speed of light) to that of charged particles and will be considered separately. This chapter discusses the mechanisms of interaction for both charged particles (α , protons and electrons) and electromagnetic radiation (γ rays and X rays). The characteristics and interactions of neutrons with matter are described in Chapter 6.

2. INTERACTIONS OF CHARGED PARTICLES

2.1 **Types of Interactions**

An incoming charged particle may either interact with the atom's electron cloud or directly with the nucleus. The difference in size, mass and binding energy of the nucleus and electrons determine the type of interaction the incoming particle will undergo. In every collision energy is exchanged between the target and the incoming particle but the energy before and after the collision must be preserved (conservation of energy law). There are two types of collisions: elastic and inelastic scatterings which differ in energy distribution after the collision. Incoming particle bring kinetic energy into the system and the collision is elastic if none of this energy is transferred to the target. These collisions are conceptually similar to collisions between billiard balls. However, if a portion of the incoming kinetic energy imparted on the target atom then the collision is considered to be inelastic.

2.1.1 Elastic Scattering of Charged Particles

When a charged particle passes through matter there is a significant probability that an elastic scattering event will take place. In principle, there are no elastic interactions with the bound electrons in an atom because the electron subsequently transfers the energy to the nucleus and the collision is analyzed as a collision with the whole atom. Since the mass and charge of an atom is dominated by that of its nucleus, such a collision is generally considered as a direct collision between the charged particle and the nucleus. As described in Chapter 2, Rutherford's gold foil experiment uncovered many aspects of charged particle collisions with matter. For example, if a charged particle passes very close to the nucleus, the electron cloud distribution is nearly symmetric with respect to the incoming particle, and the electronic Coulomb forces are neglected. When the charged particle passes further away from the nucleus through the electron cloud, the electrons reduce the effect. Due to this screening effect, the analyses of such collisions require a correction to the total charge seen by the incoming particle, called the effective charge that is always less than the charge of the

nucleus, $Z_{eff} < Z$. This allows the elastic scattering of a charged particle with an atom to be simplified as a direct interaction with a nucleus of charge Z_{eff} .



Figure 5-1. Rutherford scattering of charged particle with the nucleus

In the elastic collisions, also known as *Rutherford scattering*, the direction and the energy of the incoming charged particle may be changed. Since the interaction is strongly dependent on Coulomb forces it is also referred to as *Coulomb scattering*.

The Rutherford scattering formula gives angular deflection probability of incident particle (see Fig. 5-1) usually discussed in terms of the cross section, *i.e.* the effective target area seen by the incident particle (see Chapter 6) as shown in Fig. 5-1. For a gold nucleus (A = 197), the radius can be estimated according to the Fermi model given in Eq. 3-1

 $R = 1.07 A^{1/3} = 6.2 \text{fm}$

For example, if an α particle with kinetic energy, T = 6 MeV approaches the gold nucleus with the impact parameter, b, equal to the radius of a gold nucleus, it will be scattered at an angle of ~ 161° according to Eq. 2-3

$$b = \frac{k(Ze)(ze)}{K\tan(\theta/2)} = \frac{k(79e)(2e)}{K\tan(\theta/2)} \implies \theta = 161^{\circ}$$

with cross sectional area

Area:
$$\sigma = \pi r^2 = \pi (6.2 \times 10^{-15} \text{ m})^2 = 1.21 \times 10^{-28} \text{ m}^2 = 1.21 \text{ barn}$$

Thus the cross section for scattering at the angle of ~ 161° is ~ 1.21 barns.

The differential scattering cross section, $\sigma(\theta)$, is the probability of scattering the incident particles at a certain angle, θ , from a single nucleus, and is given by the Rutherford scattering formula

$$\sigma(\theta) = \frac{k^2 Z_1^2 Z_2^2 e^2}{m_1^2 v^4} \frac{1}{\sin^4(\theta/2)} = \frac{k^2 Z_1^2 Z_2^2 e^4}{4K^2} \frac{1}{\sin^4(\theta/2)}$$
(5-146)

where $T = m_1 v^2/2$ is the kinetic energy of an incoming charged particle with charge Z_1e , and Z_2e is the charge of the target nucleus. The above relation indicates

- The probability of deflection is proportional to the square of the product of the charges of the incident particle and the target nucleus. That is, a larger deflection is obtained for incoming particles of greater charge or for heavier target nuclei.
- The incoming charged particle deflection is smaller if its energy is larger, since the probability of the angular distribution is inversely proportional to the square of the kinetic energy of the incoming charged particle.
- Smaller angles have a higher probability since the differential scattering cross section is inversely proportional to the fourth power of half the scattering angle, $\theta/2$.

The probability that an incoming charged particle will transfer all or part of its energy to a target nucleus (which is assumed to be at rest) depends on a number of factors and may be written as

$$\frac{d\sigma(K)}{dK} \propto \frac{Z_1^2 Z_2^2 e^4}{K^2 M \upsilon^2}$$
(5-147)

- The probability of energy transfer is directly proportional to the charges of the incoming particle and the target nucleus squared.
- The probability of smaller energy transfer is inversely proportional to the energy of the incoming particle (energy that is to be transferred) squared.
- If the target is lighter, the transfer of energy is more probable since it is inversely proportional to the mass of the target nucleus (M).
- If the incident particle velocity (v) is small, it will deflect more and

transfer more energy since the probability of energy transfer is inversely proportional to the square of the incoming particle velocity.

The maximum energy transfer, governed by the energy and momentum conservation laws, occurs during a head-on collision. It should, however, be mentioned that the head-on collision is a very rare event. The energy exchange depends directly on the masses of the incoming particle, m and the target, M; for example, when the mass of the incoming particle is smaller than the mass of the target nucleus the incoming particle is repelled

$$\frac{E'}{E} = \left(\frac{M-m}{M+m}\right)^2 \tag{5-148}$$

where E is the particle energy before the collision and E' the particle energy after the collision. From this relation it can be seen that when two masses are equal, the energy difference of the incoming particle, before and after the collision, is zero.

The incoming particle is thus stopped and all of its energy is transferred to the target nucleus. Conversely, if M >> m, the right hand side of Eq. (5-148) approaches unity and the energy of the incoming particle remains unchanged after the collision. Equation (5-148) suggests that in a collision of an α particle with a gold nucleus, as in Rutherford's experiment, the maximum energy that the α particle will lose is ~ 10%. The maximum energy that the target nucleus may receive (head–on collision) from an incoming charged particle of energy *E* is

$$E_{t \arg et} = E \frac{4Mm}{(M+m)^2}$$
 (5-149)

Since the incoming particles are usually much lighter than the target nuclei, the collision leads to a change of their directions while the change of their energies can almost be neglected.

2.1.2 Inelastic Scattering of Charged Particles with Electrons

In an inelastic scattering, the incoming particle may transfer all or part of its energy to the electrons in an atom. The energy transferred to the electrons may cause excitation of the electron or ionization of the atom. The excitation and ionization processes are described in Chapter 2. If the energy of incoming charged particle is larger than the binding energy of the electron it interacts with, then the collision is similar to elastic scattering. In this case, the probability of the angular deflection is proportional to the square of the target's charge. In the collision with an electron, the incoming particle is deflected at an angle which is a factor of $1/Z^2$ smaller than in a direct collision with a nucleus of charge Z.

2.1.3 Inelastic Scattering of Charged Particles with a Nucleus

When passing close to the nucleus, charged particles are attracted or repelled by the Coulomb force. The acceleration of a particle, a, is proportional to the charges of the nucleus and of the particle itself

$$a \propto \frac{Z_1 Z_2 e^2}{m} \tag{5-150}$$

This acceleration causes the particle to deflect from the original trajectory (see Fig. 5-2). An electron will, for example, deflect towards the nucleus, while an α particle will deflect away from the nucleus because of the opposite signs of their respective charges. According to classical electrodynamics, every charged particle that accelerates emits electromagnetic radiation with an intensity that is proportional to the square of the acceleration. Thus:

- The intensity of electromagnetic radiation decreases for heavier particles. For example, the intensity of this radiation for the α particles is a million times smaller than for electrons.
- The intensity of radiation is greater for heavier target materials.

This type of electromagnetic radiation is also called radiative loss, "bremsstrahlung" (German for *braking* radiation), or continuous X radiation. Quantum mechanics gives a correct interpretation of bremsstrahlung since it defines it as a quantum process in which an electron emits a photon. Bremsstrahlung photons have a continuous energy distribution that ranges from zero to a theoretical maximum that is equal to the kinetic energy of the β particle (electron). The emitted energy spectrum is in the range of X rays and the energy is higher for materials of higher Z. For example, since the use of light materials reduces bremsstrahlung, Plexiglas[®] is often used to shield against β radiation. The greatest bremsstrahlung occurs when high energy β particles interact with high density materials such as lead. In general, the probability of bremsstrahlung production increases with the energy of the incoming charged particle and the mass (charge) of the target material.

The bremsstrahlung hazard due to β particles of maximum energy *E* that interact with a target material with atomic number *Z* may be estimated from the following approximation

$$f = 3.5 \times 10^{-4} ZE \tag{5-151}$$

where f represents the fraction of incident β particle energy converted into bremsstrahlung photons.



Figure 5-2. Bremsstrahlung radiation

Example 5.1 Bremsstrahlung radiation

A 1 mCi ⁶⁰Co source is encapsulated in a spherical lead (atomic number 82) shield that has a thickness that is sufficient to stop all the β particles emitted by the source. Calculate the bremsstrahlung radiation flux as a function of distance outside the spherical shield. The maximum energy of emitted β particle is 0.3179 MeV.

The fraction of incident β particle energy that is converted into an X-ray in each decay of ⁶⁰Co is

$$f = (3.5 \times 10^{-4})(82)(0.3179 \text{ MeV}) = 0.009124$$

The source energy (S) of the photons is determined from the assumption that the average β energy is one-third of the spectrum's maximum value, $E_{\beta max} = 0.3179$ MeV. For the activity of the ⁶⁰Co source of A = 1 mCi

$$S = fA \frac{E_{\beta \max}}{3} = (0.009124) \left(10^{-3} Ci \times 3.7 \times 10^{10} \frac{\text{decays/sec}}{\text{Ci}} \right) \left(\frac{0.3179 \text{MeV/decay}}{3} \right)$$

S = 35,773 MeV/sec

It is important to mention that the maximum β energy spectrum value should be assumed for the photons whenever bremsstrahlung is considered in the radiation exposure of humans In other cases it sufficient to assume that each photon receives the average β energy. Thus, the photon generation rate if the maximum β energy is taken can be expressed as

 $\frac{35,773 \text{MeV/sec}}{0.3179 \text{MeV/photon}} = 1.125 \times 10^{5} \text{ photon/sec}$

Assuming a point ⁶⁰Co source, the bremsstrahlung flux as a function of distance from the spherical shield is

 $\phi(r) = \frac{1.125 \times 10^5 \,\text{photons/sec}}{4\pi r^2}$

2.2 Loss of Energy

The mechanisms by which charged particles transfer their energy in inelastic collisions with matter are expressed in one or more of the following forms: stopping power, relative stopping power, specific ionizations and loss of energy per ionization.

2.2.1 Stopping Power (-dE/dx)

Stopping power is defined as the amount of energy, dE, which a charged particle loses along the length of its path through matter, dx. This quantity always represents the average energy loss per number of interacting particles. It is proportional to the square of the charge of the incoming particle, Z_1^2 , and it is inversely proportional to its velocity; thus the stopping power increases as the particle velocity is decreased.

The value of -dE/dx along a particle track is also called *specific energy loss*, *S*, the rate of energy loss, or the linear energy transfer (LET). The classical formula that describes the specific energy loss is known as the *Bethe–Bloch Formula*, which is valid for all types of heavy charged particles with velocities that are large compared to orbital electron velocities.

The *Bethe–Bloch* formula has different forms for heavy and light charged particles:

• For heavy charged particles (α particles and protons):

$$-\frac{dE}{dx} = \frac{4\pi Z^2 e^4}{m_e v^2} NB$$

$$B = Z \left[\ln \frac{2m_e v^2}{I} - \ln(1 - \frac{v^2}{c^2}) - \frac{v^2}{c^2} \right]$$
(5-152)

v: velocity of the charged particle
Ze: charge of the charged particle
N: number density of the target
m_e: rest mass of the electron
I: experimentally evaluated average excitation and ionization potential (see Chapter 2)
B: stopping number

• For light charged particles (electrons and positrons):

$$-\frac{dE}{dx} = \frac{2\pi e^4}{m_e v^2} NB$$

$$B = \begin{bmatrix} \ln \frac{m_e v^2 E}{2I^2 (1 - \beta^2)} - (\ln 2) (\sqrt{1 - \beta^2} - 1 + \beta^2) + \\ 1 - \beta^2 + \frac{1}{8} (1 - \sqrt{1 - \beta^2})^2 \end{bmatrix}$$
(5-153)
$$\beta = v/c$$

For the charged particles with $v \ll c$ (non-relativistic particles) only the first term in the stopping number (B) equation is necessary. Equations (5-152) and (5-153) show that B varies slowly with particle energy and is proportional to the atomic number (Z) of the absorber material. Thus the stopping power varies as $1/v^2$, or inversely with particle energy.

The Bethe–Bloch formula also shows that higher–Z materials have greater stopping powers. The ionization/excitation parameter I is an experimentally determined value (see Section 2.2.4) and the ratio I/Z is approximately constant for absorbers with Z > 13. This ratio ranges from 10 eV for heavy elements to 15 eV for light elements (see Fig. 5-3).

The loss of energy due to ionization and excitation shows a general trend for all charged particles (see Fig. 5-4):

- For each charged particle, the maximum energy loss occurs at a characteristic incoming particle velocity.
- The stopping power then decreases to a minimum value on the order of



1 MeV for electrons and higher for heavier charged particles.

Figure 5-3. Average ionization and excitation potential as a function of Z



Figure 5-4. General trend of dE/dx as a function of particle energy E

2.2.2 Relative Stopping Power

The relative stopping power for a charged particle that interacts with a

given material is defined as the ratio of particle energy loss per atom of the given material to the energy loss per atom that will be experienced by the same particle in standard material (air for β particles or aluminum for α particles)

• Relative linear stopping power (MeV/cm)

$$S_{linear} = \frac{(dE \mid dx)_{material}}{(dE \mid dx)_{st}}$$
(5-154)

• Relative mass stopping power (MeV/g cm²)

$$S_{m} = \frac{\rho_{st} (dE / dx)_{material}}{\rho_{material} (dE / dx)_{st}}$$
(5-155)

• Relative stopping power per atom (MeV/atom cm)

$$S_{m} = \frac{N_{st} \left(dE / dx \right)_{material}}{N_{material} \left(dE / dx \right)_{st}}$$
(5-156)

• Relative stopping power per electron (MeV/electron cm)

$$S_{m} = \frac{N_{st} Z_{st} (dE / dx)_{material}}{N_{material} Z_{material} (dE / dx)_{st}}$$
(5-157)

Figures 5-5 to 5-7 illustrate the stopping power of aluminum for electrons, α particles, and protons.

2.2.3 Secondary Electrons

As a charged particle passes through a medium it ionizes some of the atoms by ejecting the electrons. This involves a transfer of energy from the charged particle to the electrons, which may receive sufficient kinetic energy to cause further ionizations. This process is known as secondary ionization. The total ionization is thus the sum of both primary and secondary processes.



Figure 5-5. Total mass stopping power of electron in aluminum (National Institute of Standards and Technology tables)



Figure 5-6. Total mass stopping power of α particle in aluminum (National Institute of Standards and Technology tables)



Figure 5-7. Total mass stopping power of proton in aluminum (National Institute of Standards and Technology tables)

The energy of secondary electrons ranges from zero to a theoretical maximum which depends on the mass and energy of the primary charged particle.

For example, in a collision between an α particle with energy *E* and mass m_{α} , and an electron of mass m_e , the maximum energy that the α particle can transfer to the electron, E_{target} , is given by Eq. (5-149)

$$E_{t \arg et} = E \frac{4m_{\alpha}m_{e}}{\left(m_{\alpha} + m_{e}\right)^{2}}$$

Since the mass of an electron is significantly less than the mass of an α particle, the above equation reduces to

$$E_{\text{target}} \approx E \frac{4m_{\alpha}m_e}{(m_{\alpha})^2} \approx 4E \frac{m_e}{m_{\alpha}} \approx 5.44 \times 10^{-4} E \text{ for } \alpha \text{ particles}$$
 (5-158)

It follows that the maximum energy an α particle can transfer to an electron is 0.0544% of the energy before the collision.

A 6 MeV α particle can transfer a maximum energy of 3.26 keV to an electron (where $m_e = 0.511 \text{ MeV}/c^2$ and $m_{\alpha} = 4 m_{\text{H}} = 4 \times 940 \text{ MeV}/c^2$). In a collision between two electrons in which both leave the atom, it is impossible to distinguish the primary electron from the secondary one. By

convention, the secondary electron is considered to be the one with lower energy or with energy below 50 eV. In general, the secondary electron yield is greater for targets of high atomic number. Secondary electrons with energies greater than a few hundred electron volts are referred to as delta rays or delta electrons, δ .

2.2.4 Specific Ionization and Ion Pairs

Specific ionization (SI) is defined as the total number of ionizations (ion pairs), both primary and secondary, formed per unit track length along a charged particle's path. In other words, it represents the number of ion pairs produced per unit track length. If W represents the average energy needed to create a single ion pair, the SI is defined as

$$SI = \frac{dE / dx}{W}$$
(5-159)

The unit of specific ionization is [number of ion pairs per unit track length] and W ranges from 22 eV to 46 eV. At high energies, W is nearly constant and has similar value for all incoming charged particles. For example, at 4 MeV α and β particles have nearly equal values for W. It has also been shown empirically that β particles have a constant W value for energies above a few keV. For α and β particles, the values for W increase at lower energies, since the probability for ionization is reduced. Table 5-1 shows some measured W values. The ionization density produced by a single charged particle depends on its charge and velocity. For example, a slower moving particle spends more time in the vicinity of an atom or molecule thereby increasing the chance of ionization events. Thus, an α particle creates thousands more ion pairs per centimeter than an electron (β particle) of the same energy (approximately 100 ion pairs per cm).

Material	Ion pair generation energy, $W(eV)$	lon pair generation energy, W(eV)		
Air	33.9			
Silicon (Si)	3.6			
Germanium (Ge)	2.8			
Silicon-oxide (SiO ₂)	17			
Hydrogen (H)	37			
Helium (He)	46			
Nitrogen (N)	36			
Oxygen (O)	32			
Neon (Ne)	37			

Table 5-1. Ion pair generation energy for different materials

Example 5.2 Ion pair production from α particle interaction

An α particle loses about 35.5 eV for each ion pair formed.

Calculate the number of ion pairs produced by an α particle with a kinetic energy of 5.5 MeV.

The number of ion pairs produced is

 $\frac{5.5 \times 10^6 eV}{35.5 eV / i.p.} = 154,930 \text{ ion pairs.}$

2.2.5 Range of Interactions

Heavy particles such as protons and α particles will deposit all their energies along a definite depth of penetration in a medium. This depth or distance is called the *range* of the particle and it depends on the energy and mass of the particle.

The range is longer for particles of higher energy and shorter for heavier particles. For example, consider two particles with the same kinetic energy; the heavier particle has a shorter range.

The range may either be defined as linear range (units of length) or the mass range (units of mass per area).

Theoretically, the range of a charged particle in a medium may be obtained from the integration of the inverse of a particles energy loss per unit length, *i.e.*

$$R(E_{in}) = \int_{0}^{E_{in}} \frac{dE}{dE/dx}$$
(5-160)

where dE/dx represents the total stopping power and the final particle velocity is assumed to be zero.

The evaluation of this term is complicated, especially for light charged particles (see Section 4.1), and its reciprocal is commonly assumed to go to zero at zero particle energy and increases linearly to the known value of least energy. The use of these assumptions in the calculation of range is referred to as the continuous slowing down approximation (CSDA).

Figures 5.8 show the ranges of a proton, electron and an α particle passing through aluminum. This illustrates the tendency of the CSDA range and its difference for light and heavy charged particles.



*Figure 5-8.*a) CSDA range of electron in aluminum (National Institute of Standards and Technology tables)



Figure 5-8. b) CSDA range of α particle in aluminum (National Institute of Standards and Technology tables)



Figure 5-8. c) CSDA range of proton in aluminum (National Institute of Standards and Technology tables)

Example 5.3 Ion–pair density from α particle interaction

If the range of an α particle is 10 cm, determine the average ion-pair density using data from Example 5.2.

The ion pair density is obtained as the ratio of the number of ion pairs produced to the length of track of the ionizing particle

 $\frac{154,930i.p.}{10cm} = 15,493 \text{ ion pairs per unit length (cm)}.$

3. ALPHA PARTICLES AND PROTONS

3.1 Mechanism of Energy Loss

The α particles have a short range and high specific ionization due to their large mass. The range may be only few centimetres in air down to a few microns in tissue. This indicates that a simple shielding from an external α emitter would be a single sheet of paper.

Since α particles have a strong ionizing effect on the medium they are passing through (see Examples 5.2 and 5.3), they are used as a basic *agent* in damaging cancer cells in a method called neutron capture therapy see Chapter 1).

When an α particle interacts with an atom, its electric field ejects electrons to form an ion pair. On average, an α particle loses about 35.5 eV for each ion pair formed. For example, in order to ionize a hydrogen atom, 13.6 eV energy is required. The excess energy, 21.9 eV, lost by the α particle is transferred to the electron as kinetic energy. Thus, the ejected electron is set into motion and can produce another ion pair or secondary electrons.

A fast moving α particle may lose energy without causing ionization as it passes through a medium. In such cases, the electrons do not receive sufficient energy to be ejected and they simply change orbits (moving to higher energy levels). Thus, the α particle caused only excitation of the medium and not ionization. The fast moving α particle has less time for interactions and the specific ionization consequently decreases at higher energies (see Fig. 5-9).



Figure 5-9. Specific ionization of α particle versus its energy

In other words, the specific ionization of a high-energy α particle will increase as the velocity decreases. This tendency of increasing ionization probability with the continuous slowing down of the α particle towards the end of its range is known as the Bragg curve and is illustrated in Fig. 5-10. As soon as the energy of the α particle drops below the energy required for ionization of the atoms in a medium, its ionization efficiency abruptly reduces to zero. The highest localized ionization energy deposition is expected around the Bragg peak.



Figure 5-10. Specific ionization of α particle versus its range

3.2 Range - Energy Relationship

The general expression for linear stopping power (linear energy loss) for a charged particle that is slowing down in a medium is the Bethe–Bloch formula (as discussed in Section 2.2.1). Since the energy loss is proportional to the square of the charge of the incoming particle, an α particle is expected to stop much faster than a proton in a given medium.

Semi-empirical formulas express the range of charged particles as a function of kinetic energy.

For α particles, the range in air at a temperature of 15°C and 760 mm pressure is given by the equations

$$R_{air}(\text{cm}) = \begin{cases} 0.56 \left(\frac{\text{cm}}{\text{MeV}}\right) E(\text{MeV}) & E < 4\text{MeV} \end{cases}$$
(5-161)
$$1.24 \left(\frac{\text{cm}}{\text{MeV}}\right) E(\text{MeV}) - 2.62(\text{cm}) & 4\text{MeV} < E < 8\text{MeV} \end{cases}$$

The range (expressed as density thickness) of an α particle in any other medium, R_m , is given by

Chapter 5

$$R_{m}(\text{cm}) = \frac{0.00056A^{1/3}}{\rho_{m}}R_{air}$$
(5-162)

where A is the atomic mass number of the medium, R_{air} is the range of the α particle in air, and ρ_m is the density of the medium.

The effective atomic composition of tissue is very similar to that of air and the Bragg–Kleeman rule (which states that the atomic stopping power is proportional to the square root of the atomic weight of the medium) gives the formula for the calculation of the range of α particles in tissue

 $R_{tissue}\rho_{tissue} = R_{air}\rho_{air} \tag{5-163}$

The density of air at standard pressure and temperature is $1.293 \times 10^{-3} \text{ g/cm}^3$.

The density of tissue is usually assumed to be that of water, *i.e.* 1.0 g/cm^3 .

The charged particle range is affected by the following factors

• Energy:

The range is approximately linear with energy since the Bethe–Bloch formula for stopping power is inversely proportional to E.

• Mass:

With the same kinetic energy, an electron is much faster than an α particle because of its smaller mass; therefore, incoming electrons spend less time near the orbital electrons. This reduces the effect of Coulomb interactions (consequently stopping power) and increases the range.

• Charge:

Stopping power increases with charge while the range decreases. Range is inversely proportional to the square of the charge of the incoming particle. For example, a tritium particle with Z=1 will have ¹/₄ the stopping power of a ³He particle with Z=2.

• Density:

Stopping power increases with density. The range is inversely proportional to the density of the absorbing medium.

The proton range in air is defined as

$$R_{air}(m) = \left[\frac{E_p(MeV)}{9.3}\right]^{1.8}$$
 for $E_p(few MeV \sim 200MeV)$ (5-164)

The range of protons in aluminum is given by the semi-empirical

formula

$$R_{Al}(\mu m) = \begin{cases} \frac{10.5E_p^2}{0.68 + 0.434 \ln(E_p)} & 2.7 \text{MeV} \le E_p \le 20 \text{MeV} \\ \\ 14.21E_p^{1.5874} & 1 \text{MeV} < E_p \le 2.7 \text{MeV} \end{cases}$$
(5-165)

The rate of energy loss for α particles and protons and their ranges are shown in Tables 5-2 to Table 5-5 for different materials and particle energies.

Data was taken from the National Institute of Standards and Technology ASTAR and PSTAR tables.

Example 5.4 Range of an α particle and shielding

Estimate the range of a 3 MeV α particle in air and tissue.

Calculate the linear aluminum thickness required to totally stop these α particles. Investigate the accuracy of by comparing with Table 5-3.

A density of aluminum is 2.7 g/cm³.

The range of a 3 MeV α particle in air is

$$R_{air}(cm) = 0.56(cm/MeV)E(MeV) = 1.68cm$$

From Table 5-3 the range of 3 MeV α particle in air is 2.116 x 10⁻³ g/cm² giving a linear range of 1.64cm.

The range of a 3 MeV α particle in tissue is

$$R_{tissue} = \frac{R_{air}\rho_{air}}{\rho_{tissue}} = 1.293 \times 10^{-3} R_{air} = (1.293 \times 10^{-3})(1.68 \text{cm}) = 0.0022 \text{cm}$$

Table 5-2. Total stopping power (MeV cm²/g) of α particles in different materials

α particle	Hydrogen	Air	Water	Tissue	Aluminum
energy					
(MeV)				_	
0.001	1.264E+03	2.215E+02	3.271E+02	3.688E+02	1.305E+02
0.005	1.136E+03	2.937E+02	3.667E+02	4.382E+02	2.095E+02
0.01	1.292E+03	3.625E+02	4.304E+02	5.227E+02	2.790E+02
0.05	2.746E+03	7.310E+02	8.230E+02	9.924E+02	6.444E+02
0.1	4.123E+03	1.031E+03	1.151E+03	1.375E+03	9.056E+02

α particle	Hydrogen	Air	Water	Tissue	Aluminum
energy					
(MeV)					
0.5	8.220E+03	1.964E+03	2.184E+03	2.698E+03	1.300E+03
1	7.167E+03	1.924E+03	2.193E+03	2.522E+03	1.226E+03
1.5	5.654E+03	1.626E+03	1.898E+03	2.062E+03	1.100E+03
2	4.593E+03	1.383E+03	1.625E+03	1.729E+03	9.859E+02
3	3.354E+03	1.072E+03	1.257E+03	1.324E+03	8.217E+02
4	2.678E+03	8.865E+02	1.035E+03	1.086E+03	6.991E+02
5	2.244E+03	7.612E+02	8.855E+02	9.267E+02	6.053E+02
10	1.284E+03	4.637E+02	5.344E+02	5.556E+02	3.762E+02
15	9.200E+02	3.425E+02	3.930E+02	4.070E+02	2.809E+02
20	7.245E+02	2.748E+02	3.146E+02	3.250E+02	2.272E+02

Table 5-3. CSDA range (g/cm²) of α particles in different materials

α particle	Hydrogen	Air	Water	Tissue	Aluminum
energy					
(MeV)					
0.001	7.480E-07	5.377E-06	3.273E-06	2.985E-06	9.964E-06
0.005	4.230E-06	2.079E-05	1.489E-05	1.292E-05	3.329E-05
0.01	8.380E-06	3.605E-05	2.746E-05	2.334E-05	5.381E-05
0.05	2.882E-05	1.097E-04	9.179E-05	7.632E-05	1.418E-04
0.1	4.344E-05	1.665E-04	1.425E-04	1.186E-04	2.059E-04
0.5	1.034E-04	4.188E-04	3.699E-04	3.063E-04	5.421E-04
1	1.671E-04	6.698E-04	5.931E-04	4.922E-04	9.343E-04
1.5	2.459E-04	9.520E-04	8.374E-04	7.118E-04	1.365E-03
2	3.445E-04	1.287E-03	1.123E-03	9.777E-04	1.845E-03
3	6.030E-04	2.116E-03	1.829E-03	1.646E-03	2.961E-03
4	9.391E-04	3.147E-03	2.711E-03	2.485E-03	4.283E-03
5	1.349E-03	4.368E-03	3.759E-03	3.485E-03	5.825E-03
10	4.424E-03	1.309E-02	1.130E-02	1.072E-02	1.666E-02
15	9.097E-03	2.581E-02	2.236E-02	2.138E-02	3.224E-02
20	1.527E-02	4.222E-02	3.668E-02	3.523E-02	5.216E-02

Table 5-4. Total stopping power (MeV cm²/g) of protons in different materials

Proton	Hydrogen	Air	Water	Tissue	Aluminum
energy					
(MeV)					
0.001	9.730E+02	1.414E+02	1.769E+02	2.180E+02	1.043E+02
0.005	1.741E+03	2.776E+02	3.153E+02	4.067E+02	2.131E+02
0.01	2.402E+03	3.850E+02	4.329E+02	5.620E+02	2.966E+02
0.05	3.818E+03	6.897E+02	7.768E+02	9.887E+02	4.749E+02
0.1	3.493E+03	7.301E+02	8.161E+02	1.004E+03	4.477E+02
0.5	1.160E+03	3.501E+02	4.132E+02	4.395E+02	2.550E+02
1	6.771E+02	2.229E+02	2.608E+02	2.737E+02	1.720E+02
1.5	4.902E+02	1.683E+02	1.957E+02	2.045E+02	1.328E+02
2	3.885E+02	1.371E+02	1.586E+02	1.653E+02	1.095E+02
3	2.788E+02	1.018E+02	1.172E+02	1.217E+02	8.250E+01
4	2.197E+02	8.197E+01	9.404E+01	9.738E+01	6.707E+01
5	1.825E+02	6.909E+01	7.911E+01	8.174E+01	5.695E+01

Proton	Hydrogen	Air	Water	Tissue	Aluminum
energy					
_(MeV)					
10	1.019E+02	4.006E+01	4.567E+01	4.692E+01	3.376E+01
15	7.239E+01	2.894E+01	3.292E+01	3.373E+01	2.466E+01
20	5.679E+01	2.294E+01	2.607E+01	2.667E+01	1.969E+01
					· · · · · · · · · · · · · · · · · · ·
Table 5-5. CS	SDA range (g/cm	n ²) of protons in	different materia	als	
Proton	Hydrogen	Air	Water	Tissue	Aluminum
energy					
(MeV)					
0.001	1.091E-06	9.857E-06	6.319E-06	5.418E-06	1.471E-05
0.005	4.058E-06	2.891E-05	2.262E-05	1.825E-05	3.981E-05
0.01	6.473E-06	4.400E-05	3.599E-05	2.857E-05	5.943E-05
0.05	1.849E-05	1.152E-04	9.935E-05	7.769E-05	1.560E-04
0.1	3.194E-05	1.842E-04	1.607E-04	1.268E-04	2.632E-04
0.5	2.598E-04	1.021E-03	8.869E-04	7.801E-04	1.503E-03
1	8.476E-04	2.867E-03	2.458E-03	2.270E-03	3.945E-03
1.5	1.728E-03	5.479E-03	4.698E-03	4.410E-03	7.287E-03
2	2.883E-03	8.792E-03	7.555E-03	7.147E-03	1.146E-02
3	5.968E-03	1.737E-02	1.499E-02	1.429E-02	2.210E-02
4	1.004E-02	2.839E-02	2.458E-02	2.355E-02	3.563E-02
5	1.506E-02	4.173E-02	3.623E-02	3.481E-02	5.188E-02
10	5.346E-02	1.408E-01	1.230E-01	1.191E-01	1.705E-01
15	1.126E-01	2.899E-01	2.539E-01	2.467E-01	3.462E-01
20	1.913E-01	4.855E-01	4.260E-01	4.147E-01	5.748E-01

The tabulated value shown in Table 5-3 is 0.0018 cm. The aluminum thickness required to totally stop a 3 MeV α particle is

$$R_{Al}(\text{cm}) = \frac{0.00056A^{1/3}}{\rho_m} R_{air} = \frac{0.00056(27)^{1/3}}{2.7g/\text{cm}^3} (1.68\text{cm}) = 0.00105\text{cm}$$

This is in good agreement with the value given in Table 5-3 (0.002961 / 2.7 = 0.001cm).

Example 5.5 Range of proton

Estimate the range of a 3 MeV proton in air and aluminum. Compare this value to the value given in Table 5-5. The range of 3 MeV proton in air is

$$R_{air}(\mathbf{m}) = \left[\frac{E_p(\mathrm{MeV})}{9.3}\right]^{1.8} = \left[\frac{3}{9.3}\right]^{1.8} = 0.130\mathrm{m}$$

The range of 3 MeV proton in aluminum is

$$R_{Al}(\mu m) = \frac{10.5E_{p}^{2}}{0.68 + 0.434\ln(E_{x})} = \frac{10.5(3)^{2}}{0.68 + 0.434\ln(3)} = 0.0082 \text{ cm}$$

Table 5-5 gives a range of 13.4 cm in air and 0.0082 cm in aluminum for a 3 MeV proton.

4. BETA PARTICLES (ELECTRONS AND POSITRONS)

4.1 Mechanism of Energy Loss

The mechanism of energy loss and the type of interactions for β particles in matter are more complex than for α particles due to the smaller mass and higher speed. Beta particles are emitted during the decay of radionuclides with a continuous energy spectrum with a maximum energy that is characteristic of the radionuclide (see Chapter 4). This maximum value is taken as the total transition energy. The difference between this maximum value and the emitted β particle energy is carried off by an electrically neutral particle. The maximum energy for β radiation from the majority of radionuclides is in the range of 0.5 to 3.5 MeV. When passing through a medium, the β particles interact with atomic nuclei and electrons; the β particle range is not as well defined as for α particles. This is due to the combined effect of the continuous energy spectrum and the scattering characteristics. The characteristics of the range are described in Section 4.2.

The loss of β particle energy in a medium consists of two components. The total stopping power (energy loss) is expressed as a summation of the two terms

- The collision term, $(dE/dx)_{coll}$, represents the energy loss due to Coulomb interactions (ionization and excitation).
- The radiative term, $(dE/dx)_{rad}$, accounts for the energy loss due to bremsstrahlung, Cerenkov radiation, or nuclear interactions.

Therefore, the total stopping power (as illustrated in Fig. 5-11) is written

as

$$\frac{dE}{dx} = \left(\frac{dE}{dx}\right)_{coll} + \left(\frac{dE}{dx}\right)_{rad}$$
(5-166)

where the collision term is referred to as the linear energy transfer (LET), *i.e.* the linear rate of energy loss of a β particle due to ionization and excitation (see Section 2.2.1). The LET is related to the local energy deposition while the radiative stopping power takes into account the total energy loss due to bremsstrahlung radiation and the formation of secondary and δ electrons. The collision term and total stopping power are nearly equal for heavy charged particles (see Figures 5-12 and 5-13). Notice that in the case of heavy charged particles, the collision stopping power is called *electronic stopping power*. It is also important to note that the nuclear stopping power is only significant for heavy charged particles and it represents an average rate of energy loss per unit path length due to the transfer of energy to recoiling atoms in elastic collisions.

Except for highly relativistic electrons, ionization and excitation are the main forms of energy loss, which may therefore be calculated with the Bethe–Bloch equation.



Figure 5-11. Components of total stopping powers for electrons in aluminum (National Institute of Standards and Technology tables)



Figure 5-12. Components of total stopping powers for α particle in aluminum (National Institute of Standards and Technology tables)



Figure 5-13. Components of total stopping powers for proton in aluminum (National Institute of Standards and Technology tables)

The general form of this equation is described in Section 2 for the different types of particles. The condensed form of this equation for the ionization and excitation energy loss of electrons can be written as

$$-\left(\frac{dE}{dx}\right)_{coll} = \rho \frac{Z}{A} f_{coll}(I,\beta)$$
(5-167)

The equation illustrates the following:

- The collision energy loss is proportional to the electron density in the medium, ρ, and the ratio Z/A, where Z is the atomic number of a medium and A its atomic weight. This ratio varies slowly with increasing Z (for example the ratio is 0.5 for low Z materials and reduces to ~ 0.39 for uranium).
- For electron energies up to 1 MeV, the collision term of the total stopping power decreases due to the increase of the β = υ/c term. The collisional stopping power decreases as 1/β² for increasing velocity until it reaches a minimum value at electron energy of about 1.5 MeV (see Fig. 5-14). For higher electron energies where β ~ 1, the energy loss due to ionization and excitation increases logarithmically (relativistic rise) until it reaches a constant value (Fermi plateau).
- As discussed in Chapter 2, the ionization potential (*I*) increases with *Z*; but loses significance due to the logarithmic dependence in the collision stopping power equation. However, as illustrated in Fig. 5-14, the loss of energy decreases with increasing *Z* of a medium.



Figure 5-14. Energy loss of electrons due to ionization and excitation (collision term) in air, aluminum, lead and tissue (National Institute of Standards and Technology ESTAR tables)

For electron energies above a few MeV, an additional density-effect correction is required. This accounts for the reduction in the collision stopping power due to the incident electron's polarization of the medium. Descriptions of the average radiative loss of electron energy in the form of bremsstrahlung radiation are only approximate. Although there are no adequate equations to express the radiative stopping power over a wide range of electron energies, a general equation can be used

$$-\left(\frac{dE}{dx}\right)_{rad} = \frac{Z^2 \rho}{A} \left(E + m_e c^2\right) f_{rad}(E, Z)$$
(5-168)

From this equation and the trends illustrated in Fig. 5-15 (radiative stopping power curves for various materials), the following is understood about the radiative stopping power

- It is proportional to Z^2 and as a result the radiative stopping power becomes comparable to the collision term for higher Z.
- It is proportional to the electron energy, *E*, and as a result it becomes comparable to the energy loss in ionization and excitation at specific electron energy values. At even higher energy values it begins to exceed these competing energy loss contributors.



Figure 5-15. Energy loss of electrons due to radiative processes (radiative term) in, air, aluminum, lead and tissue (National Institute of Standards and Technology ESTAR tables)

For relativistic electron energies the ratio of the radiative and the collision stopping power becomes

$$\frac{-(dE/dx)_{rad}}{-(dE/dx)_{coll}} \approx \frac{EZ}{F}$$
(5-169)

where *E* is in MeV and *F* has a value of 700 for lighter elements and 800 for higher *Z* materials (see Example 5.6). The above relations can be generalized for any charged particle of rest mass *M* and energy $E >> Mc^2$

$$\frac{-\left(dE/dx\right)_{rad}}{-\left(dE/dx\right)_{coll}} \approx \frac{EZ}{F} \left(\frac{m_e}{M}\right)^2$$
(5-170)

For example, this ratio is equal to one, that is the bremsstrahlung and ionization/excitation energy losses become equal, at electron energy of 47 MeV in aluminum and 7 MeV in lead (see Fig. 5-16).



Figure 5-16. Collision and radiative energy losses of electrons (National Institute of Standards and Technology ESTAR tables) in water

Example 5.6 Energy loss of an electron to bremsstrahlung and ionization and excitation

Estimate the energy at which an electron will start losing its energy equally in both bremsstrahlung and ionization/excitation while moving through lead (Z = 82) and water. Compare the results with the Fig. 5-16.

Lead

$$\frac{-(dE/dx)_{rad}}{-(dE/dx)_{coll}} = 1 \approx \frac{EZ}{800} \implies E = 9.76 \text{MeV}$$

which is in good agreement with ~ 10 MeV shown in Fig. 5-16.

• Water

$$\frac{-(dE/dx)_{rad}}{-(dE/dx)_{coll}} = 1 \approx \frac{EZ}{700} \implies E = 53.8 \text{MeV}$$

This is in good agreement with the value of ~ 52 MeV shown in Fig. 5-16.

4.2 Range - Energy Relationship

As β particles travel through a medium, their interactions with atomic nuclei and electrons cause them to deflect from their initial trajectory. The resulting trajectory depends on the medium and the energy of the β particle. The range is defined as the average distance along the trajectory that the β particle travels in the medium. Unlike heavy charged particles, light particles have no definite range. Since the mass of a β particle is much smaller than the mass of an atom, it is deflected considerably in elastic scattering with the atoms. The probability of deflection is inversely proportional to the square of the energy and as a result low–energy β particles are deflected more than high–energy. That is, β particles with energy above a few MeV will pass through material in almost a straight line. The deflection also depends strongly on material and is approximately proportional to Z^2 . Thus, the β particle trajectory is expected to be a nearly–straight line in light materials and very erratic line in heavy materials. It can be concluded that the trajectory of β particles

- is nearly a straight line for energies above 1 MeV. With decreased energy of β particles the deflection is more pronounced and particles start to diffuse in a medium.
- fluctuates along the trajectory more than heavy particles.
- the depth of penetration for most of the β particles is smaller than the length of range.

The range of β particles in material is a complex function of their energy, the type and the atomic number of the absorber material. From the macroscopic point of view the absorption of β particles is a function of distance travelled and the density of material. It has been observed that the absorption (attenuation of β particle beam, see Fig. 5-17) in the absorber is approximately exponential function of the density of the absorber (ρ), distance through the absorber (x) and the absorbing property of the material (μ). Thus the absorption is approximately similar to that of photon beam: ln(I/I_o) = ($x\rho$)(μ/ρ) However due to multicollision nature of β particle interactions with absorber the absorption curve does not follow exactly the exponential decline in beam intensity:

- The ionization caused by β particles falls off exponentially with distance.
- For thick absorbers the absorption curve (curve of activity versus the absorber thickness as sketched in Fig. 5-17) becomes almost horizontal indicating a nearly constant absorption, *i.e.* ionization occurs. Thick absorbers are expected to stop all incoming β particles while only a part of the β particle energy is lost in thin absorbers.



Figure 5-17. Beta particles attenuation and the absorption curve

- The absorption depth (range) depends on β particle energy as well; for example, very high energy β particles can penetrate to a depth of about one centimeter in tissue.
- The "tail" at the end of the absorption curve indicates the presence of bremsstrahlung radiation. This is especially prevalent in materials with high atomic number such as lead. Even though high atomic number materials are the most effective in stopping high energy β particles, the presence of bremsstrahlung makes lighter materials such as Lucite or plywood a better choice as absorber materials.
- Although β particles do not have definite range it is possible to specify an absorber thickness that will reduce the ionization to a *zero* level.
- Given the complexity of β interactions and the β spectrum it is difficult to develop theoretical range-energy dependence. As a result experimental energy-range measurements are used to approximate the range of β particles. Fig. 5-18 shows the range-energy curve and equations that may be used to compute the range. The range is often
expressed in terms of the mass thickness rather than linear distance because mass thickness is independent of the material density. The mass thickness is given in mg/cm^2 . The linear thickness (range) in cm is obtained by dividing the mass thickness with the density of absorber.



Figure 5-18. Range–energy curve for β particle transport

-1121712 , $7^{\circ}17$, 101111 , 30017171112 , 1071004 , 0111727 , 1071012 , 101101000 , 1110101010 , 1110101010 , 1110101000 , 1110101000 , 111010000 , 111010000 , 1110000 , 1110000 , 1110000 , 1110000 , 1100000 , 110000 , 100000 , 100000 , 100000 , 100	Table 5-6.	Fotal stopping	power (MeV	cm^2/g) for (B particles in	different	material
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Electron	Hydrogen	Air	Water	Tissue	Aluminum
energy					
(MeV)					
0.01	5.124E+01	1.976E+01	2.256E+01	2.257E+01	1.650E+01
0.05	1.424E+01	5.822E+00	6.607E+00	6.597E+00	5.046E+00
0.1	8.738E+00	3.637E+00	4.119E+00	4.111E+00	3.185E+00
0.5	4.196E+00	1.809E+00	2.041E+00	2.034E+00	1.604E+00
1.0	3.821E+00	1.674E+00	1.862E+00	1.851E+00	1.486E+00
1.5	3.796E+00	1.680E+00	1.841E+00	1.829E+00	1.491E+00
2	3.835E+00	1.711E+00	1.850E+00	1.838E+00	1.518E+00
3	3.943E+00	1.783E+00	1.889E+00	1.876E+00	1.580E+00
4	4.047E+00	1.850E+00	1.931E+00	1.917E+00	1.637E+00
5	4.140E+00	1.911E+00	1.971E+00	1.957E+00	1.690E+00
10	4.479E+00	2.159E+00	2.149E+00	2.131E+00	1.921E+00
15	4.714E+00	2.359E+00	2.306E+00	2.283E+00	2.134E+00
20	4.903E+00	2.539E+00	2.454E+00	2.425E+00	2.340E+00

The total stopping power and the CSDA range for electrons in various materials are shown in Table 5-6 and 5-7 respectively (data is from the ESTAR tables of the National Institute for Standards and Technology).

Electron	Hydrogen	Air	Water	Tissue	Aluminum
energy					
(MeV)					
0.01	1.076E-04	2.884E-04	2.515E-04	2.512E-04	3.539E-04
0.05	1.970E-03	4.913E-03	4.320E-03	4.324E-03	5.738E-03
0.1	6.650E-03	1.623E-02	1.431E-02	1.433E-02	1.872E-02
0.5	8.480E-02	1.995E-01	1.766E-01	1.770E-01	2.260E-01
1.0	2.117E-01	4.912E-01	4.367E-01	4.385E-01	5.546E-01
1.5	3.433E-01	7.901E-01	7.075E-01	7.110E-01	8.913E-01
2	4.744E-01	1.085E+00	9.785E-01	9.839E-01	1.224E+00
3	7.316E-01	1.658E+00	1.514E+00	1.523E+00	1.869E+00
4	9.819E-01	2.208E+00	2.037E+00	2.050E+00	2.491E+00
5	1.226E+00	2.740E+00	2.550E+00	2.566E+00	3.092E+00
10	2.383E+00	5.192E+00	4.975E+00	5.011E+00	5.861E+00
15	3.470E+00	7.405E+00	7.219E+00	7.276E+00	8.328E+00
20	4.510E+00	9.447E+00	9.320E+00	9.401E+00	1.056E+01

Table 5-7. CSDA range (g/cm^2) for β particles in different materials

Example 5.7 Range of β particles

Calculate the distance a β particle will travel in aluminum ($\rho = 2.7 \text{ g/cm}^3$) as it slows down from 15 MeV to 0.5 MeV. What is the average linear stopping power?

Table 5-7 gives the CSDA mass range values and the resulting linear distances are

$$R(15 \text{MeV}) = (8.328 \text{g/cm}^2) / (2.7 \text{g/cm}^3) = 3.084 \text{cm}$$
$$R(0.5 \text{MeV}) = (0.226 \text{g/cm}^2) / (2.7 \text{g/cm}^3) = 0.084 \text{cm}$$

Thus the β particle travels 3.084 - 0.084 = 3.0 cm in aluminum while it deposits an energy of 14.5 MeV. The average stopping power is obtained as:

 $\frac{dE}{dx} = \frac{14.5 \text{MeV}}{3.0 \text{cm}} = 4.833 \text{MeV/cm}$

Example 5.8 Energy deposition in tissue cell

Using the data provided for the CSDA range for 1.5 MeV α and β particles in Tables 5-3 and 5-7 respectively, comment on the liner ranges in a human tissue cell. Assume the radius of a human cell is 15 μ m with the density of 1 g/cm³.

The ranges are:

α particle

$$R = (7.840 \times 10^{-4} \text{ g/cm}^2) / (1 \text{ g/cm}^3) = 7.84 \times 10^{-4} \text{ cm} = 7.84 \mu \text{m}$$

β particle

 $R = (0.711 \text{g/cm}^2) / (1 \text{g/cm}^3) = 0.711 \text{cm}$

It can be seen that a 1.5 MeV α particle travels only 7.84 μ m and thus deposits all of its energy inside the cell volume, while the β particle leaves the cell and will deposit its energy over a much longer range. In boron neutron capture therapy for brain cancer treatments, the α particle emitted in boron-neutron interaction has the energy of nearly 1.5 MeV and because of its short range represents the key agent in killing the cancer cells.

Example 5.9 Summation of ranges in different materials

The range of an unknown β particle is measured to be 0.111 mm in aluminium. Calculate the energy of the β particle if the β emitter is placed in air at 1cm from the aluminium sheet and with a 1.7 mg / cm² mica absorber between the counter and the aluminium sheet.

Summation of ranges is allowed if the ranges are expressed as density thicknesses:

• Air

$$R_{air} = 1.293 \text{ mg/cm}^3 \times 1 \text{ cm} = 1.293 \text{ mg/cm}^2$$

Aluminum

$$R_{Al} = 2.7 \text{g/cm}^3 \times 0.0111 \text{cm} = 29.97 \text{mg/cm}^2$$

• Mica

$$R_{mica} = 1.7 \,\mathrm{mg/cm^2}$$

Thus, the total range is

$$R_{total} = 1.293 \text{ mg/cm}^2 + 29.97 \text{ mg/cm}^2 + 1.7 \text{ mg/cm}^2 = 32.96 \text{ mg/cm}^2$$

Fig.5-18 shows that this range corresponds to energy of 0.17 MeV.

5. PHOTONS (GAMMA AND X - RAYS)

5.1 Exponential Absorption Law

Many nuclear reactions, radioactive decays, and particle interactions result in the emission of gamma (γ) rays, the highest–energy electromagnetic waves (or photons). Their energies range from thousands of electron volts (keV) to millions of electron volts (MeV) and their wavelengths are very short (10⁻¹¹ m to 10⁻¹³ m). These high–energy particles have found application in the medical profession, especially in cancer treatments.

As explained in previous sections both α and β radiation can be completely absorbed by properly selected materials and their thicknesses. Gamma radiation, however, can only be reduced in intensity. This intensity reduction or attenuation is governed by the exponential absorption law

$$I = I_0 e^{-\mu_l x_l}$$
(5-171)

where

I: γ -ray intensity transmitted through an absorber of thickness x

 I_0 : γ -ray intensity at zero absorber thickness

 x_l : linear absorber thickness

 μ_l : linear absorption coefficient.

The linear absorption coefficient is related to the mass absorption coefficient, μ_m , through the density of the absorber materials, ρ

$$\mu_{l}(cm^{-1}) = \mu_{m}(cm^{2}/g) \times \rho(g/cm^{3})$$
(5-172)

If the mass thickness, x_m , is defined as the mass per unit area obtained by multiplying the linear thickness x_l by the density ($x_m = \rho x_l$), then the exponential absorption law can be written in the following way

$$I = I_0 e^{-\mu_l x_l} = I_0 e^{-(\mu_l / \rho) x_m}$$
(5-173)

and μ_i / ρ can be obtained from empirical measurements of I_0 , I and x. These values are tabulated for different materials and photon energies. Figures 5-19 a) and b) show the mass absorption coefficient for aluminum and lead, respectively.

The *total absorption coefficient* or *attenuation coefficient* represents the fraction of the γ ray beam attenuated per unit thickness of absorber.



Figure 5-19.a) Mass absorption coefficient for y rays in aluminum



Figure 5-19.b) Mass absorption coefficient for γ rays in lead

The *atomic absorption coefficient*, μ_a , is the fraction of an incident γ ray beam that is absorbed by a single atom, *i.e.* the probability that an absorber atom will interact with the γ rays in the incoming beam. If N is the number of absorber atoms per cm³, the atomic absorption coefficient is

$$\mu_a = \frac{\mu_l}{N} \equiv \sigma \; (\frac{\mathrm{cm}^2}{\mathrm{atom}}) \tag{5-174}$$

The atomic absorption coefficient has units of area and is thus referred to as the "cross section" of the absorber (for the discussion on the cross section see Chapter 6). The atomic absorption coefficient is called the microscopic cross section (σ), while the linear absorption coefficient is called macroscopic cross section (Σ). The microscopic cross section may be expressed in barns (1 barn = 10⁻²⁴ cm²) while the unit of the macroscopic cross section is cm⁻¹. These two cross sections are related as

$$\Sigma(\text{cm}^{-1}) = \sigma(\frac{\text{cm}^2}{\text{atom}}) \times N(\frac{\text{atoms}}{\text{cm}^3})$$
(5-175)

Thus the attenuation of γ rays can be expressed in terms of cross sections

$$I = I_0 e^{-\mu_a N x_i} = I_0 e^{-\Sigma x_i}$$
(5-176)

Gamma ray interaction data is usually expressed as mass attenuation coefficients (examples shown graphically in Fig. 5-19 and values given in Table 5-8). Neutron interaction data are usually expressed as cross sections.

	ata base				
Photon	Hydrogen	Air	Water	Tissue	Aluminum
energy					
(MeV)					
0.01	2.954E.01	5 12012 00	5 220É 100	4.027E+00	2 622 E 101
0.01	3.854E-01	5.120E+00	5.529E+00	4.93/E+00	2.0236+01
0.05	3.355E-01	2.080E-01	2.269E-01	2.223E-01	3.681E-01
0.1	2.944E-01	1.541E-01	1.707E-01	1.688E-01	1.704E-01
0.5	1.729E-01	8.712E-02	9.687E-02	9.593E-02	8.445E-02
1.0	1.263E-01	6.358E-02	7.072E-02	7.003E-02	6.146E-02
1.5	1.027E-01	5.175E-02	5.754E-02	5.699E-02	5.006E-02
2	8.769E-02	4.447E-02	4.942E-02	4.893E-02	4.324E-02
3	6.921E-02	3.581E-02	3.969E-02	3.929E-02	3.541E-02
4	5.806E-02	3.079E-02	3.403E-02	3.367E-02	3.106E-02
5	5.049E-02	2.751E-02	3.031E-02	2.998E-02	2.836E-02
10	3.254E-02	2.045E-02	2.219E-02	2.191E-02	2.318E-02
15	2.539E-02	1.810E-02	1.941E-02	1.913E-02	2.195E-02
20	2.153E-02	1.705E-02	1.813E-02	1.785E-02	2.168E-02

Table 5-8. γ rays mass attenuation (absorption) coefficients (cm²/g) from the NIST X ray attenuation data base

The energy absorption coefficients shown in Fig. 5-19 are the total absorption coefficients and they account for both primary and secondary radiation. Primary radiation considers the local energy deposition during the

photon interactions with matter, while secondary radiation considers the energy deposited elsewhere via secondary radiation such as Compton scattered photons, bremsstrahlung, fluorescence, and annihilation photons.

For a mixture or composite materials, the mass attenuation coefficient, $\mu_{m-mixture}$, is the weighted average of the individual mass coefficients, μ_{mi} .

$$\mu_{m-mixture} = w_1 \mu_{m1} + w_2 \mu_{m2} + \dots \tag{5-177}$$

Example 5.10 Attenuation of γ rays

Calculate the linear and density thickness of aluminium and lead needed to transmit not more than 5 % of a 0.60 MeV γ ray beam and compare the density thicknesses. The density of aluminium is 2.7 g/cm³ and the density of lead is 11.35 g/cm³. The mass absorption coefficients are: 7.802 x 10⁻² cm²/g for aluminum and 0.1248 cm²/g for lead.

• Aluminum linear thickness

$$\mu_{l}(\text{cm}^{-1}) = \mu_{m}(\text{cm}^{2}/\text{g}) \times \rho(\text{g/cm}^{3}) = 0.07802 \times 2.7 = 0.2107 \text{cm}^{-1}$$
$$\frac{I}{I_{0}} = \frac{5}{100} = e^{-\mu_{l}x_{l}} \implies x_{l} = 14.22 \text{cm}$$

Density thickness

$$x_d = x_l \times \rho = 14.22 \times 2.7 = 38.4 g / cm^2$$

Lead linear thickness

$$\mu_{l}(cm^{-1}) = \mu_{m}(cm^{2}/g) \times \rho(g/cm^{3}) = 0.1248 \times 11.35 = 1.416cm^{-1}$$
$$\frac{I}{I_{0}} = \frac{5}{100} = e^{-\mu_{l}x_{l}} \implies x_{l} = 2.115cm$$

Density thickness

$$x_d = x_l \times \rho = 2.115 \times 11.35 = 24.0$$
g/cm²

Example 5.11 Attenuation coefficient and cross section for $\boldsymbol{\gamma}$ ray interactions

Knowing that the linear absorption coefficient represents the macroscopic cross

section for γ ray interactions that is predominantly with the electrons of an atom, calculate the microscopic cross section for lead if the mass attenuation coefficient for 0.6 MeV γ ray is 0.1248 cm²/g (density of lead is 11.35 g/cm³). The atomic weight of the lead is 207.2.

$$\mu_{i}(\text{cm}^{-1}) = \mu_{m}(\text{cm}^{2}/\text{g}) \times \rho(\text{g/cm}^{3}) = 0.1248 \times 11.35 = 1.416 \text{cm}^{-1}$$
$$\mu_{i} = N\sigma \equiv \Sigma \quad \Rightarrow$$
$$\sigma = \frac{\mu_{i}}{N} = \frac{\mu_{i}}{N_{a}Z\rho/A} = \frac{1.416}{6.02 \times 10^{23} \times 82 \times 11.35/207.2}$$
$$\sigma = 0.524 \text{ b}$$

Example 5.12 Attenuation of γ rays in a composite material

The soft tissue can be approximated as a mixture of four elements: 10.1174 % of hydrogen, 11.1 % of carbon, 2.6 % of nitrogen and 76.1826 % of oxygen. This composition gives a soft tissue density of 1 g/cm³. Determine the linear attenuation coefficient for 0.6 MeV γ rays for which the mass attenuation coefficients in these four elements are: 0.1599 cm²/g in hydrogen, 0.08058 cm²/g in carbon, 0.08063 cm²/g in nitrogen, and 0.08070 cm²/g in oxygen.

The general definition for the total mass attenuation coefficient for the mixture

$$\mu_{m-tissue} = w_H \mu_{mH} + w_C \mu_{mC} + w_N \mu_{mN} + w_O \mu_{mO}$$

 $\mu_{m-tissue} = 0.101174 \times 0.1599 + 0.111 \times 0.08058 + 0.026 \times 0.08063 + 0.761826 \times 0.08070 = 0.088698 \text{cm}^2/\text{g}$

 $\mu_{l-tissue} = \mu_{m-tissue} \times \rho_{tissue} = 0.088698 \times 1.0 = 0.088698 \text{cm}^{-1}$

5.2 Mechanism of Energy Loss

Photons are energy quanta of electromagnetic nature and interact with particles that have electrical charge or, with smaller probability, with particles that behave as small magnets (possess magnetic momentum). The main interactions of photons with matter are with the electrons and nuclei through

- Absorption of photons: in this interaction the initial photon disappears as it transfers all of its energy to an electron or nucleus.
- Scattering of photons: photon can be scattered through an elastic or inelastic interaction. In elastic scattering, the wavelength of the scattered photon is almost the same as that of the initial photon. If the interaction leads to interference, it is referred to as coherent scattering. In inelastic, incoherent scattering the initial photon transfers its energy to the matter and scatters with a longer wavelength.

The types of photon interactions are summarized in Table 5-9 and show that photoelectric absorption and Compton scattering are interactions that are limited to the orbital electrons of the absorber. These interactions are probable for incident photon energies less than or not significantly higher than the energy equivalent of the rest mass for two electrons (1.022 MeV). Pair production dominates in the energy range above this threshold.

Tuble 5-9. Types of ph	oton interactions		
Interaction with	Absorption	Elastic scattering	Inelastic scattering
Electrons in atoms	Photoelectric effect	Rayleigh scattering	Compton scattering
Electromagnetic field of a nucleus or electron	Pair production		
electron	····		

Table 5-9. Types of photon interactions

5.2.1 Photoelectric Effect (γ + atom \rightarrow e⁻ + ion)

In 1886, Heinrich Hertz discovered that photons in the ultraviolet region of the spectrum (wavelengths of 200-400 nm) could eject electrons from a metal surface (see Fig. 5-20). The experiment showed that the emission of electrons and the incoming light had certain dependencies

- The number of electrons emitted by the metal was found to directly depend on the intensity of the light, i.e. the number of emitted electrons increased with increasing light intensity.
- The emitted electrons moved faster if the light had a higher frequency.
- There was a cut-off frequency, f_c , for the incident photons, below which no electrons were emitted.

According to classical mechanics and the wave theory of light that was valid at the time, it was expected that the intensity of the emitted light would determine the kinetic energy of the ejected electrons. The experiments, however, showed that the kinetic energy of the ejected electrons depended on the incoming photon frequency instead of its intensity. The photon intensity thus only affected the number of ejected electrons and not their kinetic energies. This was the discovery of a new phenomenon called the photoelectric effect and it was defined as the emission of electrons from a metal surface exposed to photon radiation. The full physical explanation of the phenomenon was given in 1905 by Albert Einstein who applied Planck's idea of energy quanta and additionally assumed that the light had particle properties. He proved that the incoming photon could be represented as discrete quanta of energy, hf, where f is the photon frequency and h Planck's constant (see Chapter 3, Section 4). It thus follows that every photon carries a specific energy that is related to its frequency or its wavelength, such that photons of short wavelength (for example blue light) transmit more energy than long wavelength (for example red light) photons. Einstein's equation that explained the photoelectric effect based on the experimental observations is

$$hf = W + \frac{1}{2}m_e v^2 \tag{5-178}$$

where W is called the work function and represents the minimum energy required to remove an electron from the metal surface, and $m_e v^2/2$ is the maximum kinetic energy of the emitted photoelectron. The work function for most metals is around 4.5 eV (see Table 5-10).



Figure 5-20. Schematics of the experiment for the photoelectric effect

Example 5.13 Work function and photoelectric effect

Using the data shown in Table 5-10, determine if green light with $\lambda = 505$ nm can cause electrons to be ejected from cesium.

The energy of the incoming photon

$$hf = \frac{hc}{\lambda} = \frac{(6.63 \times 10^{-34} \,\mathrm{Js})(3 \times 10^8 \,\mathrm{m/s})}{505 \times 10^{-9} \,\mathrm{m}} = 3.94 \times 10^{-19} \,\mathrm{J}$$

From Table 5-10 the work function for cesium is:

$$W = 2.1 \text{eV} = 2.1 \times 1.6 \times 10^{-19} \text{ J} = 3.36 \times 10^{-19} \text{ J}$$

$$hf = W + \frac{1}{2}m_ev^2 \quad \Rightarrow \quad hf - W = \frac{1}{2}m_ev^2 = 5.8 \times 10^{-20} \,\mathrm{J}$$

The photon of given energy will eject an electron from the surface of cesium metal and the energy of the ejected electron will be 0.36 eV.

Element	W (eV)
Aluminum	4.08
Beryllium	5.0
Cadmium	4.07
Calcium	2.9
Carbon	4.81
Cesium	2.1
Cobalt	5.0
Copper	4.7
Gold	5.1
Iron	4.5
Lead	4.14
Magnesium	3.68
Mercury	4.5
Nickel	5.01
Niobium	4.3
Potassium	2.3
Platinum	6.35
Silver	4.73
Uranium	3.6
Zink	4.3

Table 5-10. Work function, W (eV), for some metals

Example 5.14 Cut-off frequency and photoelectric effect

Calculate the cut-off frequency for cesium and plot the kinetic energy of ejected electron *vs.* frequency of photons.

The cut-off (threshold) frequency is the lowest frequency, or longest wavelength, that permits photoelectrons to be ejected from the surface of a metal. At this frequency the photoelectrons have zero kinetic energy:

$$hf = W + \frac{1}{2}m_ev^2 \implies hf_c = W \implies f_c = 5.07 \times 10^{14} \,\mathrm{Hz}$$

Since the kinetic energy of electrons is equal to the stopping potential, eV_0 , in the experimental measurements (see Fig. 5-21), Einstein's equation for the photoelectric effect can be written in the following alternative form

$$eV_0 = hf - W \tag{5-179}$$



Example 5.15 Stopping potential and photoelectric effect

Assume that a potential of 0.54 V is required to stop all the electrons in a photoelectric experiment. Calculate the maximum electron kinetic energy and determine the material (comparing the work function with the values listed in Table 5-10) if the incident photons have the wavelength of 360 nm. What is the longest wavelength that will eject any electron from this metal?

A potential of 0.54 V stops all of the electrons and thus the maximum kinetic energy of the electrons must be equal to the kinetic energy equivalent of a potential of 0.54 V, that is

$$(m_e v^2 / 2)_{\text{max}} = eV_0 = (1.6 \times 10^{-19} \text{ C}) \times (0.54 \text{ V}) = 0.864 \times 10^{-19} \text{ J} =$$

= $(0.864 \times 10^{-19} \text{ J}) \frac{\text{eV}}{1.6 \times 10^{-19} \text{ J}} = 0.54 \text{eV}$

The incident photons thus have energy of



$$hf = \frac{hc}{\lambda} = \frac{(6.63 \times 10^{-34} \text{ Js})(3 \times 10^8 \text{ m/s})}{360 \times 10^{-9} \text{ m}} = 5.525 \times 10^{-19} \text{ J}$$
$$hf = \frac{hc}{\lambda} = \frac{1240 \text{ eV nm}}{360 \text{ nm}} = 3.44 \text{ eV}$$

The electrons then must have lost (3.44 - 0.54) eV = 2.9 eV which represents the work function of the metal or the electron energy lost leaving the metal. From Table 5-10 it can be seen that the material is calcium.

The longest wavelength that will eject an electron from this metal corresponds to the minimum energy needed to remove an electron from the material, i.e. the work function, W = 2.9 eV



Figure 5-22. Photoelectric effect

In the photoelectric effect, the incoming photon is absorbed through interaction with an orbital electron (for example the K-shell electron, see Chapter 2). The process can be sketched as shown in Fig. 5-22. If the photon energy is above the work function, the orbital electron will be ejected from an atom. The vacancy is then filled by an electron from an outer shell and this produces either fluorescence X rays (as indicated in Fig. 5-22) or Auger electrons. The probability for X ray emission is given by the fluorescence yield and, for K-shell electrons, varies from 0.005 for Z = 8 to 0.965 for Z =90. During the photoelectric absorption of light by an atom, one quantum (photon) is absorbed by one of the orbital electrons. The orbital electron is ejected such that the incoming photon energy, hf, and the binding energy of electron, E_b , are distributed between the recoil atom and ejected electron

$$E_{\rm pe} = hf - E_b \tag{5-180}$$

Virtually all of this energy is carried away by the ejected electron (also called the *photoelectron*), E_{pe} , because the electron has much smaller mass than the recoil atom.

The electron binding energy, E_b , depends on its orbit (shell) and assumes discrete values (see Chapter 2)

$$E_b = E_K, E_{L1}, E_{L2}, E_{L3}, E_{M1}, \dots$$
(5-181)

Nearly all photoelectric events in light nuclei involve K-shell electrons. Binding energy in the K-shell varies from 13.6 eV for hydrogen to 7.11 keV for iron and 88 keV in lead. The cross section for the photoelectric effect thus depends on the binding energy of the electrons in different materials. Figure 5-23 illustrates the cross sections for various photon interactions in aluminum and lead.



Figure 5-23. a) Scattering cross sections of photon interactions with aluminum



Figure 5-23. b) Photoelectric effect and pair production cross sections of photon interactions with aluminum



Figure 5-23. c) Scattering cross sections of photon interactions with lead



*Figure 5-23.*d) Photoelectric effect and pair production cross sections of photon interactions with lead

The probability for the photoelectric effect for a given orbital electron is maximum if $hf = E_b$ and it is zero, that is the photoelectric effect can not occur, when $hf < E_b$. As the incident photon energy increases above E_b , the probability for the photoelectric effect decreases. This trend can be observed in Fig. 5-23 for any of the indicated edges (peaks). The edges correspond to the electron shells, K, L, M, etc. For energies below 150 keV, the cross section varies as $(hf)^{-3}$. Above 150 keV but below 5 MeV, it varies as $(hf)^{-2}$ and at energies above 5 MeV it becomes proportional to $(hf)^{-1}$.

The atomic cross section for the photoelectric effect is proportional to Z^m , where *m* depends on the incident photon energy. For a 100 keV photon, m = 4 and for a photon energy of 3 MeV, m = 4.6. Thus, the cross section for the photoelectric effect is strongly dependent on the photon energy as well as on *Z*, the atomic number of the material

$$\sigma_{ph} \propto \begin{cases} \frac{Z^5}{(hf)^{7/2}} & \text{for low photon energies} \\ \\ \frac{Z^{4.5}}{(hf)} & \text{for } 0.1 \text{ MeV} < hf < 5 \text{ MeV} \end{cases}$$
(5-182)

Low energy photons will thus ionize the material they interact with

through the generation of photoelectrons. The range of a photoelectron is calculated in the same manner as that for a β particle (described in Section 4).

5.2.2 Compton Effect (γ + Atom $\rightarrow \gamma$ + e⁻ + Ion)

The Compton Effect, or Compton scattering, is an inelastic collision of a photon with an electron that is loosely bound to an atom or molecule. Such an electron can be considered free if its binding energy is much smaller than the energy of the incident photon. Under such conditions, Compton scattering is more probable than the photoelectric effect. After the interaction, an electron is ejected from the atom along with the scattered photon. The energy of the scattered photon is less than that of the incident photon; that is, compared to the incident photon it has a longer frequency and a smaller wavelength. The Compton Effect is illustrated in Fig. 5-24.



Figure 5-24. Compton scattering

This scattering experiment was performed by Compton in 1923 and showed that light had a corpuscular nature as well as wave-like characteristics. This conclusion was mainly due to the difference in wavelength between the incident and the scattered photon. This change in wavelengths could not be explained by the wave theory of light alone, since it does not predict this change in wavelength. Compton analysed the experimental results by adopting Planck's hypothesis of considering light as an energy quanta, and assigned energy values of E = hf to the photons. Accordingly, the momentum of a massless particle is given by $p = h / \lambda$. Consequently, Compton assumed the incident photon to be equivalent to a particle with mass $m = hf/c^2$. By the conservation of energy (see Fig. 5-24)

$$hf + m_e c^2 = E + hf'$$
 (5-183)

and by the conservation of momentum

$$\vec{p} = \vec{p'} + \vec{p_e} \tag{5-184}$$

where p = E / c for photons, and $p_e = m_e v$ for the electron. Squaring this equation and using the scalar product (see Fig. 5-25) gives

$$p_{e}^{2} = (\vec{p} - \vec{p'})(\vec{p} - \vec{p'}) = p^{2} + p'^{2} - 2pp'\cos\theta$$
(5-185)



Figure 5-25. Scalar product of two vectors

Multiplying the above equation by c^2 and replacing the momentum of photons with p = E / c = hf / c, the momentum conservation equation becomes

$$p_e^2 c^2 = (hf)^2 + (hf')^2 - 2(hf)(hf')\cos\theta$$
(5-186)

The energy conservation equation can be squared and rewritten in the following way

$$hf - hf' + m_e c^2 = E$$

$$(hf - hf')^2 + 2(hf - hf')m_e c^2 = E^2 - m_e^2 c^4$$
(5-187)

Recall from Chapter 3, Eq. (3-7), the energy – momentum relation for a relativistic particle

$$E^{2} = (p_{e}c)^{2} + (m_{e}c^{2})^{2}$$

Thus the above energy conservation equation can be written as

$$p_e^2 c^2 = (hf)^2 + (hf')^2 - 2(hf)(hf') + 2(hf - hf')m_e c^2$$
(5-188)

The left-hand sides of Eqs. (3-7) and (5-188) are equal and thus the right-hand sides must also be equal

$$(hf)^{2} + (hf)^{2} - 2(hf)(hf')\cos\theta =$$

$$(hf)^{2} + (hf')^{2} - 2(hf)(hf') + 2(hf - hf')m_{e}c^{2}$$
(5-189)

Rearranging Eq. (5-189)

$$-(hf)(hf')\cos\theta = -(hf)(hf') + (hf - hf')m_ec^2$$
(5-190)

$$\cos\theta = 1 - \frac{(hf - hf')}{(hf)(hf')} m_e c^2$$
(5-191)

Finally, the Compton scattering formula is

$$\frac{1}{hf} - \frac{1}{hf} = \frac{1 - \cos\theta}{m_e c^2} \quad or \quad \lambda - \lambda = \Delta\lambda = \frac{h}{m_e c} (1 - \cos\theta)$$
(5-192)

This shows that the wavelength change of the incoming photon in a Compton scattering event depends only upon the scattering angle for a given target particle. The constant in the Compton formula above can be calculated explicitly as

$$\frac{h}{m_e c} = \frac{hc}{m_e c^2} = \frac{1240eVnm}{0.511 \times 10^6 eV} = 0.00243nm$$
(5-193)

and is called the *Compton wavelength for the electron*. It corresponds to the wavelength of a photon that has energy equal to the rest mass of an electron. With this taken into account, the Compton scattering formula for an electron can be written as

$$\lambda' = \lambda + \Delta\lambda = \lambda + \frac{h}{m_e c} (1 - \cos\theta) = \lambda + 0.00243 nm(1 - \cos\theta)$$
(5-194)

From this equation it can be concluded

- the change in wavelength, $\Delta \lambda$, does not depend upon the wavelength of the incident photon
- for higher-energy photons, the wavelength decreases such that the same change in wavelength corresponds to a larger difference in energies
- for low photon energies, the energy difference, (hf) (hf'), is small, while for high photon energies (for example order of MeV) the electron may receive over 75 % of energy of the incoming photon
- the change in wavelength, $\Delta \lambda$, depends only on the electron scattering angle
- the change in wavelength, $\Delta \lambda$, is independent of the medium.

The following relation between the scattering angles of the photon and the recoil electron may be determined from Fig. 5-24

$$\cot\frac{\theta}{2} = \left(1 + \frac{hf}{m_e c^2}\right) \tan\phi \tag{5-195}$$

Example 5.16 Energy of Compton scattered photons

For a photon of energy hf = 200 keV that is Compton scattered on electron through an angle of 45°, calculate the energy and frequency of the scattered photon as well as the energy and the momentum of the recoil electron.

Applying the Compton scattering formula it follows

$$\lambda' = \lambda + \Delta \lambda = \lambda + \frac{h}{m_e c} (1 - \cos \theta) = \lambda + 0.00243 \operatorname{nm}(1 - \cos \theta)$$

$$\frac{\lambda}{hc} = \frac{\lambda}{hc} + \frac{(1 - \cos\theta)}{m_e c^2} \quad \rightarrow \quad \frac{1}{E} = \frac{1}{E} + \frac{(1 - \cos\theta)}{m_e c^2}$$

$$\frac{1}{E'} = \frac{1}{200 \text{ keV}} + \frac{(1 - \cos 45^\circ)}{511 \text{ keV}} \rightarrow E' = (hf') = 179 \text{keV}$$

The frequency of the scattered photon is

$$f' = \frac{179 \text{keV}}{h} = \frac{(179 \times 10^3 \text{ eV})(1.6 \times 10^{-19} \text{ J/eV})}{6.63 \times 10^{-34} \text{ Js}} = 4.32 \times 10^{19} \text{ Hz}$$

The energy given to a recoil electron

$$\Delta E = hf - hf' = 200 - 179 = 21 \text{keV}$$

The total energy and the momentum of the recoil electron

$$E = \Delta E + m_c c^2 = 21 \text{keV} + 511 \text{keV} = 532 \text{keV}$$

$$E^{2} = (p_{e}c)^{2} + (m_{e}c^{2})^{2} \rightarrow$$

$$p_{e} = \frac{\sqrt{E^{2} - m_{e}^{2}c^{4}}}{c} = \frac{144.94 \times 10^{3} \text{ eV}}{3 \times 10^{8} \text{ m/s}} \times 1.6 \times 10^{-19} \text{ J/eV} \rightarrow$$

$$p_{e} = 7.73 \times 10^{-23} \text{ kgm/s}$$

The following is an analysis of some aspects of Compton scattering:

1. The dependence of the scattered photon energy on incident photon energy and photon scattering angle (θ):

The energy of the scattered photon, (E' = hf') depends on the energy of incident photon, (E = hf) and the scattering angle, (θ) as

$$\frac{1}{hf'} - \frac{1}{hf} = \frac{1 - \cos\theta}{m_e c^2} \to E' = \frac{E(m_e c^2)}{m_e c^2 + E(1 - \cos\theta)}$$
(5-196)

If the ratio of energies, E'/E, is plotted against the incident photon energy for various scattering angles (see Fig. 5-26), the following can be observed:

- For incoming photon energies smaller than ~ 50 keV, the energy of the scattered photon is nearly equal to that of the incident photon. At these low incident photon energies, Compton scattering is similar to Rayleigh (coherent) scattering in which the energy of the scattered photon remains unchanged (the scattered photon is only deflected).
- In the case of complete forward photon scattering ($\theta = 0$), the energy of the incident photon is unchanged.



Figure 5-26. Ratio of scattered to incident photon energy *vs.* incident photon energy and photon scattering angle in the Compton Effect

• Compton scattering is an efficient interaction type for reducing photon energy at large scattering angles. The maximum reduction in photon energy is obtained for backscattering, at $\theta = 180^{\circ}$.

2. The angular distribution of the scattered photons and recoil electrons:

The scattering angle for the recoil electron varies from 0° to 90° . The maximum energy that a recoil electron can obtain in Compton scattering is in a head—on collision in which the electron scatters at nearly zero angle (it continues its trajectory in straight line of the impact photon) and the photon is scattered backward at the angle of 180° . The minimum energy that a recoil electron receives is during the collision in which the photon trajectory is constant (scattering angle of a photon is zero) while the electron scatters at nearly 90° . The probability for an electron to be scattered at an angle of zero increases with incident photon energy as shown in Table 5-11. This table further shows that for a given photon scattering angle, the recoil electron scattering angle decreases with increasing incident photon energy.

3. Cross section for Compton scattering:

The cross section for the Compton scattering of photons with incident

energy hf, through a scattering angle θ , is given by the Klein–Nishina formula. In general, the formula suggests that the probability for the Compton Effect to occur for an element Z is proportional to Z/hf. If the incident photon energy is measured in the units of electron rest mass, *i.e.* $\alpha = hf / m_e c^2$, then the Klein–Nishina formula for total Compton scattering cross section (integrated over the photon scattering angle θ to give the energy dependence of the cross-section per electron) can be written as

$$\sigma_{Compton} = 2\pi r_e^2 \begin{cases} \frac{1+\alpha}{\alpha^2} \left[\frac{2(1+\alpha)}{1+2\alpha} - \frac{1}{\alpha} \ln(1+2\alpha) \right] \\ + \frac{1}{2\alpha} \ln(1+2\alpha) - \frac{1+3\alpha}{(1+2\alpha)^2} \end{cases}$$
(5-197)

where r_e is the classical electron radius, also called the Compton radius, and is defined as the radius, r_e , of a sphere which has charge e and electrostatic potential energy, U, equal to the rest mass energy of the electron. That is

$$U = \frac{ke^2}{r_e} = m_e c^2$$
 (5-198)

Table 5-11. Angular distribution of recoil electron (ϕ) as a function of incident photon energy (*hf*) and photon scattering (θ)

hf	$\theta =$	$\theta =$	$\theta =$	$\theta =$	$\theta =$	$\theta =$	$\theta =$	$\theta =$
(MeV)	1°	5°	10°	30°	60°	90°	120°	150°
0.01	89.49	87.45	84.90	74.72	59.52	44.44	29.52	14.72
0.1	89.40	87.01	84.03	72.24	55.38	39.91	25.77	12.63
1.0	88.52	82.64	75.50	51.61	30.36	18.68	11.05	5.18
10	79.82	48.07	29.06	10.28	4.81	2.78	1.61	0.75
100	30.22	6.64	3.33	1.09	0.50	0.29	0.17	0.08

Solving for the electron radius

$$r_{e} = \frac{ke^{2}}{m_{e}c^{2}} = \frac{(8.987 \times 10^{9} \,\mathrm{Nm^{2}/C_{-}^{2}})(1.6 \times 10^{-19} \,\mathrm{C})^{2}}{(0.511 \times 10^{6} \,\mathrm{eV})(1.6 \times 10^{-19} \,\mathrm{Nm/eV})}$$
(5-199)
= 2.8×10⁻¹⁵ m

The total Compton scattering cross section plotted against incident photon energy is shown in Fig. 5-27. This shows that the probability of Compton scattering decreases with increasing incident photon energy.



Figure 5-27. Total Compton scattering cross section vs. incident photon energy

5.2.3 Correction for Bound Electrons and Coherent (Rayleigh) Scattering

Compton scattering is valid under the assumption that the electron is free. This assumption is only applicable when the binding energy of the electron is much smaller than the energy of the incident photon. When the incident photon energy is comparable to the electron binding energy, a more complicated, semi-empirical relation must be used to evaluate the incoherent scattering. Such scattering interactions occur for low incident photon energies, small photon scattering angles and highly bound electrons (electrons in the inner shells of an atom). Thus, the scattering cross section for bound electrons decreases at low photon energies. The dominant interaction at low photon energies is the photoelectric effect. The effect of electron binding energy thus becomes negligible at these energies and the error introduced by neglecting the binding energy is small.

In competition with the incoherent scattering of photons by individual electrons is coherent (Rayleigh) scattering. When low energy photons scatter at a small angle in a high–Z medium, the energy transferred to an electron is

so small that even excitation of that atom is not possible. The energy is thus absorbed by the entire atom and even this small amount of energy will cause an atom to recoil. The energy loss of the incoming photon is considered to be negligible. Fig. 5-23 shows that coherent scattering cross sections greatly exceed the incoherent scattering at low photon energies in a high–Z medium. In radiation shielding calculations, however, this type of scattering is usually neglected since the dominant method of energy attenuation is through photoelectric effect.

5.2.4 Pair Production (γ + Atom \rightarrow e⁺ + e⁻ + Atom)

In this process, the incident photon is absorbed and an electron-positron pair is created (see Fig. 5-28). The photon generates this electron-positron pair in the Coulomb field of the nucleus and this interaction has a photon threshold energy that is equal to the rest mass energies of two electrons, $2m_ec^2 = 1.022$ MeV. The same interaction can occur in the Coulomb field of an electron, with a threshold energy of $4m_ec^2 = 2.044$ MeV. The probability of pair production in the electric field of nucleus is however significantly higher and is the only interaction analyzed further.



Figure 5-28. Pair production

In pair production

- *The total charge is conserved*: a photon with zero electric charge generates a pair which also has a total charge of zero (electron with negative charge and positron with positive charge)
- According to the energy conservation law:

Incident photon energy = Energy used to generate the pair + Kinetic energy of the positron + Kinetic energy of the electron

$$hf = 2m_e c^2 + T^+ + T^- = 1.022 + T^+ + T^- \quad (MeV)$$
(5-200)

According to the momentum conservation law: pair production cannot take place in an empty space because some third entity must absorb the momentum (p=h/λ =hf/c) of the initial photon. The photon momentum is usually absorbed by an atomic nucleus. The following example shows why it is impossible for a photon to transfer all of its energy to a free electron. Consider a photon of energy hf and momentum hf/c. If the photon was to transfer all of its energy to an electron of mass m and velocity v, then from the conservation of energy

$$hf = \frac{1}{2}mv^2$$

and conservation of momentum

$$h\frac{f}{c} = mv$$

Eliminating hf from these two equations gives

$$v = 2c$$
,

which is an impossible result since no particle can travel faster than light.

The electron and positron have energies equal to the difference between the initial photon energy and $2m_ec^2$. The energy spectra of the emitted electron and positron are continuous and are very similar to one another. The scattering angles of the positron and electron as well as the angular dependence on photon energy are complex and not easy to describe. This is due to the involvement of the nucleus in the momentum distribution after the interaction. For very high photon energies, the average scattering angle of the electron and the positron is proportional to 0.511 MeV/hf (MeV).

The total cross section for pair production per atom divided by Z^2 is graphically shown for various materials in Fig. 5-29. It can be observed that the cross section for all of the elements does not significantly change for incoming photon energies up to 10 MeV. For higher energies, the cross section for different materials starts to depart. The cross section for pair production in the electric field of an electron is also depicted in Fig. 5-23.



Figure 5-29. Cross section for pair production in different materials (cross section for pair production in the Coulomb field of the nucleus is divided by Z^2 , cross section for the pair production in the Coulomb field of an electron is divided by Z)

The cross section depends on Z of the material and thus it can be considered important for low-Z media. The cross section also increases with incident photon energy. This dependence is nearly logarithmic

$$\sigma_{pp} \propto Z^2 \ln(hf) \tag{5-201}$$

The positron that is formed very quickly disappears in an annihilation process that involves another electron. Annihilation $(e^+e^- \rightarrow \gamma)$, which is the inverse of pair production $(\gamma \rightarrow e^+e^-)$, occurs when a positron encounters an electron. The energy conservation equation for an annihilation event is

$$2m_e c^2 + K^+ + K^- = 2hf \tag{5-202}$$

The first term represents the rest energy of the electron-positron pair, the second and third terms are the kinetic energies of the positron and electron before the collision, and the term on the right-hand side represents the energy of the two photons created in the reaction, each having the same frequency f and energy hf. According to the energy conservation law, the value of hf must be at least $m_ec^2 = 0.511$ MeV.

NUMERICAL EXAMPLE

Photon Attenuation in Common Shielding Materials

Aluminum and lead are two materials commonly used in high energy photon shielding. Using the data in Table 5-8, construct an attenuation plot of a 1 MeV photon beam passing through aluminum ($\rho = 2.7$ g/cm3) and lead ($\rho = 11.34$ g/cm3). Comment on the apparent effect of the material density on gamma attenuation.

Solution in MATLAB

```
clear all
% Mass attenuation coefficients at 1MeV
mu_Al = 0.06146; \% cm^2/g
mu_Pb = 0.0757;
rho_Al = 2.7; %g/cm^3
rho_Pb = 11.34;
mu = [mu_Al*rho_Al mu_Pb*rho_Pb];
x = linspace(0,30);
for i = 1:2
  for i = 1:100
     I(i,j) = \exp(-mu(j)*x(i));
  end
end
figure
hold on
plot(x,I(:,1),k')
plot(x,I(:,2),'k:')
xlabel('Distance (cm)')
```

ylabel('Fractional Intensity') legend('Aluminum','Lead')

Results show that higher-Z materials are more effective as photon shields.



Figure 5-30. Attenuation of a 1-MeV photon beam in aluminum and lead

PROBLEMS

5.1. Expain do α particles produce bremsstrahlung radiation?

5.2. Estimate the source energy of bremsstrahlung radiation from the lead container shielding 5 mCi source of ³²P (maximum β energy is 1.71 MeV). How much heat will be deposited in the wall of the container?

5.3. An energy of 35.5 eV is required to produce an ion pair. Estimate how many ion pairs are produced by α particle with a 1.0 MeV kinetic energy and how much total charge is produced?

5.4. If the ionization potential of air is 33.9 eV, how many ion pairs are produced by an 5MeV α particle? How many ion pairs would produce a β particle of the same energy? What would be the linear ranges of these two particles?

5.5. Determine the range of 2 MeV α particle in aluminum. Compare the value with that given in Table 5-3.

5.6. The half-value shielding layer is 5 mm thick. Calculate the shiled thickness to attenuate 99.912 % of the incoming γ radiation.

5.7. Use the data from Table 5-8 to calculate the relative number of 1 MeV and 0.1 MeV γ rays that emerge from 15 cm thick water tank. Assume that the γ rays beam consists of equal number of both when entering the water tank.

5.8. Calculate the thickness of air, water and aluminum that will stop 20 % of a beam of 1.5 MeV γ rays.

5.9. In the table <u>http://physics.nist.gov/PhysRefData/contents.html</u> find the values needed to determine and calculate the fraction of energy in a 30 keV X-ray beam deposited in 5 mm of soft tissue.

5.10. A γ ray (1.46 MeV) from ⁴⁰K is scattered through an angle of 30° and then again through an angle of 150°. Calculate the energy of γ ray after second scattering.

5.11. If the light of wavelength 400 nm is incident on a metal with a work function 5.5 V calculate the external voltage that must be applied to the metal to have the electrons be released from its surface?

5.12. A completely ionized carbon nucleus is accelerated through a potential difference of 7000 V. What is the final kinetic energy of the carbon?

5.13. If the work function of a material is 10 eV what is the lowest frequency photon that can cause electrons to be ejected?

5.14. For a 200 keV Compton photon scattered at 45° calculate its energy and the magnitude and direction of the momentum of the recoil electron.

5.15. Calculate and plot the linear and mass ranges of α particle, proton and electron as a function of energy in water, aluminum, lead and graphite.

5.16. Determine the linear energy loss resulting from the passage of a 0.1 MeV β particle through the graphite (density = 2.25 g/cm³)? Calculate the mass stopping power and the relative (to air) mass stopping power.

5.17. From <u>http://physics.nist.gov/PhysRefData/contents.html</u> determine the minimum energy that a proton must have to penetrate 30 cm of tissue (density 1 g/cm³), the approximate thickness of the human body. Using the same table calculate how much energy does an α particle need to penetrate 1 cm of the tissue layer?

5.18. In a Compton scattering experiment it is found that the fractional change in the wavelength is 1.0 % when the scattering angle is 60° . What was the wavelength of the incident photons, and what would be the wavelength of the photons scattered through an angle of 90° .

5.19. Plot the Compton scattering energy of scattered beam (hf'/hf), for the initial photon energies of 0.05, 0.1, 0.2, 0.5, 1.0, 2.0, 5.0 and 10.0 MeV as a function of photon scattering angle.

5.20. Calculate the necessary shielding (glass with density of 2.23 g/cm³ and plastic with density of 1.03 g/cm³) to completely stop the β particles from ³H. The maximum β particles energy is 0.019 MeV and the average energy is 0.0057 MeV.

5.21. Tabulate the cut-off frequency for elements given in Table 5-10. Calculate the kinetic energy of ejected electrons.

5.22. Prove the Eq. (5-195).

5.23. Write the computer code to compute the maximum range of a proton in aluminium, air, silicon and water for the range of energies from 0.001 eV to 1 GeV.

5.24. Use the Bethe-Block formula and write the computer code to calculate energy loss of an α particle and proton in varying the ratio of particle velocity to the speed of light from zero to one.

5.25. Repeat the previous problem with electrons. What can you conclude from the results?

5.26. Discuss the head–on collision of charged particles.

5.27. Describe the inelastic scattering of charged particles with electrons.

5.28. How inelastic scattering of charged particles take place with the nucleus? Compare the aspects of interactions with the Problem 5.27.

5.29. Explain the bremsstrahlung radiation and define the bremasstrahlung hazard.

5.30. Explain the condition for electron positron annihilation process.

Chapter 6

NEUTRON PHYSICS

Interactions, Fission and Cross Sections

"...I feel that I ought to let you know of a very sensational new development in nuclear physics. In a paper in the Naturwissenschaften Hahn reports that he finds when bombarding uranium with neutrons the uranium breaking up into two halves giving elements of about half the atomic weight of uranium. This is entirely unexpected and exciting news for the average physicist. The Department of Physics at Princeton, where I spent the last few days, was like a stirred-up ant heap. Apart from the purely scientific interest there may be another aspect of this discovery, which so far does not seem to have caught the attention of those to whom I spoke. First of all it is obvious that the energy released in this new reaction must be very much higher than in all previously known cases. It may be 200 million (electron-) volts instead of the usual 3-10 million volts. This in itself might make it possible to produce power by means of nuclear energy, but I do not think that this possibility is very exciting, for if the energy output is only two or three times the energy input, the cost of investment would probably be too high to make the process worthwhile. Unfortunately, most of the energy is released in the form of heat and not in the form of radioactivity.

I see, however, in connection with this new discovery potential possibilities in another direction. These might lead to a large-scale production of energy and radioactive elements, unfortunately also perhaps to atomic bombs. This new discovery revives all the hopes and fears in this respect which I had in 1934 and 1935, and which I have as good as abandoned in the course of the last two years"... *Leo Szilard* (1898 - 1964) in his letter to Luis Strauss on January 25th, 1939.

1. INTRODUCTION

Neutrons together with protons are the constituents of atomic nuclei. The neutron was discovered after more than two decades of speculation that electrically neutral particles exist in atoms (see Chapter 3). Because the neutron is electrically neutral, it easily interacts with nuclei and does not interact directly with electrons. Since the nucleus of an atom is about one ten-thousandth the size of the electron cloud, the chance of neutrons interacting with a nucleus is very small, allowing them to travel long distances through matter. As a free particle, the neutron is an important and yet unique tool used for various applications: in medicine to initiate powerful nuclear interactions whose products can directly destroy cancer cells (neutron capture therapy for example), for research on physical and biological materials, for imaging through easy allocation of light atoms especially hydrogen, to investigate properties of magnetic materials (neutrons possess a magnetic moment and thus act as small magnets), to track atomic movement (thermal neutron energies almost directly coincide with the energies of atoms in motion), and to maintain the fission chain reaction in nuclear reactors. Free neutrons are unstable (see Chapter 3) and break up in short time by β^- decay to a proton, electron and a neutrino. However, free neutrons will most likely interact with the surrounding matter and disappear through nuclear interactions long before they decay.

2. NUCLEAR REACTIONS

A nuclear reaction involves interactions between nuclear particles (nucleons, nuclei); the outcome of which are other nuclear particles or γ rays. Assuming, for simplicity, only two initial and two produced particles, a nuclear reaction is usually written as follows (see Fig. 6-1)

 $A + B \rightarrow C + D$

Every nuclear interaction must obey the following laws

- *Conservation of nucleons*: the total number of nucleons before and after a nuclear reaction is not changed
- *Conservation of charge*: the sum of the charges of all particles involved in the reaction before and after must be preserved
- *Conservation of momentum*: the total momentum of interacting particles before and after the reaction is not changed
- *Conservation of energy*: energy, including the rest mass energies of particles, is not changed by a nuclear reaction.



Figure 6-1. Schematics of a typical nuclear reaction

The law of conservation of energy can be also used to predict whether a certain interaction is energetically possible. For the assumed interaction of particle A with particle B that produces two particles C and D, the sum of energies before and after the interaction takes into account the kinetic energies (T) and rest mass energies (mc^2) of each individual particle

$$T_A + T_B + m_A c^2 + m_B c^2 = T_C + T_D + m_C c^2 + m_D c^2$$
(6-1)

Equation (6-1) may be rewritten as

$$(T_C + T_D) - (T_A + T_B) = [(m_A + m_B) - (m_C + m_D)]c^2$$
(6-2)

showing that the change in kinetic energies of the particles involved in a reaction is equal to the change in their rest mass energies. The change in rest mass energies of the particles involved in the reaction is known as the Q-value of the reaction

$$Q = [(m_A + m_B) - (m_C + m_D)]c^2$$
(6-3)

The sign of the *Q*-value defines the reaction

- *Exothermic reaction* for which Q > 0: nuclear mass is converted into kinetic energy and there is a net increase in kinetic energies of the particles
- Endothermic reaction for which Q < 0: kinetic energy is converted into mass and there is a net decrease in the energies of the particles.

Example 6.1 Nuclear reaction

Complete the following reaction, calculate the *Q*-value, and comment on its sign 235 U (n, ?) 236 U. The rest masses: $m_{235} = 235.0439231$ amu, $m_n = 1.0086649$ amu, $m_{236} = 236.0455619$ amu.

The atomic number of ²³⁵U is 92 and that of the neutron is zero. The sum of the atomic numbers of the incident particles is thus 92. Since the atomic number of ²³⁶U is also 92, it follows that the produced particle should have an atomic number equal to zero. The total atomic mass number of the incident particles is 235 + 1 = 236. The total atomic mass number of the produced particles must be the same. Since the atomic mass number of ²³⁶U is 236 it follows that the additional particle has atomic mass number zero. It therefore follows that the other particle is a γ ray:

 235 U (n, γ) 236 U

For this reaction the Q-value is

 $Q = [(m_{235} + m_p) - (m_{236} + m_{\gamma})]c^2 = 0.0070261$ amu

 $Q = 0.0070261 \times 931.5 = 6.54 \text{ MeV} > 0$, thus the reaction is exothermic.

3. NEUTRON SOURCES AND NEUTRON CLASSIFICATION

Neutrons are produced from neutron sources such as a nuclear reactor, a radioisotope, or an accelerator-based source. A nuclear reactor is the most inexhaustible source for the production of neutrons of all energies. However, the complexity of a reactor and the systems involved as well as the cost make simple and broad use of reactors impractical for small scale industrial, medical, or research applications. On the other hand, radioisotope neutron sources are used in an innumerable amount of industrial applications and are ideal when a continuous source is needed. However, such a source is not appropriate for applications that require neutrons of a specific energy or emission of neutrons in specified time pulses. One example of a large accelerator-based neutron source is the Spallation Neutron Source under construction at Oak Ridge National Laboratory in the United States. Small scale accelerators and compact pulse neutron sources use nuclear reactions to produce neutrons. The most common are the deuterium-deuterium ($^{2}H - ^{2}H$) and deuterium-tritium ($^{2}H - ^{3}H$) reactions

```
{}^{3}\text{H}({}^{2}\text{H}, n) {}^{4}\text{He} Q = 17.59 \text{ MeV}
```

 2 H (2 H, n) 3 He Q = 3.27 MeV

These reactions produce 14.1 MeV and 2.5 MeV neutrons, respectively.

Pulse neutron sources (also called pulse neutron generators) have found a number of applications in science, industry, medicine, and technology. To name a few

- Real-time analysis of bulk materials: Materials such as cement and coal moving on conveyor belts are examples of bulk materials that are extensively examined by applying fast and thermal neutron beams for activation analyses. The purpose of such analysis is to measure the content and the amount of the elements present in the material. For example, the information obtained from neutron activation analysis of cement enables the optimal combination of raw material constituents as well as verification of chemical consistency. Another example is the application of neutron activation tests in on-line measurements of sulfur and the content of other elements in coal which are important for predicting its combustion efficiency and environmental impact.
- Detection of explosive, chemical and nuclear materials: Such materials may be accurately detected for fast security checks of airline-cargo or other unknown packages.
- *Medical applications*: An accurate and simple measurement of the body's fat is achieved using neutron pulse generators. The measurement is based on neutron interactions with carbon and oxygen. By examining the quantity and distribution of carbon and oxygen, it is possible to evaluate the health of individuals with respect to obesity, aging and cardiovascular disease.

A very special interaction that results in a high production rate of neutrons of various energies is the interaction of an α particle with a beryllium atom:

$${}^{9}\text{Be}(\alpha, n) {}^{12}\text{C} \qquad Q = 5.75 \text{ MeV}$$

Since the Coulomb repulsion force between the beryllium nucleus and the incoming α particle is not high, this reaction is very suitable for neutron production. The α particles are emitted through the radioactive decay of isotopes such as ²²⁶Ra, ²²²Rn, ²¹⁰Po, ²³⁹Pu, and ²⁴¹Am. Beryllium is the only naturally occurring isotope of beryllium and thus a neutron source utilizing this element is easy to realize. Namely, powders of both beryllium and the α emitter are mixed together in ratios from 20:1 to 300:1 and the mixture is encapsulated. Such sources constantly emit neutrons and the energy spectrum is usually complex because decay products have different α energies and thus produce neutrons with different energies. Figure 6-2 depicts the neutron energy spectrum emitted from an americium–beryllium (AmBe) neutron source. Neutrons can also be produced in the reaction of γ rays with targets most commonly made of beryllium or deuterium (for
example heavy water). Such reactions are referred to as photoneutron sources. The binding energy of the neutrons in these light elements is low and a large amount of energy is therefore not required for the reaction to occur:

$${}^{9}\text{Be}(\gamma, n) {}^{8}\text{Be} \qquad Q = 1.63 \text{ MeV}$$

2
H (γ , n) 1 H $Q = 2.23$ MeV

Neutrons produced by photodisintegration of nuclei are monoenergetic and such sources are reproducible (in terms of neutron energy). The most common sources of γ rays used for these interactions are the γ rays emitted in radioactive decays of ²⁴Na ($E_{\gamma} = 2.8$ MeV, $T_{1/2} = 15$ hours) or ¹²⁴Sb ($E_{\gamma} = 1.67$ MeV, $T_{1/2} = 60.9$ days).



Figure 6-2. Typical neutron spectrum from an americium-beryllium source

Example 6.2 Nuclear reaction that revealed the existence of neutron

As described in Chapter 3, Rutherford was the first to correctly predict the existence of a neutral particle as a constituent of the nucleus as early as 1920. That idea has inspired many scientists around the world to start the search for other constituents of nuclei. Two German scientists, Bothe and Becker, studied the interaction that is today commonly used to produce neutrons: ${}^{9}Be(\alpha,n){}^{12}C$. In their experiment they discovered that nearly 5 cm of lead reduced the radiation emerging from the reaction and attributed this phenomenon incorrectly to γ rays. Now, consider the same interaction and assume that a neutron produced in that interaction

has an energy of 5.3 MeV. Calculate the energy of the recoil proton if such a neutron encountered a head-on collision with a paraffin block (assume the collision is with a proton only).

Before the interaction, the neutron of mass m_n had a velocity v_{n1} while the velocity of the proton of mass m_p was zero. After the interaction, the neutron moves with velocity v_{n2} and the proton recoils with velocity v_p . According to the law of conservation of energy

$$\frac{1}{2}m_n v_{n1}^2 = \frac{1}{2}m_n v_{n2}^2 + \frac{1}{2}m_p v_p^2$$
(6-4)

The conservation of momentum for the head-on collision (see Chapter 3) gives

$$m_n v_{n1} = m_n v_{n2} + m_p v_p \tag{6-5}$$

Equations (6-4) and (6-5) can be simplified and combined assuming the mass of a proton is nearly equal to that of a neutron to give

$$v_p = v_{n1} \quad v_{n2} = 0 \tag{6-6}$$

This result shows that in a head-on collision a neutron is stopped by a proton, transferring all of its energy to the target. In our example, therefore, the energy of the target proton after the reaction is equal to the energy of the incident neutron, or 5.3 MeV.

Neutrons are classified according to their energies because their interactions with matter are energy dependent. The most common classification is shown in Table 6-1.

Neutron energy	Name
0 - 0.025 eV	Cold
0.025 eV	Thermal
0.025 eV - 0.4 eV	Epithermal
0.4 eV - 0.6 eV	Cadmium
0.6 eV - 1 eV	Epicadmium
1 eV - 10 eV	Slow
10 eV - 300 eV	Resonance
300 eV - 1 MeV	Intermediate
1 MeV - 20 MeV	Fast
> 20 MeV	Relativistic

Table 6-1. Classification of neutrons

(6-8)

4. **NEUTRON ATTENUATION**

4.1 **Concept of the Cross Section**

The quantitative description of nuclear interactions requires known neutron cross section data. A rate at which a particular neutron interaction with a given target material will occur depends on the neutron energy and speed, as well as the nature of the target nuclei. The cross section of a target material for any given reaction thus represents the probability of a particular interaction and is a property of the nucleus and incident neutron energy. In order to introduce the concept of a neutron cross section, consider a parallel monoenergetic neutron beam falling on thin target of thickness x and area A, as shown in Fig.6-3. The intensity of the incident neutron beam is described with the number of neutrons per unit volume, n, and their velocity, v, as

$$I_0 = n v \left[(\text{neutrons/cm}^3)^{-} (\text{cm/s}) = \text{neutrons/cm}^2 / \text{s} \right]$$
(6-7)

The total number of nuclei in the target of atomic density N is

Total number of nuclei in target = Nax



Figure 6-3. Concept of neutron cross section

The number of neutrons that collide with the target nuclei is proportional to the neutron beam intensity and the total number of nuclei in the target

Number of neutron collisions per second in the whole target = $\sigma I_0 Nax$ (6-9)

where σI_0 represents the number of neutron collisions with the single target's nuclei per unit time, and σ is referred to as the effective cross sectional area, frequently called the *microscopic cross section*. It follows

 σ = number of neutron collisions per unit time with one nucleus per unit intensity of the incident neutron beam

The neutron microscopic cross section thus represents a visible area and for some interactions is closely equal to an actual area, πR^2 (see Example 6.3). The accepted unit of microscopic cross sections is the barn (b), which is equal to 10^{-24} cm². All neutron cross sections are functions of neutron energy and the nature of the target nucleus. The probability of a neutron undergoing an interaction in the target as sketched in Fig. 6-3 is equal to the ratio of the reaction area to the total area:

$$\Sigma x = [\text{Reaction area}] / [\text{Total area}]$$
(6-10)

The reaction area of the target (of volume Ax) is defined as the number of nuclei in the target material, NAx, multiplied by the area of each nucleus, σ

$$\Sigma x = \frac{N\sigma Ax}{A} = N\sigma x \tag{6-11}$$

Thus, the relation between the microscopic (σ) and macroscopic (Σ) cross section is

$$\Sigma = N\sigma \ [\text{cm}^{-1}] \tag{6-12}$$

The number of nuclei in a target material made of a single element (also called the number density), N, is obtained from (see Chapter 2)

$$N = \frac{N_a \times \rho}{A} \tag{6-13}$$

where A is the atomic mass number and N_a is Avogadro's number.

Example 6.3 Microscopic and macroscopic cross sections for a single isotope

Calculate the microscopic cross section based on geometrical area and estimate the macroscopic cross section for ⁵⁴Fe, which has a density of 7.86 g/cm³. Use the following empirical relation to estimate the radius of the nucleus, R: $R = (1.4 \text{ A}) \times 10^{-16} \text{ m}.$

The microscopic cross section is estimated based on the nuclear radius calculated from the Fermi model of the nucleus (see Chapter 3)

$$R = 1.4A \times 10^{-16} \text{ m} = 1.4 \times 54 \times 10^{-16} \text{ m} = 75.6 \times 10^{-16} \text{ m}$$
$$\sigma = \pi R^2 = \pi \left(75.6 \times 10^{-16} \text{ m}\right)^2 = 1.79 \times 10^{-28} \text{ m}^2 = 1.79 \text{ barns}$$

Figure 6-4 shows the neutron microscopic cross sections for 54 Fe and 55 Mn. It can be seen that the estimate is close to the measured value. The same empirical formula can be used for 55 Mn to estimate the microscopic cross section.

The number density of ⁵⁴Fe is

$$N = \frac{N_a \times \rho}{A} = \frac{(6.023 \times 10^{23})(7.86)}{54} = 8.77 \times 10^{22} \,\text{nuclei/cm}^3$$

The macroscopic cross section is thus

$$\Sigma = N\sigma = (8.77 \times 10^{22})(1.79 \times 10^{-24}) = 0.157 \text{ cm}^{-1}$$



Figure 6-4. Microscopic cross section for neutron elastic scattering on ⁵⁵Mn and ⁵⁴Fe (reproduced using the ENDF plot and MCNP cross section data)

Example 6.4 Microscopic and macroscopic cross section for a mixture of elements

Calculate the microscopic and macroscopic absorption cross sections for natural

uranium if $\sigma_{235} = 681$ b, and $\sigma_{238} = 2.7$ b. The density of uranium is 19 g/cm³.

The abundances (ε) of ²³⁸U and ²³⁵U in natural uranium (neglecting small amounts of ²³⁴U) are 99.28% and 0.72%, respectively. Thus, the number densities are

$$N_{238} = \varepsilon_{238} \frac{N_a \times \rho}{A_{238}} = 0.9928 \frac{(6.023 \times 10^{23})(19)}{238} = 4.77 \times 10^{22} \,\text{nuclei/cm}^3$$

$$N_{235} = \varepsilon_{235} \frac{N_a \times \rho}{A_{235}} = 0.0072 \frac{(6.023 \times 10^{23})(19)}{235} = 3.50 \times 10^{20} \,\text{nuclei/cm}^3$$

The macroscopic and microscopic cross sections of natural uranium are

$$\Sigma = N_{235}\sigma_{235} + N_{238}\sigma_{238} = 0.367 \text{ cm}^{-1} \text{ and } \sigma = \frac{\Sigma}{N_{235} + N_{238}} = 7.64 \text{ b}$$

4.2 **Probability of Neutron Interactions**



Figure 6-5. Neutron travel in a homogeneous medium

Neutrons travel with constant direction and speed until they interact with the medium. Considering only a homogeneous medium, the probability of a neutron interacting is a function of the distance at which a neutron will interact, x. This probability can be expressed as a MacLaurin series of distance x as

$$P_{reaction}(x) = a + bx + cx^{2} + dx^{3} + \dots$$
(6-14)

where *a*, *b*, *c*, *d*, ... are the coefficients of expansion. Since the interaction of a neutron can not occur at zero distance, the first term is equal to zero. For a sufficiently small distance δx (see Fig. 6-5), the series shown in Eq. (6-14) reduces to

$$P_{reaction}(\delta x) = b\,\delta x \tag{6-15}$$

The probability that a neutron will not interact along the distance δx is

$$P_{non-reaction}(\delta x) = 1 - b\,\delta x \tag{6-16}$$

Since every interaction is independent of the previous interaction, the probability that a neutron will not interact along the distance $x + \delta x$ can be written as a product of two probabilities

$$P_{non-reaction}(x + \delta x) = P_{non-reaction}(x)P_{non-reaction}(\delta x)$$

= $P_{non-reaction}(x)[1 - b\delta x]$ (6-17)

Rearranging terms it follows

$$\frac{P_{non-reaction}(x+\delta x) - P_{non-reaction}(x)}{\delta x} = -bP_{non-reaction}(x)$$
(6-18)

Taking the limit as $\delta x \rightarrow 0$ and replacing the constant b with Σ (macroscopic cross section)

$$\frac{dP_{non-reaction}(x)}{dx} = -\Sigma P_{non-reaction}(x)$$
(6-19)

Integrating Eq. (6-19) gives the probability that a neutron does not interact and the probability that a neutron will interact along the distance x

$$P_{non-reaction}(x) = e^{-\Sigma x}$$

$$P_{reaction}(x) = 1 - e^{-\Sigma x}$$
(6-20)

The macroscopic cross section in the above equation is replaced with the linear attenuation coefficient (μ_l) in case of γ ray attenuation (see Chapter 5).

Example 6.5 Probability of neutron interactions

Calculate the probability that a neutron will travel 5 cm in a block of 54 Fe (see Example 6.3 for other data) without an interaction. What is the probability that the neutron will interact with the medium between 5 cm and 5.5 cm?

From the Example 6.3, the macroscopic cross section for ⁵⁴Fe is $\Sigma = 0.157$ cm⁻¹. The probability of traveling 5 cm without an interaction is

$$P_{non-reaction}(5cm) = e^{-\Sigma x} = e^{-0.157 \times 5} = 0.456$$

In order to calculate the probability of having an interaction between 5 cm and 5.5 cm, we first calculate the probability of traveling an additional 0.5 cm without interaction, or

$$P_{non-reaction}(5.5cm) = e^{-\Sigma x} = e^{-0.157 \times 5.5} = 0.422$$

Thus the probability of a neutron interacting in the interval between 5 cm and 5.5 cm is

$$P_{non-reaction}(5cm) - P_{non-reaction}(5.5cm) = 0.456 - 0.422 = 0.034$$

Alternatively, the product of two probabilities may be used: the probability that a neutron will not interact along the first 5 cm of travel and the probability that it will interact in the next 0.5 cm

$$P_{non-reaction}(5cm) \times P_{reaction}(0.5cm) = e^{-0.157 \times 5} \times \left[1 - e^{-0.157 \times 0.5}\right] = 0.456 \times [1 - 0.924] = 0.034$$

4.3 Neutron Mean Free Path

The neutron mean free path is, by definition, the average distance that a neutron will travel in a medium without interacting. It can be obtained from the probability that a neutron will interact in the distance interval between x and x+dx. Thus, the probability is equal to the product of these two probabilities (see Section 4.2 and the Example 6.5)

• The probability that a neutron will not interact along the distance x

$$P_{non-reaction}(x) = e^{-\Sigma x} \tag{6-21}$$

• The probability that a neutron will interact along the distance dx

$$P_{reaction}(dx) = \Sigma dx \tag{6-22}$$

The mean free path has a continuous value and can be obtained by integrating the product of probabilities assuming the length of neutron travel can span from zero to infinity

$$\lambda \equiv \overline{x} = \frac{\int_{0}^{\infty} x e^{-\Sigma x} \Sigma dx}{\int_{0}^{\infty} e^{-\Sigma x} \Sigma dx} = \frac{1}{\Sigma}$$
(6-23)

Example 6.6 Neutron mean free path

Calculate the mean free path and the time needed for a neutron with energy 100 eV to have its first interaction in a block of ⁵⁴Fe (see Example 6.3 for other data). The neutron mass is $1.67492716 \times 10^{-27}$ kg.

The neutron mean free path is equal to the reciprocal of the macroscopic cross section of the medium, therefore

$$\lambda = \frac{1}{\varSigma} = \frac{1}{0.157 \text{ cm}^{-1}} = 6.37 \text{ cm}$$

The neutron velocity is obtained from its energy

$$v = \sqrt{\frac{2T}{m_n}} = \sqrt{\frac{2 \times 10^2 \times 1.6 \times 10^{-19}}{1.67492716 \times 10^{-27}}} = 1.38 \times 10^5 \,\mathrm{m/s}$$

The time to the first interaction is therefore

$$t = \frac{\lambda}{v} = \frac{0.0637 \text{m}}{1.38 \times 10^5 \text{ m/s}} = 0.46 \mu \text{s}$$

4.4 **Reaction Rate and Concept of Neutron Flux**

In all situations involving the evaluation of neutron behavior the concern is to analyze neutron population as a whole and almost never the history of a single neutron. For the majority of applications (like neutron population behavior in nuclear reactors, transport of neutrons through shielding materials or in biological media), it is important to determine *neutron* reaction rates. A neutron interacts with the nuclei of a medium through scattering from one nucleus to another until it is absorbed or it escapes the boundary of a system. The mean free path that a neutron travels before it interacts can be defined as the mean free path for scattering, $\lambda_s = 1/\Sigma_s$, and for absorption $\lambda_a = 1/\Sigma_a$. The total mean free path is thus equal to: $\lambda_{tot} = 1/\Sigma_{tot}$. The reaction rate per unit volume of the target material and unit time for an *i*th type of interaction is

$$R_i = \frac{\Phi}{\lambda_i} = \Phi \Sigma_i = \Phi N \sigma_i \tag{6-24}$$

where Φ represents the total distance that the neutron travels in unit time and unit volume of a given target material. This variable is also called the *neutron flux* and has units of number of neutrons per unit time and unit area, neutrons/cm²/s.

If all neutrons have the same velocity v and the neutron density is n, then the neutron flux and neutron reaction rate may be written as

$$\Phi = n\upsilon \tag{6-25}$$

$$R_i = n\upsilon N\sigma_i \tag{6-26}$$

When neutrons have different velocities, it is necessary to define the neutron density as a function of velocity distribution such that n(v)dv represents the number of neutrons having velocity between v and v + dv

$$n = \int_{0}^{\infty} n(v) dv \tag{6-27}$$

In this case, the neutron flux and reaction rate become integral values

$$\Phi = \int_{0}^{\infty} n(v)vdv \tag{6-28}$$

$$R_i = \int_0^\infty n(v) v N \sigma_i(v) dv$$
(6-29)

If the average velocity of a neutron population

$$\overline{v} = \frac{\int_{0}^{\infty} n(v)vdv}{\int_{0}^{\infty} n(v)dv}$$
(6-30)

is used, then the neutron flux is

$$\Phi = n\overline{\upsilon} \tag{6-31}$$

Also, it is possible to define the average microscopic cross section

$$\overline{\sigma_i} = \frac{\int_{0}^{\infty} \sigma_i(v)n(v)vdv}{\int_{0}^{\infty} n(v)vdv}$$
(6-32)

which gives the relation for reaction rate

$$R_i = \Phi N \overline{\sigma_i} \tag{6-33}$$

Example 6.7 Reaction rate and flux

In a medium consisting of 10^{20} atoms of fissile material, a neutron flux is sustained at 5 x 10^{14} neutrons/cm²/s. If the reaction rate is 1.5×10^{13} reactions/cm³/s, calculate the macroscopic and microscopic cross sections of the medium.

The cross sections can be obtained from the following relations

$$\Phi = nv$$

$$R_{i} = nvN\sigma_{i} = \Phi\Sigma_{i} \quad \rightarrow \quad \Sigma_{i} = \frac{R_{i}}{\Phi} = \frac{1.5 \times 10^{13}}{5 \times 10^{14}} = 0.03 \text{ cm}^{-1}$$

$$\sigma_{i} = \frac{\Sigma_{i}}{N} = \frac{0.03}{10^{20}} = 3 \times 10^{-22} \text{ cm}^{2} = 300\text{ b}$$

4.5 Neutron Interactions

Neutron interactions can be described in three steps: the condition before the

interaction when the neutron is approaching the nucleus, an intermediate stage when the incident neutron forms a compound nucleus with the target, and the condition after the interaction. In the intermediate stage, the neutron is incorporated into the nucleus and forms a compound nucleus that has an atomic mass number increased by one in comparison to the target nucleus. The formation of the compound nucleus also means that the incident neutron transfers all of its energy to the target nucleus. The time for the formation of the compound nucleus is approximately the time that an incident neutron needs to travel across the target nucleus (about 10^{-21} sec). A newly formed compound nucleus is highly excited and unstable. It therefore decays after a relatively long period of time (typically from 10^{-19} to 10^{-15} second). Different types of neutron interactions are illustrated in Fig. 6-6.



Figure 6-6. Different types of neutron interactions

One of the important and characteristic features of neutron interactions with matter that proceed through a compound nucleus formation is that cross sections exhibit maximum values at certain incident neutron energies. These maximum values are called the *resonances* (see example for neutron cross sections for different types of interactions with ⁵⁶Fe in Fig.6-7). Nuclei have various excited states that correspond to different configurations of the nucleons within the nucleus (see Chapter 3). An incident neutron and a target nucleus are more likely to combine and form a compound nucleus if the energy of the incident neutron is such that the compound nucleus is produced in one of its excited states. These resonances appear in the cross section because it is necessary to form the compound nucleus before the interaction can proceed. The excitation energy of the compound nucleus is equal to the kinetic energy of the incident neutron plus the separation

(binding) energy of the neutron in the compound nucleus.

In the following sections the reactions shown in Fig. 6-6 are discussed with the exception of the fission reaction, which is described in detail in Section 5.



Figure 6-7. Cross section for various interactions of a neutron with ⁵⁶Fe

4.5.1 Elastic Scattering (n, n)

There are two possible ways for a neutron to scatter elastically from a nucleus

- *Resonance or compound elastic scattering*: the neutron is absorbed by the target nucleus to form a compound nucleus followed by re-emission of a neutron, and
- *Potential elastic scattering*: the neutron is scattered away from the nucleus by the short range nuclear force.

Potential scattering is the most common form of neutron elastic scattering and is schematically depicted in Fig. 6-8. The more unusual of the two interactions is resonance elastic scattering which is highly dependent upon initial neutron kinetic energy. The cross section for this interaction exhibits a resonance region as shown in Fig. 6-7.



Figure 6-8. Schematics of the elastic neutron scattering

Potential elastic scattering is more common and can be understood by visualizing the neutrons and nuclei as billiard balls with impenetrable surfaces. Potential scattering in which the neutron never actually touches the nucleus and a compound nucleus is not formed takes place with incident neutrons of energies up to about 1 MeV. Neutrons are scattered by the short range nuclear forces as they approach the nucleus. The cross section is approximately constant (see Fig. 6-7) and is expressed by the relation

$$\sigma_{el}$$
 (potential scattering) = $4\pi R^2$ (6-34)

where R is the nuclear radius (see Chapter 3).

Example 6.8 Potential elastic scattering

Using the experimental elastic scattering data from Fig. 6-7, estimate the radius of the ⁵⁶Fe nucleus.

From Fig. 6-7, the potential elastic cross section has a constant value of nearly 12 b from about 0.03 eV to 0.6 MeV. Thus, $4\pi R^2 = 12 \times 10^{-24} \text{ cm}^2$. Solving for *R*, we obtain $R = 9.77 \times 10^{-13} \text{ cm}$.

An elastic scattering reaction between a neutron and a target nucleus does not involve energy transfer *into* a nucleus. Momentum and kinetic energy are, however, conserved and there is usually some transfer of kinetic energy from the neutron to the target nucleus. The target nucleus thus gains the amount of kinetic energy that the neutron loses and moves away at an increased speed. If the neutron collides with a massive nucleus it rebounds with almost the same speed and loses a negligible amount of energy. However, light nuclei will gain a significant amount of energy from such a collision and will therefore be more effective in slowing down neutrons.

The largest energy transfer occurs for a head-on collision in which the neutron does not change its initial direction. Neutrons lose most of their incident energy when they interact elastically with light elements such as hydrogen. This is because the hydrogen nucleus has a mass (of one proton) nearly equal to that of the neutron.

Materials with a large content of hydrogen, such as water or paraffin, are therefore very important in the slowing down of neutrons (see Chapter 7). For example, in the case of hydrogen, the energy of a head--on scattered neutron will be zero, which means that the neutron transferred all of its energy to the hydrogen nucleus (see Example 6.2).

4.5.2 Inelastic Scattering (n, n')

In order for a neutron to undergo inelastic scattering with a nucleus its incident energy must be sufficient to place the target nucleus in an excited state. As a result, the inelastic cross section exhibits threshold energy (and is zero up to that energy). In general, the energy levels of the excited states of a nucleus decrease with increasing mass number. Elements of high and moderate mass number usually have minimum excitation energy in the range of 0.1 MeV to 1 MeV. Elements of lower mass number have increased nuclear excitation energies. This is why neutron inelastic scattering is more probable for heavier nuclei and thus the inelastic cross section is non-zero over a large energy region for heavier nuclei.



Figure 6-9. Inelastic cross section for ²³⁸U (data plotted from ENDF)

At energies well above the threshold value, the inelastic cross section is nearly equal to the elastic cross section. Three examples of inelastic cross sections in heavy, moderate and light elements are shown in Fig. 6-9 to 6-11. For example, it can be seen that the threshold energy for oxygen is around 6 MeV while for 238 U it is only 44 keV. Neutrons cannot undergo inelastic scattering in hydrogen or deuterium (see section 4.5.5). Magic numbered nuclei behave like light nuclei with respect to inelastic scattering for the same reason.



Figure 6-10. Inelastic cross section for 56 Fe (data plotted from ENDF)



Figure 6-11. Inelastic cross section for ²³⁸U, ⁵⁶Fe and ¹⁶O (data plotted from ENDF)

Inelastic scattering proceeds in two steps as depicted in Fig. 6-12. The interaction involves formation of a compound nucleus as an intermediate stage of the interaction process.

The compound nucleus is formed in an excited state due to the energy imparted to it by the incident neutron. In the next step, a neutron of lower kinetic energy is expelled from the nucleus leaving the nucleus in a lower exited state. The nucleus then regains stability, usually by emitting the excess energy in the form γ rays.



Figure 6-12. Schematics of neutron inelastic scattering gamma ray

The energy of the emitted γ rays is equal to the excess energy of the excited state of the target nucleus. The total incident neutron energy, E_0 , is distributed between the emitted γ ray, E_{γ} and the expelled neutron, E, see Fig. 6-12

$$E = E_0 - E_{\gamma} \tag{6-35}$$

4.5.3 Radiative Capture (n, γ)

Neutron capture (absorption of a neutron) is often called radiative capture

because γ rays are produced in the majority of these reactions. In this reaction neutrons form an isotope with mass number increased by one from the original nucleus (see Fig. 6-13).

The newly formed nucleus can be radioactive and will therefore decay. The neutron capture reaction does not require any specific neutron energy and the reaction can occur at any neutron energy level. These reactions are almost always exothermic (positive Q-value) because the binding energy of the newly formed nucleus is larger than the sum of the binding energies of the neutron and the original nucleus.



Figure 6-13. Schematics of radiative neutron capture

The radiative capture cross section is usually divided into three regions:

- In the low-energy region, for most nuclei, the radiative capture cross section varies as the inverse square root of incident neutron energy. Since the neutron speed is proportional to the square root of energy, the radiative cross section is said to vary as 1/v. Since the cross sections are usually plotted on a log-log scale the 1/v dependence appears as a straight line with a slope of -1/2, as can be seen from Fig. 6-14 to 6-17. Nuclei that do not show 1/v dependence are called non-1/v absorbers.
- Above the 1/v region is a resonance region in the same energy range as the resonance region for elastic scattering (because the nucleus formed in radiative capture is identical to the compound nucleus formed in elastic scattering). The radiative capture cross section in the resonance region may be expressed using the Breit–Wigner formula.
- Above the resonance region (ending around 1 keV in heavy nuclei and at higher energies in lighter nuclei) the radiative cross section drops rapidly and smoothly to very small values, as shown in Fig. 6-14 to 6-17.



Figure 6-14. Radiative capture cross section for ⁵⁶Fe in comparison with its total and elastic scattering cross section



Figure 6-15. Radiative capture cross section for ²³⁸U



Figure 6-16. Radiative capture cross section for ⁹³Nb



Figure 6-17. Radiative capture cross section for ⁵⁶Fe

4.5.4 Charged Particle Emission (n, α) , (n, p)

A charged particle reaction usually leads to emission of an α particle or a proton from the nucleus (see Fig. 6-18); thus charged particle reactions with slow neutrons are rare.



Figure 6-18. Schematics of charged particle emission

Examples of reactions in which the Q-value is positive (no incident neutron energy required) are

- ${}^{10}\text{B} + n \rightarrow {}^{11}\text{B}^* \rightarrow {}^{7}\text{Li} + \alpha$: The cross section for this reaction is shown in Fig. 6-19. It can be observed that the cross section is very large at low neutron energies. For this reason, ${}^{10}\text{B}$ is used as an absorber material for unwanted low energy neutrons. As neutron energy increases, the cross section decreases following $1/\nu$ dependence. The charged particles produced in this reaction are ejected in opposite directions with relatively high energies. They produce considerable ionization along a short range (see Chapter 5) and are capable of causing considerable damage to biological tissue. This reaction is the basic interaction upon which boron neutron capture therapy for the treatment of brain and skin cancers was developed.
- ${}^{6}\text{Li} + n \rightarrow {}^{7}\text{Li}^{*} \rightarrow {}^{3}\text{H} + \alpha$: This reaction is similar to the previous one and also shows strong 1/v dependence. The remaining nucleus is tritium, a β emitter and an isotope of special interest in fusion science. This reaction is used for the production of tritium.

• ${}^{16}O + n \rightarrow {}^{16}N + p$: is an endothermic reaction of interest in reactor design since it represents the source of radioactivity when water is used as a moderator.

The majority of interactions involving charged particle emission, however, are threshold reactions requiring the neutron to posses a minimum amount of energy. The cross sections tend to be small, especially for heavy nuclei (see Fig. 6-20).



Figure 6-19. Cross section for ${}^{10}B$ + n interaction

4.5.5 Hydrogen and Deuterium

Hydrogen and deuterium are present in a majority of nuclear reactors. These nuclei interact with the neutrons in a specific manner (see Fig. 6-21)

- interactions with neutrons do not involve the formation of a compound nucleus (these nuclei have no excited states because all states are filled for the given number of nucleons)
- there are no resonances (because there is no formation of a compound nucleus)
- elastic scattering cross section is constant up to 10 keV
- radiative capture cross section at all energies shows 1/v dependence, and
- inelastic scattering does not occur (because there is no formation of a compound nucleus).

4.5.6 Cross Sections for Different Neutron Interactions

The concept of microscopic, σ , and macroscopic, Σ , cross sections is described in Section 4.1. The cross sections for any neutron interaction, *i*, are

related as follows

$$\Sigma_i = N\sigma_i \tag{6-36}$$



(b) Figure 6-20. Cross section for charged particle emission from neutron interaction with (a) 56 Fe and (b) 197 Au



Figure 6-21. Neutron cross sections for (a) 1 H and (b) 2 H

The total macroscopic cross section for all interactions is a summation of individual values

$$\Sigma = \sum_{i} N\sigma_i \tag{6-37}$$

The values of both cross sections express the probability for neutron interaction to occur. If the material that a neutron interacts with consists of a

mixture of different atoms, the macroscopic cross section representing the summation of individual values will be used to determine the probability of interaction. For example, the macroscopic radiative capture cross section of the material is

$$\Sigma_{\gamma} = N_1 \sigma_{\gamma,1} + N_2 \sigma_{\gamma,2} + \dots = \sum_j N_j \sigma_{\gamma,j}$$
(6-38)

where N_j represents the number density of nuclei of each constituent in a material. For neutrons traveling in a material the probability of certain interactions is determined based on known macroscopic cross section values. For example, the probability for a neutron to be captured in the next collision with the atoms of material j is given by

$$\frac{N_j \sigma_{\gamma,j}}{\Sigma} \tag{6-39}$$

In the analysis of cross sections and interactions it is common to group similar interactions. For example, the absorption cross section relates to all interactions that terminate the neutron history: capture interaction, fission and charged particle interactions

$$\sigma_a = \sigma_\gamma + \sigma_f + \sigma_p + \sigma_\alpha + \dots \tag{6-40}$$

Example 6.9 Probability of neutron interactions in a homogeneous medium

Estimate the probability of a neutron interacting with ²³⁵U to be captured if the microscopic cross sections are: $\sigma_{\gamma} = 98.6$ b, $\sigma_f = 582.2$ b and $\sigma_s = 13.8$ b.

Since the medium is homogeneous and thus composed of only one type of atom, the probability can be computed using the microscopic cross section values. The probability that the neutron will be captured is

$$\frac{\sigma_{\gamma}}{\sigma_{\gamma} + \sigma_{f} + \sigma_{s}} = \frac{98.6}{98.6 + 582.2 + 13.8} = 0.142$$

Neutron reaction cross sections vary with neutron energy, neutron interaction type, and isotope type. Those interactions that do not exhibit threshold values, such as capture and fission in ²³⁵U or capture in ²³⁸U, have large cross sections at low neutron energy. A threshold interaction observes zero cross section values up to certain energy, such as fission in ²³⁸U for which fission becomes significant only if the neutron energy is above 1MeV.

The energy of interest in reactor physics ranges from the high energy that fission neutrons are born with to thermal neutron energies in thermal nuclear reactors. Across this wide span of energies, the cross sections for different neutron interactions show different dependence. The mean value of the fission neutron spectrum (the energies with which fission neutrons are born - see Section 5) is around 2 MeV, while neutrons that are slowed to the thermal region have energies of 0.025 eV. The high energy neutrons are moving at a high speed relative to the nuclei in a medium; therefore the dominant interactions are scattering in which neutrons slow down. In materials that have a large scattering cross section (like hydrogenous medium) neutrons lose most of their energy after only a few interaction events and come into thermal equilibrium with the nuclei of the medium. Since the nuclei themselves are in thermal motion there is an exchange of momentum in scattering interactions. Such neutrons have a Maxwellian spectrum (see Section 4.6) dependent on the temperature of the medium. Therefore, the neutron population in a reactor has a complicated spectrum that is a mixture of fast, intermediate and slow neutrons. The particular spectrum characteristics are determined by the materials present in the medium. For example, in a medium with a high scattering to absorption cross section ratio, the spectrum of neutrons will fall predominantly in the thermal energy region. However, in the opposite case of a medium consisting of materials with high absorption to scattering ratios, the neutron spectrum will not differ much from the source spectrum.

At low energies the total microscopic cross section for the non-threshold interactions behaves as

$$\sigma_{tot} = 4\pi R^2 + \frac{C}{\sqrt{E}} \tag{6-41}$$

where C is a constant, E is the neutron energy and R represents the radius of a nucleus.

The first term in the above equation represents the elastic cross section, while the second term gives the cross section for radiative capture or other exothermic reactions possible at that energy. If the first term dominates over the second term, then the total cross section is constant at low energies. An example is shown in Fig. 6-22 for ⁵⁶Fe for which the total cross section is constant at low energies. If the second term dominates over the first term, the total cross section behaves as $1/\nu$. An example is shown in Fig. 6-22 for ²³⁹Pu for which the cross section varies with the inverse square root of neutron energy at low energies. Cross section data libraries usually give the capture and fission cross sections for thermal energy neutrons traveling at the speed of $\nu_p = 2200$ m/s (which corresponds to neutron energy

 $E_p = 0.025$ eV and temperature 293 K, as explained below). For the nuclei for which $1/\nu$ dependence of the absorption cross section is valid, the absorption cross section at any other energy of up to few eV can be estimated from



$$\sigma_a(E) = \sigma_a(E_p) \sqrt{\frac{E_p}{E}} \qquad \sigma_a(\nu) = \sigma_a(\nu_p) \frac{\nu_p}{\nu} \qquad (6-42)$$

Figure 6-22. Total cross section dependence on neutron energy for ⁵⁶Fe and ²³⁹Pu

In the resonance region, elastic scattering, radiative capture, and inelastic scattering, and thus total cross section, all exhibit resonance in same energy region. The cross section at the peak values can be as high as a few thousand barns. The resonances correspond to the discrete energy levels of the compound nucleus formed after neutron interaction. Neutrons with energy comparable to the energy levels of a compound nucleus have a high probability of interaction. The lowest energy at which resonances begin to appear is around 0.5 eV and the maximum is about 0.1 MeV. As can be seen from Fig. 6-22, as energy is increased the resonances become closer. All values for cross sections are obtained experimentally; however, in the region where resonances are too close together an experiment can not resolve them (region called the unresolved resonances). In the high energy region (0.1 MeV and above), the total cross section becomes a smooth function of neutron energy. The cross section is small rarely reaching values greater than 5 b. The charged particle reactions become significant (see Fig. 6-20). The elastic scattering cross section remains almost constant across the energy

region below the resonances for almost all isotopes. The average value for the cross section ranges between one and ten barns from one isotope to another over a wide energy range (see Fig. 6-23).



Figure 6-23. Comparison of elastic scattering cross sections for ¹H, ⁵⁶Fe, ²³⁵U and ²³⁹Pu

4.6 Maxwell-Boltzmann Distribution

In a medium in which neutrons are not absorbed and from which neutrons cannot escape, the only possible interaction is scattering with the nuclei of the atoms. The scattering interactions reduce the neutron energy. However, an endless slowing down process is not possible because of the thermal motion of the atoms. Due to that fact they cannot be assumed to be stationary, which is usual approximation in analysing neutron interactions. When neutron energy becomes comparable to the energy of thermal motion of the atoms, the neutrons come to a thermal equilibrium. It means that the probability that a neutron will gain or lose energy in a collision with the nuclei is equal. The average kinetic energy of thermal motion of the atoms (according to the kinetic theory of gases) is given by

$$\overline{E} = \frac{3}{2}kT \tag{6-43}$$

where k is the Boltzmann constant (1.380662 x 10^{-23} J/K), and T is temperature of the medium (in Kelvin). Therefore, in a thermal equilibrium

state, neutrons can gain or lose kinetic energy $(mv^2/2)$, *i.e.* exchange their kinetic energy with the nuclei of atoms in the medium. In an ideal medium without absorption and leakage, the neutron energy distribution will be the same as that of the atoms in thermal motion. The thermal neutrons, even at a specific temperature, do not all have the same energy or velocity. Such spectrum is called a *Maxwellian-Boltzmann distribution*, or referred as a Maxwellian distribution. Although such conditions are not satisfied in a real reactor system, it is useful to assume that neutrons become thermalized to the extent that they follow the Maxwellian distribution

$$\frac{n(E)}{n} = \frac{2\pi}{\left(\pi kT\right)^{3/2}} e^{-E/kT} E^{1/2} \iff \frac{n(\upsilon)}{n} = \frac{4\pi \upsilon^2}{\left(2\pi kT/m\right)^{3/2}} e^{-m\upsilon^2/2kT}$$
(6-44)

where:

 $n \equiv$ thermal neutron population per unit volume

 $m \equiv$ neutron rest mass

 $T \equiv$ temperature in K

n(E) and $n(v) \equiv$ Maxwellian energy (or velocity) distribution of neutrons per unit volume and unit energy (or velocity) interval

The left side of Eq. (6-44) represents the fraction of neutrons having energies (or velocities) within a unit energy interval (or velocity interval) and the right side represents the Maxwellian distribution curve as shown in Fig. 6-24. The most probable neutron velocity, v_p , is found by setting the derivative of n(v) with respect to velocity equal to zero

$$\frac{dn(\upsilon)}{d\upsilon} = \frac{8\pi\upsilon n}{\left(2\pi kT/m\right)^{3/2}} e^{-m\upsilon^2/2kT} - \frac{4\pi\upsilon^2 n}{\left(2\pi kT/m\right)^{3/2}} \frac{2m\upsilon}{2kT} e^{-m\upsilon^2/2kT} = 0 \quad (6-45)$$

$$\upsilon_p = \sqrt{\frac{2kT}{m}} \tag{6-46}$$

The most probable energy can be obtained in the same way to give kT/2. The kinetic energy of thermal neutrons with most probable velocity is

$$E_{p} = \frac{mv_{p}^{2}}{2} = \frac{m}{2}\frac{2kT}{m} = kT$$
(6-47)



Figure 6-24. Maxwellian velocity distribution of neutrons

Note that the most probable (as well as average) kinetic energy is independent of particle mass. For thermal neutrons at 20°C (or 293K) the most probable velocity and the corresponding kinetic energy are

$$\upsilon_p = \sqrt{\frac{2kT}{m}} = \sqrt{\frac{2 \times 1.38 \times 10^{-23} \text{ J/K} \times 293 \text{ K}}{1.66 \times 10^{-27} \text{ kg}}} = 2200 \text{ m/s}$$
$$E_p = kT = 1.38 \times 10^{-23} \text{ J/K} \times 293 \text{ K} = 4.043 \times 10^{-21} \text{ J} \times \frac{1}{1.6 \times 10^{-19} \text{ J/eV}}$$
$$= 0.025 \text{ eV}$$

The values for microscopic cross sections provided on most charts and tables are measured for this neutron velocity (2200 m/s), which corresponds to an ambient temperature of 68° F (see Section 4.5.6) and energy of 0.025 eV.

The average neutron velocity is obtained from

$$\overline{\upsilon} = \frac{\int_{0}^{\infty} n(\upsilon)\upsilon d\upsilon}{\int_{0}^{\infty} n(\upsilon)d\upsilon} = \frac{\int_{0}^{\infty} \frac{4\pi v \,\upsilon^{3} e^{-m\upsilon^{2}/2kT}}{(2\pi kT/m)^{3/2}} d\upsilon}{\int_{0}^{\infty} \frac{4\pi v \,\upsilon^{2} e^{-m\upsilon^{2}/2kT}}{(2\pi kT/m)^{3/2}} d\upsilon} = \sqrt{\frac{8kT}{\pi m}}$$
(6-48)

The ratio of the average velocity to the most probable velocity of neutrons in the Maxwellian spectrum is

$$\frac{\overline{v}}{v_p} = \frac{\sqrt{8kT/\pi n}}{\sqrt{2kT/m}} = \frac{2}{\sqrt{\pi}} = 1.128$$

The cross section at these velocities changes accordingly and is shown as follows. The neutron flux for the Maxwellian distribution of neutrons is given by

$$\phi(E) = \upsilon n(E) = \frac{2\pi n}{(\pi kT)^{3/2}} e^{-E/kT} E \sqrt{\frac{2}{m}}$$
(6-49)

The average absorption cross section for this population of neutrons assuming 1/v dependence can be estimated

• As described in Section 4.4.6 for the 1/v absorption cross section dependence, the following correlation between the cross sections holds

$$\sigma_a(E) = \sigma_a(E_p) \sqrt{\frac{E_p}{E}}$$
 where $E_p = kT$ (6-50)

• The average absorption cross section is then

$$\overline{\sigma_{a}(E_{p})} = \frac{\int_{0}^{\infty} \sigma_{a}(E)\phi(E)dE}{\int_{0}^{\infty} \phi(E)dE}$$

$$= \frac{\sigma_{a}(E_{p})\int_{0}^{\infty} \sqrt{\frac{E_{p}}{E}} \frac{2\pi n}{(\pi kT)^{3/2}} \sqrt{\frac{2}{m}} Ee^{-E/kT}dE}{\int_{0}^{\infty} \frac{2\pi n}{(\pi kT)^{3/2}} \sqrt{\frac{2}{m}} Ee^{-E/kT}dE} =$$

$$= \frac{\sigma_{a}(E_{p})\int_{0}^{\infty} \sqrt{\frac{kT}{E}} Ee^{-E/kT}dE}{\int_{0}^{\infty} Ee^{-E/kT}dE} = \frac{\sqrt{\pi}}{2}\sigma_{a}(E_{p})$$
(6-51)

The values for microscopic absorption cross sections at a higher temperature are lower than the tabulated value (which is generally for the most probable neutron velocity at ambient temperature) and any cross sections which involve absorption (fission, capture) must be corrected for the existing temperature. The average absorption cross section at the average neutron velocity and temperature, T, higher than the ambient is given by

$$\overline{\sigma_a(E_p,T)} = \frac{\sqrt{\pi}}{2} \sigma_a(E_p, 293K) \sqrt{\frac{293}{T}}$$
(6-52)

Example 6.10 Average and temperature corrected 1/v absorption cross section

The absorption cross section for 235 U at the most probable neutron velocity and energy is 680.8 barns. Assuming the cross section follows the 1/v rule, determine the average cross section at the temperatures of 293K and 600K.

The average absorption cross section at the most probable neutron energy is

$$\overline{\sigma_a(E_p)} = \frac{\sqrt{\pi}}{2}\sigma_a(E_p) = \frac{\sqrt{\pi}}{2} \times 680.8 = 603.3$$
barns

If the temperature of neutron population is increased to 600K, the average absorption cross section will change as

$$\overline{\sigma_a(E_p,T)} = \frac{\sqrt{\pi}}{2} \sigma_a(E_p, 293K) \sqrt{\frac{293}{T}} = 603.3 \times \sqrt{\frac{293}{600}} = 421.6$$
barns

However, the absorption cross sections of some materials important in reactor neutronic design do not exhibit exact 1/v dependence. Examples are ²³⁵U, ²³⁸U, and ²³⁹Pu. In these cases, an empirical factor, g(T), based on actual cross section measurements is introduced to correct for the departure from 1/v behaviour. The actual thermal cross section corrected for the average absorption temperature is then

$$\overline{\sigma_a(E,T)} = g(T) \frac{\sqrt{\pi}}{2} \sigma_a(E_p, 293K) \sqrt{\frac{293}{T}}$$
(6-53)

Example 6.11 Average and temperature corrected non-1/v absorption cross section

The radiative capture cross section for ²³⁵U at the most probable neutron velocity and energy is 98.81 barns. From the table of nuclides (http://atom.kaeri.re.kr/), the

g(T) factor is found to be 0.9898. Calculate the average radiative capture cross section at energy 0.0253 eV. Calculate the value of the cross section at 600K?

The average radiative capture cross section for a Maxwellian distribution of the neutron population is

$$\overline{\sigma_a(E_p)} = g(T)\frac{\sqrt{\pi}}{2}\sigma_a(E_p) = 0.9898 \times \frac{\sqrt{\pi}}{2} \times 98.81 = 86.67 \text{ barns}$$

If the temperature of the neutron population is increased to 600K, the average radiative capture cross section becomes

$$\overline{\sigma_a(E_p,T)} = g(T) \frac{\sqrt{\pi}}{2} \sigma_a(E_p, 293K) \sqrt{\frac{293}{T}} = 86.67 \times \sqrt{\frac{293}{600}} = 60.57 \text{ barns}$$



Figure 6-25. Energy spectrum of thermal neutrons (departure from Maxwellian distribution)

In thermal reactors, it is not possible to obtain a neutron spectrum that will follow exactly the Maxwellian distribution. The reasons for this are

 Neutrons produced by the fission process are high-energy neutrons that are (in thermal reactors) slowed down by primarily elastic collisions with moderator (light) nuclei. The proportion of neutrons of higher energy is greater than that required by the Maxwellian distribution (see Fig. 6-25). This is because neutrons that are absorbed or that leak out of the reactor do not have a chance to slow down. This shift of the neutron energy spectrum from Maxwellian toward the high neutron energy region is called absorption hardening.

2. In the low energy region, a real neutron spectrum approaches the Maxwellian distribution. The departure depends on the absorption and leakage (escape from the geometrical boundaries) rate in the system, as neutrons may either be absorbed or lost before they come to equilibrium with the moderator atoms. In this energy region, the absorption cross section is inversely proportional to the neutron speed. In spite of these facts, the neutron spectrum in the thermal region is usually approximated by the Maxwellian distribution at a temperature somewhat higher than the moderator temperature. This temperature is called an effective neutron temperature.

4.7 Doppler Broadening



Figure 6-26. Doppler broadening

Cross sections are commonly associated with neutron energy. However, they actually depend on the *relative energy* of the interacting neutron and nucleus. The relative energy is identical to the neutron energy only if the nucleus is at rest is. In reality, the nuclei in a solid are "vibrating" about fixed points, and this energy of vibration increases with temperature. At some given temperature, the vibration energies tend to follow a Maxwellian distribution over a wide range of the energy spectrum. Therefore, even for monoenergetic neutrons, the energies relative to the target nuclei vary over a wide range of values (below and above the incident neutron energy). This phenomenon is called the *Doppler Effect* because of similarity with the change in wavelength observed with a moving source of light or sound of constant frequency. Since the vibration energies increase with temperature, the range of the neutron-nucleus relative energies also increases. As a result of the Doppler Effect, the width of a resonance peak increases with temperature (see Fig. 6-26), an effect known as *Doppler broadening*. The increase in the resonance width is accompanied by a reduction in resonance height, while the area under the resonance remains constant. The total rate of neutron absorptions in the resonance region (a product of neutron flux and cross section) increases with temperature. This aspect is important in analyzing the temperature reactivity coefficients in reactors.

4.8 Neutron Beam Attenuation and Neutron Activation

Neutron beam attenuation is determined from

$$I = I_0 e^{-\Sigma x} \tag{6-54}$$

where:

 $I_0 \equiv$ initial intensity of the neutron beam

 $\Sigma \equiv$ macroscopic cross section (cm⁻¹)

 $x \equiv$ thickness (cm) of the attenuating material

The above equation can be expressed in term of the attenuation factor, AF, given as

$$AF = \frac{I_0}{I} = e^{\Sigma x} \tag{6-55}$$

Example 6.12 Thermal neutron attenuation factor

Calculate the attenuation factor (AF) for thermal neutrons passing through a layer of water 2.5 cm thick. The macroscopic cross section for thermal neutrons is 0.02 cm^{-1} .

From the definition of the neutron beam attenuation factor, it follows

$$AF = \frac{I_0}{I} = e^{\Sigma x} = e^{0.02 \times 2.5} = 1.05$$

Materials exposed to a neutron flux will absorb neutrons in proportion to the cross section at that neutron energy. Once an atom absorbs a neutron it changes into a heavier isotope that is most likely radioactive (unstable). The absorption of neutrons by certain materials permits the production of sources of radioactivity in a reactor, but also affects the structural components of the reactor core. The same principle is used to infer the level of neutron flux at points of interest in a reactor core using neutron-absorbing foils. The activity of the foils following irradiation is proportional to the neutron flux in which the foil was placed. For example, if an isotope formed in neutron flux, ϕ , is unstable, it will start to decay as soon as it is produced. Assuming there are N nuclei of a newly formed isotope and N_0 nuclei of the original target isotope, the rate of change of new nuclei can be obtained from

$$\frac{dN}{dt} = \phi N_0 \sigma_a - \lambda N = \phi \Sigma_a - \lambda N \tag{6-56}$$

where λ is the decay constant of the newly formed, unstable isotope. The above equation can be rearranged to obtain the first-order differential equation as

$$\frac{dN}{dt} + \lambda N = \phi \Sigma_a \tag{6-57}$$

the solution of which is of the form

$$N = \frac{1}{e^{\int \lambda dt}} \int e^{\int \lambda dt} \phi \Sigma_a dt - \frac{C}{e^{\int \lambda dt}}$$
(6-58)

where C is a constant of integration. Equation (6-58) can be rearranged to obtain

$$N = \frac{1}{e^{\lambda t}} \int e^{\lambda t} \phi \Sigma_a dt - \frac{C}{e^{\lambda t}} = \frac{\phi \Sigma_a}{\lambda} - \frac{C}{e^{\lambda t}}$$
(6-59)

The constant of integration is obtained from the initial condition

$$N(t=0) = 0 \implies 0 = \frac{\phi \Sigma_a}{\lambda} - \frac{C}{1} \implies C = \frac{\phi \Sigma_a}{\lambda}$$
 (6-60)

Thus

$$N = \frac{\phi \Sigma_a}{\lambda} \left(1 - e^{-\lambda t} \right) \tag{6-61}$$

The buildup of a radioactive isotope during irradiation in a neutron flux
is depicted in Fig. 6-27. The material will decay with its characteristic half–life once removed from the neutron flux.



Figure 6-27. Buildup of radioactive isotope during irradiation in neutron flux

Example 6.13 Neutron activation

A cylinder made of ⁵⁹Co has a volume of 1 cm³. It was placed in a reactor core with a flux of 10⁸ n/cm²/sec for one year. Calculate the activity of the sample on removal from the reactor, and the activity of the same sample one year following later. The temperature of the sample during irradiation was 200 °C. After the absorption of a neutron, ⁵⁹Co forms ⁶⁰Co in its isomeric state. The unstable ⁶⁰Co decays in two ways, either through internal conversion or beta minus decay as shown in Fig. 6-28. The density of a sample is 8.71 g/cm³. The atomic weight of ⁵⁹Co is 58.94 gr/gr-atom.

```
<sup>59</sup>C<sub>0</sub> + n \longrightarrow <sup>60</sup>C<sub>0</sub>*

Internal conversion to <sup>60</sup>C<sub>0</sub>, T_1 = 10.5 minutes, \sigma_1 = 18 barns

<sup>60</sup>C<sub>0</sub>* \longrightarrow

\beta- decay to <sup>60</sup>Ni, T_2 = 1925.1 days, \sigma_2 = 19 barns
```

Figure 6-28. Neutron absorption by ⁵⁹Co

Let's first determine the decay constants for the two isomers (data are given in Fig. 6-24)

$$\lambda_1 = \frac{\ln 2}{T_1} = \frac{\ln 2}{10.6} \times 60 = 3.97 \,\mathrm{hr}^{-1} \qquad \lambda_2 = \frac{\ln 2}{T_2} = \frac{\ln 2}{1925.1 \times 24} = 1.50 \times 10^{-5} \,\mathrm{hr}^{-1}$$

The number of target nuclei is

$$N_0 = \frac{V\rho N_a}{A} = \frac{(1\text{cm}^3)(8.71g/\text{cm}^3)(6.023 \times 10^{23} \text{ at/gr atom})}{58.94 \text{gr/gr atom}} = 0.890 \times 10^{23} \, {}^{59}\text{Co atoms}$$

Since the temperature of the sample was higher than 293K, the average cross sections must be corrected

$$\overline{\sigma_{a1}(E_p)} = \frac{\sqrt{\pi}}{2} \sigma_{a1}(E_p) = \frac{\sqrt{\pi}}{2} \times 18 = 15.95 \text{ barns}$$

$$\overline{\sigma_{a1}(E_p,T)} = \frac{\sqrt{\pi}}{2}\sigma_{a1}(E_p,293\text{K})\sqrt{\frac{293}{T}} = 15.95 \times \sqrt{\frac{293}{473}} = 12.55\text{ barns}$$

$$\overline{\sigma_{a2}(E_p)} = \frac{\sqrt{\pi}}{2} \sigma_{a2}(E_p) = \frac{\sqrt{\pi}}{2} \times 19 = 16.84 \text{ barns}$$

$$\overline{\sigma_{a2}(E_p,T)} = \frac{\sqrt{\pi}}{2} \sigma_{a2}(E_p,293\text{K}) \sqrt{\frac{293}{T}} = 16.84 \times \sqrt{\frac{293}{473}} = 13.25 \text{ barns}$$

The one-year irradiation period will saturate the short-lived isomer and the second term in Eq. (6-61) can be neglected to give

$$N_{1} = \frac{\phi N_{0} \overline{\sigma_{a1}(E_{p},T)}}{\lambda_{1}} = \frac{(10^{8} \text{ n/cm}^{2} \text{s})(0.89 \times 10^{23} \text{ atoms})(12.55 \times 10^{-24} \text{ cm}^{2})}{3.97 \frac{1}{3600 \text{s}}}$$

 $N_1 = 1.01 \times 10^{11} \, {}^{60}$ Co atoms

The concentration of the longer-lived isomer is

$$N_{2} = \frac{\varphi^{1+0} \sigma_{a2} (D_{p}, Y)}{\lambda_{2}} \left(1 - e^{-\lambda_{2}t}\right)$$
$$= \frac{(10^{8} \text{ n/cm}^{2} \text{s})(0.89 \times 10^{23} \text{ atoms})(13.25 \times 10^{-24} \text{ cm}^{2})}{1.50 \times 10^{-5} \frac{1}{3600 \text{s}}} (1 - e^{-1.50 \times 10^{-5} \times 1 \times 365 \times 24})$$

 $N_2 = 3.48 \times 10^{15}$ ⁶⁰ Co atoms

 $\phi N \sigma (E T)$

The activity on removal is

$$A_0 = N_1 \lambda_1 + N_2 \lambda_2 = 1.11 \times 10^8 \text{ Bq} + 1.45 \times 10^7 \text{ Bq} = 1.26 \times 10^8 \text{ Bq}$$
$$A_0 = 1.26 \times 10^8 \text{ Bq} \times \frac{1}{3.7 \times 10^{10} \text{ Bq/Ci}} = 3.4 \text{mCi}$$

One year following removal from the reactor core, the activity of the sample will be the activity of the long-lived isotope since the short-lived will have decayed away

$$A = A_0 \left(e^{-\lambda_2 t} \right) = (0.39 \text{ mCi}) \left(e^{-1.50 \times 10^{-5} \times 365 \times 24} \right) = 0.34 \text{ mCi}$$

5. FISSION

5.1 Mechanism of the Fission Process

Fission represents a class of nuclear interactions in which the original target nucleus splits into smaller nuclei. Fission also represents the class of neutron interactions that produces neutrons and energy and as such is a basic principle of nuclear power generation. Fission can be a spontaneous process. For example, ²⁴⁰Pu and ²⁵²Cf decay by spontaneous fission; however, such nuclei are rare and the decay rate is very low.

In the fission process, a neutron interacts with the target nucleus creating a compound nucleus that is unstable and splits into smaller nuclei releasing two or more neutrons and energy. The compound nucleus thus temporarily contains all of the charge and mass involved in the reaction and exists in an excited state. The excitation energy added to the compound nucleus is equal to the sum of the binding energy of the incident neutron and its kinetic energy. A schematic of the fission process is illustrated in Fig. 6-29 for neutron interaction with ²³⁵U. The smaller nuclei formed after the compound nucleus decays are called fission products or fission fragments. They are usually radioactive and decay by β^- decay. Not every interaction of a neutron with a nucleus leads to fission after forming the compound nucleus. Since the compound nucleus is in an excited state, it can reach stability by emitting γ rays. Such reactions as explained in Section 4.5.3 are called radiative capture reactions.



Figure 6-29. Schematics of a fission process for ²³⁵U



Figure 6-30. Critical energy for fission

If the excitation energy of the compound nucleus is greater than a certain critical energy, the compound nucleus may become dumbbell-shaped due to forces acting between the nucleons and eventually splits into smaller nuclei as shown in Fig. 6-29. The mechanism of fission can also be understood from the graphical representation of potential energy levels in a compound nucleus and in fission fragments as sketched in Fig. 6.30. At the extreme

right, fission fragments are apart and the potential energy of the system is virtually zero. As fission fragments become closer, there is an increase in potential energy due to the electrostatic repulsion force acting between their positive parts. The potential energy reaches its maximum value when the fission fragments are in contact with one another. At this point, the attractive nuclear forces become dominant and the potential energy decreases up to a certain value that corresponds to the ground state of the compound nucleus. In order for fission to occur, the system must transition from the left to the right side in Fig. 6-30. The energy difference between the maximum value and the energy that corresponds to the ground state of the compound nucleus represents the critical energy (also called the activation energy) for fission. According to the liquid drop model, the critical energy for fission decreases as Z^2/A increases. This is explained by the fact that repulsion between nucleons (which favours fission) increases with Z^2 , while the attraction force is nearly proportional to A: for $Z^2/A < 35$, the critical energy is so large that neutrons (or other particles) of high energy are required to cause fission; for $Z^2/A > 35$, the critical energy is on the order of the binding energy of the incident neutron and thus fission can be caused by even a low-energy neutron.

5.2 Fission Rate and Reactor Power

As described in Section 4.4, the rate of any interaction involving monoenergetic neutrons is equal to $\Sigma \phi$. For fission reactions it follows

Fission rate =
$$\sum_{f} \phi [fissions/m^3/s]$$
 (6-62)

where:

 $\Sigma_f = N\sigma_f$ $\phi = n\upsilon$ $N \equiv \text{number of fissile nuclei [nuclei/m^3]}$ $\sigma_f \equiv \text{fission cross section [m^2/nucleus]}$ $n \equiv \text{neutron density [neutrons/m^3]}$ $\upsilon \equiv \text{neutron speed [m/s]}$

In a reactor, neutrons are not monoenergetic, but rather cover a wide range of energies. Neutron flux and cross sections, and thus reaction rates, are energy dependent. At a given neutron energy, the neutron flux at a given time varies with the spatial position in the reactor. Also, the spatial distribution of fissile material is not entirely uniform initially and is not uniform after the reactor has been operating for a certain time. In order to determine a fission rate at a given time, the above equation has to be integrated over all neutron energies and spatial positions in the reactor. In practice, this is done using computer codes. However, for the present purpose, an approximate method will be shown. In thermal reactors, the majority of fissions occur in the thermal energy region where flux and macroscopic cross sections are both very large. The fission rate can be roughly estimated assuming the average values (space and energy) for flux and cross section. Therefore, in a reactor of volume $V[m^3]$

$$Total number of fissions = V \Sigma_f \phi$$
(6-63)

Assuming that the reactor has been operating for enough time that nearly all of the radioactive decay energy is being deposited as heat, and that a fission rate of 3.1×10^{10} *fissions/s* is required to produce 1 *watt* of thermal power, thermal reactor power can be approximated as

$$P_{th} = \frac{V\Sigma_f \phi}{3.1 \times 10^{10}} [W]$$
(6-64)

Example 6.14 Reactor power

A water-moderated reactor contains 100,000 kg of uranium dioxide enriched to an average of 2.5% by weight in ²³⁵U. The atomic ratio $H/^{235}U$ is 200. Calculate the approximate (spatial) average thermal neutron flux for a thermal power of 3000 MWth with an average moderator temperature of 310°C.(Adopted from: Glasstone and Sesonske, 1994)

For ²³⁵U at T = 300K, the total fission cross section at 0.0253 eV is 584.4 barns and g(T) = 0.9786.

$$\overline{\sigma_f(E_p)} = g(T) \frac{\sqrt{\pi}}{2} \sigma_f(E_p) = 0.9786 \times \frac{\sqrt{\pi}}{2} \times 584.4 = 506.8 \text{ barns}$$

If the temperature of the neutron population is increased to 310°C (583K), the average radiative capture cross section becomes

$$\overline{\sigma_f(E_p,T)} = g(T) \frac{\sqrt{\pi}}{2} \sigma_f(E_p, 300\text{K}) \sqrt{\frac{300}{T}}$$
$$= 506.8 \times \sqrt{\frac{300}{583}} = 363.5 \text{ barns}$$

The fraction of 235 U in 235 UO₂ is 235/(235+(2 x 16) = 235/267. Therefore, the mass of 235 U is

$$m = 10^5 \text{ kg} \frac{235}{267} \frac{2.5}{100} = 2.2 \times 10^3 \text{ kg}$$

The total number of ²³⁵U nuclei in a reactor is

$$NV = \frac{mN_a}{A} = \frac{(2.2 \times 10^3)(6.023 \times 10^{23})}{235 \times 10^{-3}} = 5.6 \times 10^{27} \text{ nuclei}$$

and the neutron flux is

$$\overline{\phi} = \frac{3.1 \times 10^{10} P_{th}}{NV \overline{\sigma_f(E_p, T)}} = 4.6 \times 10^{17} \,\mathrm{n/cm^2 s}$$

5.3 Fission Neutrons

In the first 10^{-14} seconds following the fission process, 99% of the neutrons are emitted; these are called the prompt neutrons. The prompt neutrons accompany the emission of fission fragments and prompt γ -rays. Over a period of several minutes, the unstable fission fragments emit so-called delayed neutrons. The role of each group of neutrons, prompt and delayed, in reactor kinetics is explained in Chapter 7.

The average number of neutrons emitted per each neutron absorbed that causes a fission reaction is usually denoted as v and for thermal reactor fuel is ~ 2.5 (see Table 6-2). This number is not an integer because it represents the average value over a number of fission events (each single fission event emits an integer number of neutrons).

Neutron	²³³ U		²³⁵ U		²³⁸ U		²³⁹ Pu	
energy								
	V	η	V	η	ν	η	V	η
0.025 eV	2.50	2.30	2.43	2.07	-	-	2.89	2.11
1 MeV	2.62	2.54	2.58	2.38	-	-	3.00	2.92
2 MeV	2.73	2.57	2.70	2.54	2.69	2.46	3.11	2.99

Table 6-2. Number of neutrons emitted per fission, *v*, and per neutron absorbed, η

The number of neutrons emitted per each neutron absorbed (in fission and all other interactions) in the fissile materials is denoted as η

$$\eta = v \frac{\Sigma_f}{\Sigma_a} \tag{6-65}$$

where, for a single fissile material, the macroscopic cross sections for fission and absorption can be replaced with microscopic values

$$\frac{\Sigma_f}{\Sigma_a} \to \frac{\sigma_f}{\sigma_a} \tag{6-66}$$

This ratio represents the fraction of neutrons that are absorbed and subsequently cause fission in a given material and is usually written as

$$\frac{\sigma_f}{\sigma_a} = \frac{\sigma_f}{\sigma_f + \sigma_\gamma} = \frac{1}{1 + \alpha} \quad \leftarrow \quad \alpha = \frac{\sigma_\gamma}{\sigma_f} \tag{6-67}$$

where α represents the capture-to-fission ratio, an energy dependent parameter of great importance in reactor core design, as explained later. The number of neutrons emitted per each neutron absorbed can now be expressed in terms of α

$$\eta = \frac{\nu}{1 + \alpha} \tag{6-68}$$

However the reactor core consists of more than one single fissile material, and thus Eq. (6-65) must be written in a more generalized form

$$\eta_{fuel} = \frac{\sum_{i} \left(\nu \Sigma_{f} \right)_{i}}{\Sigma_{a}} \tag{6-69}$$

where the numerator represents the sum over all fissile nuclides and the denominator represents the total absorption cross section for all materials present in fuel. For example, for a thermal reactor in which the fuel is in the form of uranium oxide and the uranium is a mixture of 235 U and 238 U, the above equation reduces to

$$\eta_{fuel} = v^{235} \frac{\Sigma_f^{235}}{\Sigma_a^{235} + \Sigma_a^{238}}$$

knowing that the only fissile material is ²³⁵U and that the absorption cross section for oxygen is small enough to be neglected.

Prompt neutrons are emitted with different energies. As a result, the population of prompt neutrons exhibits a distribution or so-called energy

spectrum. The prompt neutron energy spectrum is depicted in Fig. 6-31 for thermal fission of 235 U. The spectrum shows a peak (most probable value) at an energy of approximately 1 MeV and an average value of 2 MeV. The energy spectrum is important because, in additional to the fissile material present in a reactor core, there is usually an amount of fertile materials (such as 238 U or 232 Th) for which the fission cross sections have a threshold value, or a certain energy value below which the fission cross section is zero. The prompt neutron energy spectrum shown in Fig. 6-31 can be described by the following equation

$$\chi(E) = 0.453e^{-1.036E} \sinh(2.29E)^{0.5} \tag{6-70}$$



Figure 6-31. Prompt fission neutron energy spectrum for thermal fission of ²³⁵U

5.4 Fission γ Rays

The γ radiation emitted per each fission event is divided into two groups: prompt and delayed. The prompt γ rays are emitted within 0.1 µs of the fission event (arbitrarily defined time) with an average energy of 1 MeV. One portion of the prompt γ rays is emitted at about the same time as the prompt neutrons, and another portion is represented by the γ rays from the decay of fission fragments with short half–lives. The delayed γ rays come from the decay of fission fragments having half–lives longer than the arbitrarily defined time of $0.1 \ \mu s$.

The approximate gamma ray energy distribution is shown in Figure 6-32 for the fission of 235 U. The spectrum can be divided into three regions approximately represented by the following relations

$$\Gamma(E) = \begin{bmatrix} 6.6 & E = 0.1 \sim 0.6 \text{MeV} \\ 20.2e^{-1.78E} & E = 0.6 \sim 1.5 \text{MeV} \\ 7.2e^{-1.09E} & E = 1.5 \sim 10.5 \text{MeV} \end{bmatrix}$$
(6-71)

The total energy of the prompt γ rays is close to 7.3 MeV per fission event with an average value of around 0.9 MeV.



Figure 6-32. Prompt fission γ rays energy spectrum

5.5 Fission Products

5.5.1 Fission Yield

Majority of fission events produces two fission products. The pair formed per single fission varies from event to event giving a broad distribution of isotopes. For example, a detailed study of the thermal neutron fission of ²³⁵U has shown that about 80 different isotopes are created. Some of these fission products are shown in Table 6-3.

Element	A	Half–life	Fission yield (%)
Strontium	89	51 d	4.8
Strontium	90	28 у	5.8
Yttrium	91	58 d	5.4
Zirconium	95	65 d	6.3
Ruthenium	103	40 d	3.0
Ruthenium	106	1 y	0.4
Antimony	125	2 у	0.02
Tellurium	127	105 d	0.04
Tellurium	129	37 d	0.35
Cesium	137	30 y	6.2
Cerium	141	33 d	6.0
Cerium	144	280 d	6.0
Promethium	147	2.6 y	2.4
Samarium	151	80 y	0.44

Table 6-3. ²³⁵U thermal fission products



Figure 6-33. ²³⁵U thermal fission yield versus atomic mass number

The yield represents the proportion (percentage) of all nuclear fissions that form isotopes of a given mass. The 235 U fission yield is plotted in Fig. 6-33 versus atomic mass number. This plot is shown to illustrate that most of

the fission fragments are radioactive and decay via β decay, which changes the atomic number but not the atomic mass number. The fission yield curve indicates that the maximum yield for any one isotope is less than 7%. It also indicates that fission products fall into two broad groups: a group of light nuclei with mass number between 80 and 110, and a heavy group with mass numbers between 125 and 155.

The most probable isotopes to be produced have mass numbers between approximately 95 and 139, each having a yield of about 6.4%. The kinetic energy of fission fragments per fission event is also distributed according to the fission fragment distribution given in Figure 6-33. For the most abundant isotope in the heavy group, the kinetic energy is around 67 MeV and around 98 MeV for the isotopes in light group. The ratio of these two energies (98/67) is 1.46, which is equal to the ratio of their masses (139/95).

5.5.2 Formation and Removal of Fission Products in a Reactor

The amounts and activities of individual fission products are important in reactor design because:

- it is necessary to evaluate the potential hazards associated with an accidental release of fission products into the environment
- it is necessary to determine a proper cooling time for the spent fuel (before it becomes ready for reprocessing), which depends on the decay times of fission products
- it is necessary to estimate the rate at which heat is released as a result of radioactive decay of the fission products after the shut down of a reactor
- it is necessary to calculate the poisoning effect of the fission products (the parasitic capture of neutrons by fission products that accumulate during the reactor operation)

The rate at which the concentration of a nuclear species (N_i) in a reactor core changes with time is given by (see Figure 6-34)

$$dN_i/dt$$
 = Formation Rate - Destruction rate - Decay Rate (6-72)

The *formation* of a nuclide *i* (atomic mass number *A*, atomic number *Z*) is defined by: fission, neutron capture in nuclide *j* (atomic mass number A - 1, atomic number *Z*), and radioactive decay (usually β decay) of nuclide *k* (atomic mass number *A*, atomic number *Z* – 1). It can be expressed as

Formation rate =
$$\gamma_i N_j \sigma_j \phi + N_j \sigma_j \phi + \lambda_k N_k$$
 (6-73)

where: γ_i is the fission yield of that nuclide,

 N_{f} , N_{i} and N_{k} are the nuclear number densities of the fissile

nuclides,

 σ_{f} is the fission cross section of the fissile material,

 σ_j is the capture cross section of the nuclide j,

 ϕ is the neutron flux, and

 λ_k is the radioactive decay constant of nuclide k.



Figure 6-34. Formation and removal of fission products

The *destruction* of a nuclide i (atomic mass number A, atomic number Z) by neutron capture is defined as

Destruction Rate = $N_i \sigma_i \phi$ (6–74)

Destruction of a nuclide also occurs through its own β decay, which is expressed as

Decay Rate =
$$\lambda_i N_i$$
 (6-75)

Thus the rate at which the concentration of a nuclear species (N_i) in a reactor core changes with time becomes

$$dN_i/dt = \gamma_i N_f \sigma_f \phi + N_i \sigma_i \phi + \lambda_k N_k - N_i \sigma_i \phi - \lambda_i N_i$$
(6-76)

This equation can be solved for N_i , at any time, assuming that all other concentrations and constants are known. This equation develops into coupled differential equations for which the exact solution is obtained using computer codes.

After a certain time of reactor operation, a concentration of any fission fragment should reach an equilibrium (saturation) value. At that point, the rate of production is equal to the rate of removal of that nuclide. For many important fission products, like ⁹⁰Sr or ¹³¹I, only the first and the last terms in Eq. (6-76) are significant

$$dN_i/dt \sim \gamma_i N_f \sigma_f \phi - \lambda_i N_i \tag{6-77}$$

At the reactor start–up (t = 0), we may assume that the concentration of fission fragment *i* is zero. Also, a good assumption is that the neutron flux reaches a constant value shortly after start–up. At that point in time, a saturation concentration (density) of the nuclide *i* is

$$N_{i,sat} \sim \frac{\gamma_i N_f \sigma_f \phi}{\lambda_i} \tag{6-78}$$

It follows that for a given flux and fission fragment cross section (σ_j), the saturation number density is increased by large fission yield (γ_i), and long half–life (small λ_i). If other conditions are equal, the saturation number density increases with the neutron flux.

The ratio of the number density at any time to the saturation value is then given by

$$\frac{N_i}{N_{i,sat}} \sim 1 - e^{-\lambda_i t} \tag{6-79}$$

When the reactor is shut-down, the neutron flux becomes negligible and the rate at which the concentration of a nuclear species (N_i) in a reactor core changes with time reduces to

$$dN_i/dt = \lambda_k N_k - \lambda_i N_i \tag{6-80}$$

If the rate of decay of k into i is larger than the decay rate of i, then the nuclear density of the fission fragment i increases with time. If i decays faster than it is generated by the decay of k, then the fission fragment concentration decreases with time. In this case, however, after a certain period of time, the decrease in k decay will produce a situation where the concentration of i attains its maximum value (when $\lambda_k N_k = \lambda_i N_i$). After that, the concentration decreases again with time.

The activity after shut-down may be determined using a semi-empirical approach (for times 10s to 100d after shut-down), which gives a close estimate to detailed calculations using computational methods. The total rate of β emission is given by the following semi-empirical relation

Rate of
$$\beta$$
 emission per fission event ~ 3.2 $t^{-1.2}$ [1/s] (6-81)

where t is given in seconds after the fission event. If every fission

product is assumed to emit a β particle when it decays, the activity may be determined by

Fission product activity per fission ~
$$3.2 t^{-1.2} [Bq]$$

~ $8.6 x 10^{-11} t^{-1.2} [Ci]$ (6-82)

5.6 Energy Released in Fission

The energy released by fission can be calculated based on the difference in mass between the masses of the neutron and the fissile nucleus before fission and the fission fragments and fission neutrons after fission. There is a variation in the total energy released per fission that depends on the fissionable isotope and the products of the fission event. On average, some 200 MeV is released per thermal fission. This energy is distributed as shown in Table 6-4.

Table 6-4. Fission energy distribution

¥	
Fission Product	Energy (MeV)
Kinetic energy of fission fragments	165 +/- 5
Instantaneous gamma rays	7 +/- 1
Kinetic energy of neutrons	5 +/- 0.5
Beta particles from product decay	7 +/- 1
Gamma rays from product decay	6 +/- 1
Neutrinos from product decay	10
TOTAL	200 +/- 6

Example 6.15 Energy released per thermal fission event

In a typical thermal fission of 235 U as shown below, calculate the instantaneous fission energy.

$${}^{1}_{0}n + {}^{235}_{92}U \rightarrow \left({}^{236}_{92}U \right)^{*} \rightarrow {}^{140}_{55}Cs + {}^{93}_{37}Rb + 3 \left({}^{1}_{0}n \right)$$

$$m_{\text{reactants}} = m_{\frac{215}{92}U} + m_{\frac{1}{9}n} = (235.043924 + 1.008665) = 236.052589 \text{amu}$$
$$m_{\text{products}} = m_{\frac{93}{37}Rb} + m_{\frac{140}{55}Rb} + 3(m_{\frac{1}{9}n})$$
$$= (92.91699 + 139.90910 + 3.02599) = 235.85208 \text{amu}$$

The instantaneous fission energy is the energy released immediately after the

fission process. It is equal to the energy equivalent of the mass lost in the fission process. It can be calculated as follows

$$\Delta m = m_{\text{reactants}} - m_{\text{products}} = 236.052589 \text{amu} - 235.85208 \text{amu} = 0.200509 \text{amu}$$

 $E_{\text{instantaneous}} = 0.200509 \left(\frac{931.5 \text{MeV}}{\text{amu}}\right) = 186.8 \text{MeV}$

NUMERICAL EXAMPLE

Neutron Attenuation in Common Moderator Materials

Graphite and water are two common materials used as moderators in nuclear reactors. Using the given data, construct an attenuation plot of two beams of thermal neutrons passing through water and graphite. Comment on the apparent effectiveness of each material as a moderator.

	ρ	$\sigma_{t}(b)$	M
	(g/cm^3)		(g/mole)
Water	1.0	5.33	18.015
Graphite	1.6	103.66	12.000

Solution in MATLAB:

```
clear all
Na = 6.022e23; % Avagadro's Number
% Total thermal microscopic cross section
sigma_C = 5.33; %b
sigma_Water = 103.66; %b
s = 10^{-24*}[sigma_C sigma_Water];
rho(1) = 1.6; % carbon g/cm^3
rho(2) = 1; \% water g/cm<sup>3</sup>
M = [12 \ 18.015];
for i = 1:2
  Sigma(i) = s(i)*rho(i)*Na/M(i);
end
x = linspace(0, 15);
for i = 1:2
  for i = 1:100
     I(i,j) = \exp(-Sigma(j)*x(i));
  end
```

```
end
figure
hold on
plot(x,I(:,1),'k')
plot(x,I(:,2),'k:')
xlabel('Distance (cm)')
ylabel('Fractional Intensity')
legend('Graphite','Water')
```



Figure 6-35. Neutron attenuation in graphite and water

Water appears to be a generally more effective moderating material.

PROBLEMS

6.1. Uranium oxide (UO₂) has a theoretical density of 10.96 g/cm³. Calculate the number density (nuclei/cm³) of uranium and oxygen if a sample of UO₂ has a density equal to theoretical density. Calculate the number densities for the fuel in a reactor that has usually a density equal to 0.95 the theoretical density.

6.2. The microscopic cross sections at 0.0253 eV for tungsten are given in table below. Calculate the capture cross section for the element tungsten. Which isotope contributes the most to the capture cross section? If only the isotopes 180, 184 and 186 produce a radioactive daughter by the reaction (n,γ) what is the activation cross section for tungsten?

Isotope and % abundance		$\sigma_c (0.0253 \text{ eV})$	
^{-180}W	0.12	30.0	
^{182}W	26.3	20.0	
^{183}W	14.3	10.3	
^{184}W	30.7	1.8	
¹⁸⁶ W	28.6	38.0	

6.3. Calculate the macroscopic absorption and scattering cross section for 4.8 atom percent enriched UO₂ fuel both at 20°C and 300°C. Assume the density of UO₂ is 92 % theoretical density (see Problem 6.1).

6.4. What thickness of water is necessary to reduce the intensity of a collimated beam of 1 MeV and 10 MeV neutrons by factor 10^6 ? Repeat for lead.

	σ (barns)	Atoms/cm ³	Σ (/cm)	
<u>1 MeV:</u>				
Hydrogen	4.2	6.70 E+22	0.281	
Oxygen	8	3.35 E+22	0.268	
Lead	5.5	3.23 E+22	0.178	
<u>10 MeV:</u>				
Hydrogen	0.95	6.70 E+22	0.064	
Oxygen	1.5	3.35 E+22	0.050	
Lead	5.1	3.23 E+22	0.165	

6.5. A sample of 10 g of ⁵⁵Mn is irradiated by a flux of $10^8 \text{ m}^{-2} \text{ s}^{-1}$ of thermal neutrons. Calculate the saturation activity of ⁵⁶Mn produced after an irradiation time of 7 h. The cross-section for ⁵⁵Mn(n, γ)⁵⁶Mn is 13.41 b and the half-life of ⁵⁶Mn is 2.6 h.

6.6. If 10 g of gold sample is inserted into the reactor at neutron flux of 10^9 n/cm²s, how many atoms of ¹⁹⁸Au will be formed after 30 minutes? What is the activity of the sample after it is removed from the reactor assuming none of the gold atoms decays until removed from the reactor.

6.7. Discuss the following two nuclear reactions:

35
Cl(n, α) 32 P 32 S(n, p) 32 P

6.8. Calculate the threshold energy for the reaction ${}^{13}C(n,a){}^{10}Be$. The atomic masses in amu are: $M({}^{13}C) = 13.0033548$; $M({}^{10}Be) = 10.0135337$.

6.9. A parallel beam of 0.25 MeV neutrons impinges on target of aluminium that is 1 cm thick. Calculate what fraction of neutrons will undergo a neutron capture

event on their first collision in the last 1 mm of a target (σ_{tot} (Al) = 3b and σ_{γ} (Al) = 1b).

6.10. If an isotropic source is placed in the center of a sphere what is the probability (in percent) that a neutron will be emitted in a cone with a solid angle of 0.30 steradians?

6.11. Prove the Eq. (6-48). Calculate the most probable energy for neutrons with Maxwell – Boltzmann distribution and explain why it is not the energy corresponding to the most probable velocity?

6.12. Evaluate the nuclear reaction ${}^{4}N + {}^{4}He \rightarrow {}^{17}O + {}^{1}H$ is it endothermic or exothermic? Calculate the energy (in MeV), Q, of the reaction. Masses in amu: H = 1.007825; neutron = 1.008665; He = 4.00260; ${}^{14}N = 14.00307$; and ${}^{17}O = 16.99914$.

6.13. Some stars at the end of their lives collapse combining their protons and electrons to form a so called neutron star. Such a star could be approximated by a giant atomic nucleus. Assume its mass is equal to that of the Sun $(2 \times 10^{30} \text{ kg})$ and that it collapsed into neutrons $(1.67 \times 10^{-27} \text{ kg})$, what would be the radius of this star?

6.14. Boron is a common material used to shield against thermal neutrons. Calculate the thickness of boron required to attenuate an incident thermal neutron beam to 0.1% its intensity. Use the thermal cross section of 103 cm^{-1} .

6.15. Calculate the fission rate density to produce a thermal power density of 400 kW/litter (typical for fast breeder reactors), assuming that the main fissile isotope is 239 Pu.

6.16. Follow the numerical example as given and calculate and plot the neutron beam attenuation through beryllium.

6.17. Plot the fission cross section to show that 232 Th requires a very fast neutron to induce fission. Compare it to the conditions for fission on 238 U.

6.18. ²³⁶U fissions into ¹⁰²Mo and ¹³¹Sn isotopes. Knowing that the number of nucleons must be conserved write the reaction. How many free neutrons are produced in this and how many in the fission process that produces ⁸⁸Br and ¹⁴⁰La?

6.19. If one of fission fragments for the 240 Pu fission is 90 Sr what is the second element? If the mass number of the second element is 142, how many free neutrons are produced? Write the equation.

6.20. For the fission reaction $^{235}U + n \rightarrow {}^{142}Cs + {}^{90}Rb + 4 n$ estimate the energy released per reaction.

6.21. A borated-steel sheet (relative density 7.8) which is used as a control rod in a reactor is 2 mm thick and contains 2% boron by weight. The atomic masses of boron and iron are 10.8 and 55.9 and their nuclear absorption cross sections for thermal neutrons are 755 x 10^{-28} m² and 2.5 x 10^{-28} m² respectively. Assuming that the thermal neutrons strike the sheet at normal incidence, what fraction of them is absorbed?

6.22. The nuclide ²⁵⁶Fm decays through spontaneous fission with a half-life of 158 minutes. If the energy released is about 220 MeV per fission, calculate the fission power produced by 1 μ g of this isotope.

6.23. The thermal fission cross section for 235 U is 577 b while its thermal capture (non-fission) cross section is 101 b. The isotope 238 U does not fission for neutrons with thermal energies but does have a small capture cross section of 2.75 b. Naturally occurring uranium is 99.3% 238 U and 0.7% 235 U. Given that an average of 2.44 fast neutrons is produced per fission calculate how many of these fast neutrons are produced for each thermal neutron absorbed in natural uranium.

6.24. A 100 MW reactor consumes half its fuel in three years. How much 235 U does it contain?

6.25. A beam of thermal neutrons is incident upon a thick layer of cadmium (density 8650 kg m⁻³, cross section 24506 barn). Find the absorption length (*i.e.* the distance in which the beam is reduced by a factor 1/e).

6.26. A free neutron decays into a proton, electron and antineutrino. Assuming the latter to be massless and the original neutron to be at rest, calculate the maximum momentum that could be carried off by the electron and compare this with the maximum momentum which the antineutrino could have.

6.27. A spectrum of β particles are emitted during the fission process. How far will a 9 MeV β travel in a water moderated reactor? (Recall the radiation interactions with matter described in Chapter 5).

6.28. Cadmium and boron are strong neutron absorbers and are the most common materials used in control rods. Write neutron absorption reaction in boron and calculate the Q - value for this reaction.

6.29. Find the energy of a hydrogen atom moving at speed of 2.2 x 10^6 cm/sec. What is the kinetic energy of the thermal neutron at room temperature moving at the speed of 2200 m/sec?

6.30. Show that the number of neutrons per absorption, η , for ²³⁵U homogeneous thermal reactor is ~2.08.

6.31. Calculate the neutron density from a reactor thermal flux of 10^{12} n/cm²sec. Compare it with the number of particles 1cm³ contains at standard temperature and standard pressure.

6.32. Estimate the reactor power which fuel is made of 5 % enriched uranium metal. The total weight of the fuel is 100 kg. The average neutron flux is 10^{13} n/cm²s. Assume the density of the fuel is 18.7 g/cm³. The microscopic fission cross section for ²³⁵U is 549 b.

6.33. Determine the probability that a 2 MeV neutron will undergo its first collision in 0.476 cm diameter UO₂ fuel rod enriched to 4 % in ²³⁵U. Assume that the neutron is born in the center of the fuel rod and that it travels radially toward the fuel boundary. The fuel density is 94 % theoretical density (10.96 g/cm³).

Chapter 7

NEUTRON TRANSPORT

Time Independent and Time Dependent Neutron Transport Theory - Concepts and Examples

"When we have carried out the indicator experiments that proved that barium was present, I wrote some personal letters to Lise Meitner, telling her of our results. In my letter of 19 December I wrote: ... The thing is there is something so odd about the 'radium isotopes' that for the moment we don't want to to tell anyone but you. The half-lives of three isotopes are pretty accurately determined; they can be separated from all elements except barium; all reactions are correct. Except for one - unless there are some very weird accidental circumstances involved: the fractionation doesn't work. Our Ra isotopes behave like Ba... Strassmann and I agree that for time being nobody should know but you. Perhaps you can put forward some fantastic explanation..." Otto Hahn (1879 - 1968)

1. INTRODUCTION

Design of a reactor core requires detailed prediction of the *balance* between neutron production and neutron loss. The rates of neutron production, transport and absorption are key information not only for core design and analysis but also for thermal-hydraulic, heat-mass transfer, accident scenarios and radioactivity release estimates. After neutrons are born in fission reactions, they move through the reactor core and undergo collisions of various types (absorption and scattering). There are two main absorption processes which may occur, radiative capture and fission. In fission, the target isotope splits and releases additional neutrons. In radiative capture, the neutron is parasitically absorbed and does not contribute to sustaining the chain reaction. In scattering collisions (elastic or inelastic)

neutrons change their energy, spatial position and direction of motion in a process known as *slowing down*. In general, the interaction of neutrons with nuclei in medium may be considered as neutrons being *transferred or transported* from one location to another, from one energy to another, and from one direction of motion to another. A schematic diagram of the various paths for a neutron born in a thermal reactor is depicted in Fig 7-1. The details of neutron interactions as well as the concept of the sustained (and controlled) chain reaction are described in the succeeding sections.



Figure 7-1. Schematic diagram of the history of neutron born in thermal nuclear reactor

2. CONCEPT OF TIME INDEPENDENT NEUTRON TRANSPORT

2.1 The Nuclear Chain Reaction

Seven months after the discovery of the neutron and more than six years before the discovery of uranium fission (September, 1932) Leo Szilard postulated that a controlled release of nuclear power may be possible if materials that would sustain the neutron chain production could be identified. In 1934 he filed a patent application for a weapon based on the release of nuclear power from such materials and also defined the concept of critical mass. A year later, he received the patent which made him the legal inventor of the nuclear bomb. The reason he patented the idea was to protect the use of such powerful weapon and prevent the destruction Second World War brought to humanity.

After the discovery of neutrons, many scientists across the world developed a number of experiments to analyze the effects of bombarding different materials with this new particle.

In late 1938, Otto Hahn and Lise Meitner were able to develop a theoretical interpretation of experiments involving neutron interactions with uranium. On December 21, 1938, Hahn submitted a paper to a German journal, *Naturwissenschaften*, in which he showed convincing evidence of the fission leading to production of radioisotopes from uranium irradiated with thermal neutrons. Soon after the concept of the fission was understood, a number of trials followed to find the method to produce a self–sustained reaction in which neutrons born in fission would induce fission in other uranium nuclei.

As described in Chapter 6, on average 2.5 neutrons are emitted per thermal fission event. In order to sustain a fission reaction, at least one should be conserved to continue the fission process. The essential problem in achieving a sustained nuclear fission reaction is related to the neutron economy.

A history of a single neutron born from fission in enriched uranium is schematically depicted in Fig. 7-1. Interaction of ²³⁵U with a neutron of any energy will split the nucleus into two smaller nuclei and release a few fast neutrons. However, ²³⁸U can absorb neutrons in the non–fission reaction called radiative capture that remove neutron from the chain reaction. This is why the fuel in thermal reactors is enriched in ²³⁵U; increasing its content from the natural value of 0.7%. The typical enrichment in nuclear power reactors is about 5%. Fast neutrons can produce fission of ²³⁸U nucleus and the probability of this interaction depends on reactor core structure, fuel type and fuel composition. Along with being absorbed (radiative capture by fuel or other materials present in a core) neutrons can be removed by escaping the physical boundaries of the system. As long as more neutrons are produced than lost the chain reaction will be sustained and the fission process will generate additional neutrons and energy.

In a nuclear weapon, the chain reaction is uncontrolled and a giant amount of energy is generated in a short period of time leading to an explosion. In nuclear reactors the control and sustainability of the chain reaction is achieved by introducing materials which absorb neutrons.

2.2 Fick's Law

The number of neutrons per unit volume is a function of neutron energy,

neutron spatial position and its direction of motion, and is referred as angular neutron density

$$N = N$$
 (spatial position, direction, energy) = $N(r, \Omega, E)$ (7-83)

Neutron balance is described by the *neutron transport equation* which expresses the distribution of the neutron population in space, energy and time. In a steady-state condition, the neutron density is assumed to be constant with respect to time.

The neutron transport equation is also called the *Boltzmann equation* because it is derived from the kinetic theory of gases developed by Boltzmann in the later part of the 19^{th} century.

Neutrons of a given energy moving in a given direction collide with nuclei of atoms in a reactor core producing other neutrons that have a wide range of energies and directions of motion. It is thus necessary to describe neutron transport by integrating over all neutron energies and spatial directions. The neutron transport equation is therefore an integro-differential equation which can be solved exactly for only a few simple cases. For practical applications, various simplifications and computational methodologies are developed and solutions are produced using complex software packages.

One of the simplest approximations to transport theory is *diffusion theory*. The name is given because it involves relationships similar to Fick's law of gas diffusion. Diffusion theory is explained in detail in the following sections. A numerical example based on what is currently the most attractive and advanced deterministic approach in neutron transport modelling in complex geometries (method of characteristics) is presented at the end of this Chapter.

Diffusion is defined as the random walk (Brownian motion) of a group of particles from a region of high concentration to a region of lower concentration. This means that the diffusing mass flows in the direction of decreasing concentration and such a flow rate is proportional to the negative concentration gradient.

By definition, the gradient (see Fig. 7-2 and Fig. 7-3) of a straight line is an indication of how steep that line is and may be calculated as follows

Gradient = Change in
$$Y$$
 / Change in X . (7-84)

From Fig. 7-3, it follows that the gradient can be defined as

Gradient (slope) =
$$\frac{\Delta f}{\Delta x}$$
, (7-85)

 Δf and Δx represent finite quantities; for infinitesimal quantities, it follows that the gradient is represented as



Figure 7-2. Examples of a gradient: starting from the left end of the line, going to the right the gradient is *positive*, up is positive, and down is negative, across to the left is also negative



Figure 7-3. Definition of a gradient

$$\lim_{\Delta \to 0} \frac{\Delta f}{\Delta x} = \frac{df}{dx}$$
(7-86)

Fick's law defines diffusion of particles from the region of higher concentration to the region of lower concentration as (see Fig. 7-4)

$$J_x = -\chi \frac{dC}{dx} \tag{7-87}$$

where J_x [cm⁻² s⁻¹] represents the net current, *C* is the particle concentration, *x* is position, and χ is the diffusivity constant [cm²/s] which describes how fast (or slow) an object diffuses. Concentration is defined as the amount of mass in a given volume represented in units of mol/cm³ or mol/liter. The negative sign indicates that J_x is positive when the movement

is down the gradient, *i.e.*, the negative sign cancels the negative gradient along the direction of the positive net current.



Figure 7-4. Fick's law



Figure 7-5. Vector notation of the current in three-dimensional space

Fick's law can also be written in terms of particle flux. ϕ , as

$$J_x = -D\frac{d\phi}{dx} \tag{7-88}$$

where $d\phi/dx$ [cm⁻³ s⁻¹] represents the flux gradient, and D [cm] is called the *diffusion coefficient*. Fick's law can be written in vector form to analyze three–dimensional space (see Fig. 7-5)

$$\vec{J}(\vec{r},t) = -D\nabla\phi(\vec{r},t) \tag{7-89}$$

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where: $\vec{J}(\vec{r},t)$ represents the neutron current density or the net flow vector of neutrons passing through a unit area perpendicular to the direction of neutron motion per unit time. Divergence of the neutron current density represents the net number of neutrons leaking from the unit volume per unit time (see next Section) and the term $\nabla \phi(\vec{r},t)$ represents the gradient of neutron flux in three-dimensional space.

2.3 Diffusion Coefficient and Diffusion Length

Neutron current density, neutron flux and the diffusion coefficient are correlated variables. In order to derive the relation for the diffusion coefficient which depends on the nuclear characteristics of the medium the following assumptions are made:

- 1. There is no neutron sources in the medium of interest
- The medium is homogeneous, i.e. neutron cross section is independent of spatial position
- 3. Angular neutron distribution in the medium is isotropic
- 4. Neutron flux is nearly uniform in the medium
- 5. The medium is considered to be infinite



Figure 7-6. The formation of neutron current

According to Fig. 7-6, the unit area dA, is located at the origin in the zy plane. The differential volume dV represents the volume from which neutrons will scatter through the area dA contributing a differential current flow in the negative z direction, dJ_z^- . The net current flow in the z direction, dJ_z^- from the upward flow in the lower hemisphere, dJ_z^+

$$J_{z} = J_{z}^{+} - J_{z}^{-}$$
(7-90)

The number of neutrons which are elastically scattered per unit time from the differential volume dV placed at distance r from the origin is equal to

$$\sum_{s} \phi(r) dV \tag{7-91}$$

where Σ_s is the elastic scattering cross section and is not a function of position due to the assumption 2, however the neutron flux is position dependent. Because it was assumed that neutrons are scattered isotropically in the medium (assumption 3) the number of neutrons which will pass through the unit area dA is

$$\Sigma_s \phi(\vec{r}) dV \frac{dA\cos\theta}{4\pi r^2} \tag{7-92}$$

where $dA\cos\theta$ represents the projection of the unit area dA onto the plane perpendicular to r or the effective surface area as seen from dV. The number of neutrons scattered through the area dA is $dA\cos\theta/4\pi r^2$ under the assumption that there are no interactions as neutrons travel from dV to dA. However, due to interactions between these two position in space, the number of neutrons that reach the area dA is the fraction $\exp(-\Sigma_{tot} r)$ of the total neutrons where Σ_{tot} is the total neutron cross section. The remainder of neutrons are scattered or absorbed in the medium. In spherical coordinates, the elementary volume is defined as

$$dV = r^2 \sin\theta dr d\theta d\phi \tag{7-93}$$

Assuming the medium is only weakly absorbing $(\Sigma_{tot} \sim \Sigma_s)$ the number of neutrons passing through the unit area in the plane *xy* in direction *z* is

$$J_{z}^{-} = \frac{\sum_{s}}{4\pi} \int_{\varphi=0}^{2\pi} \int_{\theta=0}^{\pi/2} \int_{r} e^{-\sum_{tor} r} \phi(\vec{r}) \cos\theta \sin\theta dr d\varphi d\theta$$
(7-94)

Although flux is not known, under the assumption that it is nearly independent of spatial position (assumption 4), using the McLaurin series and by neglecting all terms except the first two, it follows

$$\phi(\vec{r}) = \phi_0 + x \left(\frac{\partial \phi}{\partial x}\right)_0 + y \left(\frac{\partial \phi}{\partial y}\right)_0 + z \left(\frac{\partial \phi}{\partial z}\right)_0$$
(7-95)

Index 0 denotes the origin point. In the spherical coordinate system

$$\begin{cases} x = r\sin\theta\cos\varphi \\ y = r\sin\theta\sin\varphi \\ z = r\cos\theta \end{cases}$$
(7-96)

It therefore follows that

$$J_{z}^{-} = \frac{\sum_{s}}{4\pi} \int_{\varphi=0}^{2\pi} \int_{\theta=0}^{\pi/2} \int_{r} e^{-\sum_{s} r} \left[\phi_{0} + \left(\frac{\partial \phi}{\partial z}\right)_{0} r \cos \theta \right] \cos \theta \sin \theta dr d\varphi d\theta$$
(7-97)

Assumption 5 states that the medium is infinite and the integration over r is from 0 to infinity reducing the above integral to

$$J_{z}^{-} = \frac{\Sigma_{s}}{4\pi} \phi_{0} \left[\frac{-e^{\Sigma_{s}r}}{\Sigma_{s}} \right]_{0}^{\infty} \left(\frac{1}{2} \right) \sin^{2} \theta \left]_{0}^{\pi/2} \varphi \right]_{0}^{2\pi} + \frac{\Sigma_{s}}{4\pi} \left(\frac{\partial \phi}{\partial z} \right)_{0} \left[\frac{e^{-\Sigma_{s}r}}{\Sigma_{s}^{2}} \left(-\Sigma_{s}r - 1 \right) \right]_{0}^{\infty} - \frac{\cos^{3} \theta}{3} \right]_{0}^{\pi/2} \varphi \right]_{0}^{2\pi}$$
(7-98)

Following substitution of the limits

$$J_{z}^{-} = \frac{\Sigma_{s}}{4\pi} \phi_{0} \left[\frac{1}{\Sigma_{s}} \right] \left(\frac{1}{2} \right) (2\pi) + \frac{\Sigma_{s}}{4\pi} \left(\frac{\partial \phi}{\partial z} \right)_{0} \left[\frac{1}{\Sigma_{s}^{2}} \right] \left(\frac{1}{3} \right) (2\pi)$$
(7-99)

$$J_{z}^{-} = \frac{\phi_{0}}{4} + \frac{1}{6\Sigma_{s}} \left(\frac{\partial\phi}{\partial z}\right)_{0}$$
(7-100)

The upward current flow through the area dA from the lower hemisphere is obtained by integration as above with θ limits from π to $\pi/2$. Therefore, the number of neutrons passing through the unit area in direction +z is

$$J_{z}^{+} = \frac{\phi_{0}}{4} - \frac{1}{6\Sigma_{s}} \left(\frac{\partial\phi}{\partial z}\right)_{0}$$
(7-101)

Thus the total net flow of neutrons in direction z is

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$$J_{z} = J_{z}^{+} - J_{z}^{-} = -\frac{1}{3\Sigma_{s}} \left(\frac{\partial \phi}{\partial z} \right)_{0}$$
(7-102)

the net flow of neutrons through the areas in xz and in yz plane are

$$J_{y} = -\frac{1}{3\Sigma_{s}} \left(\frac{\partial \phi}{\partial y}\right)_{0}$$
(7-103)

$$J_x = -\frac{1}{3\Sigma_s} \left(\frac{\partial \phi}{\partial x}\right)_0 \tag{7-104}$$

The neutron current density (number of neutrons per unit time crossing unit area normal to direction of flow) is according to Fig. 7-5

$$\vec{J}(\vec{r}) = \vec{a_x}J_x + \vec{a_y}J_y + \vec{a_z}J_z = -\frac{1}{3\Sigma_x} \left[\vec{a_x}\frac{\partial\phi}{\partial x} + \vec{a_y}\frac{\partial\phi}{\partial y} + \vec{a_z}\frac{\partial\phi}{\partial z} \right]$$
(7-105)

In this equation the flux is valid for any point in the medium not just the origin as previously assumed. In comparison with Eq. (7-89)

$$D = \frac{1}{3\Sigma_s} \tag{7-106}$$

where λ_s represents the mean free path for neutron scattering. The diffusion coefficient is corrected for anisotropic scattering using the transport mean free path. If the average cosine of the scattering angle for collision in laboratory system (as explained in Section 3.3) is

$$\overline{\mu} = \overline{\cos\psi} = \frac{2}{3A} \tag{7-107}$$

where A is the atomic mass number of the medium, the diffusion coefficient can be written as a function of the transport cross section, Σ_{tr}

$$\Sigma_{tr} = \Sigma_{tot} - \Sigma_s \overline{\mu} = \frac{1}{\lambda_{tr}}$$
(7-108)

Eq. (7-106) may therefore be written as

$$D = \frac{1}{3\Sigma_{\nu}} = \frac{\lambda_{\nu}}{3} \tag{7-109}$$

which, for a weakly absorbing medium, becomes

$$\Sigma_{tr} = \Sigma_s - \Sigma_s \overline{\mu} = \frac{1}{\lambda_{tr}}$$
(7-110)

$$D = \frac{1}{3\Sigma_s (1 - \overline{\mu})} = \frac{\lambda_s}{3(1 - \overline{\mu})}$$
(7-111)

Example 7.1 Diffusion coefficient

Estimate the diffusion coefficient of graphite at 1eV. The scattering cross section at 1eV is 4.8 barns.

For graphite A = 12, thus from Eq. (7-107) it follows

$$\overline{\mu} = \overline{\cos \psi} = \frac{2}{3A} = 0.055$$

The macroscopic scattering cross section for graphite is

$$\Sigma_s = N\sigma_s = (0.08023 \times 10^{24} \text{ at/cm}^3)(4.8 \times 10^{-24} \text{ cm}^2) = 0.385 \text{ cm}^{-1} \implies D = \frac{1}{3\Sigma_s (1 - \overline{\mu})} = \frac{1}{3 \times 0.385 (1 - 0.055)} = 0.916 \text{ cm}$$

Example 7.2 Neutron transport mean free path

The transport mean free path is a scattering mean free path which is corrected for the slightly larger distance travelled in the laboratory system due to preferential forward scattering. Calculate the transport mean free path for thermal neutrons in beryllium oxide (*BeO*), if $\rho(Be) = 2.70 \text{ g/cm}^3$, A(BeO) = 25.01, $\sigma_s(Be) = 7 \text{ b}$ and $\sigma_s(O) = 4.2 \text{ b}$.

The atom densities are

$$N(\text{Be}) = N(\text{O}) = \frac{\rho \times N_a}{A} = \frac{2.7 \times 6.022 \times 10^{23}}{25.01} = 6.51 \times 10^{22} \text{ at/cm}^3$$

The average cosine of the scattering angle for collision in laboratory system, from Eq. (7-107), and the transport mean free path from Eq. (7-108) are

$$\overline{\mu}(\text{Be}) = \frac{2}{3 \times 9} = 0.0741 \quad \overline{\mu}(\text{O}) = \frac{2}{3 \times 16} = 0.0417$$

$$\lambda_{\mu} = \frac{1}{\sum_{s} (\text{Be})(1 - \mu(\text{Be}) + \sum_{s} (\text{O})(1 - \mu(\text{O}))} = \frac{1}{(6.51 \times 10^{22})(7 \times 10^{-24})(1 - 0.0741) + (6.51 \times 10^{22})(4.2 \times 10^{-24})(1 - 0.0417)} = \frac{1}{0.422 + 0.262} = 1.46\text{ cm}$$

The diffusion coefficient divided by the absorption cross section has the dimension of the squared length. The square root of which is called the *diffusion length*, L

$$L^{2} = \frac{D}{\Sigma_{a}} = \frac{1}{3\Sigma_{a}\Sigma_{s}(1-\overline{\mu})}.$$
(7-112)

<i>Table 7-1</i> , Diffusion	parameters for neutrons at $T = 293$ K
	•

Moderator	$D [\mathrm{cm}^{-1}]$	$\Sigma_a [cm^{-1}]$	<i>L</i> [cm]	ML [cm]	
H ₂ O	0.144	0.0189	2.75	5.6	
D_2O	0.810	0.00007	161.0	11.0	
Be	1.85	0.00053	21.2	9.2	
Graphite	1.60	0.00031	52.5	18.7	

The diffusion length represents the distance a neutron passes from the point of thermalization to the point of absorption. The distance from the point where a neutron is born to the point where it is thermalized is called the moderation length, *ML*. It determines the optimum distance between adjacent fuel channels in a heterogeneous reactor (called the pitch). The moderator and diffusion lengths for few materials commonly used in thermal reactors are listed in Table 7-1. The small diffusion length of H₂O is due to its high absorption cross section. If a light water reactor is over-moderated (the lattice pitch is large) it will result in increased neutron absorption. However, if a D₂O moderated reactor is over-moderated it will have no significant effect on neutron economy.

2.4 Neutron Diffusion Theory

2.4.1 One-Speed Neutron Diffusion Equation

The exact interpretation of neutron transport in heterogeneous domains such as a reactor core is so complex that simplified approaches are often used. Though simplified, they are accurate enough to give an estimate of the average characteristics of neutron population in a given medium. The simplest form of neutron transport equation is the *one-speed diffusion equation* developed under the assumptions:

- 1. *neutrons are monoenergetic*: average neutron energy and average cross sections for neutron interactions are selected;
- 2. *absorption in a medium is small*: macroscopic absorption cross section is small in comparison with scattering cross section;
- 3. *neutron scattering is isotropic in the laboratory system*: valid for neutron scattering with heavy nuclei, and not true for thermal reactor moderators (corrections must be applied);
- 4. *angular neutron distribution is isotropic*: valid if neutron flux is nearly constant which is approximately satisfied far from the system boundary, neutron source or points of strong absorptions (if neutron flux gradient is large, there are preferable directions of neutron motion toward low neutron flux region).

In a reactor core, neutrons are produced or lost through capture and leakage. Thus the net rate of change in neutron density per unit volume and time is

$$\frac{\partial n(\vec{r},t)}{\partial t} = S(\vec{r},t) - \Sigma_a \phi(\vec{r},t) - LE$$
(7-113)

where $S(\vec{r},t)$ is neutron source rate, $\sum_{a} \phi(\vec{r},t)$ neutron absorption rate, and *LE* neutron leakage, per unit time and unit volume. *LE* represents the rate of neutrons flowing in a given direction per unit time through unit area (see Fig. 7-7) normal to direction of flow

Neutron leakage per unit volume
$$= div J(\vec{r}, t) = \nabla \cdot J(\vec{r}, t)$$
 (7-114)

Thus, Eq. (7-113) is re-written in the following way

$$\frac{\partial n(\vec{r},t)}{\partial t} = S(\vec{r},t) - \Sigma_a \phi(\vec{r},t) - \nabla \cdot J(\vec{r},t)$$
(7-115)



Figure 7-7. Neutron leakage from an elementary volume

Neutron diffusion through any material is the result of scattering interactions. In reactor analysis, it is assumed that neutrons do not collide with one another. This is valid because the neutron density is much lower than the atomic density of a medium. Due to nearly constant collisions, neutrons in a scattering medium travel *zigzag* trajectories. When considering a large number of neutrons assumed to be monoenergetic, there is an overall motion of neutrons from regions of higher to regions of lower neutron density (or neutron flux). This is the reason why Fick's law of diffusion is applied to define the net rate of neutron flow. Fick's law, Eq. (7-89), may be inserted into Eq. (7-115) to give

$$\frac{\partial n(\vec{r},t)}{\partial t} = S(\vec{r},t) - \Sigma_a \phi(\vec{r},t) - \nabla \cdot [-D\nabla \phi(\vec{r},t)]$$
(7-116)

which can be re-written as

$$\frac{\partial n(\vec{r},t)}{\partial t} = \frac{1}{v} \frac{\partial \phi(\vec{r},t)}{\partial t} = \nabla \cdot [D\nabla \phi(\vec{r},t)] + S(\vec{r},t) - \Sigma_a \phi(\vec{r},t)$$
(7-117)

Under the assumption that the medium is homogenous, the diffusion coefficient becomes independent of neutron position and the leakage term reduces to

$$LE = -D\nabla^2 \phi(\vec{r}, t) \tag{7-118}$$

where ∇^2 represents the Laplacian operator which is defined for various coordinate systems as

Rectangular coordinate system:
$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$
 (7-119)

Spherical coordinate system:
$$\nabla^2 = \frac{d^2}{dr^2} + \frac{2}{r}\frac{d}{dr}$$
 (7-120)

Cylindrical coordinate system:
$$\nabla^2 = \frac{d^2}{dr^2} + \frac{1}{r}\frac{d}{dr} + \frac{d^2}{dz^2}$$
 (7-121)

Combining Eq.(7-118) with Eq. (7-117), the one-speed diffusion equation for neutrons interacting with a homogeneous medium is

$$\frac{\partial \vec{n(r,t)}}{\partial t} = \frac{1}{v} \frac{\partial \vec{\phi(r,t)}}{\partial t} = D\nabla^2 \vec{\phi(r,t)} + S(\vec{r},t) - \Sigma_a \vec{\phi(r,t)}$$
(7-122)

The following cases introduce important simplifications to Eq. (7-122)

• Steady-state condition

$$D\nabla^2 \phi(\vec{r}) + S(\vec{r}) - \sum_a \phi(\vec{r}) = 0$$
 (7-123)

• Steady-state, non-multiplying medium (neutron source = 0)

$$\nabla^2 \phi(\vec{r}) - \frac{\phi(\vec{r})}{L^2} = 0$$
 (7-124)

where

$$L^2 \equiv \frac{D}{\Sigma_a} \tag{7-125}$$
2.4.2 Solution to One–Speed Neutron Diffusion Equation in Infinite Medium

The simplest case to demonstrate diffusion theory is diffusion of neutrons from a point source in a large infinite medium. Neutrons are emitted from such a source in all directions with equal probability giving a spherical symmetry in regard to the position of source. If r represents the distance from the origin where point neutron source is located, the one-speed diffusion equation in Eq. (7-124) expressed in spherical coordinates, becomes

$$\frac{d^2}{dr^2}\phi(r) + \frac{2}{r}\frac{d}{dr}\phi(r) - \frac{\phi(r)}{L^2} = 0$$
(7-126)

Introducing $y = \phi r$ the above equation reduces to

$$\frac{d^2 y}{dr^2} - \frac{y}{L^2} = 0 ag{7-127}$$

whose solution has the following general form

$$y = Ae^{-r/L} + Ce^{r/L}.$$
 (7-128)

Re-introducing the variable r, the solution becomes

$$\phi = A \frac{e^{-r/L}}{r} + C \frac{e^{r/L}}{r}$$
(7-129)

where A and C are constant determined from the boundary conditions. Far from the neutron source of intensity S the neutron flux must decrease, which determines the C constant to be zero:

$$\phi = A \frac{e^{-r/L}}{r} \tag{7-130}$$

The total number of neutrons passing through the entire surface of a sphere whose center is the point neutron source is $4\pi r^2 J$ where

$$J = -D\frac{d\phi}{dr} = DAe^{-r/L} \left(\frac{1+r/L}{r^2}\right)$$
(7-131)

The limiting value of the total number of neutron passing through the surface of the sphere as distance becomes zero is equal to the source strength

$$S = \lim_{r \to 0} \left(4\pi r^2 J \right) = 4\pi D A \lim_{r \to 0} \left(e^{-r/L} \frac{1+r/L}{r^2} \right) = 4\pi D A$$
(7-132)

giving

$$A = \frac{S}{4\pi D} \tag{7-133}$$

and the solution for flux is thus

$$\phi = \frac{S}{4\pi D} \frac{e^{-r/L}}{r}$$
(7-134)



Figure 7-8. Distance between a point of neutron source to a point of neutron absorption

Neutrons travel a certain distance, r, during diffusion through a medium along which they collide until they are absorbed, creating a path similar to that shown in Fig. 7-8. The mean square of this distance is obtained from the neutron flux distribution from a point neutron source. In a differential ring of thickness dr placed r from the neutron source, there will be $4\pi r^2 dr \Sigma_a \phi$ neutrons absorbed per unit time (number of neutrons absorbed is equal to the number of neutrons created in the system). This also represents the probability that a neutron will be absorbed at a distance r from the source. Thus

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$$\overline{r^2} = \frac{\int\limits_{r=0}^{\infty} r^2 \left(4\pi r^2 \Sigma_a \phi\right) dr}{\int\limits_{r=0}^{\infty} \left(4\pi r^2 \Sigma_a \phi\right) dr},$$
(7-135)

and inserting Eq. (7-134) for the flux, it follows

$$\overline{r^{2}} = \frac{\int_{r=0}^{\infty} (r^{3} e^{-r/L}) dr}{\int_{r=0}^{\infty} (r e^{-r/L}) dr} = \frac{6L^{4}}{L^{2}} = 6L^{2}.$$
(7-136)

2.4.3 Solution to One–Speed Neutron Diffusion Equation in Finite Medium

In order to solve the neutron diffusion equation for a medium of finite dimensions, or in the medium composed of two different materials, a set of boundary conditions are specified as follows

a) At the interface between the two media, *A* and *B*, with different diffusion properties (neither of which is a vacuum) the neutron flux must be the same for both media (continuity of flux)

$$\phi_{A_0} = \phi_{B_0}, \tag{7-137}$$

where the subscript 0 denotes the interface plane between the two media.

b) At a plane interface between two media (neither of which is a vacuum) the neutron currents are equal. Assuming the x – direction we can write

$$-D_{A}\frac{d\phi_{A_{0}}}{dx} = -D_{B}\frac{d\phi_{B_{0}}}{dx}.$$
(7-138)

c) In the case when one of the media is a vacuum (or air) the boundary conditions are different because there is no scattering from vacuum. In other words, the flow of neutrons exists only in one direction, toward vacuum. The boundary condition at the interface between the diffusion medium and the vacuum (or air) specifies that the neutron flux gradient vanishes at a certain point beyond the physical boundary, called the extrapolated distance or extrapolated boundary. The concept is

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hypothetical because there is no indication that neutron flux is actually zero at that particular point

$$\left(\frac{d\phi}{dx}\right)_0 = -\frac{\phi_0}{d},\tag{7-139}$$

where *d* is the distance called the linear extrapolation distance (see Fig. 7-9) and is equal to 0.71 λ_{tr} (valid for plane surfaces). Diffusion theory gives the extrapolation distance to be nearly equal to 2/3 of λ_{tr} (see Section 2.4.5).



Figure 7-9. Extrapolation of neutron flux at the interface between diffusion medium and vacuum

2.4.4 Neutron Diffusion in Multiplying Medium

The main interest in applying diffusion theory in neutron transport is to analyze the neutron population, neutron flux and power distribution in a reactor core. A reactor core is a finite multiplying medium with a sustaining fission chain reaction. As neutrons diffuse through the core they can be absorbed by fuel, moderator or structural materials present in the core; leak out from the geometrical boundaries of the reactor core; or act as a source for new neutrons to be born in fission reactions.

In a critical (or steady-state) reactor core, the number of neutrons produced by fission is the same as the number of neutrons lost by absorption or leakage in a given unit time. Thus we can define

• *Infinite neutron multiplication factor* which represents the number of neutrons produced per fission per one neutron absorbed in a medium

$$k_{\infty} = \frac{\text{neutron production rate}}{\text{neutron absorption rate}}.$$
 (7-140)

• In an infinitely large system the leakage is neglected, and the neutrons are lost only by absorption. However, in a finite medium, like a reactor core, neutrons are lost also by leaking through the geometrical boundaries and by absorption. The criticality condition is then defined in terms of the *effective neutron multiplication factor*:

$$k_{eff} = \frac{\text{neutron production rate}}{\text{neutron absorption rate + neutron leakage rate}}.$$
 (7-141)

If neutron production rate is S, neutron absorption rate A and neutron leakage rate LE, it follows

$$\frac{k_{eff}}{k_{\infty}} = \frac{\frac{S}{A+LE}}{\frac{S}{A}} = \frac{A}{A+LE},$$
(7-142)

which represents the probability that a neutron will be lost in a system by absorption. Since the alternative loss mechanism is leakage, this equation also represents the probability that a neutron will not be lost through leakage, *i.e.* it represents the non-leakage probability, $P_{non-leak}$. Therefore

$$\frac{k_{eff}}{k_{\infty}} \equiv P_{non-leak}.$$
(7-143)

In order for a reactor to be critical the infinite multiplication factor must be greater than unity. The neutron leakage is generally proportional to the surface area, SA, and neutron production is proportional to the volume, V. If the size of a system is expressed in unit of a

$$\frac{LE}{S} \prec \frac{SA}{V} \prec \frac{a^2}{a^3} \prec \frac{1}{a},\tag{7-144}$$

The ratio between the number of neutrons leaked and number of neutrons produced is inversely proportional to the linear dimension of the finite multiplying system. Thus, by changing the size of the core, the leakage rate changes affecting the effective neutron multiplication factor to range between 0 and k_{∞} . The infinite multiplication factor is a function of the materials present in the core (fuel, moderator, coolant, structures). The non-leakage probability is dependent on the reactor materials and its geometry (size, shape). For thermal neutrons, exactly k_{∞} new thermal neutrons is created per each neutron absorbed and thus the neutrons source is written

$$S = \overline{\Sigma_a} k_{\infty} \phi \tag{7-145}$$

Thus, assuming a homogeneous system and the steady-state condition, and applying one-speed diffusion theory, the diffusion equation can be written in a following form

$$\nabla^2 \phi + B^2 \phi = 0 \tag{7-146}$$

where

$$B^{2} \equiv \frac{k_{\infty} - 1}{L^{2}}$$
(7-147)

The square root of Eq. (7-147) is referred to as the *material buckling* (B_m) of the reactor core because it is a measure of the bending or the curvature of the spatial distribution of the neutron flux. The overall neutron production must balance the neutron absorption plus leakage during the steady-state operation of the reactor. The relation for material buckling can be rearranged

$$1 = k_{\infty} \left[\frac{1}{B_m^2 L^2 + 1} \right]$$
(7-148)

Comparing Eq. (7-148) with Eq. (7-143) yields an expression for the non-leakage probability in a critical reactor

$$P_{non-leak} = \frac{1}{B_m^2 L^2 + 1} = \frac{\overline{\Sigma_a}\phi}{\overline{\Sigma_a}\phi + B_m^2\phi} = \frac{\overline{\Sigma_a}\phi}{\overline{\Sigma_a}\phi + (-D\nabla^2\phi)}$$
(7-149)

Example 7.3 Material buckling

Calculate the material buckling and thermal neutron leakage probability for a critical homogeneous reactor consisting of a mixture of 200 moles of graphite per mole of 5.5% enriched uranium fuel. The overall temperature of the reactor core is

20 °C. The density of graphite and uranium are: $\rho_C = 1.6 \text{ g/cm}^3$ and $\rho_U = 18.9 \text{ g/cm}^3$. The microscopic cross section for thermal neutron scattering at carbon is 4.8 b and at uranium 8.3 b. The microscopic cross section for absorption in carbon 0.0034 b, in ²³⁵U is 694 b and in ²³⁸U is 2.73 b. The infinite multiplication factor is 1.2. (Adopted from "*Basic Nuclear Engineering*", A. R. Foster and R. L. Wright Jr., Allyn and Bacon Inc., 1968)

The volumes of the uranium fuel, graphite moderator and the core are

$$V_U = \frac{238 \text{g/mole}}{18.9 \text{g/cm}^3} = 12.6 \text{cm}^3 \text{mole U}$$

$$V_C = \frac{200 \text{moles C/mole U} \times 12 \text{g C/mole C}}{1.6 \text{g/cm}^3} = 1500 \text{cm}^3 \text{mole C}$$

$$V = V_{U} + V_{C} = 12.6 + 1500 = 1512.6 cm^{3}$$
 mixture/mole U

The atom densities of uranium, ²³⁵U, ²³⁸U and carbon are

$$N_U = \frac{N_a}{V} =$$

= $\frac{6.022 \times 10^{23} \text{ atoms U/g mole U}}{1512.6 \text{ cm}^3/\text{g mole U}} = 3.98 \times 10^{20} \text{ atoms U/cm}^3 \text{ mixture}$

$$N_{235} = 0.055 \times (3.98 \times 10^{20}) = 0.219 \times 10^{20} \text{ atoms}^{235} \text{ U/cm}^3 \text{ mixture}$$

$$N_{238} = 0.945 \times (3.98 \times 10^{20}) = 3.761 \times 10^{20} \text{ atoms}^{238} \text{ U/cm}^3 \text{ mixture}$$

 $N_C = (200 \text{ atomsC/atomU}) \times (3.98 \times 10^{20}) = 7.96 \times 10^{22} \text{ atomsC/cm}^3 \text{ mixture}$

The transport macroscopic cross section for thermal neutrons in this mixture is

$$\Sigma_{tr}^{th} = N_C \sigma_s^C (1 - \overline{\mu_C}) + N_U \sigma_s^U (1 - \overline{\mu_U}) =$$

= (7.96×10²²)(4.8×10⁻²⁴) $\left(1 - \frac{2}{3×12}\right) +$
+ (3.98×10²⁰)(8.3×10⁻²⁴) $\left(1 - \frac{2}{3×238}\right) =$
0.361+0.0033 = 0.364cm²/cm³ mixture

The average absorption cross section at the most probable neutron energy assuming 1/v dependence in thermal reactors (see Chapter 6, Section 4.6) is

$$\Sigma_{a} = \left[N_{235} \sigma_{a}^{235} + N_{238} \sigma_{a}^{238} + N_{c} \sigma_{a}^{C} \right] \frac{\sqrt{\pi}}{2}$$

$$\Sigma_{a} = \begin{bmatrix} (0.219 \times 10^{20})(694 \times 10^{-24}) + (3.761 \times 10^{20})(2.73 \times 10^{-24}) + \\ + (7.96 \times 10^{22})(0.0034 \times 10^{-24}) \end{bmatrix} \frac{\sqrt{\pi}}{2}$$

$$\Sigma_a = 0.0165 \frac{\sqrt{\pi}}{2} = 0.0146 \text{ cm}^2/\text{cm}^3 \text{ mixture}$$

Giving the material buckling and the neutron leakage probability as

$$L^{2} = \frac{D}{\Sigma_{a}} = \frac{1}{3\Sigma_{a}\Sigma_{s}(1-\overline{\mu})} = \frac{1}{3\Sigma_{a}\Sigma_{tr}} = \frac{1}{3\times 0.0146 \times 0.364} = 62.6 \text{ cm}^{2}$$

$$B_m^2 = \frac{k_\infty - 1}{L^2} = \frac{1.2 - 1}{62.6} = 0.0032 \text{cm}^{-2} \rightarrow B_m = 0.0566 \text{cm}^{-1}$$

$$P_{leak} = 1 - P_{non-leak} = 1 - \frac{1}{B_m^2 L^2 + 1} = 1 - \frac{1}{0.0032 \times 62.6 + 1}$$
$$= 1 - 0.833 = 0.167$$

2.4.5 Solution to One–Speed Neutron Diffusion Equation in Infinite Slab Bare Reactor

The diffusion equation, Eq. (7-146), will be solved for an infinite slab reactor of a finite thickness in order to determine a criticality condition (directly dependent on the slab thickness). The slab is assumed to be infinite in the y or z direction, thus neutrons can leak only along the x direction through slab faces (Fig. 7-10); the neutron flow (neutron flux gradient) will exist only in the x direction. The flux falls off from the center toward either of two slab faces and falls to a zero value at the extrapolated distance.



Figure 7-10. Infinite slab bare reactor

For the half-size of the slab the distance where flux becomes zero is equal to

$$\frac{a_0}{2} = \frac{a}{2} + d \tag{7-150}$$

where d is the extrapolated distance by which the geometrical boundary of the slab reactor core is extended. In the case of a bare reactor, neutrons leave the reactor geometrical boundaries and almost none scatter back into the core. Therefore, the return current is assumed to be zero

$$J_{x}^{-} = \frac{\phi_{0}}{4} + \frac{1}{6\Sigma_{x}} \left(\frac{d\phi}{dx}\right)_{0} = \frac{\phi_{0}}{4} + \frac{D}{2} \left(\frac{d\phi}{dx}\right)_{0} = 0$$
(7-151)

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$$\left(\frac{d\phi}{dx}\right)_0 = -\frac{\phi_0}{2D} \tag{7-152}$$

Assuming the extrapolation of flux is a straight line the slope is equal to

$$\left(\frac{d\phi}{dx}\right)_{0} = -\frac{\phi_{0}}{a_{0}/2 - a/2} = -\frac{\phi_{0}}{d}$$
(7-153)

Combining Eq. (7-153) and Eq. (7-152) gives the extrapolation distance

$$d = 2D = \frac{2}{3}\lambda_{tr} \tag{7-154}$$

as mentioned in Section 2.4.3. The most sophisticated transport theory predicts the extrapolation distance to be 0.71 λ_{tr} . It is always much smaller than the size of a reactor and these two different values do not introduce significant error into flux estimates.

The neutron flux in an infinite slab varies along the x direction. The diffusion equation reduces to an ordinary second-order linear differential equation

$$\frac{d^2\phi}{dx^2} + B^2\phi = 0$$
(7-155)

If B^2 is real and positive the general solution of this equation is

$$\phi(x) = A\cos Bx + C\sin Bx \tag{7-156}$$

The boundary conditions are:

1. The neutron flux drops to zero at the extrapolated distance and is finite at the geometrical boundaries

$$\phi\left(\pm\frac{a_0}{2}\right) = 0 \tag{7-157}$$

2. The neutron flux is symmetric about the origin

$$\left. \frac{d\phi(x)}{dx} \right|_{x=0} = 0 \tag{7-158}$$

From the second boundary condition, the flux gradient is

$$\frac{d\phi(x)}{dx} = -AB\sin Bx + CB\cos Bx = 0$$

At the origin, the flux gradient is zero which eliminates the sine term, *i.e.* $\sin Bx = 0$. Since B is real and positive, C must be equal to zero; thus

$$\phi(x) = A\cos Bx \tag{7-159}$$

The first boundary condition gives

$$\phi(x) = 0 = A\cos\left(\pm\frac{a_0}{2}\right) \tag{7-160}$$

Since constant A cannot be zero (in which case the flux would be zero), this equation is satisfied only if

$$B\left(\pm\frac{a_0}{2}\right) = \frac{\pi}{2}, \frac{3\pi}{2}, \frac{5\pi}{2}, \dots = \frac{n\pi}{2} \quad (n = 1, 3, 5, \dots)$$
(7-161)

The various values of a_0 are called the eigenvalues

$$a_0 = \frac{\pi}{B}, \frac{3\pi}{B}, \frac{5\pi}{B}, \dots$$
 (7-162)

Only the first value is used to define the flux in critical reactors, π/B , (the fundamental mode).

For a steady-sate critical infinite slab reactor it follows

$$\phi(x) = A\cos\left(\frac{\pi x}{a_0}\right) \tag{7-163}$$

The value πa_0 is called the geometric buckling. If the reactor is critical the material buckling must be equal to geometrical buckling

$$B_m^2 = B_g^2 \quad \rightarrow \quad \frac{k_\infty - 1}{L^2} = \left(\frac{\pi}{a_0}\right)^2$$

The constant A in flux relation is an arbitrary value. However, at the

center of a slab reactor it is equal to the maximum value of neutron flux

$$\phi(x=0) = \phi_{\max} = A \tag{7-164}$$

Example 7.4 Infinite slab reactor

Calculate the thickness of a critical infinite slab homogeneous reactor consisting of a mixture of 200 moles of graphite per mole of 5.5% enriched uranium fuel. Assume that the overall temperature of the reactor core is 20 °C and that the reactor is critical.

The density of graphite and uranium are: $\rho_c = 1.6 \text{ g/cm}^3$ and $\rho_u = 18.9 \text{ g/cm}^3$.

The microscopic cross section for thermal neutron scattering at carbon is 4.8 b and at uranium 8.3 b. The microscopic cross section for absorption in carbon 0.0034 b, in 235 U is 694 b and in 238 U is 2.73 b. The infinite multiplication factor is assumed to be 1.2.

(Adopted from "*Basic Nuclear Engineering*", A. R. Foster and R. L. Wright Jr., Allyn and Bacon Inc., 1968)

Since the reactor is critical the material buckling is equal to geometrical buckling, therefore

$$a_0 = \frac{\pi}{B} = \frac{\pi}{0.0566} = 55.5$$
cm $d = 0.71\lambda_{tr} = \frac{0.71}{\Sigma_{tr}^{th}} = \frac{0.71}{0.364} = 1.95$ cm

$$\frac{a_0}{2} = \frac{a}{2} + d \quad \to \quad a = a_0 - 2d = 55.5 - 2 \times 1.95 = 51.6 \text{ cm}$$

2.4.6 Solution to One–Speed Neutron Diffusion Equation in Rectangular Bare Parallelepiped Reactor

For the rectangular parallelepiped reactor core is shown in Fig. 7-11, Eq. (7-146) can be written as

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} + B^2 \phi = 0$$
(7-165)

This equation is solved by the method of variable separation

$$\phi(x, y, z) = X(x)Y(y)Z(z) \equiv XYZ$$
(7-166)



Figure 7-11. Rectangular Bare Parallelepiped Reactor Core

This expression indicates that the flux in the x, y or z directions is independent of that in other two directions.

Differentiating the above equation yields

$$\frac{\partial \phi}{\partial x} = YZ \frac{\partial X}{\partial x} \quad \frac{\partial^2 \phi}{\partial x^2} = YZ \frac{\partial^2 X}{\partial x^2}$$

$$\frac{\partial \phi}{\partial y} = XZ \frac{\partial Y}{\partial y} \quad \frac{\partial^2 \phi}{\partial y^2} = XZ \frac{\partial^2 Y}{\partial y^2}$$

$$\frac{\partial \phi}{\partial z} = XY \frac{\partial Z}{\partial z} \quad \frac{\partial^2 \phi}{\partial z^2} = XY \frac{\partial^2 Z}{\partial z^2}$$
(7-167)

Substituting these partial second order derivatives into Eq. (7-165) gives

$$YZ\frac{\partial^2 X}{\partial x^2} + XZ\frac{\partial^2 Y}{\partial y^2} + XY\frac{\partial^2 Z}{\partial z^2} + B^2 XYZ = 0$$
(7-168)

Dividing by XYZ reduces Eq. (7-168) to

$$\frac{1}{X}\frac{\partial^2 X}{\partial x^2} + \frac{1}{Y}\frac{\partial^2 Y}{\partial y^2} + \frac{1}{Z}\frac{\partial^2 Z}{\partial z^2} + B^2 = 0$$
(7-169)

Since each of the terms is a function of a single variable, the above equation may be written as

$$B^2 = \alpha^2 + \beta^2 + \gamma^2 \tag{7-170}$$

where α , β and γ are constants such that

$$\frac{d^2 X}{dx^2} + X \alpha^2 = 0 \quad \frac{d^2 Y}{dy^2} + Y \beta^2 = 0 \quad \frac{d^2 Z}{dz^2} + Z \gamma^2 = 0 \tag{7-171}$$

Since the derivatives are functions of only one variable, the partial derivative is replaced with a total derivative to give:

$$X = A_x \cos \alpha X + C_x \sin \alpha x$$

$$Y = A_y \cos \beta Y + C_y \sin \beta y$$

$$Z = A_z \cos \gamma Z + C_z \sin \gamma z$$

(7-172)

The boundary conditions for the *x* direction are:

1. For
$$x = a_0/2$$
, $X = 0$

2. For x = 0, gradient of X is zero, $\partial X / \partial x = 0$ Following the procedure as described for the infinite slab, it is obtained

$$\alpha = \frac{\pi}{a_0} \quad \beta = \frac{\pi}{b_0} \quad \gamma = \frac{\pi}{c_0} \tag{7-173}$$

$$X = A_x \cos \frac{\pi}{a_0} x$$

$$Y = A_y \cos \frac{\pi}{b_0} y$$

$$Z = A_z \cos \frac{\pi}{c_0} z$$

(7-174)

The flux and the geometrical buckling then can be written as

$$\phi = XYZ = A\cos\left(\frac{\pi}{a_0}x\right)\cos\left(\frac{\pi}{b_0}y\right)\cos\left(\frac{\pi}{c_0}z\right)$$
(7-175)

$$B_{g}^{2} = \left(\frac{\pi}{a_{0}}\right)^{2} + \left(\frac{\pi}{b_{0}}\right)^{2} + \left(\frac{\pi}{c_{0}}\right)^{2}$$
(7-176)

In case of a cubic reactor, the geometrical buckling becomes

$$B_g^2 = 3 \left(\frac{\pi}{a_0}\right)^2 \quad \leftrightarrow \quad a_0 = \frac{\pi}{B_g} \sqrt{3} \tag{7-177}$$

It can be understood that the extrapolated length of a side of a cubic core is larger than the extrapolated thickness of an infinite slab of the same material by a factor of $\sqrt{3}$.

2.4.7 Solution to One–Speed Neutron Diffusion Equation in Spherical Bare Reactor



Figure 7-12. Spherical bare reactor

A spherical configuration requires the minimum amount of fuel to achieve criticality because the leakage is minimum (the area to volume ratio is minimal compared to other geometries). In a spherical reactor, neutron flux varies along the radial coordinate (see Fig. 7-12). The Eq. (7-146) written in spherical coordinates become

$$\frac{d^2\phi}{dr^2} + \frac{2}{r}\frac{d\phi}{dr} + B^2\phi = 0$$
(7-178)

This equation is solved by introducing $y = \phi r$ similar to the solution of the one-speed neutron diffusion equation shown in Section 2.4.2 for a point neutron source. With the given substitution, Eq. (7-178) reduces to

$$\frac{1}{r}\frac{d^2y}{dr^2} + B^2\frac{y}{r} = 0$$
(7-179)

with a solution of the form

$$y = A\cos Br + C\sin Br = \phi r \rightarrow \phi = \frac{A}{r}\cos Br + \frac{C}{r}\sin Br$$
 (7-180)

The first boundary condition specifies that the flux must be finite at the origin of the sphere resulting in

$$\lim_{r \to 0} \frac{A \cos Br}{r} = \frac{A \times 1}{0} = \infty \quad \Rightarrow \quad A = 0 \tag{7-181}$$

The secondary boundary condition requires that the flux becomes zero at the extrapolated radius

$$\phi(r=r_0) = 0 \quad \Rightarrow \quad \frac{C}{r_0} \sin Br_0 = 0 \tag{7-182}$$

The constant C must be non-zero to assure the existence of neutron flux. Thus, Eq. (7-182) can be satisfied only if

$$Br_0 = 0, \pi, 2\pi, 3\pi, \dots \tag{7-183}$$

The first value is a trivial solution and disregarded. The first non-zero value is a fundamental eigenvalue followed by the harmonic eigenvalues. The fundamental flux mode gives

$$r_0 = \frac{\pi}{B} \iff B_g^2 = \left(\frac{\pi}{r_0}\right)^2$$
 (7-184)

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$$\phi = \frac{C}{r} \sin \frac{\pi r}{r_0} \tag{7-185}$$

Example 7.5 Spherical bare reactor

Calculate the critical radius of a spherical homogeneous reactor consisting of a mixture of 200 moles of graphite per mole of 5.5% enriched uranium fuel. Determine the flux ratio between the center and the core boundary. For details see the Examples 7.3 and 7.4.

(Adopted from "*Basic Nuclear Engineering*", A. R. Foster and R. L. Wright Jr., Allyn and Bacon Inc., 1968)

The extrapolated radius and macroscopic cross section are

$$r_0 = \frac{\pi}{B} = r + 0.71\lambda_{tr} \rightarrow r = \frac{\pi}{B} - 0.71\lambda_{tr} = \frac{\pi}{0.0566} - 1.95 = 53.55$$
cm

$$\Sigma_f = N_{235} \sigma_f^{235} \frac{\sqrt{\pi}}{2} = (0.219 \times 10^{20})(582 \times 10^{-24}) \frac{\sqrt{\pi}}{2} = 0.0113 \text{ cm}^2/\text{cm}^3 \text{ mixture}$$

Flux has its maximum value, ϕ_{\max} , at the center of a spherical core

$$\phi = \frac{C}{r} \sin \frac{\pi r}{r_0}$$

Constant C is determined as follows

$$\lim_{r \to 0} \phi = \lim_{r \to 0} \frac{C}{r} \sin Br = \frac{0}{0} \quad \underset{\text{L'Hospitalrule}}{\longrightarrow} \quad \lim_{r \to 0} \phi = \lim_{r \to 0} \frac{CB \cos Br}{1} = CB = \phi_{\text{max}}$$

$$C = \frac{\phi_{\text{max}}}{B} \quad \phi = \frac{\phi_{\text{max}}}{Br} \sin Br \quad \to \quad \frac{\phi_{\text{max}}}{\phi} = \frac{Br}{\sin Br} = \frac{0.0566 \times 53.55}{\sin(0.0566 \times 53.55)} = 27.4$$

Notice that the angle is expressed in units of radian.

2.4.8 Solution to One–Speed Neutron Diffusion Equation in Cylindrical Bare Reactor

The geometrical buckling of the finite cylindrical bare reactor can be

obtained from the neutron diffusion equation

$$\frac{\partial^2 \phi}{\partial r^2} + \frac{1}{r} \frac{\partial \phi}{\partial r} + \frac{\partial^2 \phi}{\partial z^2} + B^2 \phi = 0$$
(7-186)

If r_0 is the extrapolated core radius and z_0 is the extrapolated core height the flux and geometrical buckling are as follows

$$\phi = AJ_0 \left(\frac{2.405r}{r_0}\right) \cos \frac{\pi z}{z_0}$$
(7-187)

$$B^{2} = \left(\frac{2.405}{r_{0}}\right)^{2} + \left(\frac{\pi}{z_{0}}\right)^{2}$$
(7-188)

2.4.9 Two–Group Neutron Diffusion Theory

The one-speed diffusion equation is based on the assumption that neutron production, absorption and leakage occurs at single neutron energy. More accurate estimates are obtained with two group treatment according to which all neutrons are either in a fast or in a thermal energy group. The boundary between these two groups is set to 1 eV.

Thermal neutrons diffuse in a medium and encounter absorption reactions that may cause fission or leak out from the system. Fast neutrons are lost by slowing down due to elastic scattering.

The source for fast neutrons is thermal neutron fission. The source for thermal neutrons is provided by the slowing down of fast neutrons.

The neutron flux in the two groups is

Fast:
$$\phi_1(\vec{r}) = \int_{1eV}^{10MeV} \phi(E,\vec{r})dE$$

Thermal: $\phi_2(\vec{r}) = \int_{0}^{1eV} \phi(E,\vec{r})dE$
(7-189)



Figure 7-13. Schematic representation of two-group diffusion equation

In the two-group approximation, the neutron multiplication factor is defined as follows (see Fig. 7-13)

$$k = \frac{\nu_1 \Sigma_{f1} \phi_1 + \nu_2 \Sigma_{f2} \phi}{-D_1 \nabla^2 \phi_1 - D_2 \nabla^2 \phi_2 + \Sigma_{a1} \phi_1 + \Sigma_{a2} \phi_2}$$
(7-190)

The diffusion equations for the two energy groups become

• Fast energy group

$$D_{1}\nabla^{2}\phi_{1}(\vec{r}) - \Sigma_{a1}\phi_{1}(\vec{r}) + S_{1}(\vec{r}) = 0$$
(7-191)

First term describes fast neutron leakage which involves a fast diffusion coefficient.

The second term represents the removal of fast neutrons by thermalization. Σ_{a1} is the sum of the fission, capture and scattering (from group 1 to group 2) cross sections, and is called the removal cross section.

Fast neutron production is described by $S_1(\vec{r})$ representing the fast neutron source which depends on thermal neutron flux at the spatial positions where thermal neutrons cause fission (see Fig. 7-13).

The infinite multiplication factor for a thermal reactor represents the ratio of neutrons produced in any generation to the neutrons absorbed in the proceeding generation (leakage is neglected if the system is infinitely large).

Neutron loss is accounted for by resonance absorption during the slowing down process. Thus, for each thermal neutron absorbed, k_{∞}/p fast neutrons are produced by fission (*p* is the resonance escape probability, see Section 3). The number of thermal neutrons absorbed is $\Sigma_{a2}\phi_2(r)$, thus Eq. (7-191) becomes

$$D_{1}\nabla^{2}\phi_{1}(\vec{r}) - \Sigma_{a1}\phi_{1}(\vec{r}) + \frac{k_{\infty}}{p}\Sigma_{a2}\phi_{2}(\vec{r}) = 0$$
(7-192)

• Thermal energy group

$$D_2 \nabla^2 \phi_2(\vec{r}) - \Sigma_{a2} \phi_2(\vec{r}) + S_2(\vec{r}) = 0$$
(7-193)

The first term describes the leakage of thermal neutrons.

The second term accounts for thermal neutron absorptions. $S_2(r)$ represents the thermal neutron source.

If there are no resonance absorptions, $\sum_{a1} \phi_1(r)$ would give the rate at which neutrons are transferred to the thermal group.

Due to resonance capture, the probability that a fast neutron will be thermalized is p. Thus, the thermal neutron source depends on fast neutron flux, and Eq. (7-193) becomes

$$D_2 \nabla^2 \phi_2(\vec{r}) - \Sigma_{a2} \phi_2(\vec{r}) + p \Sigma_{a1} \phi_1(\vec{r}) = 0$$
(7-194)

Both equations are dependent on fast and thermal flux and thus represents a coupled system of equations. In addition, for a critical steady-state system the following equations from the diffusion theory are applied

$$\begin{cases} \nabla^2 \phi_1(\vec{r}) + B^2 \phi_1(\vec{r}) = 0\\ \nabla^2 \phi_2(\vec{r}) + B^2 \phi_2(\vec{r}) = 0 \end{cases}$$
(7-195)

Note that the buckling is same for both energy groups because it depends

only on the core geometry for the critical system. By substituting Eq. (7-195) into Eq. (7-193) and Eq. (7-194), the following system is obtained

$$\begin{cases} -(D_1 B^2 + \Sigma_{a1})\phi_1(\vec{r}) + \frac{k_{\infty}}{p} \Sigma_{a2}\phi_2(\vec{r}) = 0\\ -(D_2 B^2 + \Sigma_{a2})\phi_2(\vec{r}) + p\Sigma_{a1}\phi_1(\vec{r}) = 0 \end{cases}$$
(7-196)

The solution of these coupled equations is found by setting the determinant of the coefficients to zero (Cramer's rule)

$$\begin{vmatrix} D_1 B^2 + \Sigma_{a1} & -\frac{k_{\infty} \Sigma_{a2}}{p} \\ -p \Sigma_{a1} & D_2 B^2 + \Sigma_{a2} \end{vmatrix} = 0$$
(7-197)

or:

$$\left(D_{1}B^{2} + \Sigma_{a1}\right)\left(D_{2}B^{2} + \Sigma_{a2}\right) - k_{\omega}\Sigma_{a1}\Sigma_{a2} = 0$$
(7-198)

giving

$$\frac{k_{\infty}}{\left(1+L_{1}^{2}B^{2}\right)\left(1+L_{ih}^{2}B^{2}\right)} = k = 1$$
(7-199)

$$L_{ih}^{2} \equiv \frac{D_{2}}{\Sigma_{a2}}$$

$$L_{1}^{2} \equiv \frac{D_{1}}{\Sigma_{a1}}$$
(7-200)

Equation (7-199) represents the two-group diffusion approximation for the critical bare reactor. In comparison with the one-speed diffusion equation there is one additional leakage term.

Equation (7-199) can be rewritten as

$$\frac{k_{\infty}}{1+B^2 \left(L_{th}^2+L_1^2\right)+B^4 L_{th}^2 L_1^2}=1$$
(7-201)

For large reactors for which $B^2 \ll 1$, Eq. (7-201) reduces to

$$\frac{k_{\infty}}{1+B^2\left(L_{th}^2+L_1^2\right)} = 1 \quad \to \quad B^2 = \frac{k_{\infty}-1}{M^2}$$
(7-202)

where M is migration length as explained in Section 3. The effective multiplication factor for finite systems thus becomes

$$k_{eff} = k_{\infty} P_{non-leak}^{th} P_{non-leak}^{fast}$$
(7-203)

$$P_{non-leak}^{th} = \frac{1}{\left(1 + L_{th}^2 B^2\right)}$$

$$P_{non-leak}^{fast} = \frac{1}{\left(1 + L_1^2 B^2\right)}$$
(7-204)

2.4.10 Multi–Group Neutron Diffusion Theory

In reactors neutrons born in fission are fast. In thermal reactors, they slow down to lower energies due to scattering with the medium

- If a medium consists of dominantly heavy nuclei, neutrons scatter through inelastic processes creating energy spectrum shifted toward lower energies.
- If a medium consists of dominantly light nuclei, neutrons scatter through elastic processes resulting in thermal energy spectrum.
- In both cases, neutrons possess a wide spectrum of energies that require more than one or two energy groups for accurate estimates.

In a multi-group approach, neutrons are divided into a number of groups such that to every group corresponds an average energy and velocity with which neutrons diffuse through a medium until they are absorbed or due to slowing down removed to a lower energy group.

The n-group diffusion theory is represented by the following series of equations

$$D_{1}\nabla^{2}\phi_{1}(\vec{r}) - \Sigma_{a1}\phi_{1}(\vec{r}) - \sum_{h=2}^{n}\Sigma(1 \to h)\phi_{1}(\vec{r}) + S_{1}(\vec{r}) = 0$$

$$D_{2}\nabla^{2}\phi_{2}(\vec{r}) - \Sigma_{a2}\phi_{2}(\vec{r}) - \sum_{h=3}^{n}\Sigma(2 \to h)\phi_{2}(\vec{r}) + S_{2}(\vec{r}) + \Sigma(1 \to 2)\phi_{1}(\vec{r}) = 0$$

$$D_{3}\nabla^{2}\phi_{3}(\vec{r}) - \Sigma_{a3}\phi_{3}(\vec{r}) - \sum_{h=4}^{n}\Sigma(3 \to h)\phi_{3}(\vec{r}) + S_{3}(\vec{r}) + \sum_{h=1}^{2}\Sigma(h \to 3)\phi_{h}(\vec{r}) = 0$$

$$\vdots$$

$$D_{i}\nabla^{2}\phi_{i}(\vec{r}) - \Sigma_{ai}\phi_{i}(\vec{r}) - \sum_{h=i+1}^{n}\Sigma(i \to h)\phi_{i}(\vec{r}) + S_{i}(\vec{r}) + \sum_{h=1}^{i-1}\Sigma(h \to i)\phi_{h}(\vec{r}) = 0$$

$$\vdots$$

$$D_{n}\nabla^{2}\phi_{n}(\vec{r}) - \Sigma_{aa}\phi_{n}(\vec{r}) + S_{n}(\vec{r}) + \sum_{h=1}^{n-1}\Sigma(h \to n)\phi_{h}(\vec{r}) = 0$$
(7-205)

For each of these groups, the diffusion equation is written such that: for energy group *i*, $\Sigma \phi$ describes neutron loss (absorptions, $\Sigma_{ai}\phi_i$ and removal to a lower energy group, $\Sigma_i \phi_i$).

The source term in first energy group, S_1 , takes into account neutrons which are emitted with energies corresponding to that interval. In all other energy groups the source, S_i , is defined as a sum of neutrons emitted from that source plus all neutrons that come from other energy groups.

3. SLOWING DOWN OF NEUTRONS

Neutrons are slowed down in both elastic and inelastic scattering collisions with the nuclei of the atoms in a medium. In each collision, the neutron transfers a portion of its kinetic energy to the target nucleus in the form of kinetic energy if the collision is elastic or excitation energy if the collision is inelastic. Inelastic scattering is dominant with heavy nuclei, while elastic scattering is dominant with light nuclei. Moderator materials have low mass numbers and remove a large amount of energy from neutrons in a single collision and are also weak absorbers. This is why in a fast reactor materials of low mass number are avoided thus keeping the neutron population at a high average energy (the range where inelastic scattering by uranium or plutonium nuclei plays an important role). The one group neutron diffusion equation provides a basic understanding of neutron transport.

Most of the neutrons produced in fission have energies in range of 1 to 2 MeV. In collisions with the materials in a reactor core, neutron energies range from small fractions of eV to a few MeV. Thermal reactors incorporate moderator materials in order to reduce the neutron energies to the thermal region where fission is most likely to occur. In an accurate reactor analysis both elastic and inelastic scattering are analyzed. A simple mathematical description of the elastic scattering processes can be developed under the following assumptions

- target nuclei are at rest relative to the neutrons, and
- the nuclei are not bound in a solid, liquid or gaseous molecule.

However, in the thermal region, the energies of the nuclei cannot be neglected in comparison with the neutron kinetic energies, and the scattering nuclei should be considered bound. In this condition, low energy inelastic scattering cannot be neglected. Also, neutrons can gain or lose energy in a collision. An increase in energy is called *up-scattering*, and a decrease is called *down-scattering*.

The slowing down of a neutron from fission energies to roughly 1 eV is called *moderation* and the slowing down below 1 eV is called the *thermalization*. The following description of the neutron slowing down process refers to the moderation process for which the two assumptions stated above are acceptable.

3.1 Elastic Scattering in the Moderating Region

Elastic scattering in the moderating region is described by assuming that the colliding particles behave as elastic spheres, with the assumption that the target nuclei are stationary. In considering the scattering collision processes, two frames of references (Fig. 7-14) are used

(a) *The laboratory system* (*LS*): scattering nucleus is at rest before the collision, and the neutron is moving toward the nucleus; after the collision, the neutron changes its direction of motion and velocity, and the nucleus moves from the rest position with some velocity. The viewpoint is that of a stationary external observer.

(b) *The center of mass system (COM)*: neutron and nucleus are stationary in the collision. The observer is located at the center of mass of neutron plus the nucleus (compound nucleus) and travels with the velocity of the compound nucleus. The center of mass is an imaginary point where the system is balanced.



sculler in center of muss system

Figure 7-14. Scatter in lab and center of mass systems

Actual measurements are made in LS system, while the theoretical treatment is easier in the COM system. Since data are measured in the LS reference frame and the theoretical predictions are made in the COM reference system, a coordinate transformation is needed to compare theory to experiment. The both systems are shown in Fig. 7-14

 v_0 : initial neutron velocity in LS

 $v_{A0} = 0$: nucleus velocity in *LS*

 v_C : compound nucleus velocity in *LS*

 v_A : recoil nucleus velocity in the *LS*

v: recoil nucleus velocity in the LS

 ψ : neutron scattering angle in LS with respect to original neutron direction

 v_{A1} : recoil nucleus velocity in the *COM* system

 v_1 : scatterd neutron velocity of in the COM system

 θ : neutron scattering angle in the *COM* system

Laboratory system: Since the nucleus is stationary, its velocity is equal to zero and the momentum of a compound nucleus in *LS* is equal to the momentum of the incoming neutron

$$mv_0 + Mv_{A0} = (m+M)v_C \tag{7-206}$$

giving the velocity of the compound nucleus to be,

$$v_c = \frac{v_0}{(1+A)}$$
(7-207)

Center of mass system: In order to follow the splitting of the compound nucleus it is convenient to transfer to the center of mass system. In this system, the observer travels at the velocity and direction of the compound nucleus after the collision. Thus, the velocity of the neutron and nucleus before the collision must be reduced by the velocity of the compound nucleus v_c . The velocity of the compound nucleus itself will become zero as it will appear stationary after the collision (see Fig. 7-14). Thus

• The velocity of incident neutron

$$\upsilon_0 - \upsilon_C = \upsilon_0 - \frac{\upsilon_0}{(1+A)} = \frac{A\,\upsilon_0}{(1+A)} \tag{7-208}$$

• The velocity of nucleus: $-v_c$

According to the conservation of energy law, the kinetic energy before the collision must equal the kinetic energy of the particles after the collision. The binding energy to form and break up the compound nucleus is the same and thus cancels out. The only energy to be conserved is, therefore, kinetic energy. The kinetic energy before the collision and available to the compound nucleus is the sum of kinetic energy of neutron and nucleus:

$$T(COM) = \frac{1}{2} (v_0 - v_c)^2 + \frac{1}{2} A (-v_c)^2$$
(7-209)

Eliminating the target nucleus velocity from the above equation gives

$$T(COM) = \frac{Av_0^2}{2(1+A)} = \frac{A}{1+A}T(LS)_0,$$
(7-210)

where $T(LS)_0$ represents kinetic energy of the incident neutron in LS. From the above equation it can be seen that the kinetic energy before the collision in the *COM* system for light nuclei is half of the incident neutron energy in LS, while for an interaction with ²³⁵U (that creates ²³⁶U as a compound nucleus) it is the fraction 235/236 of the incident neutron energy. Thus, the difference between these two systems is more evident for light nuclei.

According to Fig. 7-14 the kinetic energy in the COM system is shared

between the scattered neutron and scattered nucleus flying away in opposite directions. Thus, the conservation energy law in *COM* gives

$$\frac{Av_0^2}{2(1+A)} = \frac{Av_{A1}^2}{2} + \frac{v_1^2}{2}$$
(7-211)

The conservation of momentum equation gives

$$v_{\rm I} = A v_{\rm AI} \tag{7-212}$$

By combining the last two equations it follows

$$\frac{Av_0^2}{2(1+A)} = \frac{Av_{A1}^2}{2} + \frac{A^2v_{A1}^2}{2}$$
(7-213)

$$v_{A1} = \frac{v_0}{1+A}$$

$$v_1 = \frac{Av_0}{1+A}$$
(7-214)

Laboratory system (LS): It is useful to now convert back to the LS in order to compare the kinetic energy of the scattered neutron with the kinetic energy of the incoming neutron. Conversion from the COM system to the LS system is depicted in Fig. 7-15 and shows the transfer of velocities from one system to another using the Pythagorean Theorem

$$v^{2} = (v_{1} \sin \theta)^{2} + (v_{1} \cos \theta + v_{c})^{2}$$
(7-215)

or

$$v^{2} = \left(\frac{Av_{0}}{1+A}\sin\theta\right)^{2} + \left(\frac{Av_{0}}{1+A}\cos\theta + \frac{v_{0}}{1+A}\right)^{2}$$
(7-216)

which gives

$$v^{2} = \frac{A^{2} + 2A\cos\theta + 1}{(1+A)^{2}}v_{0}^{2}$$
(7-217)



Figure 7-15. Diagram of velocities for conversion from COM to Lab system

From this equation it is possible to obtain the ratio of kinetic energy of the neutron after collision to that before the collision

$$\frac{T(LS)}{T(LS)_0} = \frac{v^2/2}{v_0^2/2} = \frac{A^2 + 2A\cos\theta + 1}{\left(1+A\right)^2}$$
(7-218)

This equation leads to the following conclusions

• This ratio reaches its maximum when $\theta = 0$, or a glancing collision. Therefore, in forward scattering, neutron energy is not changed

$$\left(\frac{T(LS)}{T(LS)_0}\right)_{\max} = \frac{A^2 + 2A + 1}{(1+A)^2} = 1$$

• The minimum ratio of energies is obtained for a head-on collision in which the neutron does not change its direction, or $\theta = \pi$

$$\left(\frac{T(LS)}{T(LS)_0}\right)_{\min} = \frac{A^2 + 2A(-1) + 1}{\left(1 + A\right)^2} = \frac{\left(A - 1\right)^2}{\left(A + 1\right)^2} \equiv \alpha$$
(7-219)

In the example of hydrogen (A = 1), the value of the defined parameter α becomes

$$\alpha_H = \frac{(A-1)^2}{(A+1)^2} = 0$$

indicating that in head–on collision with a hydrogen nucleus, the neutron energy after the collision will be zero. In other words, a hydrogen atom can cause a neutron to lose all of its energy in a single collision event. For beryllium atom for which A = 9

$$\alpha_{Be} = \frac{(A-1)^2}{(A+1)^2} = 0.64$$

indicating that a neutron will lose 36 % of its energy in a single head-on collision with a beryllium nucleus. This becomes a much smaller percentage for a heavy nucleus like 235 U

$$\alpha_{235U} = \frac{(A-1)^2}{(A+1)^2} = 0.98$$

giving that only 2 % of the initial neutron energy will be lost in a single head-on collision. Thus, for heavy nuclei in which A >> 1, it is expected that $\alpha \sim 1$ indicating, as shown in the example of uranium atom, that neutron energy after the collision is nearly equal to its energy before the collision.

Example 7.6 Scattering of a neutron in COM and LS

A neutron traveling through a medium is scattered by ⁹Be. If the initial neutron energy is 0.1 MeV and the scattering angle 45° in the *COM* system calculate the fraction of energy that the neutron will lose as well as the scattering angle in the *LS*? From

$$\frac{T(LS)}{T(LS)_0} = \frac{A^2 + 2A\cos\theta + 1}{(1+A)^2} = \frac{9^2 + 2 \times 9 \times \cos 45 + 1}{(1+9)^2} = 0.937$$

it follows that the scattered neutron energy is $0.937 \times 0.1 \text{ MeV} = 93.7 \text{ keV}$. The fraction of energy neutron has lost in this collision is

$$\frac{0.1 \text{MeV} - 93.7 \text{keV}}{0.1 \text{MeV}} = 0.063 \quad \rightarrow \quad 63\%$$

From Figure 7-15 it follows

$$v_1 \sin \theta = v \sin \psi$$
 $\frac{A v_0}{A+1} \sin \theta = v \sin \psi$

$$\frac{v}{v_0} = \sqrt{\frac{T(LS)}{T(LS)_0}} = \frac{A}{A+1} \frac{\sin\theta}{\sin\psi}$$

$$\sin \psi = \frac{9}{9+1} \frac{\sin 45}{\sqrt{0.937}} = 0.657 \quad \to \quad \psi = 41.1^{\circ}$$

3.2 Energy Distribution in Elastic Scattering -Logarithmic Energy Decrement

The energy that a neutron loses in an elastic collision with the nuclei of a medium is a function of medium atomic number and the scattering angle. The logarithmic energy decrement is defined as the logarithm of neutron energy per collision

$$\xi = \overline{\ln E_0 - \ln E} = -\ln \frac{\overline{E}}{E_0}$$
(7-220)

In the *COM* system the break up of a compound nucleus does not depend on the mode of its creation and neutrons scatter in random manner having equal probability for all directions (isotropic scattering, Fig. 7-16). The probability that a neutron will scatter into an angle between θ and $\theta + d\theta$ is the ratio of the area of the differential ring to the total area of the unit sphere

$$\frac{2\pi\sin\theta d\theta}{4\pi} = \frac{\sin\theta d\theta}{2}$$
(7-221)

The differential number of neutrons, dn, scattered into a differential angle is the product of the total number of neutrons, n, and the probability that neutrons will scatter into a differential angle between θ and $\theta + d\theta$

$$dn = n \frac{\sin \theta d\theta}{2} \tag{7-222}$$



Figure 7-16. Isotropic scattering of neutrons in COM

The differential number of neutrons, dn, multiplied by the logarithmic decrement

$$\xi dn = -\ln \frac{\overline{E}}{E_0} dn = \frac{n}{2} \sin \theta d\theta \left[-\ln \frac{A^2 + 2A\cos\theta + 1}{(A+1)^2} \right]$$
(7-223)

and integrated from 0 to π will give the total logarithmic decrement for all *n* neutrons of the system

$$\xi = -\ln\frac{\overline{E}}{E_0} = \frac{1}{n} \int_0^{\pi} \frac{n}{2} \sin\theta d\theta \left[-\ln\frac{A^2 + 2A\cos\theta + 1}{(A+1)^2} \right]$$
(7-224)

This integral can be solved introducing the following change of variables

$$x = \frac{A^2 + 2A\cos\theta + 1}{\left(A+1\right)^2} \Longrightarrow dx = -\frac{2A\sin\theta d\theta}{\left(A+1\right)^2}$$
(7-225)

with the appropriate adjustment of the limits, Eq. (7-224) becomes

$$\xi = -\ln \frac{\overline{E}}{E_0} = \int_{1}^{\alpha} \frac{\ln x}{2} \left[\frac{(A+1)^2}{2A} \right] dx = \frac{(A+1)^2}{4A} \int_{1}^{\alpha} \ln x dx$$
(7-226)

The constant term can be rearranged in the following form

$$\frac{(A+1)^2}{4A} = \frac{(A+1)^2}{(A+1)^2 - (A-1)^2} = \frac{1}{1 - \frac{(A-1)^2}{(A+1)^2}} = \frac{1}{1 - \alpha}$$
(7-227)

and the logarithmic decrement becomes

$$\xi = 1 + \frac{\alpha}{1 - \alpha} \ln \alpha \tag{7-228}$$

or,

$$\xi = 1 + \frac{(A-1)^2}{2A} \ln\left(\frac{A-1}{A+1}\right)$$
(7-229)

The average logarithmic energy loss per collision is only a function of mass of the target nucleus and is not dependent on neutron energy; it is usually approximated with

$$\xi = \frac{2}{A + 2/3} \tag{7-230}$$

Since ξ represents the average logarithmic energy loss per collision, the total number of collisions necessary for a neutron to lose a given amount of energy may be determined by expanding ξ into a difference of natural logarithms of the energy range in question.

The number of collisions (N) to travel from any energy, E_{high} , to any lower energy, E_{low} , may then be calculated as

$$N = \frac{\ln E_{high} - \ln E_{low}}{\xi}$$
(7-231)

If the medium is non-homogeneous, the effective or mean value for the logarithmic energy decrement is calculated as follows

$$\xi = -\ln \frac{\overline{E}}{E_0} = \frac{\xi_1 \sigma_{s1} + \xi_2 \sigma_{s2} + \dots}{\sigma_{s1} + \sigma_{s2} + \dots}$$
(7-232)

Example 7.7 Average number of neutron elastic collisions

Calculate the number of collisions in ⁹Be and ²³⁸U required to reduce neutron

energy from 2Mev to thermal energies (0.025 eV).

• ⁹Be:

$$\xi = 1 + \frac{(9-1)^2}{2 \times 9} \ln\left(\frac{9-1}{9+1}\right) = 0.207$$
$$N = \frac{\ln E_{high} - \ln E_{low}}{\xi} = \frac{\ln\left(2 \times 10^6 / 0.025\right)}{0.207} = 88$$

• ²³⁸U:

$$\xi = 1 + \frac{(238 - 1)^2}{2 \times 238} \ln\left(\frac{238 - 1}{238 + 1}\right) = 0.0084$$
$$N = \frac{\ln E_{high} - \ln E_{low}}{\xi} = \frac{\ln(2 \times 10^6 / 0.025)}{0.0084} = 2446$$

Although the logarithmic energy decrement is a convenient measure of the ability of a material to slow neutrons, it does not measure all necessary properties of a moderator. How rapidly slowing down will occur in material is measured by the *macroscopic slowing down power* (*MSDP*) which is defined as the product of the logarithmic energy decrement and the macroscopic scattering cross section for the material

 $MSDP = \xi \Sigma_s$

MSDP thus represents the slowing down power of all nuclei in a unit volume of a moderator and does not give full information about material properties such as probability of scattering or absorption of neutrons. For example (see Table 7-2), helium gas would have a good logarithmic energy decrement but very poor slowing down power due to the small probability of scattering neutrons due to its low density. Another example is boron that again has a high logarithmic energy decrement and a good slowing down power, but it is a poor moderator because it has a very high probability of absorbing neutrons.

The most complete measure of the effectiveness of a moderator is the *moderating ratio* (MR) which is defined as the ratio of the MSDP to the macroscopic cross section for absorption. The higher the MR, the more effectively the material performs as a moderator

$$MR = \xi \frac{\Sigma_s}{\Sigma_a} \tag{7-233}$$

For a single element this reduces to

$$MR = \xi \frac{\sigma_s}{\sigma_a} \tag{7-234}$$

while for a mixture of two elements it becomes

$$MR = \frac{\xi_1 \Sigma_{s1} + \xi_2 \Sigma_{s2}}{\Sigma_{a1} + \Sigma_{a2}}$$
(7-235)

ξ	N to thermalized	MSDP	MR
0.927	19	1 425	62
0.510	35	0.177	4830
0.427	42	8.87 x 10 ⁻⁶	51
0.207	86	0.724	126
0.171	105	0.092	0.00086
0.258	114	0.083	216
	<i>ξ</i> 0.927 0.510 0.427 0.207 0.171 0.258		

Table 7-2. Characteristics of moderators

Relative merits of some moderator materials used in current thermal reactors are given in Table 7-2. Ordinary water has high ξ and a good *MSDP*. However because of 0.332 b absorption cross section it has the lowest *MR* of all moderators. The use of enriched fuel is thus required for a reactor to be critical. But the low cost and high availability are crucial factors in the wide use in the majority of nuclear power plant designs. Graphite is also widely used due to good moderation parameters and low cost. Heavy water has superior characteristics as a moderator, but is very expensive and therefore used in only a small number of reactor configurations. Helium is not used because of its low density while beryllium is avoided due to its high toxicity.

3.3 Average Cosine of the Scattering Angle

As described in Section 3.1, actual physical measurements are made in the LS system, while theoretical treatment is usually done in the COM system because it is simpler. In the COM system the scattering of neutrons is considered to be isotropic while in LS there is a preferential forward scattering and scattering is therefore anisotropic. This can be shown by deriving the relation for the average cosine of the scattering angle.

In the *COM* system the average value of the cosine of the scattering angle can be calculated as the product of the number of neutrons scattering into an

angle between θ and $\theta + d\theta$ and $\cos \theta$ integrated from 0 to π divided by the total number of scattered neutrons

$$\overline{\cos\theta} = \frac{1}{n} \int_{0}^{\pi} \left(\frac{n}{2}\right) \cos\theta \sin\theta d\theta = 0$$
(7-236)

This gives a value for the scattering angle in COM system of 90°; this means that an equal number of neutrons scatter forward and backward therefore proving that scattering is isotropic in the COM system.

When transfer now to the LS system the scattering angle becomes (see Figures 7-14 and 7-15)

$$\cos\psi = \frac{\upsilon_1 \cos\theta + \upsilon_c}{\sqrt{(\upsilon_1 \cos\theta + \upsilon_c)^2 + (\upsilon_1 \sin\theta)^2}} = \frac{A\cos\theta + 1}{\sqrt{A^2 + 2A\cos\theta + 1}}$$
(7-237)

The average cosine of scattering angle is

$$\overline{\mu} \equiv \overline{\cos\psi} = \frac{1}{2} \int_{0}^{\pi} \cos\psi \sin\theta d\theta = \int_{0}^{\pi} \frac{(A\cos\theta + 1)\sin\theta d\theta}{2\sqrt{A^{2} + 2A\cos\theta + 1}} = \frac{2}{3A}$$
(7-238)

For example, the average cosine of scattering angle for graphite indicates the scattering is nearly isotropic in *LS* for that material

$$\overline{\mu} \equiv \overline{\cos \psi} = \frac{2}{3A} = \frac{2}{3 \times 12} = 0.056$$

while scattering on hydrogen indicates strong forward scattering

$$\overline{\mu} \equiv \overline{\cos \psi} = \frac{2}{3A} = \frac{2}{3 \times 1} = \frac{2}{3}$$

3.4 Slowing Down of Neutrons in Infinite Medium

3.4.1 Slowing Down Density (Neutron Moderation) without Absorption

All analyses presented in this section are valid for a steady state reactor, under the assumptions that there is no loss of neutrons by absorptions or leakage since the medium is assumed infinite during the slowing down process. It is also assumed that the energy dependent relations are already integrated over the spatial coordinates (spatial dependence is given in Section 3.5). The no absorption assumption requires a moderator that does not absorb neutrons with energies greater than thermal energies. Another assumption is that the neutron source is provided inside the moderator to produce neutrons at a uniform rate and at a definite energy, $S(E_1)$. A sink is provided to absorb only neutrons which have slowed down to thermal energies. Therefore, at steady state there will be no accumulation of neutrons and the number of neutrons that enter any energy increment, dE, at given energy E will be exactly equal to the number of neutrons leaving it. The slowing down process is shown schematically in Fig. 7-17.

The slowing down density, q(E), is defined as the number of neutrons per unit volume that pass a given energy E per unit time. The derivations which follow are given for energies far from the source energy. These solutions are called *asymptotic solutions*.

Solutions applicable near the source are complex (with the exceptions of hydrogen moderator) and are called the *transient solutions*. Each neutron generated at E_1 will be either scattered or absorbed. The scattering collisions will distribute neutrons uniformly over the energy range from E_1 to αE_1 . The slowing down density at E_1 is defined as the number of neutrons that slows down from E_1 per unit volume and in unit time

$$q(E_1) = S(E_1) \frac{\sum_{s} (E_1)}{\sum_{tot} (E_1)}$$
(7-239)

According to the assumption of no absorption in the system, the above relation reduces to

$$\Sigma_{tot}(E_1) = \Sigma_s(E_1) \quad \to \quad q(E_1) = S(E_1) \tag{7-240}$$

In an energy increment dE' (see Fig. 7-17) lying in energy interval between E/α and E, the number of collisions per unit volume in unit time is

$$\Sigma_{s}(E')\phi(E')dE' \tag{7-241}$$


Figure 7-17. Neutron slowing down in energy space

If the fraction of neutrons that will have energy less than E after scattering from dE' is

$$\frac{E - \alpha E'}{E' - \alpha E'} \tag{7-242}$$

then the number of neutrons passing an energy level E in unit volume per unit time, that originate from energy increment dE' is

$$\Sigma_{s}(E')\phi(E')\frac{E-\alpha E'}{E'-\alpha E'}dE'$$
(7-243)

Therefore, the slowing down density becomes

$$q(E) = \int_{E}^{E/\alpha} \Sigma_{s}(E') \phi(E') \frac{E - \alpha E'}{E' - \alpha E'} dE'$$
(7-244)

A more explicit relation can be obtained for the slowing down density by recognizing that at steady state the number of neutrons scattered into the increment dE at E must be equal to those scattered out (since there is no absorption and no leakage of neutrons)

$$\phi(E) = \frac{q(E)}{E\xi\Sigma_s(E)} = \frac{S(E)}{E\xi\Sigma_s(E)}$$
(7-245)

Since no neutrons are lost in an infinite non-absorbing medium at steady state, the number of neutrons slowing down past any energy is constant, or in other words the slowing down density is constant. The scattering cross section does not vary greatly in moderating energy region (see examples in Fig. 7-18) and the flux is proportional to 1/*E*.



Figure 7-18. Elastic scattering cross section in moderating energy region for ¹H and ¹²C

Example 7.8: Slowing down of neutrons

Neutrons of 1.5 MeV are introduced at the rate 2 x 10^{15} n/cm³-s in an infinite slab of graphite. Calculate the number of elastic scattering collisions occurring per second in cm³ in the energy interval from 0.5 to 0.3 MeV.

The average logarithmic energy loss per collision

$$\xi = 1 + \frac{(A-1)^2}{2A} \ln\left(\frac{A-1}{A+1}\right) = 0.158 \quad A = 12$$

Since no absorptions or leakage are assumed, the only interaction neutrons may undergo is scattering with the nuclei in the graphite slab. Thus, the slowing down density equals the neutron source, *i.e.* the neutron rate at energy 1.5 MeV. Hence, we may write

$$\phi(E) = \frac{S(E)}{E\xi\Sigma_s(E)} \rightarrow$$

$$\phi(E)\Sigma_s(E) = \int_{0.3}^{0.5} \frac{S(E)}{E\xi} dE = \frac{S}{\xi} \int_{0.3}^{0.5} \frac{dE}{E} = \frac{S}{\xi} \ln E\Big|_{0.3}^{0.5} =$$

$$= \frac{2 \times 10^{15}}{0.158} \ln \frac{0.5}{0.3} = 6.466 \times 10^{15} \,\text{n/cm}^3 \text{s}$$

3.4.2 Lethargy

The equations involving energy and energy changes may be expressed in terms of a quantity called *lethargy*. By definition, the lethargy is

$$u = \ln \frac{E_0}{E} \tag{7-246}$$

where E_0 is an arbitrary starting energy usually taken to be 10 MeV. As neutron energy decreases the lethargy increases (see Fig. 7-19). Low lethargy media are such that the energy change after a collision is small. This is true for high mass nuclei. If E_1 represents the neutron initial energy and E_2 neutron energy after the collision, the corresponding lethargies are u_1 and u_2 respectively, and then the lethargy change is given by

$$\Delta u = u_1 - u_2 = \ln \frac{E_1}{E_2} \tag{7-247}$$

Since the average value of $\ln E_1/E_2$ represents the average logarithmic energy loss, ξ

$$\Delta \overline{u} = \xi \tag{7-248}$$

it can be also regarded as the average change in lethargy. As stated before, for the isotropic scattering in the moderating energy region of the *COM* system, ξ is independent of energy. That means that neutrons, regardless of their initial energy, must undergo on average the same number of collisions in a given medium to increase their lethargy by a specific amount (because the reciprocal value $1/\xi$ represents the average number of collisions).



Figure 7-19. Neutron lethargy distribution

3.4.3 Slowing Down Density (Neutron Moderation) with Absorption

In any actual situation neutrons are absorbed during the slowing down process. The slowing down density with absorption can be expressed as

$$q(E) = q(E')p(E) = S(E')p(E)$$
(7-249)

where q(E') is the slowing down density without absorption, and p(E) is the fraction of neutrons that escape capture while slowing down from E'(energy of the source neutrons) to E, and is called the *resonance escape* probability.

For a homogeneous system assumed to be infinite with the fuel distributed throughout the moderator, the neutron flux is independent of position. The neutron absorption rate is then

Absorption from E' to
$$E = \int_{E}^{E'} \Sigma_a(E'')\phi(E'')dE''$$
 (7-250)

In order to determine neutron absorption it is necessary to know the flux distribution as a function of energy. That is difficult to determine exactly and some approximations are customarily introduced. One such approach is called the *narrow resonance* (NR) approximation. This approximation states that inside the resonance region, a neutron cannot be scattered from one energy to another. In other words, a neutron that enters the resonance region is either absorbed or is scattered to energy below the resonance.

Neutrons reaching the energy interval dE within the resonances will be

only those scattered from higher energies. In the NR approximation, the number of neutrons entering this energy interval is independent of whether or not neutrons are absorbed in this region and it is equal to $q(E) dE / E\xi$, or $S(E) dE / E\xi$. Neutrons are lost from the energy interval dE by absorption and scattering. The loss rate is $(\Sigma_{aF} + \Sigma_s) \phi(E) dE$, where Σ_{aF} is the absorption cross section in the fuel (absorber) and Σ_s is the total scattering cross section of the fuel and moderator, all of which are functions of energy.

In steady state, the number of neutrons entering an energy interval dE is equal to the number of neutrons which are lost

$$S(E)\frac{dE}{E\xi} = \left(\Sigma_{aF} + \Sigma_{s}\right)\phi(E)dE$$
(7-251)

giving the flux to be

$$\phi(E) = \frac{S(E)}{E\xi(\Sigma_{aF} + \Sigma_s)}$$
(7-252)

The presence of the absorption cross section in the denominator means that the neutron flux decreases in the resonance region.

The resonance escape probability then becomes

$$p(E) = \exp\left[-\frac{1}{\xi} \int \frac{\Sigma_{aF}}{\Sigma_{aF} + \Sigma_s} \frac{dE}{E}\right]$$
(7-253)

where the integration is over the resonance region energies.

A further approximation is called the narrow resonance infinite mass, NRIM approximation in which the mass number of the absorber is assumed to be infinitely large. In such a case, the scattering cross section is that for the moderator only. An alternative expression for the resonance escape probability may be written in the following way

$$p(E) = \exp\left[-\frac{N_F}{\xi \Sigma_s} \int \frac{\Sigma_s}{\Sigma_{aF} + \Sigma_s} \sigma_{aF} \frac{dE}{E}\right]$$
(7-254)

where the scattering cross section and the average energy loss are assumed to be independent of energy. The integral in last equation is called the *effective resonance integral*, I and has the same dimension as the microscopic cross section. Thus, $N_{\rm F}I$ has the dimension of macroscopic cross section.

Actual reactors are heterogeneous systems where fuel and moderator are physically separated. The fuel is present in distinct units called fuel rods that are spaced in a lattice array with the moderator region in between. If the neutron mean free path at given energy is less than or equal to the rod diameter, the probability that neutron will be absorbed in the fuel rod is large. This means that the flux at that given energy in the fuel rod will be lower than the flux in the moderator region. Resonance neutrons are largely absorbed in the outer regions of the fuel rods, especially if the resonance peak is narrow and high. As a result, nuclei in the interior are exposed to a very low neutron flux and the amount of absorptions is small. This effect is called self-shielding. The net result is that the probability of resonance capture is less than in the case of a uniform distribution of the fuel within the moderator. Therefore, the resonance escape probability is larger in heterogeneous systems. Also, it increases with fuel radius. Another factor that increases the escape probability in a fuel region is that some neutrons are slowed down in the moderator region to energies below the resonance region and therefore they escape capture. Neutrons absorbed by resonance capture in a thermal reactor fuel region (i.e. ²³⁸U) are lost from the fission chain reaction. Thus, most thermal reactors are designed to maximize the resonance escape probability. For fuel rods placed far enough that resonance neutrons cannot pass directly between the rods, the rods are said to be "isolated". The resonance escape probability is then found to be

$$p(E) = \exp\left[-\frac{N_F V_F}{\xi_F \Sigma_F V_F + \xi_M \Sigma_M V_M}I\right]$$
(7-255)

In closely packed or so called "tight" lattices, like in water moderated reactors, some resonance neutrons that would normally enter a fuel rod will be intercepted by adjacent fuel rods. The resonance flux is then less, on average, than it would be if the rods were well separated. Thus, each fuel rod in a tight lattice configuration is said to be partially "shadowed" by the other rods. The effective resonance integral is smaller, and thus the escape probability is larger. Corrections are made by introducing the Dancoff factor which depends on the spacing and radius of fuel rods and the fuel material cross sections.

3.5 Spatial Distribution of the Slowing Down Neutrons

3.5.1 Fermi Model

The proceeding models were developed for an infinite medium in which

the neutron flux distribution was not a function of spatial coordinates. However, in reality the system has finite dimensions in which the neutron flux distribution is a function of energy as well as spatial position $\phi(E, r)$. A useful approach in studying the spatial distribution of neutrons is to consider the slowing down density in the moderating region. Slowing down density can be expressed analytically only under certain approximations. A fairly simple analytical approach is the so called continuous slowing down model or the Fermi model. In the Fermi model the following assumptions are made:

- 1. The scattering of neutrons is isotropic in the *COM* system, thus the *average logarithmic energy decrement*, ξ , is independent of neutron energy. This also represents the *average increase in lethargy* per collision, *i.e.* after *n* collisions the neutron lethargy will be increased by $n\xi$ units (see Section 3.4.2).
- 2. Every neutron gains exactly ξ units of lethargy in every collision, *i.e.* each neutron is supposed to behave as an average neutron. Therefore, the only lethargy values possible in the moderating region are discrete values of $n\xi$, where n = 1, 2, 3, etc.
- 3. The lethargy is a continuous function, *i.e.* the steps in lethargy change are approximated by continuous change, see Fig. 7-20.

The Fermi model is a reasonably good for describing neutron slowing down process in a material with a large mass number; because the average logarithmic energy loss is small (the spread of neutron energies after scattering is relatively small). Thus, the assumption that each neutron behaves like an average neutron is nearly accurate. In addition, since ξ is small, the steps shown in Fig. 7-20 are small in height but large in number. Therefore, it is acceptable to approximate the steps with the continuous curve. If neutrons slow down in materials of low mass number (like hydrogenous materials), the energy spread after collision is large and the average lethargy change is large. For example, in hydrogen it is possible that a neutron would lose all of its energy in a single collision. In this case, the Fermi model is inapplicable.

The neutron conservation equation in a reactor for the energy range E and E + dE, assuming

- continuous slowing down of neutrons
- weak neutron absorptions in the moderator
- finite size of the reactor (leakage cannot be neglected)
- •

may be written as

$$-\left[-D\nabla^{2}\phi\left(E,\vec{r}\right)\right]dE - \Sigma_{a}\left(E\right)\phi\left(E,\vec{r}\right)dE + S\left(E,\vec{r}\right) = 0$$
(7-256)

with the terms defined as follows

 $-\left[-D\nabla^2\phi(E,\vec{r})\right]dE$: number of neutrons with energy dE leaking out of the system

 $\Sigma_a(E)\phi(E,\vec{r})dE$: number of neutrons with energy dE being absorbed in the medium

 $S(E, \vec{r})$: neutron source (number of neutrons slowing down out of *dE* as shown in Fig. 7-21.

The source term can thus be expressed in terms of slowing down density

$$S(E,\vec{r}) = q(E + dE,\vec{r}) - q(E,\vec{r}) = \frac{\partial}{\partial E}q(E,\vec{r})dE$$
(7-257)

which may be inserted into Eq. (7-256) to give

$$-\left[-D\nabla^{2}\phi\left(E,\vec{r}\right)\right]dE - \Sigma_{a}\left(E\right)\phi\left(E,\vec{r}\right)dE + \frac{\partial}{\partial E}q\left(E,\vec{r}\right)dE = 0$$
(7-258)



Figure 7-20. Continuous slowing down approximation



Figure 7-21. Definition of the neutron source term

If the medium is a weak absorber, Eq. (7-258) reduces to

$$D\nabla^2 \phi(E, \vec{r}) + \frac{\partial}{\partial E} q(E, \vec{r}) = 0$$
(7-259)

In the absence of absorption, the change in neutron slowing down density is due to leakage.

Combining Eq (7-259) with Eq. (7-245) gives

$$D\nabla^{2}\left[\frac{1}{\xi\Sigma_{s}(E)}\frac{q(\vec{E},\vec{r})}{E}\right] = -\frac{\partial}{\partial E}q(\vec{E},\vec{r})$$
(7-260)

or,

$$\nabla^2 q(E, \vec{r}) = -\frac{1}{\left(\frac{D}{\xi \Sigma_s(E)E}\right)} \frac{\partial}{\partial E} q(E, \vec{r})$$
(7-261)

Equation (7-261) can be simplified by introducing the variable, τ , called the *Fermi age*

$$d\tau = -\frac{D}{\xi \Sigma_s(E)E}$$

$$\tau = -\int_{E_0}^{E} \frac{D}{\xi \Sigma_s(E)E} dE = \int_{E}^{E_0} \frac{D}{\xi \Sigma_s(E)E} dE$$
(7-262)

Fermi age does not have units of time but the units of distance-squared and represents the *chronological age of neutrons*. In other words, it indicates the time elapsing as neutrons travel away from their source (with energy E_0) to the point where its energy has been reduced to E. For neutrons of source energy ($E = E_0$) the Fermi age is zero, $\tau = 0$. The Fermi age increases as energy decreases (as a neutron slows down its age increases).

The slowing down density can be now expressed in terms of Fermi age

$$\nabla^2 q(\tau, \vec{r}) = \frac{\partial}{\partial \tau} q(\tau, \vec{r})$$
(7-263)

and is valid for a medium with no absorption of neutrons. However, the age equation can be modified for weakly absorbing medium in the following way: if q(E) is the neutron density in non-absorbing medium, then q(E)p(E) is the slowing down density in a medium in which there is weak absorption of neutrons, p(E) being the resonance escape probability.

Example 7.9: Fermi age equation

Find and interpret the solution for the Fermi age equation for a point source of monoenergetic fast neutrons (10 MeV) undergoing continuous slowing down in non-absorbing medium.

The solution of the equation

$$\nabla^2 q(\tau, \vec{r}) = \frac{\partial}{\partial \tau} q(\tau, \vec{r})$$

is

$$q(\tau, \vec{r}) = \frac{e^{-\frac{r^2}{4\tau}}}{(4\pi\tau)^{3/2}}$$
(7-264)

It represents the slowing down density for neutrons of age τ at distance r from a point source of 1 n/s. This expression has the form of a Gaussian error curve, thus distribution of slowing down densities for a given age is sometimes referred to as

Gaussian distribution.

Example 7.10: Fermi age for different moderators

For water (density 1.0 g/cm³) and graphite (density 1.6 g/cm³) determine the Fermi age at 1 MeV. Assume neutrons initial energy is 2 MeV.

Data: $\sigma_s^H = 38b$ $\sigma_s^O = 3.76b$ $\sigma_s^C = 4.75b$ Fermi age

$$\tau = -\int_{E_0}^{E} \frac{D}{\xi \Sigma_s(E)E} dE = -\frac{D}{\xi \Sigma_s} \ln \frac{E}{E_0}$$

Water

$$N^{H_2O} = \frac{\rho N_a}{M} = \frac{1 \times 6.023 \times 10^{23}}{18} = 3.35 \times 10^{22} \text{ at/cm}^3$$

$$\Sigma_s^{H_2O} = 0.0335(2 \times 38 - 3.76) = 2.66 \text{ cm}^{-1}$$

$$\Sigma_{tr}^{H_2O} = \Sigma_s^{H_2O} \left(1 - \frac{2}{3A} \right) = 0.0335 \left[2 \times 38 \times \left(1 - \frac{2}{3 \times 1} \right) + 3.76 \times \left(1 - \frac{2}{3 \times 16} \right) \right] = 0.969 \text{ cm}^{-1}$$

$$D^{H_2O} = \frac{1}{3\Sigma_{tr}} = 0.344 \text{cm} \qquad \qquad \xi^{H_2O} = \frac{2\sigma_s^H \xi^H + \sigma_s^O \xi^O}{2\sigma_s^H + \sigma_s^O} = 0.958$$

$$\tau^{H_2 O} = -\frac{D}{\xi \Sigma_s} \ln \frac{E}{E_0} = -\frac{0.344}{0.958 \times 2.66} \ln \frac{1}{2} = 0.093 \text{ cm}^2$$

Carbon

$$N^{C} = \frac{\rho N_{a}}{M} = \frac{1.6 \times 6.023 \times 10^{23}}{12} = 8.03 \times 10^{22} \text{ at/cm}^{3}$$

 $\Sigma_s^C = 0.0803 \times 4.75 = 0.381 \text{cm}^{-1}$

$$\Sigma_{tr}^{C} = \Sigma_{s}^{C} \left(1 - \frac{2}{3A} \right) = 0.38 \, l \left(1 - \frac{2}{3 \times 12} \right) = 0.360 \, \mathrm{cm}^{-1}$$

$$D^{C} = \frac{1}{3\Sigma_{tr}} = 0.926 \text{cm}$$
 $\xi^{C} = 0.158$

$$\tau^{C} = -\frac{D}{\xi \Sigma_{s}} \ln \frac{E}{E_{0}} = -\frac{0.926}{0.158 \times 0.381} \ln \frac{1}{2} = 10.66 \text{ cm}^{2}$$

3.5.2 Migration Length

The Fermi age of neutrons is related to the mean square distance travelled while slowing down. For thermal neutrons of age τ_{th} the $\sqrt{\tau_{th}}$ represents a measure of net vector distance travelled from the formation as fission neutrons to their appearance as thermal neutrons. The mean square distance which corresponds to the Fermi age is calculated as

$$\overline{r^{2}} = \frac{\int_{0}^{\infty} r^{2} q(E, \vec{r}) 4\pi r^{2} dr}{\int_{0}^{\infty} q(E, \vec{r}) 4\pi r^{2} dr} = \frac{\int_{0}^{\infty} r^{4} e^{-\frac{r^{2}}{4\tau}} dr}{\int_{0}^{\infty} r^{2} e^{-\frac{r^{2}}{4\tau}} dr} = 6\tau$$
(7-265)

The neutron age is analogous to the square of diffusion length. The above equation means that neutron travels $1/6^{th}$ the mean square distance in going from the lethargy level before collision ($u_0 = 0$), to lethargy level after the collision (u). It also represents the slowing down length. The sum of the square of the diffusion length and the age is called the *migration area*

$$M^{2} = L_{th}^{2} + \tau_{th} \tag{7-266}$$

and its square root the *migration length* (see Table 7-3). The criticality equation in the slowing down approximation for a large reactor is

$$k_{\infty} = 1 + M^2 B^2 \tag{7-267}$$

Moderator Diffusion length Slowing-down Migration length (cm) length (cm) (cm) Water 0.027 0.052 0.059 Heavy water 1.000 0.114 1.010 Beryllium 0.210 0.100 0.233 Graphite 0.575 0.540 0.192

Table 7-3. Migration lengths for most common moderators and thermal neutrons

Example 7.11: Critical core dimensions

Calculate the migration length, critical core radius and critical mass of a spherical reactor moderated by unit-density water. The core contains 235 U at concentration of 0.0145 g/cm³.

Data: Fermi age is 27 cm², thermal diffusion area 3.84 cm², and buckling 2.8 x 10^{-3} cm⁻².

From

$$M = \sqrt{L_{th}^2 + \tau_{th}} = \sqrt{3.84 + 24} = 5.55 \text{cm}$$

Geometrical buckling for the spherical core will give the critical radius

$$B_g^2 = \left(\frac{\pi}{R_c}\right)^2 \rightarrow R_c = 59.4 \mathrm{cm}$$

Thus the critical reactor core mass is

$$m_c = 0.0145 \times \frac{4\pi}{3} R_c^3 = 12.7 \text{kg}$$

4. NEUTRON TRANSPORT IN THERMAL REACTORS

4.1 Neutron Life Time in Thermal Reactors

The neutron life time in a reactor is characterized through the fast fission

factor, fast non-leakage probability, resonance escape probability, thermal non-leakage probability, thermal fuel utilization factor, and reproduction factor used to define the six factor formula.

<u>Fast Fission Factor, </u>

In a thermal reactor some fast neutrons before they slow down, will cause fission of both ²³⁵U and ²³⁸U. At neutron energies above 1 MeV, most of the fissions will be in ²³⁸U because of its large proportion in the fuel. Since each single fission event produces more than one neutron, there will be an increase in the number of neutrons available. This effect is described by the *fast fission factor* (Fig. 7-22) which represents the ratio of the total number of neutrons (k_1+k_2), to the number of neutrons produced by thermal fissions (k_1). The fast fission factor is fixed once the fuel is fabricated. As the fuel ages (due to fuel burn up), the number of ²³⁸U atoms is depleted by fast fissions (and consequently converted into ²³⁹Pu). ²³⁹Pu is fissionable with the epithermal neutrons. In further considerations, these fissions are included in the fast fission factor as fast fissions. Thus, the change of fast fission factor over the reactor core lifetime can be assumed to be insignificant.



Figure 7-22. Neutron full life cycle, $k_1 = v_1 \Sigma_{f1} / (D_1 B^2 + \Sigma_{a1}); k_2 = \Sigma_{s1 \to 2} v_2 \Sigma_{f2} / (D_1 B^2 + \Sigma_{a1}) (D_2 B^2 + \Sigma_{a2})$

Fast Non–Leakage Probability, Pf

In thermal reactor, where there is a significant amount of moderator material, fast neutrons will slow down. They also may leak out of the reactor core, or may proceed to slow down through interactions with the nuclei in media. The ratio of the number of fast neutrons which begin to slow down to the number of fast neutrons from all fissions is called the *fast neutron non-leakage probability* (Fig. 7-22).

Resonance Escape Probability, pesc

During the slowing down process neutrons may escape or may be captured in the resonance region. The number of neutrons which become thermalized to the number of neutrons that started to slow down represents the so called *resonance escape probability* (Fig. 7-22).

Thermal Non–Leakage Probability, Pth

Of the total number of neutrons which are thermalized, a certain number will leak out of the core. The ratio of the number of thermal neutrons that are absorbed in the core to the number of neutrons that are thermalized is called the *thermal non-leakage probability* (Fig. 7-22). Like the fast non-leakage probability, the thermal non-leakage probability also strongly depends on the core size. As the core is smaller, the leakage is larger.

Thermal Utilization Factor, f

One of the most important factors in the life cycle of neutrons is the *thermal utilization factor* (Fig. 7-22). This factor takes into account absorption of thermal neutrons in materials other than the fissile fuel. It accounts for the control rods, chemical shim (boron), and thermal neutron poisons (the most important one being Xe). Thus, the thermal utilization is defined as the ratio of thermal neutrons absorbed in a fuel to the thermal neutrons absorbed in the entire core

$$f = \frac{\sum_{a}^{\text{fuel}} \overline{\phi^{\text{fuel}} V^{\text{fuel}}}}{\sum_{a}^{\text{fuel}} \overline{\phi^{\text{fuel}} V^{\text{fuel}}} + \sum_{a}^{\text{mod}} \overline{\phi^{\text{mod}} V^{\text{mod}}} + \sum_{a}^{\text{other}} \overline{\phi^{\text{other}} V^{\text{other}}}}$$
(7-268)

<u>Reproduction Factor, *n*</u>

The *reproduction factor* represents the number of neutrons released in thermal fission per number of neutrons absorbed by fissile fuel (Fig. 7-22).

Multiplication factor: k_{eff}

Figure 7-22 also represents the full neutron life cycle, or the relationship of one generation of neutrons to the next. This relationship is given in Eq. (7-203) and is called the effective neutron multiplication factor.

Assuming an infinite core size the criticality of the reactor will be determined through so called infinite multiplication factor since there will be no leakage of neutrons. For such a case, the infinite multiplication factor represents the ratio of neutrons in the current generation to the number of neutrons in the previous generation. In actual finite systems it is necessary to take into account the diffusion of neutrons from the center of the reactor core toward its geometrical boundaries and account for neutron loss due to leakage. In such systems the effective multiplication factor is obtained as a product of the infinite multiplication factor and neutron non-leakage probability as defined in Eq. (7-203).

For a reactor to be critical the effective multiplication factor must be equal unity. This means that the number of neutrons is constant in each generation and that the fission rate, and thus the reactor power, is maintained at the constant rate. With the k_{eff} greater than one the reactor power will raise exponentially and the reactor become supercritical. With the k_{eff} below unity reactor becomes subcritical and the number of neutrons in every coming generation decreases causing the reactor power to drop.

The infinite multiplication factor must be greater than unity for the reactor to be critical to allow for:

- Loss of neutrons due to leakage
- Buildup of fission fragments with time as some of them have very large absorption cross sections that toward the end of fuel cycle will reduce the neutron population, and thus the reactor power
- Consumption of fissionable nuclei that are depleted by time and thus neutron population decreases toward the end of fuel cycle
- Changes in temperature and pressure in the core that may cause change in fission rates.

Example 7.12 Infinite multiplication factor

A bare spherical reactor is made of a homogeneous mixture of heavy water and ²³⁵U, with the composition that for every uranium atom there are 2000 heavy water atoms. Using the one-speed diffusion theory, calculate the total absorption cross section, the thermal utilization factor and the infinite multiplication factor if

$$\eta = 2.06 \quad \sigma_a^{235} = 678b \quad D = 0.87 \text{ cm} \quad p_{esc} = 0.6$$

$$\Sigma_a^{D_2O} = 3.3 \times 10^{-5} \text{ cm}^{-1} \quad \sigma_a^{D_2O} = 0.001b$$

For the homogeneous reactor the neutron flux is the same in the core regardless of the material type, thus

$$f = \frac{\sum_{a}^{\text{fuel}} \overline{\phi}^{\text{fuel}} V^{\text{fuel}}}{\sum_{a}^{\text{fuel}} \overline{\phi}^{\text{fuel}} V^{\text{fuel}} + \sum_{a}^{\text{mod}} \overline{\phi}^{\text{mod}} V^{\text{mod}} + \sum_{a}^{\text{other}} \overline{\phi}^{\text{other}} V^{\text{other}}} = \frac{\sum_{a}^{\text{fuel}} \overline{\Sigma}_{a}^{\text{fuel}}}{\sum_{a}^{\text{tot}} \overline{\Sigma}_{a}^{\text{tot}}}$$

$$\Sigma_a^{\text{tot}} = \Sigma_a^{\text{fuel}} + \Sigma_a^{D_2 O} \qquad \qquad \Sigma_a^{D_2 O} = N^{D_2 O} \sigma_a^{D_2 O} \qquad \qquad \Sigma_a^{\text{fuel}} = N^{\text{fuel}} \sigma_a^{\text{fuel}}$$

$$\frac{N^{D_2 O}}{N^{fuel}} = 2000 \qquad N^{D_2 O} = \frac{\sum_a^{D_2 O}}{\sigma_a^{D_2 O}}$$

$$\Sigma_{a}^{\text{tot}} = \Sigma_{a}^{\text{fuel}} + \Sigma_{a}^{D_{2}O} = \Sigma_{a}^{D_{2}O} \left[1 + \frac{N^{\text{fuel}}}{N^{D_{2}O}} \frac{\sigma_{a}^{\text{fuel}}}{\sigma_{a}^{D_{2}O}} \right] = 0.01122 \text{cm}^{-1}$$

$$f = \frac{\sum_{a}^{\text{tot}}}{\sum_{a}^{\text{tot}}} = \frac{678}{678 + 2000 \times 0.001} = 0.997$$

For the homogeneous mixture $\varepsilon = 1$.

 $k_{\infty} = \epsilon p_{esc} f \eta = 1 \times 0.6 \times 0.997 \times 2.06 = 1.232$

Example 7.13 Neutron generation doubling time

If the effective multiplication factor is 1.1 how many generations of neutrons are required to double neutron population? If there are 1000 neutrons at the beginning (see Fig. 7-22) how many neutrons will produce 50 generations?

After *n* generations there will be k_{eff}^n neutrons produced. In order to double the number of neutrons

$$k_{eff}^n = 2 \rightarrow n = \frac{\ln 2}{\ln k_{eff}} = \frac{\ln 2}{\ln 1.1} = 7$$

The number of neutrons generated after 50 generations is

$$k_{eff}^n = N \rightarrow N = (1.1)^{50} = 117$$

meaning the initial number of neutrons is increased 117 times, therefore the total number of neutrons after 50 generations is $1000 \times 117 = 117,000$.

4.2 Homogeneous and Heterogeneous Reactors

The models used in the previous sections to describe the neutron transport and parameters of thermal nuclear reactors were related to a

homogeneous mixture of fuel and moderator. In a homogeneous reactor core the nuclear properties like neutron flux and average cross sections are spatially uniform. Although homogeneous systems are practical to use for theoretical analysis, in practice most reactor concepts are based on heterogeneous configurations. In heterogeneous cores the fuel and moderator are separated as all other structural and reactor control components. Thus nuclear properties change from one region to another such that for example the neutron flux can vary drastically over a very short distance. The basic reason for the spatial variation of neutron flux in heterogeneous reactors is because adjacent material regions can have different absorption cross sections or some zones can have materials with strong resonance peaks. The neutron flux is always depressed in a material region of high absorption cross section, like the control rods consisting of strong absorber materials (see Chapter 8). Materials with high resonance absorptions (i.e. ²³⁸U or ²³²Th) cause the neutron flux to be reduced in the resonance energy region. The neutron resonance absorption rate in ²³⁸U is smaller in heterogeneous than in homogeneous reactors. The following is a brief summary of how some main reactor parameters which influence criticality conditions change in heterogeneous as opposed to homogenous systems.

Homogeneous reactors

In homogeneous reactors the fission neutrons are in immediate contact with the atoms of the moderator. The neutrons are moderated through elastic scattering before they are absorbed by the nuclei of the fuel. As a consequence, the neutron will not have the energy necessary to cause fission in ²³⁸U (fast fissions), thus fast fission factor is nearly equal to unity, $\varepsilon \approx 1$ (the ratio of the total number of (fission, fast) neutrons slowing down past the fission threshold of ²³⁸U, to the number of neutrons produced by thermal fission).

The value of η does not vary since it depends on the composition of the fuel alone. In the case of natural uranium for example $\eta = 1.34$. Assuming an infinite reactor in its critical state, it follows

- $\mathcal{E} = 1$
- $\eta = 1.34$
- $p_{esc} \bullet f = k_{\infty} / \varepsilon \bullet \eta$

Thus the value for $p_{esc} \cdot f = 1 / 1 \cdot 1.34 = 0.746$ assures for chain reaction to be maintained. This value can be varied by changing the ratio of moderator to fuel in a homogenous mixture. Examples of homogenous systems include natural uranium and graphite, natural uranium and D₂O, natural uranium and H₂O and natural uranium and beryllium.

Heterogeneous reactors

In heterogeneous reactors the fuel rods are surrounded by moderator material. Fission takes place within the fuel and the neutrons are partially moderated through inelastic scattering until they escape from the fuel and initiate the principal process of moderation via elastic scattering with the nuclei of the moderator. The separation which exists between two fuel rods determines how many elastic scattering collisions can take place. Since neutrons travel through a fuel region before they enter moderator region there is a slight gain in fast fissions given that the neutrons emitted within the fuel rod can cause fast fission with ²³⁸U before escaping the rod. This is why the value of the fast fission factor, ε , increases to some extent. The ε value ranges between 1.02 and 1.03.

The resonance escape probability p_{esc} increases significantly in heterogeneous systems as a result of two effects

- *Pitch* (distance between the fuel rods): if the pitch is large, the majority of the neutrons will be moderated below resonant energies before entering a fuel element.
- *Fuel Self-Shielding*: fast neutrons born in the fuel region are mainly slowed down in the moderator region. After being thermalized, neutrons may diffuse back into the fuel region. Those with energies that correspond to the peak resonance region of the fertile nuclei in the fuel region will immediately be absorbed. The most significant resonance in the case of ²³⁸U is at energy of 6.7 eV with a peak cross section of 8000b. Therefore, absorptions at this energy level arise on the surface of the fuel rods, permitting the interior of the fuel to "see" no neutrons of epithermal energies consequently reducing the number of ²³⁸U atoms available for resonant capture. The result is an improvement in the resonance escape probability since only a small fraction of fuel volume is involved in resonance capture.

As a result of these two reasons, the usual value for resonance escape probability is about 0.9.

The thermal utilization factor, f, decreases in heterogeneous cores because of the fuel self-shielding for the absorption of thermal neutrons. The general expression for thermal utilization factor can be written as

$$f = \frac{\Sigma_a^{\text{fuel}}}{\Sigma_a^{\text{fuel}} + \Sigma_a^{\text{mod}} \frac{\overline{\phi}^{\text{mod}}}{\overline{\phi}^{\text{fuel}}} + \Sigma_a^{\text{other}} \frac{\overline{\phi}^{\text{other}}}{\overline{\phi}^{\text{fuel}}}}$$
(7-269)

If the flux in the moderator region and other components of the reactor core are larger than the flux in the fuel region, the thermal utilization factor will be reduced. The flux ratios in the denominator are called the *thermal disadvantage factors*.

The flux distribution of fast and thermal neutrons in a heterogeneous

lattice is depicted in Fig. 7-23 (numerical example is given at the end of this Chapter). Fast neutrons are born in the fuel region from fission events. Once they reach the moderator region they are lost from the fast group because they slow down in elastic collisions and become thermal neutrons. The slow neutrons are therefore born in moderator region when as fast neutrons lose the energy. Fuel elements represent a strong sink (absorber) of thermal neutrons and thus the thermal flux drops in fuel region and peaks in moderator region. Conversely, the fast flux peaks in fuel region and dips in moderator region.



Figure 7-23. Variation of thermal and fast neutron flux in a heterogeneous reactor fuel lattice

4.3 Bare and Reflected Reactors

The theory developed so far has referred to only bare reactors (reactors without a reflector). However, in reality the reactor core is usually surrounded by a neutron reflector made of a material which possesses good scattering properties. As a general rule, the reflector in thermal reactors is made of the same material as the moderator region; ordinary water, heavy water, or graphite. Since the majority of neutrons that reach the reflector region are returned to the core from scattering collisions, the size of the critical reactor core is smaller than in case of bare reactor. Therefore, the use of reflector decreases the mass of fissile material (fuel) required for a critical

system.

The reflector also changes the flux spatial distribution as depicted in Fig. 7-24. The figure shows

- The peak in the thermal flux distribution is at the center of the core and the dimensions of the core are assumed to be the same in both reactors, bare and reflected. The increase in thermal flux in the reflector beyond the core boundary is due to the slowing down of fast neutrons which escaped from the core into the thermal energy range. These thermal neutrons are not absorbed as quickly in the reflector as those in the core (because the reflector has no fuel and a much smaller absorption cross section). The flux gradient in the reflector near the boundary results in the return of thermal neutrons back to the core. This is why the flux is greater near the boundary in a reflected reactor in comparison to a bare reactor. Therefore, the reflector acts as a source of thermal neutrons due to the slowing down of fast neutrons (in thermal reactors).
- The average flux over the entire reactor core is increased in a reflected reactor. Since the power of a reactor is proportional to the neutron flux, the addition of a reflector increases power output.



Figure 7-24. Neutron flux distribution in bare and reflected thermal reactors

A reflector reduces the critical size of the reactor and therefore the fissile mass needed to produce a critical reactor. The decrease in critical dimension of a reactor with the reflector is called the *reflector savings*, δ

$$\delta = R_0 - R \tag{7-270}$$

where R_0 is the bare core radius, and R is the core radius of a reactor with

the reflector.

The reflector savings depends on the thickness of the reflector. The maximum reflector savings is obtained for the reflector thickness of about two migration lengths (assuming the reflector and moderator are of the same material).

5. CONCEPT OF THE TIME DEPENDENT NEUTRON TRANSPORT

All previous chapters were concerned with a reactor in which the flux (or neutron population) varied only with spatial position assuming a steady state reactor (reactor that operates at constant power). Analysis of how the neutron population varies with time is also very important and is called the transient behavior of the reactor.

Issues of the time dependent reactor can be grouped as follows

- 1. Behavior of the reactor in the non-critical regime (for example at startup of a reactor or when its power is to be raised a reactor has to be supercritical; also in order to shut down a reactor it must be subcritical). The study of the behavior of a neutron population in a non-critical reactor is called reactor kinetics. It assumes the analysis of the prompt neutron lifetime, the reactor without delayed neutrons, and the reactor with delayed neutrons, the prompt critical stage and the prompt jump approximation (all to be described in this chapter).
- 2. Regulation of the degree of reactor criticality (reactor is usually regulated by the use of control rods or chemical shim, where control rods are parts of fuel assemblies, and chemical shim is usually a boric acid mixed with the water moderator or coolant). Insertion of control rods make the reactor subcritical (more neutrons are absorbed), while withdraw causes the neutron multiplication factor to increase. In the case of chemical shim, the reactor is controlled by changing the concentration of a neutron absorbing chemical in the moderator or coolant region. The basics of reactor control are described in Chapter 8.
- 3. Temperature effects on neutron population (several of the factors defining the multiplication factor are temperature dependent) as described in Chapter 8.
- 4. Fission product poisoning (accumulation of fission products takes place during the operation of reactor). Some fission products have very large absorption cross sections and their presents in a reactor can have a profound effect on the neutron population. Xenon-155 and Samarium-149 are particularly important in analyzing reactor fuel consumption as well as the condition of the reactor after shut down. This aspect is

described in Chapter 8.

5. Reactor core properties during the life time of the core (fuel burnup and fission product formation affects the power level over time and thus power costs). Analysis related to this issue is called fuel management and is not addressed in this book.

The departure from the steady state neutron population, or the percent change in multiplication factor is called *reactivity*

Reactivity for a finite reactor:
$$\rho = \frac{k_{eff} - 1}{k_{eff}} = \frac{\Delta k_{eff}}{k_{eff}}$$
 (7-271)

Reactivity for an infinite reactor:
$$\rho = \frac{k_{\infty} - 1}{k_{\infty}} = \frac{\Delta k_{\infty}}{k_{\infty}}$$
 (7-272)

From these equations it can be understood that reactivity changes according to

$$\rho = 1 - \frac{1}{k_{eff}} = \begin{bmatrix} k_{eff} = 1 \rightarrow \rho = 0 & \text{critical} \\ k_{eff} > 1 \rightarrow \rho > 0 & \text{supercritical} \\ k_{eff} < 1 \rightarrow \rho < 0 & \text{subcritical} \end{bmatrix}$$
(7-273)

Thus, reactivity is restricted to the following ranges from $-\infty < \rho < 1$.

5.1 Neutron Life Time and Reactor Period without Delayed Neutrons

The total neutron lifetime accounts for the average time that a neutron spends in a reactor before it is absorbed or leaks out. In a thermal reactor it represents the sum of the slowing down time and the thermal (diffusion) time

$$l = l_s + l_{th} \tag{7-274}$$

The slowing down lifetime, l_s , is much shorter than the thermal neutron lifetime, l_{th} . It represents the time that a neutron spends while slowing down from fission energies to thermal energies. The thermal or diffusion lifetime corresponds to the time that neutrons spend diffusing before they are absorbed. In an infinite thermal reactor the neutron lifetime is obtained as

the ratio of the absorption mean free path and the average neutron velocity

$$l_{\infty} \approx l_{th\infty} = \frac{\lambda_{th}}{\overline{\nu}}$$
(7-275)

The neutron lifetime in a finite thermal reactor is shorter than that in an infinite reactor. If N represents the number of neutrons per generation and $P_{non-leak}$ represents the non-leakage probability then N x $P_{non-leak}$ neutrons remain in the core to contribute to the effective neutron lifetime

$$Nl_{th} = Nl_{th\infty}P_{non-leak} \longrightarrow$$

$$l \approx l_{th} = l_{th\infty}P_{non-leak} = \frac{l_{th\infty}}{1 + B^2L^2} = \frac{1}{\Sigma_a \overline{\nu}(1 + B^2L^2)}$$
(7-276)

The slowing and thermal lifetimes in thermal reactors are shown in Table 7-4 for a few most common moderator materials. The slowing down lifetime in fast reactors has no practical meaning. The total neutron lifetime in fast reactors is on the order of 10^{-7} seconds. The neutron generation time is defined as the integral time until a neutron is produced

$$\Lambda = \frac{\lambda_p}{\overline{\upsilon}} = \frac{1}{\overline{\upsilon}\Sigma_f}$$
(7-277)

where λ_p represents the mean free path for neutron production.

If G represents the number of neutron generations, or the number of neutron lifetimes, between 0 and time t that the effective multiplication factor is very close to unity. The neutron density and neutron flux in a thermal infinite reactor will change as follows

$$n(t) = n(0) \left(k_{eff} \right)^G$$

$$\phi(t) = \phi(0) \left(k_{eff} \right)^G$$
(7-278)

where

 $\phi(0)$ - initial (steady state) neutron flux

$$k_{eff} = \Delta k_{eff} + 1$$
$$G = \frac{t}{l_{\infty}}$$

Thus, the flux change can be expressed as

$$\ln \frac{\phi(t)}{\phi(0)} = \frac{t}{l_{\infty}} \ln \left(1 + \Delta k_{eff} \right) = \frac{t}{l_{\infty}} \left[\Delta k_{eff} - \frac{1}{2} \left(\Delta k_{eff} \right)^2 + \dots \right]$$
(7-279)

for very small change in multiplication factor, Eq. (7-279) reduces to

$$\ln \frac{\phi(t)}{\phi(0)} = \frac{t}{l_{\infty}} \left[\Delta k_{eff} \right] \quad \to \quad \phi(t) = \phi(0) e^{\frac{\Delta k_{eff}}{l_{\infty}} t}$$
(7-280)

Table 7-4. Neutron lifetime in thermal reactors

Moderator	Slowing down time (sec)	Thermal time (sec)	
Carbon	1.5 x 10 ⁻⁴	1.8 x 10 ⁻²	
Water	5.6 x 10 ⁻⁶	2.1×10^{-4}	
Heavy water	4.3×10^{-5}	1.4 x 10 ⁻¹	
Beryllium	5.7 x 10 ⁻⁵	3.7 x 10 ⁻³	

The reactor period taking into account only prompt neutrons (or e folding time), T, is defined as the time needed for flux to change by a factor e

$$T \equiv \frac{l_{\omega}}{\Delta k_{eff}}$$
(7-281)

The reactor period must be long enough to prevent a dangerous excursion of reactor power. All reactors employ automatic safety systems to suddenly shutdown a reactor if the period becomes too short. The following example illustrates the importance of this concept.

Example 7.14 Reactor period in the absence of delayed neutrons

For the reactor described in Example 7.2 calculate how the reactor power changes if $\Delta k_{eff} = 0.01$?

From the data calculated in Example 7.2

$$l_{\infty} \approx l_{th\infty} = \frac{\lambda_{th}}{\overline{\upsilon}} = \frac{1}{\Sigma_a \overline{\upsilon}} = \frac{1}{0.0146 \text{ cm}^{-1} \times 2.2 \times 10^5 \text{ cm/s}} = 3.1 \times 10^{-4} \text{ s}$$

$$T = \frac{l_{\infty}}{\Delta k_{eff}} = \frac{3.1 \times 10^{-4}}{0.01} = 3.1 \times 10^{-2} \quad \to \quad \phi(t) = \phi(0)e^{32t}$$

This means every second the power will increase by a factor of e^{32} .

5.2 Delayed Neutrons and Average Neutron Lifetime



Figure 7-25. Delayed neutron precursors

Not all neutrons are released at the same time following a fission event. Nearly 99 % of all neutrons are released virtually instantaneously (within about 10^{-13} seconds) after the actual fission event. These neutrons are called prompt neutrons. The remainder of neutrons are released after the decay of fission products. These neutrons are called delayed neutrons (with respect to the fission event). They are emitted immediately following the first β decay of a fission fragment, known as a delayed neutron precursor. Although delayed neutrons represent a very small fraction of the total number of neutrons, they play an extremely important role in the control of the reactor. Beta delayed neutron emission is improved when the emitted neutron binding energy is minimum. This is true when the neutron emitter has an odd neutron number, just above neutron shell closure. In particular, β decaying nuclei with neutron numbers equal to 52 (N=50 closed shell) and 84 (N=82 closed shell) are very important delayed neutron precursors as shown for ⁸⁷Br and ¹³⁷I, in Fig. 7-25. The delay is determined by the β decay constant. Delays vary from fractions of seconds to tens seconds. Probabilities for delayed neutron emission are on the order or less than 1 % per fission, or per prompt fission neutron. For example, the decay time of 55.72 seconds corresponds to the half-life of ⁸⁷Br (see Fig. 7-25) and defines the first decay group. Similarly, the decay of 131 I is followed by the emission of neutron after 2.72 seconds specifies the second group. In total, there are six groups of delayed neutrons (see Table 7-5).

Beta delayed neutrons are characterized by their yields β_{i} relative to the

total neutron number per fission, and their *decay constants* τ_i . The *total delayed neutron yield* per fission depends on the actual nuclear fuel that is used in a reactor, and is defined as

$$\beta = \sum_{i=1}^{6} \beta_i \tag{7-282}$$

Group	Energy for ²³⁵ U fission	Group half- life for ²³⁵ U	$\beta_i \text{ for } {}^{235}\text{U}$ (%)	eta_i for 233 U (%)	β_i for ²³⁹ Pu (%)
	(MeV)	fission			
Prompt:					
0	~ 2	~ 10 ⁻³	99.359	99.736	99.790
Delayed:					
1	0.25	55.72	0.021	0.023	0.007
2	0.56	22.72	0.140	0.079	0.063
3	0.43	6.22	0.126	0.066	0.044
4	0.62	2.30	0.253	0.073	0.069
5	0.42	0.61	0.074	0.014	0.018
6		0.23	0.027	0.009	0.009
β			0.641	0.264	0.210

Table 7-5. Prompt and delayed neutron groups and parameters for thermal reactors

Delayed neutrons do not have the same properties as the prompt neutrons released directly from fission. The average energy of prompt neutrons is about 2 MeV which is much greater than the average energy of delayed neutrons, ~ 0.5 MeV (see Table 7-5). The fact that delayed neutrons are born at lower energies has two significant impacts on the way they precede through the neutron life cycle:

- Delayed neutrons have a much lower probability of causing fast fissions than prompt neutrons because their average energy is less than the minimum required for fast fission to take place.
- Delayed neutrons have a lower probability of leaking out of the core while they are at fast energies, because they are born at lower energies and subsequently travel a shorter distance as fast neutrons.

The average neutron lifetime in a thermal reactor is defined as

/

$$\bar{l} = \frac{\sum_{i=0}^{6} \beta_i \bar{l}_i}{\sum_{i=0}^{6} \beta_i}$$
(7-283)

where $\overline{l_i}$ represents the mean lifetime of a delay group defined as reciprocal of the decay constant of the delayed group. For example, for ²³⁵U (from Table 7-5) the average neutron life time for all neutrons (prompt and delayed) is 0.0843 seconds. This means that 0.641 % of the total number of neutrons increases the effective neutron generation time by a factor of 84.

Example 7.15 Reactor period including all neutrons

For the reactor described in Example 7.2 and Example 7.14 calculate how the reactor power changes if $\Delta k_{eff} = 0.01$ and all neutrons are considered. Use Table 7-5 to estimate the delayed neutron contribution.

In Table 7-5 the prompt neutron lifetime was assumed to be 0.001 seconds. In Example 7.14 that time was calculated to be 0.00031 seconds. Thus, the average neutron lifetime for all neutrons is 0.0836 sec.

$$T = \frac{l}{\Delta k_{eff}} = \frac{0.836}{0.01} = 83.6s \quad \to \quad \phi(t) = \phi(0)e^{t/83.6}$$

Thus every second the reactor power will change by factor $e^{0.012} = 1.012$.



Figure 7-26. Effect of delayed neutron on power change in thermal reactors

The effect of delayed neutrons on reactor power changes as shown in Fig. 7-26

- Without delayed neutrons the power will rise exponentially and in a very short time (see Example 7.14)
- When the effect of delayed neutrons is taken into account, the power of a

thermal reactor changes as shown in Fig. 7-26 for $\Delta k_{eff} > 0$. At the very beginning the reactor behaves as if all neutrons were prompt. This is because the delayed neutrons are not yet effective. However, after a few seconds when delayed neutrons start to appear the rate of neutron flux and reactor power starts to level off. The rate of flux increase approaches the constant value determined by the stable reactor period.

• When $\Delta k_{eff} < 0$ the rate at which neutron power decreases is very fast and as soon as delayed neutrons appear the curve tends to flatten out. Since the flux is dying out, the short-lived delayed neutrons disappear completely and the curve approaches a slope with the value determined by the longest-lived neutron group.

5.3 Diffusion Equation for Transient Reactor

In an accurate reactor kinetics analysis all six groups of delayed neutrons are considered in detail (their production and decay). In order to simplify the complex calculation procedure, these six groups are considered as one group of delayed neutrons that appear from the decay of a single hypothetical precursor. The time dependent diffusion equation is given by Eq. (7-113).

The neutron source, S, in a transient reactor takes into account both, prompt and delayed neutrons

$$S = S_p + S_d \tag{7-284}$$

The fraction of prompt neutrons that slow down to thermal energies is 1 - β (see Fig. 7-27). Assuming the reactor to be infinite, this fraction contributes to the neutron source as

$$S_p = (1 - \beta)k_{\infty}\phi\Sigma_a \tag{7-285}$$

where $k_{\infty} \phi \Sigma_a$ means that k_{∞} thermal neutrons will appear for each neutron absorbed.

The delayed neutron source is defined with six delayed neutron groups that are for simplicity in this derivation assumed to all belong to one group. The contribution to the delayed neutron source is equal to the rate of decay for all precursors multiplied by the probability that delayed neutrons will escape resonance capture while slowing down, p_{esc}

$$S_d = p_{esc} \lambda C \tag{7-286}$$

where λ is the decay constant of the precursor, and C is the number of

delayed neutrons reaching thermal energies. For the reactor transient conditions near steady state (critical) the shape of the spatial flux distribution remains constant and only the magnitude changes. This eliminates the spatial dependence, allowing the diffusion transient equation to reduce to

$$D\nabla^2 \phi \approx -B^2 \phi$$

$$\frac{dn}{dt} = -DB^2 \phi - \Sigma_a \phi + S$$
(7-287)



Figure 7-27. Neutron cycle chart in transient thermal

Substituting Eq. (7-285) and Eq. (7-286) as well as assuming an infinite homogeneous reactor results in the following equation

$$\frac{dn}{dt} = -\Sigma_a \phi + (1 - \beta) k_{\infty} \phi \Sigma_a + p_{esc} \lambda C$$
(7-288)

By replacing the neutron density in terms of neutron flux and introducing the prompt neutron lifetime, the above equation becomes

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$$l_{th\infty} \frac{d\phi}{dt} = -\phi + (1 - \beta)k_{\infty}\phi + \frac{p_{esc}}{\Sigma_a}\lambda C$$
(7-289)

In an infinite reactor composed of a homogeneous mixture of the fuel and moderator, the total macroscopic thermal absorption cross section is the average value of the sum of the fuel and moderator cross sections.

The total number of neutrons absorbed anywhere in a reactor is equal to $\Sigma_a \phi$ per unit volume and unit time. Of this number, a fraction is absorbed in the fuel (fuel utilization, or in thermal reactors the thermal utilization factor).

Therefore, there are $f \Sigma_a \phi$ neutrons absorbed in fuel per unit volume and unit time. As a result $f \Sigma_a \varepsilon \eta \phi$ fission neutrons are emitted where η represents the average number of neutrons emitted per thermal neutron absorbed in fuel. Thus, the fission rate at which prompt and delayed neutrons are produced is

$$\eta \varepsilon f \Sigma_a \phi = k_\infty \Sigma_a \phi \frac{1}{p_{esc}}$$
(7-290)

The rate at which delayed neutrons are produced is

$$\beta k_{\infty} \Sigma_a \phi \frac{1}{p_{esc}} \tag{7-291}$$

which represents also the rate at which fission fragments (precursors) are produced (since delayed neutrons appears as a result of precursors decay). The precursors decay at the rate $\dot{\lambda}C$, thus

$$\frac{dC}{dt} = \beta k_{\infty} \Sigma_a \phi \frac{1}{p_{esc}} - \lambda C$$
(7-292)

Equations (7-289) and (7-292) represent a system of coupled differential equations to be solved simultaneously in order to obtain C and ϕ . The solution can be found for the following specific example: assuming that up to time t = 0 the reactor is critical (therefore, $k_{\infty} = 1$). If the small step change in reactivity is introduced after that time the question is: how will the thermal neutron flux behave with time? The solutions for the above two equations can be assumed in the form

$$\phi = Ae^{\omega t} \qquad C = C_0 e^{\omega t} \tag{7-293}$$

where A and C_0 are the constants and ω is a parameter to obtain. Inserting the assumed solutions into Eq. (7-292), it follows that

$$C_0 = \frac{\beta k_{\infty} \Sigma_a A}{p_{esc} \left(\lambda + \omega\right)}$$
(7-294)

Using the differential equation for neutron flux it follows

$$l_{th\infty}A\omega e^{\omega t} = -Ae^{\omega t} + (1-\beta)k_{\omega}Ae_{\omega t} + \frac{p_{esc}}{\Sigma_{a}}\lambda C_{0}e^{\omega t}$$
(7-295)

Rearranging

$$\frac{k_{\infty}-1}{k_{\infty}} = \frac{l_{lh\infty}\omega}{1+l_{lh\infty}\omega} + \frac{\omega}{1+l_{lh\infty}\omega}\frac{\beta}{\lambda+\omega} = \rho$$
(7-296)

This is known as the reactivity equation for one group of delayed neutrons. The right hand side (RHS) of this equation can be plotted as a function of parameter ω .

- If $\omega = 0$, the RHS = 0 (the solution curve will pass through the origin as shown in Figure 7-28).
- For $\omega \to \pm \infty$, the RHS $\to 1$.
- When $\omega = -\lambda$ or $\omega = -1/l_{th\infty}$, the RHS $\rightarrow \infty$.
- Since the reactivity can be positive or negative, there are two roots, ω_1 and ω_2 .

Therefore, the flux can be represented with

$$\phi = A_1 e^{\omega_1 t} + A_2 e^{\omega_2 t} \tag{7-297}$$

From Fig. 7-28 it can be observed

- When reactivity is positive $(\rho > 0)$ then ω_1 is positive and ω_2 is negative. Thus, as time increases the second term in the flux equation dies out and the flux increases as $e^{\omega_l t}$.
- When the reactivity is negative ($\rho < 0$) then both roots are negative. With time, the second term will die out faster than the first term because ω_2 is more negative than ω_1 . Thus, the flux will decrease as $e^{\omega_l t}$.

From these considerations it can be concluded that in either case, positive or negative reactivity, the flux will approach $e^{\omega_l t}$. The reciprocal of ω_l is called the reactor period or the stable period.

The one group delayed neutron reactivity equation can be generalized to

include all six delayed groups

$$\rho = \frac{l_{ih\infty}\omega}{1 + l_{ih\infty}\omega} + \frac{\omega}{1 + l_{ih\infty}\omega} \sum_{i=1}^{6} \frac{\beta_i}{\lambda_i + \omega}$$
(7-298)



Figure 7-28. Reactivity equation for one group delayed neutrons



Figure 7-29. Reactivity equation for six groups delayed neutrons

Using the same analysis as for the one group delayed neutron reactivity equation a similar plot can be obtained (see Fig. 7-29). In this case, however, there are seven roots for either positive or negative reactivity. The flux is given as a sum of exponentials

$$\phi = A_1 e^{\omega_1 t} + A_2 e^{\omega_2 t} + \dots + A_7 e^{\omega_7 t}$$
(7-299)

With increasing time flux again approaches $e^{\omega_l t}$ since all other exponents die out fast.

5.4 The Prompt Jump Approximation and Inhour Formula

The amount of reactivity necessary to make a reactor prompt critical corresponds to the prompt neutrons' multiplication factor (see Fig. 7-30)

$$(1 - \beta)k_{eff} = 1$$
 (7-300)



Figure 7-30. Flux change with the step reactivity insertion

It follows that the reactivity corresponding to a prompt critical reactor is

$$\rho = \frac{k_{eff} - 1}{k_{eff}} = \beta \tag{7-301}$$

and is used to define the unit of reactivity known as the dollar, . As shown in Table 7-5 the value of β varies with the fuel type and thus the dollar is not an absolute unit.

Example 7.16 Reactivity in dollars

Calculate the reactivity of a homogeneous ²³⁵U reactor if it suddenly becomes supercritical with $k_{eff} = 1.005$.

$$\rho = \frac{k_{eff} - 1}{k_{eff}} = \frac{1.005 - 1}{1.005} = 0.00497 \quad \rightarrow$$
$$\rho(\$) = \frac{\rho}{\beta} = \frac{0.00497}{0.0065} = 0.765\$ = 76.5 \text{ cents}$$

The exact computation of the early response of the reactor to a sudden change in reactivity is complex. However, under certain assumptions it can be significantly simplified. One such approach is called the *prompt jump approximation* and is based on the assumption that the concentration of the delayed neutron precursors does not change over the time following a sudden decrease or increase in neutron flux.

With time, as explained in previous section, the second term in Eq. (7-297) will die out quickly and the flux will decrease or increase with the reactor period *T*. Exact calculations predict that the constant A_2 is negative for positive reactivity and positive for negative reactivity. Therefore, the fast die out of a negative term will give a sudden rise in flux following the insertion of positive reactivity (see Fig. 7-30). On the other hand, the fast die out of a positive term will give a sudden drop in flux for negative reactivity insertion. With the assumption that the delayed neutron precursor concentration does not change over the time during the sudden decrease or increase of the neutron flux it follows

$$\frac{dC}{dt} = \beta k_{\infty} \Sigma_a \phi \frac{1}{p_{esc}} - \lambda C = 0 \longrightarrow C = \frac{\beta \Sigma_a \phi_0}{p_{esc} \lambda}$$
(7-302)

It is also assumed that the infinite reactor was originally critical. The flux value in the above equation is the flux prior to a sudden change in reactivity.

Therefore,

$$l_{th\infty} \frac{d\phi}{dt} = -\phi + (1 - \beta)k_{\infty}\phi + \beta\phi_0$$
(7-303)

where k_{∞} is the multiplication factor after the reactivity change. The solution is

$$\phi = \phi_0 e^{\frac{(1-\beta)k_{\infty}-1}{l_{th\infty}}t} + \frac{\beta\phi_0}{1-(1-\beta)k_{\infty}} \left[1 - e^{\frac{(1-\beta)k_{\infty}-1}{l_{th\infty}}t}\right]$$
(7-304)

or introducing the reactor stable period

$$T = \frac{l_{th\infty}}{(1-\beta)k_{\infty} - 1} \tag{7-305}$$

Eq. (7-304) becomes

$$\phi = \phi_0 e^{t/T} + \frac{\beta \phi_0}{1 - (1 - \beta) k_\infty} \left[1 - e^{t/T} \right]$$
(7-306)

The condition for a reactor to be less than prompt critical is that Eq. (7-300) be less than one. The two exponential terms in Eq. (7-306) will die out with a reactor period as given by Eq. (7-281); which is the reactor period taking into account only prompt neutrons (see Section 5.1). Thus

$$\phi = \frac{\beta \phi_0}{1 - (1 - \beta)k_{\infty}} = \frac{\beta (1 - \rho)\phi_0}{\beta - \rho}$$
(7-307)

where $k_{\infty} = 1/(1-\rho)$.

The above equation can be analyzed for the following two cases:

a) Positive reactivity change: this is an example of the reactivity required to increase the reactor power. This increase is usually small and takes a short period of time. For the example of a thermal reactor fuelled with 235 U the time is less than ~ 2 min for a reactivity insertion of 0.0006. Thus the flux will change according to

$$\phi = \frac{\beta(1-\rho)\phi_0}{\beta-\rho} = \frac{\beta(1-0.0006)}{\beta-0.0006}\phi_0 \approx \phi_0$$
This result indicates that the prompt jump in flux is usually negligible and can be assumed to rise from the initial value with the stable period.

b) Negative reactivity change: introduced whenever a reactor needs to be shutdown. The negative reactivity insertion can thus be very large. For example, if 20 % in negative reactivity is suddenly introduced into a reactor fuelled with ²³⁵U ($\beta = 0.0065$), the flux will drop by ~4% of its initial value

$$\phi = \frac{\beta(1-\rho)\phi_0}{\beta-\rho} = \frac{0.0065(1-(-0.2))}{0.0065-(-0.2)}\phi_0 = 0.038\phi_0$$

The reactivity can be also expressed in terms of the inverse hour, or "inhour" unit. The inhour reactivity is defined as the reactivity necessary to make the reactor stable period equal to 1 hour. The general inhour formula for a finite reactor including all six groups of delayed neutrons is

$$\rho(\text{inhours}) = \frac{l_{ih}}{3600k_{eff}} + \sum_{i=1}^{6} \frac{\beta_i}{1 + 3600\lambda_i}$$
(7-308)

NUMERICAL EXAMPLE

Method of Characteristics Solution to Neutron Transport in Nuclear Reactor Assembly Geometry

This numerical example illustrates the computational method of characteristics solution to the neutron transport equation. A representative geometry of a complex reactor assembly is selected to show the distribution of neutron flux and reaction rates as a function of neutron energy group and spatial coordinates. The method of characteristic solves an integrodifferential form of the transport equation along straight lines throughout the geometric domain in a discrete number of spatial directions and for discrete number of energy groups. These straight lines are interpreted as neutron trajectories similar to the Monte Carlo neutron trajectories. The method itself requires fine spatial subdivision of the geometrical domain into so called flat-flux zones where the material properties are assumed to be constant. The following example is based on the methodology developed in the AGENT code and the list of references is provided for further reading for those interested in computational neutron transport modeling.

The selected example is a two-dimensional assembly consisting of 17x17 lattice with the square fuel pin cells, as shown in Fig. 7-31. The side length of every fuel-pin cell is 1.26 cm and every cylinder is of radius 0.54

cm. The spatial fine-mesh flux distribution for each of energy regions is shown in Fig. 7-32 to 7-38, while neutron absorption rate is shown in Fig. 7-39 to 7-45. Fig. 7-46 shows the absorption rate integrated over all energies.



Figure 7-31. Fuel assembly geometry modeled with AGENT code



Figure 7-32. Neutron flux distribution for energies from 13.53MeV to 20.00MeV



Figure 7-33. Neutron flux distribution for energies from 9.12keV to 13.53MeV



Figure 7-34. Neutron flux distribution for energies from 3.93eV to 9.12keV



Figure 7-35. Neutron flux distribution for energies from 0.63eV to 3.93eV



Figure 7-36. Neutron flux distribution for energies from 0.15eV to 0.63eV



Figure 7-37. Neutron flux distribution for energies from 0.057eV to 0.15eV



Figure 7-38. Neutron flux distribution for energies from 0.00eV to 0.057eV



Figure 7-39. Absorption rate distribution for energies from 13.53MeV to 20.00MeV



Figure 7-40. Absorption rate distribution for energies from 9.12keV to 13.53MeV



Figure 7-41. Absorption rate distribution for energies from 3.93eV to 9.12keV



Figure 7-42. Absorption rate distribution for energies from 0.63eV to 3.93eV



Figure 7-43. Absorption rate distribution for energies from 0.15eV to 0.63eV



Figure 7-44. Absorption rate distribution for energies from 0.057eV to 0.15eV



Figure 7-45. Absorption rate distribution for energies from 0.00eV to 0.057eV



Figure 7-46. Absorption rate integrated over all energies

PROBLEMS

7.1 Calculate how many kilograms of 235 U are in 150 kg of U₃O₈.

7.2 Calculate the energy in eV for hydrogen atom moving at a speed of 2200 m/sec. Compare it to the energy of thermal neutron traveling at the same speed at the room temperature (293 K).

7.3 How much power will be produced from the spontaneous fission decay of 1 mg of 256 Fm (half-life is 158 min)? Assume that each fission event would release 220 MeV. How much of 235 U would be needed to produce 6 MW of power?

7.4 Calculate the neutron density in a thermal reactor with the neutron flux of 10^{12} n/cm²sec. How does this value compare with the particle density in a volume of 1 cm³ at standard conditions and how with the number of hydrogen atoms in water?

7.5 Using on-line data for neutron cross sections (<u>http://atom.kaeri.re.kr</u>) calculate the scattering mean free path for thermal neutrons in graphite, lead and beryllium. Discuss the scattering cross section dependence on material type and neutron energy.

7.6 If the average neutron flux is 10^{13} n/cm²sec calculate the average thermal power of the reactor with 5 % enriched uranium fuel of weight 150 kg. The uranium density is 18.7 g/cm³. Use the on-line data library to read necessary cross sections.

7.7 Calculate the probability that a 2MeV neutron will undergo first collision in 3/9 inch dia. UO₂ fuel rod enriched to 4 %. Assume that the neutron originated in the center of the rod and travels radially. The fuel rod has density which is 94 % of theoretical fuel density (equal to 10.96 g/cm³).

7.8 Calculate the neutron flux and neutron current density if two beams of neutrons are traveling in the same direction down to same guide tube: (a) beam 1: neuron density is $5 \times 10^7 \text{ n/cm}^2$ and neutron energy is 10 keV; (b) neutron beam 2: neutron density is $2 \times 10^7 \text{ n/cm}^2$ and neutron energy is 1 eV. How do these values change if neutron beams travel in opposite direction?

7.9 Show all steps in deriving the solution to the diffusion equation for a point neutron source placed in an infinite large medium.

7.10 A large bare reactor has the infinite multiplication factor of 1.022. The neutron diffusion length is 35 cm. Determine and compare the critical volumes of the following reactor shapes: sphere, cube, cylinder with height twice its radius, and rectangular parallelepiped having a = b = c/4.

7.11 For the homogeneous one-speed reactor of cylindrical configuration derive the formula to obtain its minimum volume (mass). Discuss the values in terms of reactor buckling.

7.12 Calculate the non-leakage probability for the bare cubic homogeneous reactor with diffusion length of 10 cm and a = b = c = 100 cm. Assume the absorption cross section of 0.1 cm⁻¹.

7.13 Determine the number of elastic scattering events occuring per 1 cm³ in the energy interval from 0.5 MeV to 0.3 MeV for neutrons of 1.5 MeV passing through an infinite slab of graphite at the rate of 2×10^{15} n/cm³sec.

7.14 How many collisions are needed to slow neutrons from 2 MeV down to thermal energy region in Be and D moderators?

7.15 Calculate the critical core radius and the critical mass of a spherical reactor moderated and reflected by water. The 235 U fuel density in a core is 0.0145 g/cm³. How does critical mass of the bare reactor compare to the one with the reflector?

7.16 A homogeneous, spherical, bare reactor of volume 250 m³ is composed of 5 % enrichment ²³⁵U and graphite. Using the six factor formula, calculate k_{eff} for the given data at a thermal energy:

- Uranium-to-moderator ratio: 5:1
- Graphite density: 2267 kg/m³
- Graphite molar weight: 12.0107 g/m
- Uranium density: 19050 kg/m³
- Graphite microscopic absorption cross section: .009 b
- Graphite microscopic scattering cross section: 10 b
- Uranium-238 microscopic absorption cross section: 90 b
- Uranium-238 molar weight: 238.0507847 g/m
- Uranium-235 microscopic total absorption cross section: 360 b
- Uranium-235 microscopic fission cross section: 270 b
- Uranium-235 molar weight: 235.0439242 g/m
- v = 2.2
- $p_{esc} = 1$
- $\varepsilon = 1$
 - $P_f = 1$

7.17 In a thermal nuclear reactor at the beginning of its life for every 1000 neutrons,

500 neutrons are absorbed in ²³⁵U

225 neutrons are absorbed in ²³⁸U

125 neutrons are absorbed in coolant and cladding, and

150 neutrons leak out from the geometrical core boundaries.

Calculate the multiplication factor for this reactor if v = 2.43. By definition the conversion factor represents the ratio of number of fissile nuclei produced to the number of fissile nuclei lost. What is the conversion ratio value for this reactor?

7.18 Inserting the control rods into the thermal reactor from the Problem 7.17, the absorption in other materials increases such that:

450 neutrons are absorbed in ²³⁵U

215 neutrons are absorbed in ²³⁸U

185 neutrons are absorbed in coolant, control rods and cladding, and

150 neutrons leak out from the geometrical core boundaries. Calculate the multiplication factor for this reactor.

7.19 The simplest form of neutron diffusion equation for thermal neutrons is one-speed theory. What are the assumptions upon which this theory is valid?

7.20 Write a computer program to follow the histories of 100 neutrons starting with energy 100 keV and slowing down to 10 eV in graphite (density 1.6 g/cm^3): absorption cross section is zero, scattering cross section is 4.8 b.

7.21 Repeat the problem 7.20 but use water instead with scattering cross section on hydrogen equal to 20 b and oxygen equal to 4 b.

7.22 Repeat previous two problems by including the absorption of neutrons. Assume that the cross section for absorption in carbon is 0.004 b, in hydrogen is 0.335 b and in oxygen is 0.002 b.

7.23 A reactor is critical at a power level of 400 MW. How long it will take to reach the power level of 3300 MW on a stable period of 100 seconds?

7.24 Using the one group delayed neutron equation calculate how long it would take to increase the power of a reactor by 10 % with the reactivity addition of 0.02 % $\delta k/k$? Assume that the reactor is critical before the addition of reactivity with thermal neutron lifetime of 5 x 10⁻⁵ sec.

7.25 Calculate the effective multiplication factor for the 235 U reactor having reactivity of – 1\$. If fuel is replaced with 239 Pu what is the multiplication factor value?

7.26 Calculate the new stable period if control rods inserted into a supercritical reactor with the stable period of 20 sec add $-0.01 \% \delta k/k$ to the reactivity. Assume thermal neutron life time is 0.0001 sec.

7.27 Calculate the size of a thermal bare spherical reactor containing 235 U and water in the atom ratio of $N(\text{water}) / N(^{235}\text{U}) = 198$ if the neutron spectrum follows Maxwellian distribution at 20 C. How does result change if temperature is changed to 300 C?

7.28 A slab of graphite contains a plane neutron source in the center. The slab is in a large pool of water. The albedo (reflection coefficient) of water is defined as J_{out} / J_{in} where J represents the neutron current. Evaluate the albedo if the slab is 60 cm thick. Assume that the source produces thermal neutrons.

Chapter 8

NUCLEAR REACTOR CONTROL

Methods of reactor control, Fission product poisoning and Reactivity coefficients

"There are two possible outcomes: If the result confirms the hypothesis, then you've made a measurement. If the result is contrary to the hypothesis, then you've made a discovery". *Enrico Fermi* (1901 - 1954)

1. METHODS OF REACTOR CONTROL

In a reactor of given volume in which fission is caused by neutrons of specified energy, the thermal power is proportional to the neutron flux and macroscopic fission cross section. As the reactor operates, the macroscopic cross section decreases as number of fissile nuclides decreases. However, over an essentially short period of time, the cross section remains constant, and the power is assumed to change only with neutron flux.

In most situations a reactor is controlled by varying the neutron flux. Among the general methods available, the insertion and withdrawal of a neutron absorber is most commonly used in power reactors. Materials used as a control absorber have large absorption cross sections, like boron, cadmium or hafnium. Strong absorbers in a core compete with fissile material for neutrons. In other words, neutrons which are absorbed by the controller are no longer available to induce fission, thus reducing the power.

1.1 Control Rods

The change in reactivity caused by control rod motion is referred to as *control rod worth*. The maximum effect (insertion of the most negative

reactivity) of a control rod is at the location in the reactor where the flux has its maximum value. Control rods are used to:

- Change reactivity in order to lower or elevate the reactor power placing it on a stable period rod worth is defined as the magnitude of reactivity required to give the observed period.
- *Keep reactor critical by compensating for changes over reactor operating time -* rod worth is measured in terms of change in neutron multiplication factor for which the rod can compensate.

Control rods can be inserted fully or partially. In either of these two cases the neutron flux is perturbed and reactor power changed. The following two sections address the effects of control rod insertion and withdrawal on fission rate, reactor flux distribution and the resulting power change.

1.1.1 Effect of Fully Inserted Control Rod on Neutron Flux in Thermal Reactors



Figure 8-1. Effect of a control rod on flux perturbation

The material used for the control rods varies depending on reactor design. Generally, the control rod material should have a high absorption cross section as well as a long lifetime in the reactor (not burn out too rapidly). A control rod which absorbs essentially all incident neutrons is referred to as a "black" absorber and generates large flux depression (see Figure 8-1). A "grey" absorber absorbs only a fraction of incident neutrons. While it takes more grey rods than black rods for a given reactivity effect, the grey rods are often preferred because they cause smaller flux depressions in the vicinity of the rod. This leads to a flatter neutron flux profile resulting in a more even power distribution across the core. Since the thermal neutron flux density generally peaks in the center of reactor core, this is where high efficiency control rods are generally placed.

A bare cylindrical reactor which is critical with control rods removed may be described by the one-speed neutron diffusion equation

$$\nabla^2 \phi + B_{out}^2 \phi = 0 \tag{8-309}$$

The multiplication factor, which is equal to unity, is given by

$$k_{out} = \frac{k_{\infty}}{1 + B_{out}^2 M^2} = 1$$
(8-310)

If a strongly absorbing control rod is fully inserted into the core the neutron flux will change as shown in Fig. 8-1 due to high neutron absorption in the rod. The flux distribution can be described as

$$\nabla^2 \phi + B_{in}^2 \phi = 0 \tag{8-311}$$

When the control rod is inserted the multiplication factor changes as

$$k_{in} = \frac{k_{\infty}}{1 + B_{in}^2 M^2}$$
(8-312)

Notice that the core buckling changes with control rod insertion and the change in multiplication factor will give the reactivity

$$\rho = \frac{k_{out} - k_{in}}{k_{in}} \tag{8-313}$$

The control rod worth, ρ_w , by definition, is equal to the magnitude of this reactivity change

$$\rho_{w} = \left|\rho\right| = \frac{\left(B_{in}^{2} - B_{out}^{2}\right)M^{2}}{1 + B_{out}^{2}M^{2}}$$
(8-314)

In order to obtain the control rod worth, Equations (8-310) and (8-312) must be solved to obtain the buckling for both cases. In initially critical reactor without control rods the buckling is given with

Chapter 8

$$B_{out}^{2} = \left(\frac{2.405}{R}\right)^{2} + \left(\frac{\pi}{H}\right)^{2}$$
(8-315)

However, the calculation of buckling when the control rod is inserted is difficult because the geometry is complicated and because the presence of strong absorber tends to deform the flux such that the diffusion approximation is not valid in its vicinity. In this case, a solution can be obtained by assuming that d represents the extrapolated distance and that the flux satisfies the following boundary condition at the surface of the control rod

$$\frac{1}{\phi}\frac{d\phi}{dr} = \frac{1}{d} \tag{8-316}$$

The final result for the extrapolation distance and control rod worth is (detailed derivation can be found elsewhere)

$$d = 2.131\overline{D}\frac{a\Sigma_{tot} + 0.9354}{a\Sigma_{tot} + 0.5098}$$
(8-317)

$$\rho_{w} = \frac{7.43M^{2}}{\left(1 + B_{out}^{2}M^{2}\right)R^{2}} \left[0.116 + \ln\left(\frac{R}{2.405a}\right) + \frac{d}{a} \right]^{-1}$$
(8-318)

where *a* is the radius of a control rod, *R* is extrapolated radius of the bare cylindrical core and *H* is its extrapolated height, \overline{D} is the diffusion coefficient and Σ_{tot} is the macroscopic cross section.

The cross section and diffusion coefficient are those for the materials surrounding the control rod which is assumed to be a black absorber.

1.1.2 Control Rod Worth in Fast Reactors

The most promising material to be used as the control absorber in fast reactors is boron-carbide (B₄C) enriched in ¹⁰B, because unlike other materials, absorption cross section for the boron is still significant at high neutron energies. Although considerably higher than for other materials, the boron absorption cross section at energies of importance in fast reactors (0.1 MeV to 0.4 MeV) is only 0.27 b (see Chapter 6). Therefore, the absorption neutron mean free path in a medium containing boron is large the atom density of boron is 0.087 x 10^{24} atoms/cm³ at a B₄C density of 2 g/cm³

400

giving $\lambda_a = 42.6$ cm. This is considerably larger than the diameter of any control rod size used in fast reactors which means that the neutron flux inside the control rod is more or less the same as in the surrounding medium. Therefore the boron contained in the rod can be assumed to be uniformly distributed in the reactor. This assumption will only affect the calculation of the fuel utilization factor in determining the control rod worth.

In actual reactor design, control rod worth is calculated using computer codes and a multigroup approach. The following is a simplified one group estimate of control rod worth in fast reactor. The multiplication factor for a fast reactor is given by

$$k_{eff} = k_{\infty} P_{non-leakage} = \eta f P_{non-leakage}$$
(8-319)

Since the uniformly distributed poison in fast reactors has an effect only on the fuel utilization factor, the control rod worth reduces to

$$\rho_{w} = \frac{k_{out} - k_{in}}{k_{in}} = \frac{f_{out} - f_{in}}{f_{in}}$$
(8-320)

$$f_{in} = \frac{\sum_{a}^{fuel}}{\sum_{a}^{fuel} + \sum_{a}^{coolant} + \sum_{a}^{boron}}$$
(8-321)

$$f_{out} = \frac{\sum_{a}^{fuel}}{\sum_{a}^{fuel} + \sum_{a}^{coolant}}$$
(8-322)

giving

$$\rho_{w} = \frac{\Sigma_{a}^{boron}}{\Sigma_{a}^{fuel} + \Sigma_{a}^{coolant}}$$
(8-323)

1.1.3 Effect of Partially Inserted Control Rod on Neutron Flux in Thermal Reactors

At the time of reactor start-up, all or most of, the control rods are fully inserted. After the start-up, they are slowly withdrawn in order to keep the reactor critical as the fuel is consumed and fission products accumulate. Therefore, it is necessary to know the control rod worth as a function of its insertion distance. The one group approximation is used to illustrate the computation of control rod worth for partially inserted rods in a thermal reactor.

For a cylindrical reactor let

- ρ_w (x): the worth of one or more control rods inserted at the distance x
 parallel to the axis of the reactor core with total height H
- $\rho_w(H)$: the worth of fully inserted control rods.



Figure 8-2. Integral control rod worth as given by Eq (8-324)

The exact effect of control rods on reactivity may be determined experimentally. For example, a control rod can be withdrawn in small increments, and the change in reactivity determined for each increment of withdrawal. By plotting the resulting reactivity versus rod position, a graph similar to that shown in Fig. 8-2 is obtained. The graph depicts *integral control rod worth* over the full range of rod withdrawal. Integral control rod worth represents the total reactivity worth of the rod at that particular degree of withdrawal

$$\rho_w(x) = \rho_w(H) \left[\frac{x}{H} - \frac{1}{2\pi} \sin\left(\frac{2\pi x}{H}\right) \right]$$
(8-324)



Figure 8-3. Differential control rod worth as given by Eq. (8-325)

The slope of the curve, and therefore the amount of reactivity inserted per unit of withdrawal, is greatest when the control rod is midway out of the core. This is because the neutron flux is maximum near the center of the core, thus the neutron absorption rate is also greatest in this area. If the slope of the curve for integral rod worth in Fig. 8-2 is plotted, the result is a value for the rate of change of control rod worth as a function of position. Such a plot is referred to as the *differential control rod worth*, and is shown in Fig. 8-3. At the bottom of the core there are few neutrons so rod movement has little effect; therefore the change in rod worth over distance is nearly constant. As the rod approaches the center of the core its effect becomes greater, and the change in rod worth per distance becomes significant. At the center of the core, the differential rod worth is greatest and varies little with rod motion. From the center of the core to the top, the rod worth per distance is the opposite of the rod worth per distance from the center to the bottom.

The integral rod worth at a given withdrawal is the summation of the entire differential rod worth up to that point of withdrawal and is also the area under the differential rod worth curve at any given withdrawal position. The differential control rod worth is obtained as a derivative of $\rho_w(x)/\rho_w(H)$

$$\frac{1}{\rho_w(H)} \frac{\rho_w(x)}{dx} = \frac{1}{H} \left[1 - \cos\left(\frac{2\pi x}{H}\right) \right]$$
(8-325)

1.2 Chemical Shim

Water moderated and cooled reactors can be in part controlled, in addition to control rod systems, by varying the concentration of the boric acid (H_3BO_3) in the coolant. This is called *chemical shim*. Because the response to a change in concentration of the solvent is not as quick as obtained by the insertion of control rods, chemical shim cannot be used to control the large reactivity insertions. Thus it is always used in conjunction with the control rod systems. In a reactor with both control systems:

- control rods are used to provide the reactivity control for fast shutdown, and for compensating reactivity variance due to temperature change
- chemical shim is used to keep the reactor critical during xenon transients, and to compensate for the depletion of fuel and build-up of fission products during reactor lifetime.

The use of chemical shim reduces the number of control rods required in a reactor. Since control rod systems are expensive, any reduction in the number of control rods reduces the total cost of the reactor. Chemical shim is almost uniformly distributed in the core and thus perturbs power distribution less as the concentration of the boric acid is changed.

Chemical shim in thermal reactors primarily affects the thermal (fuel) utilization factor. Therefore, chemical shim worth can be computed from the following relation

$$\rho_{w} = \frac{\Sigma_{a}^{boron}}{\Sigma_{a}^{fuel} + \Sigma_{a}^{mod}}$$
(8-326)

By inserting Equation (8-322) the reactivity worth reduces to

$$\rho_w = \left(1 - f_{out}\right) \frac{\Sigma_a^{boron}}{\Sigma_a^{\text{mod}}}$$
(8-327)

The boric acid concentration is usually specified in units of *ppm (parts per million)* of water.

The *ppm* represents 1 g of boron per 10^6 g of water. Therefore, if C represents the concentration in *ppm*, then the ratio of the mass of boron to the mass of water is

$$\frac{m_{boron}}{m_{H_2O}} = C \times 10^{-6} \tag{8-328}$$

giving

$$\frac{\Sigma_a^{boron}}{\Sigma_a^{\text{mod}}} = \frac{N^{boron} \sigma_a^{boron}}{N^{H_2 O} \sigma_a^{H_2 O}} = \frac{18 \times 759}{10.8 \times 0.66} \times C \times 10^{-6} = 1.92 \times C \times 10^{-3}$$
(8-329)

According to Eq. (8-327) the worth of chemical shim becomes

$$\rho_w = 1.92 \times C \times 10^{-3} \times (1 - f_{out}) \tag{8-330}$$

2. FISSION PRODUCT POISONING

Fission products and their decay products absorb neutrons to some extent. The accumulation of the parasitic absorbers during the reactor operation tends to reduce the neutron multiplication factor.

Among all non-fission materials accumulated during the reactor operation, two are of the greatest importance for thermal reactors: ¹³⁵Xe and ¹⁴⁹Sm (with large thermal neutron absorption cross sections). Since the absorption cross section decreases rapidly with increasing neutron energy (see Chapter 2), the poisoning effect is of little importance in fast reactors. The change of neutron multiplication factor with the poison materials present in a thermal reactor are discussed as follows.

The neutron multiplication factor is written as (see Chapter 7)

$$k_{eff} = k_{\infty} P = \eta \varepsilon p f P \tag{8-331}$$

where P stands for both, thermal and fast neutron non-leakage probabilities. If a poison material (strong absorber) is added

- The non-leakage probability changes slightly because it is inversely related to $L^2 = 1/3\Sigma_{tr}\Sigma_a$.
- The fast fission factor remains unchanged, $\varepsilon = \text{const.}$
- The reproduction factor does not change since it is only a function of fuel properties ($\eta = v \Sigma_f^{fuel} / \Sigma_a^{fuel}$).
- The resonance escape probability p may change depending on cross section of the poisoning material (see Fig. 8-4).
- The fuel utilization factor is inversely related to absorption cross section and thus changes drastically





Figure 8-4. Radiative capture cross section for ¹³⁵Xe and ¹⁴⁹Sm

The effect of the poison material on reactivity change is

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$$\Delta \rho = \rho - \rho = \left(\frac{k_{eff} - 1}{k_{eff}}\right) - \left(\frac{k_{eff} - 1}{k_{eff}}\right) = \frac{1}{k_{eff}} \left(1 - \frac{k_{eff}}{k_{eff}}\right) = \frac{1}{k_{eff}} \left(1 - \frac{k_{\infty}P}{k_{\infty}P}\right) (8-333)$$

Since non-leakage probability does not change significantly with the addition of poison material, $P/P' \sim 1$ and the above equation reduces to

$$\Delta \rho = \frac{1}{k_{eff}} \left(1 - \frac{f}{f} \right)$$
(8-334)

If the total absorption cross section is Σ_a it follows

$$f = \frac{\Sigma_a^{fuel}}{\Sigma_a} \tag{8-335}$$

$$f' = \frac{\Sigma_a^{fuel}}{\Sigma_a'}$$
(8-336)

where $\Sigma_a - \Sigma_a = \Sigma_a^{poison}$ and $\Sigma_a = \Sigma_a^{fuel} + \Sigma_a^{mod} + \Sigma_a^{control}$. Finally

$$\Delta \rho = \frac{1}{k_{eff}} \left(1 - \frac{\Sigma_a}{\Sigma_a} \right) = -\frac{1}{k_{eff}} \frac{\Sigma_a^{poison}}{\Sigma_a}$$
(8-337)

2.1 Xenon Poisoning

2.1.1 Production and Removal of ¹³⁵Xe During Reactor Operation

Xenon-135 (¹³⁵Xe) is the most important fission product poison and has a tremendous impact on the operation of a nuclear reactor. It is necessary to know its production and removal rate in order to predict how the reactor will respond to changes in power level. Xenon-135 is a non-1/ ν absorber (see Fig. 8-4) with a thermal neutron radiative capture (parasitic absorption) cross section of 2.6 x 10⁶ b.

$$Fission \Rightarrow {}^{135}_{51}Sb \xrightarrow{\beta'}{52}Te \xrightarrow{\beta'}{53}I \xrightarrow{\beta'}{53}I \xrightarrow{\beta'}{54}Xe \xrightarrow{\beta'}{55}Cs \xrightarrow{\beta'}{56}Ba (stable)$$

0.8sec $\uparrow\uparrow$ 19sec $\uparrow\uparrow$ 6.57h $\uparrow\uparrow$ 9.1h 2.3×10⁶ yr

Fission Fission Fission *Figure* 8-5. Production of 135 Xe in thermal reactor

Tellurium-135 (¹³⁵Te) decay chain is the primary production method of ¹³⁵Xe, however it can be produced directly from fission (see Fig. 8-5). The fission yield of ¹³⁵Xe is about 0.3 %, and is about 6 % for ¹³⁵Te. ¹³⁵Xe is a product of the β decay of ¹³⁵I which is formed by fission and by the decay of 135 Te. Tellurium-135 is fission product, but can also be formed from the β decay of ¹³⁵Sb (also a fission product). Nearly 95 % of all ¹³⁵Xe produced during reactor operation comes from the decay of ¹³⁵I.

Introducing y_i to represent the yield fraction for isotope *i* (the fraction of fission fragments that will be isotope i), and $PR = y_i \Sigma_t \phi$ to be the production rate of isotope *i*, and following the decay scheme in Fig. 8-5 it follows:
The decay times of the ¹³⁵Sb and ¹³⁵Te are very short. Thus, we may

assume that all ¹³⁵Sb and ¹³⁵Te are ¹³⁵I by defining

$$y_I = y_{Sb} + y_{Te} + y_I \tag{8-338}$$

• The last nuclide in the decay chain has a very long half-life. Thus, the stable nuclide can be taken out of our analysis and we may simplify the decay chain as follows

$$^{135}I \to ^{135}Xe \to ^{135}Cs \tag{8-339}$$

• In the case of a homogeneous thermal reactor the iodine concentration can be determined as

$$\frac{dI}{dt} = \text{Production of iodine} - \text{Loss of iodine}$$
(8-340)

or

$$\frac{dI}{dt} = y_I \Sigma_f \phi - \left(\lambda^I I + \sigma_a^I I \phi\right)$$
(8-341)

where *I* - concentration of 135 I λ^{I} - radioactive decay constant of ¹³⁵I

- σ_a^{I} thermal neutron absorption cross section of ¹³⁵I
- y_I fission yield of ¹³⁵I (=0.061 for ²³⁵U fuel)
- Σ_f macroscopic fission cross section of the fuel material in a reactor ϕ thermal neutron flux.
- Under the same assumption, the xenon concentration change can determined by:

$$\frac{dXe}{dt} = \text{Production of xenon} - \text{Loss of xenon}$$
(8-342)

or

$$\frac{dXe}{dt} = y_{Xe} \Sigma_f \phi + \lambda^I I - \left(\lambda^{Xe} Xe + \sigma_a^{Xe} Xe\phi\right)$$
(8-343)

where

Xe - concentration of ¹³⁵Xe

 λ^{Xe} - radioactive decay constant of ¹³⁵Xe

 σ_a^{Xe} - thermal neutron absorption cross section of ¹³⁵Xe

 y_{Xe} - fission yield ¹³⁵Xe (=0.002 for ²³⁵U fuel)

At steady-state the rate change of concentration of both nuclides is constant (after the reactor has been operating for some time, the *equilibrium concentration* is attained), thus by setting Equations (8-342) and (8-343) equal to zero the equilibrium concentrations may be obtained.

• ¹³⁵I equilibrium concentration

$$I_0 = \frac{y_I \Sigma_f \phi}{\lambda^I + \sigma_a^I \phi} \approx \frac{y_I \Sigma_f \phi}{\lambda^I}$$
(8-344)

The absorption cross section for 135 I is very small in the thermal energy region (see Fig. 8-6) so the above equation can be simplified by neglecting the absorption rate. The equilibrium concentration of 135 I is proportional to the fission reaction rate and power level.

• ¹³⁵Xe equilibrium concentration:

$$Xe_{0} = \frac{y_{Xe}\Sigma_{f}\phi + \lambda^{I}I_{0}}{\lambda^{Xe} + \sigma_{a}^{Xe}\phi} \approx \frac{(y_{Xe} + y_{I})\Sigma_{f}\phi}{\lambda^{Xe} + \sigma_{a}^{Xe}\phi}$$
(8-345)

The equilibrium concentration for ¹³⁵Xe increases with the power because the numerator is proportional to the fission reaction rate. Since

the thermal flux is also in the denominator, as it exceeds 10^{12} neutron/cm² sec the term including the flux becomes dominant. Thus, at nearly 10^{15} neutron/cm² sec the ¹³⁵Xe concentration approaches a limiting value.

The reactivity equivalent of the equilibrium xenon poisoning effect (by neglecting the presence of the control material) may be written in the following form

$$\Delta \rho_0 = \frac{1}{k_{eff}} \left(1 - \frac{\Sigma_a}{\Sigma_a} \right) = -\frac{1}{k_{eff}} \frac{\Sigma_a^{poison}}{\Sigma_a}$$
(8-346)





where

$$\Sigma_{a}^{poison} = Xe \sigma_{a}^{Xe} \approx \frac{(y_{Xe} + y_{I})\sigma_{a}^{Xe}\Sigma_{f}\phi}{\lambda^{Xe} + \sigma_{a}^{Xe}\phi}$$
(8-347)

To illustrate the reactivity change due to xenon accumulation, let's consider the thermal homogeneous reactor fuelled with 2 % ²³⁵U for which

$$\eta = 1.8 \qquad \nu = 2.42 \qquad \Sigma_f / \Sigma_a = 0.6$$
$$y_f + y_{xe} = 0.066 \qquad \sigma_a^{xe} = 3 \times 10^6 \text{ b} \qquad \lambda^{xe} = 2.1 \times 10^{-5} \text{ s}^{-1}$$

Using this data, and Eq (8-347)., we may re-write Eq (8-346). in the following simplified form.

$$\Delta \rho_0 = -\frac{1.15 \times 10^{-23} \phi}{2.1 \times 10^{-5} + 3 \times 10^{-22} \phi}$$
(8-348)

For a flux value of 10^{15} neutrons/cm²s the poisoning is negligible (-6 x 10^{-4}). For a flux which is ten times higher, the poisoning is still low, - 0.005, i.e. 0.5 % of all thermal neutrons are absorbed by the equilibrium amount of xenon. However, for a flux greater than 10^{16} neutrons/cm²s the poisoning increases rapidly, as shown in Fig. 8-7 and the limiting value is obtained for a flux of 10^{19} neutrons/cm²s. The equilibrium ¹³⁵I and ¹³⁵Xe concentrations as a function of neutron flux are illustrated in Fig. 8-8.



Figure 8-7. Reactivity equivalent of the equilibrium ¹³⁵Xe concentration for the example thermal reactor

2.1.2 Xenon Poisoning After Reactor Shutdown

When a reactor is shutdown, the neutron flux is reduced essentially to zero and ¹³⁵Xe is no longer produced from fission or removed by absorption.

The only remaining production mechanism is the decay of the ¹³⁵I which was in the core at the time of shutdown. The only removal mechanism for ¹³⁵Xe is its decay. Therefore, if t_s is the time after the shutdown the rate of change of xenon concentration as written in Eq. (8-343) reduces to the following

$$\frac{dXe}{dt} = \lambda^{I} I - \lambda^{Xe} Xe = \lambda^{I} I_{0} e^{-\lambda^{I} t_{s}} - \lambda^{Xe} Xe$$
(8-349)

The solution to Eq. (8-343) gives the xenon concentration over the time after reactor is shutdown



Figure 8-8. Equilibrium concentrations of ¹³⁵I and ¹³⁵Xe as a function of neutron flux

The time at which the concentration is maximum may be attained by setting Eq. (8-350) equal to zero

$$t_{\max} = \frac{1}{\lambda^{Xe} - \lambda^{I}} \ln \frac{\lambda^{Xe}}{\lambda^{I}} \left(1 - \frac{\lambda^{Xe} - \lambda^{I}}{\lambda^{I}} \frac{Xe_{0}}{I_{0}} \right)$$
(8-351)

Because the decay rate of ¹³⁵I is faster than the decay rate of ¹³⁵Xe, the ¹³⁵Xe concentration peaks. The peak value is reached when $\lambda^{I} I = \lambda^{Xe} Xe$ which is in about 10 to 11 hours for thermal reactors. The production of xenon from iodine decay is less than the removal of xenon by its own decay. This causes the concentration of ¹³⁵Xe to decrease. The concentration of ¹³⁵I at shutdown is greater for greater flux prior to shutdown which also influences the peak in ¹³⁵Xe concentration. Figure 8-9 illustrates the change in relative concentration of ¹³⁵Xe following reactor shutdown as a function of neutron flux and time after the shutdown. It can be seen that following the peak in ¹³⁵Xe controlled by the decay of ¹³⁵I and ¹³⁵Xe. A numerical example provided at the end of this Chapter describes the accumulation of xenon after reactor shut down and explains the Fig. 8-9.



Figure 8-9. ¹³⁵Xe relative concentration (Xe/Xe_0) after reactor shut down as a function of neutron flux

2.2 Samarium Poisoning

2.2.1 Production and Removal of ¹⁴⁹Sm During Reactor Operation

The fission product poison having the most significant effect on reactor operations, other than ¹³⁵Xe, is samarium–149 (¹⁴⁹Sm). Its effect is significantly different from that of ¹³⁵Xe. Samarium–149 has a thermal neutron radiative capture cross section of 4.1×10^4 b (see Fig. 8-10). It is produced from the decay of the ¹⁴⁹Nd which is itself a fission fragment as shown in Fig. 8-10. Since the ¹⁴⁹Nd decays fairly rapid in comparison to ¹⁴⁹Pm, it can be assumed that ¹⁴⁹Pm is produced directly from fission reactions with a yield of y_{Pm} .

The rate of change of its concentration is then determined by the following equation

$$\frac{dPm}{dt} = y_{Pm} \Sigma_f \phi - \lambda^{Pm} Pm$$
(8-352)

where Pm - concentration of ¹⁴⁹Pm λ^{Pm} - radioactive decay constant of ¹⁴⁹Pm

Fission
$$\Rightarrow {}^{_{49}}_{_{60}}$$
Nd $\xrightarrow{\beta}{}^{_{61}}$ Pm $\xrightarrow{\beta}{}^{_{62}}$ Sm (stable)
1.72h 53.1h

Figure 8-10. ¹⁴⁹Sm production in thermal reactor

Samarium-149 is a stable isotope and thus it is removed only by neutron radiative capture

$$\frac{dSm}{dt} = \lambda^{Pm} Pm - \sigma_a^{Sm} \phi Sm \tag{8-353}$$

where Sm - concentration of ¹⁴⁹Sm λ^{Sm} - radioactive decay constant of ¹⁴⁹Sm σ_a^{Sm} - thermal neutron absorption cross section of ¹⁴⁹Sm Solving for the equilibrium yields the equilibrium concentrations of the two isotopes

$$Pm_0 = \frac{y_{Pm} \Sigma_f \phi}{\lambda^{Pm}} \tag{8-354}$$

and

ł

$$Sm_0 = \frac{y_{Pm} \Sigma_f}{\sigma_a^{Sm}}$$
(8-355)

It can be seen from Eq. (8-355) that the equilibrium concentration of ¹⁴⁹Sm is independent of neutron flux and power level. With a change in power level, the equilibrium concentration of ¹⁴⁹Sm will go through a transient value and soon return to its original value.

2.2.2 Samarium Poisoning After Reactor Shutdown

After the reactor is shut down, Eq. (8-353) for 149 Sm production reduces to

$$\frac{dSm}{dt} = \lambda^{Pm} Pm \tag{8-356}$$

Solving this simple differential equation gives the relation for samarium concentration as a function of time after shutdown

$$Sm(t) = Sm_0 + Pm_0 \left(1 - e^{-\lambda^{Pm} t_s} \right)$$
(8-357)

where Sm_0 and Pm_0 are concentrations at shut down. Because ¹⁴⁹Sm is a stable isotope, it cannot be removed by decay, which makes its behaviour after reactor shutdown very different from that of ¹³⁵Xe, as illustrated in Fig. 8-11. The equilibrium is reached after approximately 20 days (500 hours). The concentration of ¹⁴⁹Sm remains essentially constant during reactor operation (because it is not radioactive). When the reactor is shutdown, its concentration builds up from the decay of the accumulated ¹⁴⁹Pm. The build–up after shutdown depends on the power level before reactor shutdown. The concentration of ¹⁴⁹Sm does not peak as ¹³⁵Xe, but instead increases slowly to its maximum value of $Sm_0 + Pm_0$. After shutdown, if the reactor is again operated, ¹⁴⁹Sm is burned up and its concentration returns to the equilibrium value. Samarium poisoning is miniscule when compared to xenon poisoning.



Figure 8-11. ¹⁴⁹Sm buildup as a function of time after shutdown

3. TEMPERATURE EFFECTS ON REACTIVITY

3.1 Temperature Coefficients

The change in reactivity with temperature is described in terms of the temperature coefficient of reactivity. Different materials in a reactor are at different temperatures and produce various effects on reactivity. The temperature in a reactor does not change uniformly. An increase in reactor power would first cause an increase in fuel temperature (the region where power is generated). The coolant and moderator temperatures will change after the heat is transferred from the fuel. Thus, the two main temperature coefficients which are usually specified for thermal reactors are the fuel temperature coefficient and the moderator temperature coefficient. The general definition for the temperature coefficient of reactivity is

$$\alpha_T = \frac{d\rho}{dT} \tag{8-358}$$

or replacing the reactivity (see Chapter 7)

$$\rho = 1 - \frac{1}{k_{eff}} \rightarrow \alpha_T = \frac{1}{k_{eff}^2} \frac{dk_{eff}}{dT}$$
(8-359)

Since the multiplication factor is close to unity, Eq. (8-359) is simplified

$$\alpha_T \cong \frac{1}{k_{eff}} \frac{dk_{eff}}{dT} \left[\frac{1}{\text{degree}} \right]$$
(8-360)

The response of the reactor to a change in temperature depends on the algebraic sign of the temperature coefficient

- 1. $\alpha_T > 0$: since multiplication factor is always positive value, then dk_{eff}/dT is also positive. In other words, an increase in temperature leads to an increase in neutron population.
- Increase in temperature in a reactor thus increases the reactor power. This will, in turn, increase the temperature more and thus multiplication factor will be increased further which will increase power further and so on. Thus, when the temperature increases the power of a reactor increases and it can be stopped only by outside intervention.
- If temperature is decreased, the multiplication factor will decrease as well. The reactor power will decrease which will reduce temperature further and will reduce the neutron multiplication which will reduce reactor power and temperature and so on. Thus, in this case reactor will shutdown in the absence of external intervention.
- 2. $\alpha_T < 0$: since multiplication factor is always positive value, then dk_{eff}/dT is negative. In this case, an increase in temperature decreases the neutron multiplication factor.
- An increase in reactor temperature will cause reactor power to drop which will decrease the temperature. This temperature reduction will tend to return the reactor to its original state.
- A decrease in temperature will result in an increase in multiplication factor. Therefore, if temperature is reduced, the power of the reactor will increase and the reactor has a tendency toward its original operating conditions.

Thus, a reactor with a positive temperature coefficient is inherently unstable while a reactor with a negative temperature coefficient is inherently stable.

3.2 Fuel Temperature Coefficient (Nuclear Doppler Effect)

The fuel reacts immediately to a change in a temperature. The fuel temperature reactivity coefficient is also called the prompt temperature coefficient or the nuclear Doppler coefficient. Fuel temperature promptly responds to a change in reactor power, a negative fuel temperature reactivity coefficient is more important than a negative moderator temperature coefficient. The time for heat generated in the fuel region to be transferred to the moderator is on the order of seconds. When a large positive reactivity insertion occurs, the negative moderator temperature coefficient cannot affect the power in that short time while the fuel temperature coefficient starts adding negative reactivity immediately. Two important nuclides which dominate the nuclear Doppler Effect are ²³⁸U and ²⁴⁰Pu.

In a typical light-water moderated low enriched fuel thermal reactor the fuel temperature reactivity coefficient is negative as a result of the nuclear Doppler Effect (called Doppler broadening). Doppler broadening is caused by an apparent broadening of the resonances (see Chapter 6, Fig.6-22) due to thermal motion of nuclei, explained as follows

- Stationary nuclei would absorb a neutron of energy E_0 .
- If nucleus is moving away from a neutron the velocity and energy of the neutron must be greater than energy E_0 for it to undergo resonance absorption.
- If nucleus is moving toward the neutron, the required neutron energy would be less energy than E_0 in order to be captured by the resonance.
- Increased temperature of the fuel causes nuclei to vibrate more and thus broadening the neutron energy range where they are resonantly absorbed in the fuel region.

If the temperature is increased, the magnitude of the absorption cross section is decreased due to Doppler broadening effect which will increase neutron flux (analogous to the removal of a strong absorber from the core). The number of neutrons absorbed in the resonance region is proportional to the average neutron flux thus the number of resonance absorption increases with temperature. If the parasitic absorptions are increased, the multiplication factor will be reduced which accounts for the negative value of the prompt fuel temperature coefficient. The higher temperatures lead to larger widths of resonances and thus a broader energy region where neutrons can be absorbed.

The nuclear Doppler coefficient is obtained as follows

• By expressing the neutron multiplication as in Eq. (8-331), the resonance escape probability can be obtained in the following form

$$\ln k_{eff} = \ln(\eta \epsilon f P) + \ln p_{esc}$$
(8-361)

• Differentiating with respect to temperature and assuming all parameters to be constant except the resonance escape probability results in a simple expression for the Doppler coefficient

$$\frac{d}{dT}\left(\ln k_{eff}\right) = \frac{1}{k_{eff}} \frac{dk_{eff}}{dT} = \frac{d}{dT}\left(\ln p_{esc}\right) = \frac{1}{p_{esc}} \frac{d\rho}{dT}$$
(8-362)

3.3 The Void Coefficient

The void coefficient of reactivity, α_v , is defined as a rate of change in the reactivity of a water moderated reactor resulting from a formation of steam bubbles as the power level and temperature increase. The void fraction, *x*, is defined as the fraction of a given volume which is occupied by voids. If 30% of a volume is occupied by vapor with the rest being occupied by water then x = 0.30. The void coefficient of reactivity is defined as

$$\alpha_{\nu} = \frac{d\rho}{dx} \tag{8-363}$$

The response of the reactor to a change in void fraction depends on the algebraic sign of the void coefficient

- 1. $\alpha_v > 0$: an increase in void fraction will increase the reactivity. This will cause the reactor power to rise, which will increase the boiling and void formation. More voids will increase the reactivity and reactor power further which will increase the void fraction and so on. Without external action the reactor power will continue to increase until much of the liquid is boiled and reactor core melts down.
- 2. $\alpha_{\nu} < 0$: an increase in void fraction will reduce the reactivity and thus the reactor power. This condition tends to return the reactor to its initial state.
Thus, a negative void coefficient is desirable.

The void coefficient is related to the moderator coefficient (see next Section) because the change in void fraction changes the density of the moderator, or coolant in thermal reactors. In water cooled and moderated reactors the increase in void fraction decreases the reactivity and the void coefficient is negative. In fast reactors cooled with the liquid sodium the effect of void formation is the opposite. Namely, sodium slows down neutrons through inelastic scattering at high energies and absorbs neutrons at low energies. Thus, the removal of sodium causes reduced moderation and the neutron spectrum becomes harder which, in turn, increases the reactivity (the average number of fission neutrons released per neutron absorbed, η , increases with neutron energy for all fissile nuclides in fast reactors). Also, an increase in void formation increases neutron leakage because the density of coolant is reduced. This effect reduces the void coefficient and tends to make it negative. The sign of the void coefficient is determined by the value of these two factors. In large power fast reactors the void formation has a local effect. For example, if a void is formed in the central region of the core, the void coefficient will be positive since neutron leakage has little importance. The leakage becomes more important and reduces the void coefficient if void occurs toward the peripheral region of the core.

3.4 The Moderator Coefficient

3.4.1 Moderator Temperature Coefficient

The moderator temperature coefficient, α_{mod} , determines the rate of change of reactivity with moderator temperature. This coefficient determines the ultimate response of a reactor to fuel and coolant temperature change. It is desirable to have a negative moderator temperature coefficient because of its elf-regulating effect. In thermal reactors when the moderator temperature is increased

- 1. the physical density of the moderator liquid is changed due to thermal expansions, and
- 2. thermal cross sections change.

The increased temperature of the moderator in water moderated reactors will cause the neutron flux to move toward higher neutron energies. This is an especially promoted effect when absorption cross section does not follow a 1/v dependence. Thus, the presence of, for example, ²³⁸U at higher temperatures will increase parasitic absorptions and thus tend to keep the

coefficient negative. The change in the neutron spectrum at increased moderator temperature has effect on reactivity which is more pronounced in the presence of poisons such as ¹³⁵Xe and ¹⁴⁹Sm because of their resonances placed at very low neutron energies (around 0.1 eV). The moderator expands at increased temperature which causes a reduction in the density of atoms present; therefore the efficiency of the moderator is reduced.

The magnitude and sign of the moderator temperature coefficient depends on the moderator-to-fuel ratio in such a manner that if

- reactor is under-moderated the coefficient will be negative
- reactor is over-moderated the coefficient will be positive.

3.4.2 Moderator Pressure Coefficient

The moderator pressure coefficient of reactivity is defined as the change in reactivity due to a change in system pressure. The reactivity is changed due to the effect of pressure on the moderator density. When the pressure is increased, the moderator density is increased which, in turn, increases the moderator-to-fuel ratio in the core. In the case of an under-moderated core, the increase in moderator-to-fuel ratio will result in a positive reactivity insertion. In water moderated reactors, this coefficient is much smaller than the temperature coefficient of reactivity.

NUMERICAL EXAMPLE

Xenon and Iodine concentration after shutdown

As described in Section 2.1.2 the xenon and iodine concentrations over the time after reactor is shutdown is calculated using Eq.(8-344), (8-345) and (8-350). The iodine concentration may be obtained from Eq. (8-341). For the data listed in Table 8-1, calculate the xenon and iodine concentrations as a function of time after shutdown of a 235 U thermal reactor which operated at a flux of 10¹⁵ neutrons/cm²sec. The solution was obtained using MATLAB and shown in Fig.8-12.

Table 8-1. Data for U thermal reactor	
Uranium density	19.1 g/cm ³
Xenon-135 fission yield	0.00237
Iodine-135 fission yield	0.0639
Xenon-135 decay constant	$2.09 \cdot 10^{-5} \text{ sec}^{-1}$
Iodine-135 decay constant	$2.87 \cdot 10^{-5} \text{ sec}^{-1}$
Xenon-135 absorption cross section	2.65·10 ⁶ b
Uranium-235 fission cross section	582.2 b

Table 8-1 Data for ²³⁵U thermal reactor

Solution in MATLAB:

```
clear all
lambdaXe = 2.09*10^{-5}; \% s^{-1}
lambdaI = 2.87*10^-5; % s^-1
gammaI = 0.0639; % I-135 fission yeild
gammaXe = 0.00237; % Xe-135 fission yield
sigmaf = 19.1*6.022e23*(582.2*10^-24) / 235; % U-235 fission cm^-1
sigmaaXe = (2.65e6)*10^-24; % Xe-135 absorption cm^2
flux = 10^{15}; % cm<sup>-2</sup> * s<sup>-1</sup>
t = linspace(0, 180000);
figure
hold on
% Equilibrium Concentrations
IO = gammaI * sigmaf * flux/lambdaI;
Xe0 = (lambdaI*I0 + gammaXe*sigmaf*flux) / (lambdaXe + sigmaaXe*flux);
for i = 1:100
% Build-up After Shutdown
  I(i) = I0 \exp(-lambdaI t(i));
  Xe(i)=Xe0*exp(-lambdaXe*t(i))+(lambdaI*I0/(lambdaI-
        lambdaXe))*(exp(-lambdaXe*t(i)) - exp(-lambdaI*t(i)));
end
plot(t/3600,I,k')
hold on
plot(t/3600,Xe,'k:')
xlabel('Time After Shutdown (hr)')
ylabel('Concentration (cm^-^3)')
legend('Iodine-135','Xenon-135')
```



Figure 8-12. ¹³⁵Xe and ¹³⁵I concentrations after shutdown of a ²³⁵U thermal reactor

PROBLEMS

8.1 Plot the differential and integral control rod worth curves if the differential rod worth data is given as follows:

Fractional distance from the bottom of the core Inserted reactivity

0-0.125	0.1
0.125 - 0.25	0.2
0.25 - 0.375	0.4
0.375 - 0.5	0.6
0.5 - 0.625	0.6
0.625 - 0.75	0.4
0.75 - 0.875	0.2
0.875 - 1	0.1

8.2 Explain the role of soluble poisons (chemical shim) in thermal reactors.

8.3 In order to control and minimize the corrosion in the reactor coolant system the pH of the coolant is monitored. In nuclear reactors that do not use chemical shim pH is maintained at values high as 10. In reactor systems that use chemical shim (boric acid) how would the pH limit change?

8.4 Chemical shim in thermal reactors primarily affects the thermal (fuel) utilization factor. Derive the relation for the chemical shim worth.

8.5 A common pair of fragments from ²³⁵U fission is xenon and strontium. Write the reaction and calculate: energy released per this fission event; investigate the decay scheme of xenon and strontium; discuss how xenon is removed from the reactor; discuss the equilibrium level of xenon.

8.6 Describe the effect of the poison material on reactivity change.

8.7 Sketch the behaviour of xenon poisoning.

8.8 Discuss the loss and production of xenon on reactor start-up and on power decrease from steady state to full power.

8.9 Discuss the production and removal of samarium.

8.10 Discuss the samarium response to reactor shutdown.

8.11 Solve the differential equation that describes the xenon concentration change after reactor shutdown.

8.12 Derive the relation to obtain the time needed to achieve the maximum concentration of xenon after reactor shutdown.

8.13 Define temperature coefficients.

8.14 For the moderator coefficient of -15 pcm/K calculate the reactivity change that results from a temperature decrease 3.5K.

8.15 How will macroscopic cross section of a moderator change if with increased temperature its density decreases? How will thermal utilization factor change?

8.16 Discuss the fuel temperature coefficient and why it is negative?

Appendix 1: World-Wide Web Sources on Atomic and Nuclear Data

Periodic Table of the Elements

- First ionization potential: http://web.mit.edu/3.091/www/pt/pert9.html
- Atomic and chemical characteristics of elements: <u>http://pearl1.lanl.gov/periodic/default.htm</u>
- Comprehensive set of data: http://www.chemistrycoach.com/periodic_tables.htm

Table of nuclides

- Cross section plots and fundamental characteristics of nuclides: <u>http://atom.kaeri.re.kr/</u>
- Nuclear physics data: <u>http://physics.nist.gov/PhysRefData/</u>
- Ionization potentials: http://environmentalchemistry.com/yogi/periodic/1stionization.html

Electron and photon attenuation data: <u>http://atom.kaeri.re.kr/ex.html</u>

Physical constants: <u>http://physics.nist.gov/PhysRefData/</u>

Atomic and molecular spectroscopic data: <u>http://physics.nist.gov/PhysRefData/</u>

X ray and γ ray data: <u>http://physics.nist.gov/PhysRefData/</u>

Stopping-power and range tables for electrons, protons, and helium ions:

http://physics.nist.gov/PhysRefData/Star/Text/contents.html

National nuclear data center: http://www.nndc.bnl.gov/index.jsp

- Nuclear structure and decay database: http://www.nndc.bnl.gov/databases/databases.html#structuredecay
- Nuclear reactions databases: <u>http://www.nndc.bnl.gov/databases/databases.html#reaction</u>

Appendix 2: Atomic and Nuclear Constants

Fundamental Constants

Quantity	Symbol	Value	Unit
Atomic mass unit	amu or u	1.66053 x 10 ⁻²⁴	g
		931.481	MeV
Avogadro's number	N_A	6.02217 x 10 ²³	Mole ⁻¹
Boltzmann's constant	k	1.38062 x 10 ⁻²³	J/K
Electron rest mass	m_e	9.10956 x 10 ⁻²⁸	g
		5.48593 x 10 ⁻⁴	amu
		0.511004	MeV
Elementary charge	е	1.602192 x 10 ⁻¹⁹	С
Neutron rest mass	m_n	1.67493 x 10 ⁻²⁴	g
		1.008665	amu
		939.553	MeV
Newtonian gravitational constant	G	6.6742 x 10 ⁻¹¹	$m^3 / kg s^2$
Planck's constant	h	6 626069 x 10 ⁻³⁴	Js
		4.135667×10^{-15}	eV s
Proton rest mass	m_p	1.67261 x 10 ⁻²⁴	g
	-	1.007277	amu

Quantity	Symbol	Value	Unit
		938.259	MeV
Speed of light	С	2.99792458 x 10 ¹⁰	cm/s
Stefan-Boltzmann constant	σ	5.670400 x 10 ⁻⁸	W m ⁻² K ⁻⁴

Atomic and Nuclear Constants

Quantity	Symbol	Value	Unit
Bohr radius	$a_0 = \frac{\hbar^2}{ke^2m}$	0.05291771	nm
Classical electron radius	r _e	2.817940 x 10 ⁻¹⁵	m
Compton wavelength	λ_C	2.426310 x 10 ⁻¹²	m
Rydberg constant	$R = \frac{ke^2}{2a_0} \frac{1}{hc}$	10973731.568	m ⁻¹
Rydberg energy	$E_R = hcR$	2.179872 x 10 ⁻¹⁸ 13.6	J eV

Appendix 3: Prefixes

Factor	Prefix	Symbol
10 ¹⁸	exa	Е
10 ¹⁵	peta	Р
10^{12}	tera	Т
10 ⁹	giga	G
10^{6}	mega	Μ
10^{3}	kilo	k
10^{2}	hecto	h
10^{1}	deka	da
10-1	deci	d
10 ⁻²	centi	с
10-3	milli	m
10-6	micro	μ
10 ⁻⁹	nano	n
10-12	pico	р
10 ⁻¹⁵	femto	f
10-18	atto	а

Appendix 4: Units and Conversion Factors

Angle

<u>_</u>		×	
Unit	Symbol	Value	
Radian	rad	0.01745	
Degree	0	1	
Minute	4	60	
Second	••	3600	

Energy

~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~		
Unit	Symbol	Value
Joule	J	1
Erg	erg	10 ⁷
Watt second	Ws	1
Kilowatt hour	kWh	2.7778 x 10 ⁻⁷
Mega electron volt	MeV	$6.242 \times 10^{12}$
British thermal unit	Btu	9.478 x 10 ⁻⁴

## Length/Distance

Unit	Symbol	Value
Angstrom	А	$10^{10}$
Nanometer	nm	10 ⁹
Micrometer	μm	$10^{6}$
Millimeter	mm	$10^{3}$
Centimeter	cm	$10^{2}$
Meter	m	1
Kilometer	km	10 ⁻³
Inch	in (")	39.37008
Foot	ft (')	3.28084

Unit	Symbol	Value
Yard	yd	1.09361
mile	mi	6.2137 x 10 ⁻⁴

## Mass

Unit	Symbol	Value
Milligram	mg	106
Gram	g	$10^{3}$
Kilogram	kg	1
Ounce	oz	35.274
Pound	lb	2.2046
Tonne (metric)	t	10-3

## Temperature

1 cmper atar e		
Unit	Symbol	Value
Fahrenheit	F	C x (9/5) + 32
Celsius	С	С
Kelvin	К	C + 273.15

## Time

Unit	Symbol	Value
Second	s or sec	3.1536 x 10 ⁷
Minute	m or min	$5.256 \times 10^5$
Hour	h or hr	8760
Day	da	365
Week	wk	52.14286
Month	mo	11.99203
Year	yr or a	1

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